Precise quantization of anomalous Hall effect near zero magnetic field

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We report a nearly ideal quantum anomalous Hall effect in a three-dimensional topological insulator thin film with ferromagnetic doping. Near zero applied magnetic field we measure exact quantization in Hall resistance to within a part per 10,000 and longitudinal resistivity under 1 Ω per square, with chiral edge transport explicitly confirmed by non-local measurements. Deviations from this behavior are found to be caused by thermally-activated carriers, which can be eliminated by taking advantage of an unexpected magnetocaloric effect.

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The discovery of the quantum Hall effect (QHE) [1, 2] led to a new understanding of electronic behavior in which topology plays a central role [3, 4]. Initially, the critical experimental observation was the precise quantization of the Hall resistance to integer divisions of h/e^2 , where h is Planck's constant and e is the electron charge. This quantization, immune to sample-specific disorder, now forms the basis for a metrological standard [5]. A complementary feature—zero longitudinal resistance, reflecting resistanceless transport along sample edges—could also have technological applications, were it not for the demanding environmental requirements for achieving the QHE: a large magnetic field to break timereversal symmetry (TRS) and, in most cases, cryogenic temperatures. Ideas for producing a similar phenomenology without an external magnetic field have long been considered [6], often involving the interplay of symmetry and topology in new material systems.

In the past decade, topological insulators (TIs) have emerged as a promising approach. In both twodimensional [7–9] and three-dimensional [10–14] forms, conduction in TIs is restricted to topologically-protected boundary states. In the 3D case, the presence of ferromagnetic exchange can break TRS, opening a gap in the otherwise Dirac-like surface states [15–17]. But topology adds a twist: even a uniformly magnetized sample will have, relative to the normal vector of the surface, a domain boundary where the magnetization switches from inward to outward. Along this line the gap should close, restoring conduction [16]. In a thin film geometry in which the easy axis of the magnetism is out-of-plane, confinement along the sample side wall should ensure conduction is one-dimensional while the surface gradient of the magnetism restricts it to only one direction, leading to ballistic, chiral transport. In a Hall bar geometry, this would be observed as the quantum anomalous Hall effect (QAHE), with a zero longitudinal resistance and a transverse resistance quantized to h/ne^2 , where n is typically ± 1 but can in principle be a higher integer given

sufficiently strong exchange [18].

Experimental realization of the QAHE has been swift. Doping films of the ternary TI family (Bi,Sb)₂Te₃ with Mn or Cr was found to produce robust out-of-plane ferromagnetism and a large anomalous Hall effect in transport [19–21]. Further growth optimization and chemical potential manipulation led to the recent achievement of the full quantized effect [22–24], albeit at dilution refrigerator temperatures. In two cases [22, 24], an applied magnetic field was necessary to decrease the longitudinal resistivity, presumably to eliminate other conduction channels. The possibilities for these channels include non-chiral edge modes [25], variable-range hopping, or band transport of thermally populated 2D surface or 3D bulk carriers. In contrast, the device measured in Kou et al. [23] demonstrates its lowest longitudinal resistance near zero applied field.

In this Letter, we study the QAHE in this regime using material from the same growth, demonstrating the hallmarks of the effect: vanishing longitudinal resistance, precisely quantized Hall resistance that switches sign with magnetization, and direct confirmation of edge transport, all in the absence of an applied field. Where deviations from this ideal behavior occur, we attribute them to thermally-activated carriers whose presence can be fortuitously controlled by demagnetization cooling of some other magnetic system in the sample. The material is 10 quintuple layers of $(Cr_{0.12}Bi_{0.26}Sb_{0.62})_2Te_3$ grown via molecular beam epitaxy and capped with alumina on a semi-insulating GaAs substrate. To avoid possible doping of the film through lithographic processing, following [22] we use a sharp metal tip to scratch the film into a Hall bar shape, and form ohmic contacts by placing indium metal onto each of the six terminals. The region between the voltage leads is 1.1 mm long and 0.45 mm wide (Fig. 1(a)). Four-terminal resistances are measured via standard lock-in amplifier techniques [26] with the sample in a dilution refrigerator with its mixing chamber cooled to 38 mK. We calibrate the aggregate



FIG. 1. Device demonstrating quantum anomalous Hall effect. (a), Photograph of 10 nm-thick film of $(Cr_{0.12}Bi_{0.26}Sb_{0.62})_2Te_3$ on a GaAs substrate, scratched by hand into Hall bar shape, with indium metal ohmic contacts. Schematic measurement setup included. (b), Longitudinal resistivity ρ_{xx} and transverse resistivity ρ_{yx} of the device at base temperature as a function of the applied magnetic field $\mu_0 H$ in each sweep direction, forming a ferromagnetic hysteresis loop. As the field approaches zero from either starting point, ρ_{yx} reaches its quantized value h/e^2 and ρ_{xx} approaches zero. (c), Non-local measurements verifying edge-dominated transport. The insets show the measurements performed and chirality at each magnetization.

amplifier gain of the setup by measuring a conventional $\nu = 1$ quantum Hall plateau on a separate high-mobility graphene sample [26].

At base temperature we reproduce the ferromagnetic hysteresis loop measured by the anomalous Hall effect in Kou *et al.* [23] (Fig. 1(b)). The sign of the transverse (Hall) resistivity, ρ_{yx} , reflects the device's magnetization direction, M_z , which we can set to positive ("+1") or negative ("-1") by applying a field $\mu_0 H$ with magnitude greater than the 125 mT coercive field. As we sweep H toward zero, ρ_{yx} reaches its quantized value $\pm h/e^2 \approx \pm 25,813 \ \Omega$ while the longitudinal resistivity ρ_{xx} decreases precipitously (in one case, reaching as low as 15 Ω). After crossing zero field, ρ_{xx} increases to a few k Ω before spiking higher at the coercive field as ρ_{yx} changes sign. Both measurements settle toward their quantized values as |H| increases, but only reach full quantization $\mathbf{2}$

on the return arm of the hysteresis loop, again just before zero field.

