# MAGIC, A COMPUIER CODE FOR DESIGN STUDIES OF INSERTIONS AND STORAGE RINGS 

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## ABSTRACT

MAGIC is a computer code for design study of storage ring lattices and insertions. The first version ${ }^{1}$ of this code was developed during the NAL 1973 Summer Study at ASPEN for the design of lattice insertions. Since that time, the code has been extensively modified at SLAC for the design of storage ring lattices and has been used for the study of the PEP lattices.

We have incorporated into MAGIC the experiences we acquired from the design study of SPEAR, the use of TRANSPORT ${ }^{2}$ and SYNCH ${ }^{3}$, and the use of the SPEAR control program RING. We hope that users will find MAGIC to be a useful and efficient code for lattice design and configuration survey. In order to save time, MAGIC finds an approximate solution using thin-lens magnets. However, as an option the user can obtain a tabulation of the machine functions and the values of the lattice elements for an equivalent thick-lens solution corresponding to the approximate thin-lens solution. It has been found that the agreement between the results obtained by these solutions is usually better than a few percent, except for the value of quantum lifetime which is more critically dependent upon the machine parameters than other quantities.

Some of the salient features of the code are: (1) the input and output machine parameters are given in the Courant-Snyder notation ${ }^{4}$ ( $\beta, \eta$-functions, etc);
(2) it is possible to design insertion lattices with fitting conditions specified at up to three points along the beam line; (3) it can be used for design of two lattices in cascade with the first equal to either a periodic cell or an insertion; (4) any parameter involving integration of some of the machine functions over the magnets can be easily computed because the integrand is a $\delta$-function in the thinlens approximation.

For insertion design using a least squares procedure ${ }^{5}$, MAGIC finds the values of the magnet strengths or drift lengths for the variable lattice elements such that the values of $\beta, \alpha, n, \eta^{\prime}$ at both ends of the insertion and $\Delta v$ through the insertion, or the transport matrix elements are matched to the desired values. For storage ring design, the program finds the parameter values of the variable lattice elements for specified values of $\dot{b}$ and $\eta$-functions at the interaction point and betatron tune $v$, as well as specified matching conditions of the $\beta$ and $\eta$-functions and theif:
derivatives at some desired points in the ring lattice.

For electron storage ring design ${ }^{6}$, the code also computes the synchrotron integrals, the partition constants and damping times, natural beam sizes and energy spread, luminosity for head-on colliding beams and the beam current value imposed by the beam-beam tune shift, transverse beam envelopes, chromaticities, sextupole field values for zero chromaticities, synchrotron frequency, synchrotron phase angle and RF bucket size, bunch length, quantum lifetime and momentum compaction factor.

## 1. GENERAL DESCRIPTION

MAGIC has been written for the design of two types of lattices, insertion and cell. A cell is defined as a special kind of lattice which has the following properties: (1) $\alpha=\eta^{\prime}=0$ at both ends of the lattice; (2) the $\beta$ and $\eta$ values at one end of the lattice are equal to those at the other end.

A lattice configuration is specified by a set of values of the machine functions such as $\beta, \eta, \alpha, \eta^{\prime}$ and $\Delta v$ at both ends as well as at the desired fit points along the lattice.

For survey of lattice configurations, the user specifies two sets of values: one set $\left\{\bar{V}_{i}\right\}$ for the initial configuration and the other set $\left\{\bar{V}_{f}\right\}$ for the final configuration. In addition, the code defines $N$ intermediate configurations corresponding to the $N$ sets of machine function values as defined by $\left\{\bar{v}_{k}\right\} \equiv\left\{\bar{v}_{i}+k\left[\bar{v}_{f}-\bar{v}_{i}\right] /(N+1)\right\}$ for $k=1,2, \ldots, N$ where $N$ is a number specified by the user.

To start fitting, the user makes a guess solution for the lattice element values corresponding to the initial configuration. Using the guess values, MAGIC first finds the solution for the initial configuration. Then using the initial solution as the guess solution, MAGIC finds a solution for the first intermediate configuration. This procedure continues until all the solutions are found.

Since thin-lens elements are used in MAGIC, only one value, $x$, is needed to specify an element. For a drift space, $X$ is specified by the drift length, $\ell$, in meters; for a bending magnet $X$ is specified by the angle of bend, $\ell / \rho$, in degrees, where $\ell$ is the effective magnet length and $\rho$ is the bending radius; for a quadrupole magnet $X$ is specified by $g \ell / B \rho$ in meter ${ }^{-1}$, where $\ell$ and $g$ are the magnet length and field gradient, and $B p$ is the particle rigidity.