Although the resistivity tensor takes on the expected values, the hysteresis loop does not directly verify that edge conduction dominates in this regime. Nonlocal measurement configurations, such as that shown schematically in Fig. 1(c), are one way to establish this [27]. In the limit of chiral, ballistic edge transport, the chemical potential along the chirality direction only changes at leads that act as a current sources or drains, as prescribed by Landauer-Büttiker formalism [28] and demonstrated in the QHE [29] (though not explicitly, to date, in the QAHE). For example, while flowing current between adjacent contacts (labelled 1 and 6), the remaining four contacts should maintain the same voltage as either the current source or drain, depending on whether the QAHE chirality is clockwise or counterclockwise, respectively. In Fig. 1(c) we measure the voltage drop from a contact on the opposite side of the device (3) to the drain (6), and plot the resulting three-terminal resistance $R_{16,36}$ compared to the two-terminal value $R_{16,16}$. At negative magnetization (left panel), corresponding to clockwise equilibration, both quantities approach the ballistic value h/e^2 , indicating that contact 3 is nearly equilibrated with the source. At the opposite magnetization, where voltages are propagated counterclockwise (right panel), $R_{16,16}$ approaches h/e^2 while $R_{16,36}$ approaches zero due to the equilibration of contact 3 with the drain. Near zero field, the deviations from idealized behavior (in all cases under 200 Ω), likely reflect contact resistances and possibly the presence of extra dissipative helical edge modes [25]. Using one of the remaining contacts in the role of contact 3 results in the same behavior [26].

Returning to four-terminal measurements, we find that the best quantization can be obtained by maintaining the film's magnetization (i.e. keeping $|\mu_0 H|$ smaller than the coercive field) but following the "hysteresis loops" shown in Figure 2(a). Starting from any combination of magnetization and field polarity, sweeping H toward zero suppresses the longitudinal conductivity $\sigma_{xx} = \rho_{xx}/(\rho_{xx}^2 + \rho_{yx}^2)$ to as low as $0.0003 \ e^2/h$ while the transverse conductivity $\sigma_{xy} = \rho_{yx}/(\rho_{xx}^2 + \rho_{yx}^2)$ remains quantized to within 0.01% of e^2/h . Passing through zero and then increasing |H| destroys this quantization, which we can recover by waiting at constant field for 80 minutes and then sweeping back toward zero.

These reported conductivity values have undergone one correction for imperfect device geometry. Uneven spacing between the voltage probes of the Hall bar can add a small component of ρ_{xx} to the measured value of ρ_{yx} . (In nonmagnetic samples, this is conventionally corrected by antisymmetrizing ρ_{yx} about zero field.) In a parametric plot of the resistivity data from the same hysteresis loops (Fig. 2(b)), with $|\rho_{yx}|$ along the y-axis and ρ_{xx} along the x-axis, we observe an asymmetry between the two magnetizations. Each branch deviates from a



FIG. 2. Precise quantization near zero applied field. (a), Longitudinal and transverse conductivities in hysteresis loops over field ranges smaller than the coercive field so as to maintain starting magnetization M_z . When approaching zero field from either starting point, $\sigma_{xy} = e^2/h$ to 0.01% precision while σ_{xx} reaches as low as 0.0002 e^2/h . (b), (c), Resistivities measured during the hysteresis loops, plotted parametrically, both before (b) and after (c) performing a correction for geometry. The inset of (b) shows the linear deviation of the two magnetization branches from a parabolic line, resulting from uneven spacing of the leads. The inset of (c) shows a close-up of the corrected resistivity data, with ρ_{yx} quantized to h/e^2 within 3 Ω at any given point when $\rho_{xx} < 200 \Omega$.

parabolic arc (the expected leading order contribution), with the size of the deviation explicitly verified to grow linearly with ρ_{xx} with a coefficient of 2% (Fig. 2(b), inset). By taking field sweeps at T = 40 K, above the film's Curie temperature [23], we obtain an independent but matching measure of this geometric mixing coefficient, which is also verified by a numerical Poisson simulation of current flow [26]. After removing the ρ_{xx} component from ρ_{yx} the data nearly collapse onto a single curve (Fig. 2(c)). In the vicinity of vanishing ρ_{xx} , the parametric plot after this correction demonstrates quantization of ρ_{yx} to within $\pm 3 \Omega$ (Fig. 2(c), inset).

The system stays on this curve in resistivity space, even during the wait times when ρ_{xx} falls, suggesting that the position along the arc is determined by some parameter other than magnetization or applied field. Temperature is an obvious possibility. We extend the relationship by warming the sample above 100 mK, inducing a large longitudinal conductivity that becomes comparable to e^2/h by 750 mK (Fig. 3). The trajectory of the QAHE in conductivity space during this process has been studied previously, and found to obey the same symmetry laws and renormalization group properties as the QHE [24]. We find reasonable qualitative agreement with calculated [30] renormalization group flow lines (Fig. 3, gray lines).

To obtain a functional form of the temperature dependence, we plot σ_{xx} versus reciprocal temperature (Fig. 3, inset). Such plots, useful for identifying conduction that is thermally activated over an energy barrier, are commonly used in quantum Hall systems to extract gap sizes [2]. Here, an Arrhenius (exponential) fit holds down to 60 mK, suggesting that the nonzero σ_{xx} represents carriers thermally activated into a surface band. We emphasize that this is not a direct measurement of the size of the exchange gap: with no gate electrode, the chemical potential cannot be tuned to the middle of the surface gap. Furthermore, the fit continues to work well above the extracted energy scale, where describing thermal activation requires use of the Fermi-Dirac distribution as well as knowledge of the system's density of states and mobility as a function of energy [26]. Still, the data show some form of exponential activation suggesting that the nearest band edge is 17 μ eV away, as indicated by a 200 mK characteristic temperature in the Arrhenius fit.

At the lowest temperatures, a sample's electron temperature can diverge from the cryostat's base temperature (here, the mixing chamber plate temperature). In fact, the wide variation of σ_{xx} in Fig. 2(a) indicates that the temperature may be changing substantially during a hysteresis loop. We hypothesize that this takes place via magnetization or demagnetization of some spin system in the sample that heats or cools (respectively) the sample's electrons. We test this hypothesis by sweeping $\mu_0 H$ from negative to positive, and stopping for five minutes every 5 mT to allow the sample temperature to partially equilibrate with the refrigerator. In a field region where



FIG. 3. Temperature dependence implying possible thermal activation. Parametric plot of ρ_{xx} versus ρ_{yx} at each magnetization while increasing temperature, with calculated renormalization group flow lines shown in gray. Inset, an Arrhenius plot of σ_{xx} as a function of inverse temperature, showing roughly exponential dependence. The implied energy scale of the fit (for instance, if conductivity is explained by thermal activation over a gap) is 17 μ eV, or 200 mK.



FIG. 4. Evidence for demagnetization changing temperature. (a), Effect of upward field sweep on σ_{xx} in three field/polarity regions, consistent with demagnetization hypothesis. When H < 0 (decreasing |H|), σ_{xx} decreases when the field changes and creeps back up during a five-minute wait. When H > 0 (increasing |H|), the opposite occurs regardless of magnetization. (b), Inferred temperature of the TI film, extrapolated using the temperature fit in Figure 3, during the hysteresis loop in Figure 2(a). After a long wait, the temperature approaches the fridge thermometer reading, ~40 mK, whereas sweeping |H| down drives the temperature below 30 mK and sweeping |H| up drives it above 90 mK. (c), A rudimentary demagnetization cycle, involving a slow field sweep to magnetize and a fast field sweep to zero to perform demagnetization cooling. Plotted during this cycle are the inferred temperature, ρ_{xx} (now dropping below 2 Ω), and σ_{xy} which remains within 0.01% of e^2/h during the last three stages.

H is negative and its magnitude is decreasing (Fig. 4(a), top panel), σ_{xx} decreases during the field step and then creeps back up during the wait time. We interpret this as demagnetization whose increase in entropy draws heat from the film, driving it to a lower temperature [31], followed by a partial re-equilibration while we wait. At positive *H* the opposite occurs (Fig. 4(a), middle panel). The pattern does not change after passing the coercive field and switching the film's magnetization (Fig. 4(a), bottom panel), indicating that only the polarity of the applied field matters.

As a further check on the reasonability of this hypothesis, we extrapolate the fit in Fig. 3 down to lower temperatures and apply it to the conductance data in Fig. 2(d) to obtain the approximate sample temperature during a hysteresis loop. The result (Fig. 4(b)) implies that the electron temperature after an 80 minute wait at constant field approaches the mixing chamber thermometer reading, ~40 mK. During downward field sweeps the sample drops below 30 mK, substantially below the refrigerator temperature, and during upward sweeps it exceeds 90 mK. Although the exact identity of the system responsible for this effect is unclear, a naive model of a paramagnet exchanging heat with the electrons qualitatively fits the shape of temperature variation during demagnetization and suggests a Landé g-factor of ~0.15 [26]. We further believe it to be specific to and collocated with the TI sample: the refrigerator's thermometry shows minimal change during the hysteresis loop and, if we pause the loop during demagnetization, σ_{xx} can remain below its equilibrium value for hours. Both details suggest that the TI surface and magnetic system are nearly thermally isolated from the cryostat when driven to their lowest temperatures [26].

If we wish to minimize ρ_{xx} or improve quantization of σ_{xy} , an analogy to the traditional adiabatic demagnetization cycle is useful. A slow increase in the field's magnitude followed by a long wait, allowing maximal thermal equilibration along the way, approximates an isothermal magnetization step. Then a fast decrease in field magnitude (though not so fast that the heat load from the magnet sweep becomes relevant), produces adiabatic demagnetization. We plot ρ_{xx} , σ_{xy} , and the inferred temperature during this process in Figure 4(c). Indeed, we drive ρ_{xx} to as low as 2 Ω ($\sigma_{xx} < 0.0001 \ e^2/h$) and the temperature to 25 mK, with excellent quantization in σ_{xy} along the way. We also include a long wait at the end, demonstrating the long timescale for reequilibration of ρ_{xx} . Modifying this process to end at a small nonzero applied field, we can even drive ρ_{xx} below 1 Ω [26]. In future experiments, adding a gate electrode to optimize the position of the chemical potential in the gap may yield a completely vanishing longitudinal resistance.

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Note added.—During preparation of this Letter, we became aware of work by Chang *et al.* that reports a similar degree of quantization in V-doped BiSbTe₃ [32].

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SUPPLEMENTARY INFORMATION

Material growth

Cr-doped High-quality single crystalline (Bi_xSb_{1-x})₂Te₃ films were grown in an ultra-highvacuum Perkin-Elmer molecular beam epitaxy system. A semi-insulating ($\rho > 10^6 \ \Omega \cdot cm$) GaAs (111)B substrate was cleaned by acetone in an ultrasonic bath for 10 minutes before being loaded into the growth chamber. The substrate was then annealed to 580 °C under a Se-rich environment to remove the native oxide (as shown in Fig. S1(a) in [1]). During the growth, the GaAs substrate was maintained around 200 °C (growth temperature), with the Bi, Sb, Te, and Cr shutters opened at the same time. Epitaxial growth was monitored by *in situ* reflection high-energy electron diffraction (RHEED), and the as-grown surface configuration was traced by using the *d*-spacing evolution between the two first-order diffraction lines. We observed the lattice relaxation occurring within the first QL, indicating that the surface transition from the pristine GaAs to the $Cr-doped (Bi_xSb_{1-x})_2Te_3$ completed immediately after the formation of the first quintuple layer. After the film growth, 2 nm Al was in situ evaporated (for 4 minutes at 5 Å/min) to passivate the surface at room temperature. The Al film was later naturally oxidized to form Al_2O_3 after the sample was taken out of the chamber, with the resulting oxide layer effectively protecting the grown magnetic TI film from unwanted environmental doping or other possible aging effects [2]. Previous atomic force microscope characterizations of the film surface demonstrated flat regions with quintuple layer steps both with and without this cap layer, suggesting the alumina coverage is complete and uniform [2].