The value of a lattice element can either be a fixed constant or variable as desired by the user. Constraints can be imposed upon some of the values of the variable such that $\sum C X$ is an invariant, where the summation is evaluated over all of the variables to be coupled. The values of the constants C's are specified by the user.

In order to distinguish the values of the machine functions at the beginning of a lattice from those at the fit points or end point, we use a subscript 1 to denote the initial values and a subscript 2 to denote the final values, corresponding to the beginning point. The subscripts $i$ and $f$ are used to refer to those for the initial and final configurations at the fit points and end point.

The functions to be fitted and the desired values at the fit point are specified by the user in the order of the relative position of the fit points along the lattice; those for a fit point closer to the beginning of the lattice are specified before those farther away. Those for the end point are specified last.

To compute the machine and beam parameters for an clectron storage ring lattice, the effective lengths of the bending magnets in meters are required for the evaluation of the synchrotron integrals. In addition, sextupole field corrections corresponding to zero chromaticities can be computed.

In addition to the lattice elements the user may specify points of interest such as the locations of an interaction point, fit points and sextupole magnets. Other required input values for the code are: status of the program flags; values of the internal constants; heading for each beam line; an instruction to terminate the input data.

MAGIC can also be used to find the values of the machine functions at each element for an input solution without any fitting for either a thin-lens or thick-lens lattice via the flag status. In the input data the lengths of the drift spaces are the same for both cases. For the thick-lens lattice these drift lengths are modified appropriately by the code, taking into account the finite magnet lengths.

As an example, the input data for a PEP lattice ${ }^{7}$ are given in the next section as well as descriptions for the commands in the code.
2. COMMANDS

The code is executed by a set of commands. The commands used for a storage ring lattice are described in this Section to illustrate how to set up the input data. The function of each command is also described.

There are a total of nineteen commands in the code.

A command must be entered between column 8 and 10 . The commands may be grouped into eight sets depending upon the task: they perform:

```
FLG
NUM
DRF, QUA, BBX, BBY
FIT, INT, SEX
REM, INS, CEL, VAR, CON
FUN, VAL
LUM, CLR
FIN
```

The first command in the input data musr be FLG and the last must be FIN. The names used in each command must be enterad between column 21 to 80 with five columns allowed for each name. Each nar e must be equal to or less than four characters and must be left-justified. If a name has a value, the value must be entered directly below the name on the line below in the same five columns and also must be left-justfied. However, not all commands have values. For the DRF, QUA, BBX, BBY, INS, CEL, VAR, VAL and LCY commands, the user can use as many lines as he may choose for a command provided that there is no blank entry between the names. A blank entry terminates the infut data on a line. For convenience, comments can be inserted anywhere in the input data. A comment is indicated by a non-blank character in column 1. These features can be seen from the example given in this section.

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FLG sets the control flags. The possible flags are: LB, LQ, ALL, SYN and THK. LB is used to read the bending magnet lengths if the user wishes to compute the luminosity for an $e^{+} e^{-}$storage ring lattice. LQ is used to read the quadrupole magnet lengths. Both LB and LQ are needed if the user wishes to find thick-lens solutions. ALL is used to obtain print out for all of the configurations found by the code: ie, if ALL is omitted, only output for the initial and final configurations is printed. SYN is used if no fitting is required and the machine functions are to be fomputed directly from the input data values. THK is used for finding thick-lens solutions in addition to the thin-lens solutions.

The input data for the drift lengths are the same for both thin and thick-lens solutions. IF THK is used the drift lengths are adjusted internally by subtracting one half of the lengths of the adjacent magnets from the input values. Drift length between two magnets is given by the distance between the centres of the magnets. The bending magnets are assumed to be rectangular magnets for the thicklens lattices.

NUM gives the values of two internal constants required by the code, STP and ESP. STP is the total number of configurations desired by the user. The naximum acceptable convergence value is related to $10^{-\mathrm{ESP}}$. The larger the value of ESP the smaller is the acceptable convergence value. The input data for the values of Stp and ESP must be integers. Typical values of ESP are 8 or 9 corresponding to convergence values of $10^{-6}$. The user should try different values of ESP in order to establish the acceptable convergence value for a given problem.