Measurement setup

A more detailed schematic of the measurement is shown in Figure S1(a). We apply a 1 nA AC bias to the device by sourcing 1 V RMS across a 1 G Ω reference resistor. The current flows across the device and out the drain terminal to an Ithaco 1211 current preamplifier, the output signal of which reflects the magnitude of the current. The preamplifier gain is set to $1 \text{ V}/10^{-7} \text{ A}$, with a 200 Ω input impedance. The differential voltages V_{yx} and V_{xx} are taken with NF Corporation model LI-75A voltage preamplifiers, which have 100x gain and 100 M Ω input impedances. All three preamplifier outputs are measured with SR830 lock-in amplifiers, utilizing the offset and 10x expansion feature to avoid digital discretization in V_{yx} and current. The excitation/measurement frequency is 3.889 Hz. Using higher frequencies results in large phase differences between the excitation and measurement (for instance, up to 20° at 13 Hz).

The indium contacts were tested for linearity at low temperature by taking DC current-voltage (I-V) curves with a Keithley Model 2400 Source-Measure Unit. Although the resulting I-V curves are not perfectly linear at base temperature (Fig. S1(b)), we believe this results from Joule heating and the device's sensitivity to changes in temperature. At low bias, the slopes correspond to two-terminal resistances around 30 k Ω , near h/e^2 , whereas over the full voltage range the resistances rise to 60-80 k Ω . These are reasonable values if, at the high end of the bias range, the temperature rises to ~200 mK, at which point $\rho_{xx} \sim 0.3h/e^2$. The same measurements taken at 491 mK (Fig. S1(c)) are quite linear.

Good cryogenic electronic filtering is essential to obtain low electron temperatures. At the mixing chamber stage of our cryostat, measurement lines are filtered in the GHz range by running through a cured mixture of bronze powder and epoxy [3], and in the MHz range by five-pole RC filters mounted on sapphire plates to improve thermal anchoring.

Amplifier calibration

The amplifier chain in the measurement setup requires calibration for precision measurement: the SR830 gain is rated to $\pm 1\%$, the Ithaco 1211 to $\pm 2\%$, and the NF LI-75A to $\pm 1\%$. As a resistance standard, we use a $\nu = 1$ quantum Hall plateau (where ν is the QHE filling factor) on a separate high-mobility monolayer graphene Hall bar, cooled in the cryostat at the same time. This has the advantage of being low-noise and quantized to the same value as ρ_{yx} in the QAHE system. In a -14 T magnetic field while measured in the exact same configuration as the QAHE device, a gate sweep of the graphene device yields the usual progression of integer plateaus in R_{ux} (Fig. S2(a)) A higher resolution sweep indicates that the uncalibrated measurement of R_{ux} in the $\nu = 1$ plateau is 26.581 k Ω , which is 2.977% higher than h/e^2 (Fig. S2(b)). In all other data reported in this paper we correct for this inaccuracy by multiplying resistances by a factor of 0.97109.

The stability of the calibration was tested by repeatedly measuring R_{yx} in the $\nu = 1$ plateau over an 18-hour period. During this time the measurement drift largely remained less than 0.01% (Fig. S2(c)).

Current loss to voltmeters

The finite (100 M Ω) input impedance of each connection to the voltage preamplifiers provides additional paths to ground for the applied current, and can distort four-terminal measurements if not accounted for. We discuss this effect in two limits: away from quantization,



FIG. S1. Measurement specifics. (a), Detailed schematic of Hall bar measurement. (b), (c), Two-terminal current-voltage curves at 40 mK (b) and 491 mK (c(a)). In the latter case, the indium contacts appear to be ohmic and linear, and we believe the curvature in the former case is the result of Joule heating. The insets show the same measurements over a larger voltage range.



FIG. S2. Calibration to quantum Hall plateau. (a), Integer quantum Hall effect in monolayer graphene Hall bar. (b), Uncalibrated measurement of $\nu = 1$ plateau. R_{yx} is found to be 2.977% above h/e^2 . (c), Test of calibration drift over 18-hour timescale.

when bulk/surface conduction dominates, and near quantization, when chiral edge modes dominate.

For contact *i*, let the voltage be V_i and the resistance to ground be R_i . Based on the arrangement of preamplifiers (Fig. S1(a)), $R_2 = 100 \text{ M}\Omega$, $R_3 = 50 \text{ M}\Omega$, and $R_5 = 100 \text{ M}\Omega$. The combination of contact resistance, line resistance, and current preamplifier input impedance sets $R_4 \approx 1000 \ \Omega$. The current preamplifier's reading will differ most from the actual current flowing across the Hall bar when the voltages at the various leads, and therefore the currents lost through them, are maximized. Since we apply a current bias, this happens when the film is most resistive. To make an upper approximation of the inaccuracy away from quantization, we take the largest measured two-terminal resistance, 120 k Ω , in which case the 1 nA bias sets $V_2 \approx 80 \ \mu\text{V}$ and $V_3 \approx V_5 \approx 40 \ \mu\text{V}$. The Hall effect can also raise the voltage on one side of the device relative to the other by as much as 20 μ V, leading (in the worse of the two magnetization directions) to $V_2 \approx 90 \ \mu\text{V}$, $V_3 \approx 50 \ \mu\text{V}$, $V_5 \approx 30 \ \mu\text{V}$. This results in a total lost current of of 2.2 pA. Hence, away from quantization these extra paths to ground lead to inaccuracies in R_{xx} and R_{xy} as large as 0.22%, much worse than the part-per-10,000 accuracy we achieve at quantization.

Since we calibrate our amplifiers to a system with, in principle, identical quantization, the lost current should be taken into account at the quantization limit. However, these impedances can also induce a small voltage drop along edge channels. This has been observed in the QHE [4]: at $\nu = \pm 1$, R_{xx} gains an extra component $(h/e^2)^2/R_i$ at one chirality but not the other (where R_i is the voltmeter input impedance). The asymmetry arises because V_{xx} is measured on only side of the device. At one chirality that side's voltage will be the same as the nearly-grounded drain lead, so that negligible current flows across R_i . At the other chirality, the measured side is in equilibrium with the source lead and hence has a larger potential difference with respect to ground. The resulting current flowing out the voltmeter modifies the potential at each voltage lead, as derived below.

For $M_z = +1$ (counterclockwise chirality), according to Landauer-Büttiker formalism [5] the current flowing into the device from contact *i* is given by

$$I_{i} = \frac{e^{2}}{h}(V_{i} - V_{i+1})$$

where we identify i = 7 with i = 1. We also have $V_i = -R_iI_i$ for i = 2,3,4,5, and $I_6 = 0$. Solving this system of equations yields expected measurements

$$R_{xx} = \frac{V_3 - V_2}{-I_4} = -\frac{h}{e^2} \frac{R_4 R_3}{(R_2 + h/e^2)(R_3 + h/e^2)} \approx -0.3 \ \Omega,$$

$$R_{yx} = \frac{V_5 - V_3}{-I_4} = \frac{h}{e^2} \left(1 + \frac{R_4}{R_3 + h/e^2}\right) \approx \frac{h}{e^2} + 0.5 \ \Omega.$$

For $M_z = -1$ (clockwise chirality), we have instead

$$I_i = \frac{e^2}{h}(V_i - V_{i-1})$$

which yields

$$\begin{aligned} R_{xx} &= \frac{h}{e^2} \frac{R_4 + h/e^2}{R_3} \approx 14 \ \Omega, \\ R_{yx} &= -\frac{h}{e^2} \left(1 + \frac{R_4}{R_5 + h/e^2} \right) \approx -\left(\frac{h}{e^2} + 0.3 \ \Omega\right). \end{aligned}$$

For both the calibration and QAHE quantization measurement, the systematic error in R_{yx} is within the measurement noise. We only have a sizable addition to R_{xx} when $M_z = -1$, which may be one reason we obtain lower values of ρ_{xx} and σ_{xx} for $M_z = +1$ (see top and middle panels of Fig. 2(a)). The effect also has important implications for asymmetries in four-terminal non-local measurements, as discussed in a later section.

Device dimensions

To find the diagonal resistivity, $\rho_{xx} = R_{xx}/N_{\Box}$, from the measured four-terminal longitudinal resistance, R_{xx} , the number of squares, N_{\Box} , between the longitudinal voltage contacts of the Hall bar must be known. However, since this device is not fabricated with precise lithography, N_{\Box} cannot be inferred from the device design. Instead, to calculate N_{\Box} , we numerically solve the Laplace equation on a 2D polygon model of the device.

In a resistive material with a static current distribution, no charge accumulation, and in the absence of a magnetic field, the electric potential, $\varphi(\mathbf{r})$, satisfies Laplace equation $\nabla^2 \varphi = 0$. At the interface of the material and the vacuum, the potential satisfies the Neumann boundary condition $\frac{\partial \varphi}{\partial \mathbf{n}}\Big|_{\Gamma} = 0$, where \mathbf{n} is the outward surface normal unit vector and Γ the interface, in order that the current density perpendicular to the boundary, $\mathbf{J} \cdot \mathbf{n} = \sigma \mathbf{E} \cdot \mathbf{n} = -\sigma \frac{\partial \varphi}{\partial \mathbf{n}}$, be zero. At an interface with a perfect conductor, which must be an equipotential, the potential instead satisfies the Dirichlet boundary condition $\varphi\Big|_{\Gamma} = V_c$, where V_c is the potential of the conductor.

In the case of a Hall bar, the potential at the conductors acting as voltage leads is not fixed externally, but rather set by the condition that the net current into each voltage lead be zero. Let Γ be the boundary between the Hall bar and the voltage lead (a curve, in the 2D case). We assume a uniform conductivity σ for the Hall bar. Then the net current flowing into the Hall bar from the FIG. S3. Calculated electric potential, $\varphi(\mathbf{r})$, on the Hall bar. Numerical solution for the electric potential on a polygon model of the Hall bar, in units of I_s/σ , where I_s is the source current and σ is the sheet conductivity, shown overlaid on a micrograph of the device, with a number of equipotentials (black lines). The calculation assumes a uniform sheet conductivity, with zero current flowing into the voltage leads, and finds the number of squares between the top longitudinal voltage leads to be $N_{\Box} = 2.77$.

voltage lead is

$$I = -\int_{\Gamma} ds \, \mathbf{J} \cdot \mathbf{n} = \sigma \int_{\Gamma} ds \, \frac{\partial \varphi}{\partial \mathbf{n}}, \qquad (S.1)$$

so the I = 0 condition for the voltage lead is equivalent to $\int_{\Gamma} ds \frac{\partial \varphi}{\partial \mathbf{n}} = 0$. The solution, $\varphi(\mathbf{r})$, must satisfy this condition at the four voltage leads, with the potential at the two current leads fixed.

To satisfy all of these conditions, we take advantage of the linearity and homogeneity of Laplace's equation. If $\varphi_i(\mathbf{r})$ is a (dimensionless) solution for which the potential at contact *i* (using the contact labeling scheme in Fig. S1(a)) is $V_i = 1$ and $V_j = 0$ for $j \neq i$, then for any configuration of voltages at the contacts, the full solution for the Hall bar is $\varphi(\mathbf{r}) = \sum_i V_i \varphi_i(\mathbf{r})$. It follows from this and (S.1) that if we define a matrix *G* by $G_{ij} =$ $\sigma \int_{\Gamma_i} ds \frac{\partial \varphi_j}{\partial \mathbf{n}}$, where Γ_i is the interface with contact *i*, then the current flowing from contact *i* into the device is $I_i =$ $\sum_i G_{ij} V_j$.