The set of commands which defines the laitice elements are: DRF, BBX, BBY and QUA. In the example quoted earlier, the drift lengths are $D C, D Q, D 1, \ldots$ with their values given as $4.28,1.0,10.5, \ldots m$, respectively. The horizontal bending magnet is $B B$ with the angle of $b=n d$ equal to 1.875 degrees and effective length 5.56 m . The quadrupole magnets are: QFH with strength equal to $0.03 \mathrm{~m}^{-1}$ and length 0.39 m ; QDH with strength equil to $-.027 \mathrm{~m}^{-1}$ and length 0.39 m , etc. In MAGIC the convention has been adapted that a positive value of angie is used for normal bend, and a negative value is used for reverse bend. Also, for quadrupole magnets, a positive value of strength defines a radially focussing magnet, and a negative value defires a radially defocussing magnet. The maximum number of elements in DRF, BEX, EBY and QUA commands are 50, 20, 10 and 40, respectively.

Besides the lattice elements defined in the preceding Section, the user may give names of some special points along the beam line. These points are defined by: INT, FIT and SEX. INT is a command which gives the name to be used for the interaction point for an $e^{+} e^{-}$storage ring such as $\%$ in the above example. This command is required only if computation of beam parameters is desired. The value of luminosity is to be computed using the values of machine parameters at this point. FIT is used to give the names for the fit points such as FITI in this example. The user may use up to three names in this command. The end point is always assumed to be a fit point so that no name is needed for it. If the correction of chromaticities is desired, SEX is used to give the names of two types of sextupole magnets such as $S D$ and $S F$ in this example.

The strengths of these magnets $\lambda \ell / B \rho$ will be found to yield zero chromaticity in both $x$ and $y$ planes, where the field in the magnet $B_{y}$ is given by $\lambda\left(x^{2}-y^{2}\right)$.

Unless the user is designing an $e^{+} e^{-}$storage ring lattice. INT and SEX are not needed.

This set of commands defines the elements in a beam line and specifies the variable elements. REM is used preceding INS or CEL to enter the heading for the beam line. There are two possible types of beam line: INS and CEL. INS is used for an insertion lattice and CEL is used for a periodic cell lattice. No fit point may be used within a cell lattice. In the example of this Section the beam line is an insertion with one fit point. The beam line starts at the interaction point ( $\%^{*} \%$ ) and ends at a symmetry point at the middle of a superperiod (centre of a QF magnet). The fit point (FITI) is located at the middle of the last cell at the centre of a $Q D$ magnet. One of the magnets $Q F$ and $Q D$ has been split into two halves; each half is labelled by a subscript H (QFH and QDH). The elements in the beam line must be previously defined in the commands for lattice elements and special lattice points. The first element is DI, the second is Q3H which is half of Q3, the third is DQ, the fourth is another 034 , etc. It has been found from experience that for strong quadrupole magnets such as $Q 3$ and $Q 2$, adjacent to the low- $\beta$ interaction region, it is necessary to use two thin-lens magnets to represent each of these magnets with the thin-lens magnets located $\ell / 4$ from the centre of the magnet. ( $D Q=\ell / 2$ ). The other quadrupole magnets are represented by single thin-lens magnets.

VAR is used to identify the names of the variable lattice elements in the beam line. In this example the variables are Q3H, Q2H, Q1 etc. The order in which the variable names appear in VAR is not important.

CON is used to define constraint between a subset of the variables by the equation:

$$
\sum_{i} c_{i} x_{i}=\sum_{i} c_{i} x_{i} \quad \text { (input value) }
$$

where the C's are constants in the input data and X's are the values of the variables in the subset. In this example the first CON command is used to keep the value of $Q F H$ equal to $1 / 2$ of the value of $Q F$.

$$
1.0 x_{Q F}-2.0 x_{Q F H}=1.0 \times 0.06-2.0 \times 0.03 \equiv 0
$$

Each constraint must be defined by a CON command.

Variable elements in the beam line with the same names are coupled internally in pairs. The total nurber of constraints has been chosen to be 40 . The maximum number of CON commands available to the user is ( $40-N C$ ) where NC is the number of constraints used internally for coupling between pairs of variable elements having the same names. In this example the first Q3H is coupled to the second $Q 34$ via an internal constraint with the value of $C$ equal to 1.0 for the first Q3H, and equal to -1.0 for the second $Q 3 H$. The Maximum number of variables is 40 and the maximum number of elements in a beam line is 200. Each time a variable name appears in the beam line it should be counted as one variable. The number of internal constraints for coupling between pairs of variables having the same name is equal to (the number of these variables) -1.