This equation must be inverted to find voltages that satisfy the zero current condition for the voltage leads. However, the matrix G is singular due to the freedom to offset all the voltages by a fixed constant without changing the currents. We can set the potential to zero at a particular contact d, which we take to be the drain terminal. Then the submatrix \tilde{G} of G with the d-th row and column removed is invertible, and $V_i = \sum_{j \neq d} \tilde{G}_{ij}^{-1} I_j$ for $i \neq d$. Letting $I_i = 0$ for voltage leads i, and fixing the current I_s at the source terminal s, the voltages (and correspondingly the full solution φ) are determined by $V_i = \tilde{G}_{is}^{-1} I_s$. The number of squares N_{\Box} between longitudinal voltage leads i_1 and i_2 , in this configuration, is then given by

$$N_{\Box} = \sigma R_{xx} = \sigma \frac{V_{i_1} - V_{i_2}}{I_s} = \sigma \left(\widetilde{G}_{i_1s}^{-1} - \widetilde{G}_{i_2s}^{-1} \right).$$

To apply this calculation to our device, we construct a polygon model of the Hall bar using an optical micrograph. We carry out the calculations in MATLAB, and numerically solve for the functions $\phi_i(\mathbf{r})$ on a triangular mesh using the built-in Partial Differential Equation Toolbox. We compute $N_{\Box} = 2.77$, with the full solution $\varphi(\mathbf{r})$ shown in Fig. S3. R_{xx} is measured between the top two voltage leads as shown in the figure. We also find 0.026 squares between the top-right and bottom-right voltage leads used to measure ρ_{yx} , suggesting roughly 2.6% mixing of ρ_{xx} into the measured value of ρ_{yx} , in reasonable agreement with electrical measurements (see next section).

Correction for imperfect geometry

A common practice for eliminating mixing between longitudinal and transverse resistances in magnetic field sweeps is to symmetrize even signals (ρ_{xx}) and antisymmetrize odd signals (ρ_{yx}) about zero field. In a system with ferromagnetic hysteresis one must perform the transformations by combining data from opposite sweep directions. However, for this device all magneto transport is history-dependent. For instance, a small difference in the sweep rate or starting value of the electron temperature can change the trajectories of other-





FIG. S4. Extraction of geometric correction factor. Odd and even components of ρ_{yx} measured at 40 K, above the Curie temperature. The odd components is assumed to be the true value of ρ_{yx} , while the even component is a linear pickup of ρ_{xx} , with coefficient shown here to be 2.09%.

wise identical measurements. Hence, rather than antisymmetrize (and risk combining data taken at potentially different temperatures), to remove the even component of ρ_{yx} due to uneven lead spacing we subtract from it a small multiple of ρ_{xx} .

The value of this multiple was obtained by warming the sample to 40 K, well above the Curie temperature of its ferromagnetism, and measuring the device in a regime where symmetrizing and antisymmetrizing make logical sense. We decompose a ρ_{yx} field sweep into its odd and even components (Fig. S4). At zero field, the ratio of $\rho_{yx,\text{even}}$ to ρ_{xx} is 0.0209. This coefficient works reasonably well over the full field range (Fig. S4), is in good agreement with the above Poisson calculations, and nearly eliminates asymmetries between the two magnetizations at base temperature (Figs. 2(b)-(c)). For all data other than in Figs. 1(a), 1(b), and 2(b), we report $\rho_{yx} \equiv \rho_{yx,\text{measured}} - 0.0209\rho_{xx}$.

Note that in this regime, $\rho_{yx,\text{even}} \sim \rho_{yx,\text{odd}}$ even though the geometric imperfection is small. This is due to low mobility and low magnetic field. Of course at quantization ρ_{yx} is dominated by the Hall effect, but the mixing correction remains important at the level of precision we seek.

Non-local measurements

Additional non-local measurements are shown in Fig. S5. Sourcing current from terminal 1 and draining at 6, we measure three-terminal resistances between the drain and contacts 2, 3, and 4 as the applied field is swept (Fig. S5(a)). All three measurements show similar behavior to Fig. 1(c): when the magnetization is negative, the voltages equilibrate in a clockwise man-

ner, so $R_{16,26} \approx R_{16,36} \approx R_{16,46} \approx h/e^2$; with positive magnetization, the equilibration is reversed, and $R_{16,26} \approx R_{16,36} \approx R_{16,46} \approx 0$. Away from $|H| \approx 0$, the same activated conduction discussed in the main text causes deviations from these values. The small differences between the three measurements can be attributed to the contact resistance to the drain and possibly, near quantization, effects of other conduction paths including residual regions of surface conduction and non-chiral edge conduction. These conduction channels are best characterized with four-terminal non-local measurements between adjacent pairs of contacts, as performed previously [6].

Fits of temperature dependence

It is somewhat surprising that σ_{xx} as a function of inverse temperature is fit well by a simple exponential. Thermal activation over a gap into a single band typically has the form

$$\sigma_{xx} \propto \int_{E_F}^{\infty} \mu(E) D(E) \frac{1}{1 + e^{(E - E_F)/k_B T}} dE$$

where E_F is the Fermi energy, μ is the carrier mobility as a function of energy, D is the density of states (zero in the band gap and with some dependence on E in the conduction band), and the fraction is the Fermi-Dirac function. If we assume that the Fermi level is energy Δ below the bottom of the conduction band and the product $\mu(E)D(E)$ has a simple power law form aE^m (where we set E = 0 at the band bottom), then this integral becomes

$$\sigma_{xx} \propto \int_{\Delta}^{\infty} \frac{aE^m}{1 + e^{E/k_B T}} dE.$$
 (S.2)

Leaving a and Δ as free parameters and using generic values of m (namely, 0 and $\pm 1/2$, resulting from constant μ and either linear or quadratic dispersions in 1D or 2D), fits of this integral to the data do not match (Fig. S6(a)). If we let m also be a free parameter, then we achieve a reasonable fit over the full temperature range with m = 0.78 (Fig. S6(a), red line), though without an obvious physical interpretation. Meanwhile, the simple Arrhenius fit continues to work just as well.