FUN is used to specify the machine functions to be fitted. VAL is used to enter the values of these functions at the fit points and at the end point: A pair of FUN/VAL commands must be used for each fit point. The first FUN/VAL pair is taken to be the commancs for the nearest fit point from the beginning of the beam line, and the last $F U N / V A L$ pair for the end point.

The names of the functions are: $B X, B Y, A X, A Y, E X, E Y, E X P, E Y P, X N U$ and $Y N U$, for the functions $\beta_{x}, \beta_{y}, \alpha_{x}, \alpha_{y}, \eta_{x}, \eta_{y}, \eta_{x}^{\prime}, \eta_{y}^{\prime}, \Delta \nu_{x}$ and $\Delta \nu_{y}$, respectively. The names used in VAL are the same as those used in FUN but with a subscript 1 or $F$ added to those names; 1 refers to the value of a function for the initial configuration and $F$ refers to the value for the final configuration.

In addition to the machine functions the user may specify fitting conditions for the transport matrix elements: XIJ and YIJ for the (ij) matrix elements. similarly, the names to be used in VAL are $X I J I, X I J F, Y I J I$ and $Y I J F$.

If fitting of the machine functions is desired, the user must also enter the value of these functions at the beginning point of the beam line. These values could be entered in any of the VAL commands. The subscripts 1 and 2 are used to denote the values of these functions for the initial and final configuration, respectively.

Since a periodic cell lattice has some special properties the possible machine functions to be used are: $B X, B Y, E X, E Y, X N U$ and $Y N U$. Furthermore, only one pair of FUN/VAL is needed if the CEL command is used for the beam line because no fit point is allowed.

In the example chosen here $S T P=3$, so that only one intermediate configuration will be found by the code. The variations of betatron tune values and beta values at the interaction point are: for the initial configuration $\Delta v_{x}=1.06, \Delta v_{y}=1.06$ and $\beta_{x}=7.0 \mathrm{~m}$; for the intermediate configuration $\Delta v_{x}=1.065, \Delta \nu_{y}=1.055$ and $\beta_{x}=6.5 \mathrm{~m}$; for the final conifiguration $\Delta \nu_{x}=1.07, \Delta v_{y}=1.05$ and $\beta_{x}=6.0 \mathrm{~m}$. For all three configurations $\alpha_{x}=\alpha_{y}=\eta^{\prime}=0.0$ at the fit point and at the end point; $\eta=-1.4 \mathrm{~m}$ and $\beta_{y}=0.06 \mathrm{~m}$ at the interaction point. Since the value of any function not specified in the VAL commands is set equal to zero internally by the code, then at the interaction point $\alpha_{x}=\alpha_{y}=\eta^{\prime}=0.0$ by default.

Furthermore, if the input value for XNUI, YNUI, XNUF or YNUF is given by $\Delta v=k . x x x$ the integer $k$ is ignored, eg, $X N U I=1.06$ is taken to be $\mathrm{XNUI}=0.06$ by the code. Thus, it is possible to find solutions having tune variations between two adjacent integers, $n+1>\Delta v>n$, by making a single run of the code.

To find solutions with tune variations crossing an integer it is necessary to make successive runs. For example, consider the case $2.4 \geqslant \Delta v_{x} \geqslant 1.5$. These solutions can be found by making two successive runs. The first run for $2.4 \geqslant \Delta \nu_{x} \geqslant 2.0$ and the second run for $1.999 \geqslant \Delta v_{x} \geqslant 1.5$. The solution for $\Delta v_{x}=2.0$ obtained by the first run should be used as a guess solution in the second run in order to be sure that all the solutions belong to the same family.

LUM is used for computation of natural bean size and luminosity for an $e^{+} e^{-}$ storage ring. In each run, the energy of the beam can be varied for different configurations: PI and PF are the beam energy for the initial and final configuration in GeV, respectively. More than one luminosity and beam size computation can be made for each configuration depending on the value of NLUM. NINS is the number of beam lines as defined in the INS command which makes up the storage ring. DNUI, and $V 1$ are the value of beam-beam tune shift and total RF voltage in MeV to be used for the first luminosity computation. DNU2 and V2 are those for the last computation. $H$ is the $R F$ harmonic number. NB is the number of bunches in one beam.