In quantum Hall systems, the justification for using the Arrhenius law is that D(E) can be treated as a delta function at the energy of the nearest Landau level, and the Fermi-Dirac function simplifies to a Boltzmann distribution in the limit of $k_BT \ll \Delta$. The latter condition appears to be routinely relaxed in published data, where Arrhenius fits often hold up to $k_BT = 2\Delta$ [7, 8]. In our case, it appears to hold even higher, up to 4Δ . Although we believe the exponential form is a strong indication that thermal activation is taking place, it is unclear



FIG. S5. Non-local resistance measurements. Three-terminal non-local measurements, similar to Fig. 1c, but using different pairs of voltage leads. The insets show the chiralities and terminal naming scheme. The overall behavior ($R \approx h/e^2$ at $M_z = -1$, $R \approx 0$ at $M_z = +1$) does not depend on choice of leads.



FIG. S6. Fits of temperature dependence. (a), (b), σ_{xx} as a function of inverse temperature, with various fits of (a) the Fermi-Dirac functional form in equation (S.2) and (b) variable-range hopping in the form of equation (S.3). For comparison, the Arrhenius fit from Fig. 3b is included in each.

whether this continued trend at high temperature is a coincidence resulting from the particular mobility-density of states product or the consequence of a deeper physical principle about the material or the QAHE.

In a previous QAHE study [9], the relationship between σ_{xx} and σ_{xy} suggested that bulk conduction arose from variable-range hopping. In that were the case in our sample, the temperature dependence would have the form

$$\sigma_{xx} \propto e^{-(T_0/T)^{1/(d+1)}}$$
 (S.3)

where d is the number of spatial dimensions of the system and T_0 is a temperature scale. We attempted to fit this function to the data for d = 2, d = 1, and letting d be a free parameter (Fig. S6(b)). The first two cases fit poorly while the third fits d to 0.14 (i.e., close to reducing to the Arrhenius function). We therefore believe that variable-range hopping is not an accurate description of the temperature dependence of this device.

Heating events in field sweeps

Throughout this paper we argue that – below the coercive field – the variations in transport with applied field in our magnetic TI device can largely be explained by temperature variations due to thermal contact with some (de)magnetizing system. (For further analysis about the nature of that system, see section below). In addition to this overall pattern, we observe other features in σ_{xx} that presumably arise from heating. Namely, while sweeping the applied field toward zero, σ_{xx} (and therefore the inferred temperature) briefly increases around $|\mu_0 H| = 20$ mT and also more dramatically right before reaching zero (see Fig. 2(a)). The latter was observed by some of us previously [6]. The magnitude of these effects depends strongly on the magnet ramp rate: in slower sweeps they are far less prominent, and they tend to dissipate quickly when holding field constant (see the quick drop in ρ_{xx} between the third and fourth panels of Fig. 4(c)). We do

not know the specific mechanism for either feature, but these shorter timescales suggest that the heating occurs closer to the dilution refrigerator's mixing chamber.

Analysis of demagnetization

In this section we discuss the possible sources of the observed magnetocaloric effect. A first candidate is the sample's magnetism itself. The sharpness of the anomalous Hall hysteresis loop indicates that, overall, it is a hard ferromagnet and therefore not experiencing major changes in entropy except at transitions. However, if the magnetism is spatially inhomogeneous, there may be isolated weak patches with softer ferromagnetism and a magnetocaloric effect without contributing to transport measurements. Another possibility is that clusters of chromium atoms may exhibit paramagnetism or weak ferromagnetism [10]. In both cases, we would expect the sign of the effect to change as the total magnetic field, B(which includes the sample magnetization), crosses zero. Instead, it responds to H, suggesting that the demagnetizing system is a least somewhat spatially separated from the electron system being measured. In the immediate vicinity of the TI film are the semi-insulating GaAs substrate and the indium contacts. To pin the Fermi level in its band gap, the semi-insulating GaAs wafer is doped with carbon (rather than chromium, as is sometimes used), but perhaps some remanent magnetic impurities are nonetheless present, and even carbon doping has been associated with paramagnetism in GaAs [11]. The indium metal could also contain magnetic impurities.

For now, we assume that one of the scenarios above holds – the magnetic system responsible for the effect is located near the device - and attempt to extract some information about that magnetic system based on our measurements. (We later consider the possibility that this magnetic system may be located elsewhere in the cryostat, and explain why we consider it unlikely.) We make several other simplifying assumptions: 1) that the relevant field scale B for the magnetocaloric effect is equal to the applied field $\mu_0 H$ (an underestimate if the film's magnetization contributes to B; 2) that the magnetocaloric system is in good thermal contact with a constant-intemperature heat capacity C_V that includes the TI film; 3) that we can, under the right circumstances, model the demagnetization as adiabatic; 4) that we can treat the magnetocaloric system as a system of N non-interacting spins, each of which has energy $\pm q\mu_0 B$ (where q is the Landé g-factor and μ_0 is the Bohr magneton). The latter assumption leads to canonical partition function

$$Z = \left(2\cosh\frac{g\mu_0 B}{k_B T}\right)^N$$

where k_B is the Boltmann constant and T is the temperature. Then the entropy is

$$S = \frac{\partial}{\partial T} \left(k_B T \ln Z \right) = N k_B \left[\ln \left(2 \cosh \frac{g \mu_0 B}{k_B T} \right) - \frac{g \mu_0 B}{k_B T} \tanh \frac{g \mu_0 B}{k_B T} \right]$$

To put this system in good thermal contact with the electronic system, we add $C_V \ln T/T_0$ to the entropy, where T_0 is an arbitrarily low temperature. In any adiabatic process the total entropy does not change, and so the quantity

$$k_B \frac{N}{C_V} \left[\ln \left(2 \cosh \frac{g\mu_0 B}{k_B T} \right) - \frac{g\mu_0 B}{k_B T} \tanh \frac{g\mu_0 B}{k_B T} \right] + \ln T/T_0 \tag{S.4}$$

is held constant. If we change B adiabatically, then T will adjust accordingly. In a fit a measured trajectory T(B), the only two free parameters are g and N/C_V (T_0 only adds a constant offset), where, roughly speaking, N/C_V determines the size of the effect and g determines the field scale at which it takes place.