The values of luminosity and beam size are normally computed for the optimum coupling ${ }^{8}$ case assuming equal beam-beam tune shift values for both radial and vertical motion. It is possible to compute these quantities for input values of coupling constant by adding $A 1$ and $A 2$ in the LUM command. A1 is the value of coupling constant for the first computation of luminosity and beam size and A2 for the last computation.

In addition, the effects upon the value of beta-function and betatron tunes for different off-momentum particles due to the sextupole corrections can be computed by adding the names $D R$ and NDR in the LUM command. These effects will be computed for particles with energy deviations $\Delta p / p$ equal to $k$ (DR) for $k=-N D R, \ldots, 0$, $\ldots$, NDR. NINT is the number of interaction points in a storage ring. If NINT is used in the LUM command the limiting value of the linear tune shift imposed by the change in momentum compaction value due to beam-beam interaction ${ }^{9}$ is computed. The data values for NINS, NLUM, NINT, NDR, $H$ and NB must be integers.

CLR is used to compute the values of no and no' at every element along a beam line, where $\sigma$ is the standard deviation value for a Gaussian particle distribution and $n$ is any integer. The values of $\sigma$ and $\sigma^{\prime}$ are those obtained by the LUM command. The value for $n$ is given by NSTD which must be an integer.

It is also possible to compute no and no' for input values of $\sigma$ and $\Delta p / p$ at the beginning point of an insertion. For this case the names SIGX, SIGY and SIGE are added to the daza in the CLR command, where SIGX and SIGY are the values of $\sigma$ in cm and $S I G E$ is the value of $\Delta p / p$. The values of $\sigma_{x}^{\prime}$ and $\sigma_{y}^{\prime}$ are assumed to be zero.

The following table gives a summary of some of the conditions imposed, or the types of names allowed, in each command.

| COMMAND | CONDITIONS |
| :---: | :---: |
| FLG | LB,LQ,ALL, SYN,THK |
| NUM | STP,ESP |
| DRF | Maximum elements 50 |
| QUA | Maximum elements 40 |
| BBX | Maximum elements 20 |
| BBY | Maximum elements 10 |
| FIT | Maximum elements 3 |
| INT | Maximum elements 1 |
| SEX | Elements 2 |
| REM | 1 per beam line |
| INS | Maximum elements 200; 2 per run |
| CEL | Maximum elements 200; 1 per run |
| VAR | 40 per beam line |
| CON | 40-number of internal constraints |
| Fu: | $B X, B Y, A X, A Y, E X, E Y, E X P, E Y P, X N U, Y N U, X I J, Y I J ~$ |
| VAL | Same names as FUN with subscripts 1,2,1,F |
| LUM | NINS,NLUM,NB,NINT, P1, PF, DNU1, DNU2, V1, V2, A1, A2,H,DR,NDR |
| CLR | NSTD, SIGX,SIGY,SIGE |
| FIN | 1 per run |

Integer values must be used for STP, ESP, NINS, NLUM,NB,NINT,NDR,H and NSTD.

Each time a variable name appears in the beam line it is counted as one variable. The number of internal constraints for coupling between pairs of variables having the same name is equal to (the total number of variables in the beam line - the total number of elements in the VAR command).

As an option the user can use ten columns for each input data value in the DRF, BBX, BBY and QUA commands. For this option a non-blank character must be used in column 12 of the lines containing the names of those elements whose values require greater accuracy. The names of the elements in these lines must be less
than five characters, with the first element name between column 21 and 30 , the second between column 31 and 40 , etc. Each element name and value must be leftjustified. This feature is needed when SYN is used in the FLG command to get a tabulation of the machine functions for a known solution. Whenever SYN is used the beam line must be defined for one machine superperiod.

## 3. CASCADED BEAM LINES

The commands for two beam lines in cascade are described in this Section via an example. In the example of the preceding Section, solutions are found for configurations having different desired values of betatron tune shifts for one half of a storage ring superperiod. Alternatively, it is possible to use the code to find solutions having different desired values of betatron tune shifts per periodic cell. This can be done by using two beam lines in cascade.

In this example the first beam line is used to define the elements in the cell. The second beam line is used to define the elements in one half of a superperiod beginning at a symmetry point and ending at an interaction point: The desired values of tune shift per cell are found by varying the values of the strengths of $Q F H$ and $Q D$ in the first beam line. The desired values of $\beta_{X}$ and $\beta_{y}$ and $\alpha_{x}=\alpha_{y}=$ $\eta^{\prime}=0.0$ at the interaction point are obtained by varying the strengths of the other quadrupole magnets in the second beam line.

Since the first beam line is a CEL command, the values of $\beta$ and $\eta$ for the beginning point of the lattice are not needed in the VAL command. The values of machine functions at the beginning of the second beam line, however, are given by those found for the end point of the first beam line. The values of the machine functions are matched between the two beam lines internally by the code.

In general four types of lattice are possible: a single cell, a single insertion, a cell and an insertion in cascade, and two insertions in cascade. For the multiple beam line case, the elements in both beam lines must be defined in the same commands at the beginning of the input data. The first beam line is defined by a REM command followed by INS or CEL, CON and FUN/VAL commands. The second beam line is defined by another REM command followed by the corresponding INS, CON and FUN/VAL commands. The first beam line can be either a CEL or an INS command, but the second beam line must be an INS command. For the casc of two insertions in cascade, only one insertion can have fit points. The ame values of STP and ESP are used for both beam lines. In the output, tabulations of the values of the machine functions for both beam lines are printed.

4. OUTPUT

The normal output for each configuration is: convergence value; values of the transport matrix elements; values of $\beta, \alpha, \eta, \eta^{\prime}$ and $\Delta v$ at each element ( $B X, B Y, A X, A Y, E X, E Y, E P X, E P Y, N U X, N U Y$ ) ; element values ( 2 in m for a drift space, $g l / B \rho$ in $m^{-1}$ for a quadrupola magnet, $2 / \rho$ in degrees for a bendinc magnet); location of an element from the beginning of the beam line (LENGTH); values of $\Delta v /(\Delta p / p)$.

Additional output can be obtained using the LUM command. The normal output computed by the LUM command is:
NOTATION
$I_{1}, I_{2}, I_{3}, I_{4}, I_{5}$
$(\triangle L / L) /(\triangle P / P)$
$L$
TO
$J X, J Y, J E$
$B X \%, B Y \%$, ETAX*, ETAY\%
$E$
$A$
DNU
UO
SIGE
BRHO
TAUX, TAUY, TAUE
SIGX(O), SIGY(O)
SIGX(C), SIGY(C)
SIGX(T), SIGY(T)
LX,LY

PARAMETER
Synchrotron integrals
Momentum compaction factor
Circumference
Revolution time
Partition numbers
Machine functions at the interaction point
Beam energy
Aspect ratio
Beam-beam tune shift
Energy radiation/turn
Energy spread
Particle rigidity
Damping times
$\sigma_{x}$ and $\sigma_{y}$ due to betatron motion with no coupling
$\sigma_{x}$ and $\sigma_{y}$ due to betatron motion with coupling
$\sigma_{x}$ and $\sigma_{y}$ due to both betatron motion and energy spread

Luminosity at the $x$ and $y$ tune shift limit

| NOTATION | PAPAMETER |
| :---: | :---: |
| $N X, N Y, I X, I Y$ | Number of particles per beam and beam current values at the tune shift limit |
| FRF/F0 | RF harmonic number |
| URF, FRF | RF voltage and frequency |
| PHIS | Synchrotron phase angle |
| NUS, FS | Synchrotron tune and frequency |
| DE/E | RF Bucket |
| SIGZ | Bunch length |
| TAUQ* | Quantum life time |

If sextupole magnets are used in the bcam line the output will include the strengths, $\lambda \ell / B_{p}$, of the sextupole corrections in $m^{-2}$ where the field value, $B_{y}$, is given by $\lambda\left(X^{2}-Y^{2}\right)$. In addition, if $D R$ and NDR are used in the LUM command the output will include the variations of beta and betatron tune values for particles with different momen tum.

The output computed by the CLR command is: the number of standard deviations $n$ (NSTD) used in the computation; the values of $\sigma_{x}, \sigma_{y}$ and $\Delta p / p$ at the beginning point of the beam line (SIGX, SIGY, SIGE); the values of no $x$, no $x^{\prime}$, no $y$ and no $y^{\prime}$ at each element in the beam line.

The value of TAUQ is very sensitive to the values of DE/E and TAUE; a few percent error in the values of these quantities could lead to a much larger error in the value of raup.

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