In practice, adiabaticity is a poor assumption because the sample exchanges heat with the cryostat. However, the data in Figure 4(a), when converted to temperature, can provide the rate of this heat exchange, allowing us to approximately isolate the effect of demagnetization. We do this by performing a linear fit to the temperature drift during the waiting periods and extrapolating it back to the start of the field step (Fig. S7(a)). The result provides what the approximate change in temperature for each 5 mT field step would be if it were adiabatic, which we can fit with the simple model above (Fig. S7(b)). We find that the data best match the model with a g-factor of ~0.15 and $N/C_V = 1.7 \times 10^{24}$ K/J = $23/k_B$. However, a more realistic choice of heat capacity would likely decrease at lower temperatures. The result would be a larger drop in temperature at the rightmost region of Fig. S7(b), which the fit would correct for by reducing the value of the g-factor. (On the other hand, if the magnetocaloric system is located outside the magnet bore and hence experiences a field smaller than $\mu_0 H$, the estimate



FIG. S7. Fit of magnetocaloric effect. (a), Extraction of the drop in inferred temperature for each 5 mT field step, removing the effect of thermal equilibration with the cryostat. Note that data were only taken during the five-minute waits between 50-second field steps. (b), Inferred temperature drop at each step, with a fit using (S.4).

for g would need to increase.)

For an isolated semi-insulating GaAs sample, a relatively small concentration of magnetic moments could lead to a magnetocaloric effect on the order of what we observe. Using a simple Debye model calculation (and the known GaAs Debye temperature $T_D = 345$ K in the low temperature limit [12]), the heat capacity per atom is

$$\frac{C_V}{N_{\rm atoms}} = \frac{12\pi^4}{5} k_B \left(\frac{T}{T_D}\right)^3 \approx (4 \times 10^{-10}) k_B \text{ at } 40 \text{ mK}$$

In our fit to the magnetocaloric effect, we find $N/C_V = 23/k_B$, which implies a concentration $N/N_{\rm atoms} \approx 10^{-8}$, placing N in the low 10^{14} cm⁻³ range. This number, low enough to be a reasonable impurity concentration, is a consequence of the small heat capacity of the insulating crystal. In reality, our system is also comprised of the TI film, indium contacts, wires, and eventually the rest of the cryostat. But if the film has an insulating surface and bulk, the interior of the device could become a poor thermal conductor and isolate the rest of those elements from much of the cold substrate.

The timescales of the magnetocaloric effect support this picture. As Fig. 2(d) demonstrates, ρ_{xx} (and therefore, we believe, the temperature of the film) can stay well below the equilibrium value for hours. After a field sweep down, the cooling also continues for tens of seconds (see Fig. S7(a)), a timescale that lengthens to minutes at the very lowest temperatures. Both of these details make sense if the demagnetizing process takes place at or next to the surface of the film, which itself becomes increasingly thermally resistive as it cools. The latter detail is even better explained if the cooling is spatially inhomogeneous, so that cooler and warmer parts of the film take some time to equilibrate.

In light of this information, let us summarize the various possibilities previously identified. The indium contacts are probably too easily thermalized to be a candidate, and the low extracted g-factor is probably inconsistent with the Cr cluster picture. The above analysis does support the possibility of a small amount of magnetism in the GaAs substrate, which requires a device with low heat capacity and thermal conductivity to be relevant. The scenario with patches of weak magnetism is also consistent with experiment details, but probably not well described by the simple paramagnet model above.

The other main class of scenarios involve having a paramagnetic system located elsewhere in the cryostat. We have noticed a magnetocaloric effect in measurements of this type of magnetically-doped film at both Stanford and (in retrospect) UCLA [6]. It is conceivable that both cryostats contain paramagnetic materials that give rise to this effect. During two years of measurements in our cryostat at Stanford, magnetically-doped TI films grown at UCLA are the only samples found to show magnetocaloric effect, but many other samples do not have strongly temperature-sensitive transport below 100 mK, so the effect might be missed elsewhere.

Some experimental details put constraints on where such a magnetic system may be located. The magnet is compensated so that its field at the mixing chamber is a factor of 500 lower than at the center of the bore. If the magnetic system were in such a low field region, its g-factor would have to be extremely large (~ 100) to match the measured field response. We therefore believe any candidate must be in the bottom 10 cm or so of the probe's cold finger. Its thermal conduction to the sample must be much better than to the probe's mixing chamber stage, where thermometry measurements do not show any response to demagnetizing. However, the cold finger, made of oxygen-free high conductivity copper, is designed to fully thermalize with the mixing chamber in order to maximally cool the sample at its bottom. If such a location existed, with poor conduction to the cryostat



FIG. S8. Adiabatic demagnetization cooling cycle. ρ_{xx} , σ_{xy} , and the temperature of the film, as inferred from the Arrhenius fit, are shown for an adiabatic demagnetization cycle. Beginning at H = -15 mT, the applied field is first swept slowly to -110 mT, after which the film is given time to cool. The field is then swept quickly back to -15 mT, causing demagnetization cooling that brings the apparent temperature of the film near 20 mK. The film cools further upon waiting several minutes, with ρ_{xx} dropping below 1 Ω .

but not sample, it would be likely to act as a weak link, impairing cooling power to the sample and raising its base temperature.

Alternative demagnetization cycle

To achieve the lowest possible ρ_{xx} , a sequence similar to an adiabatic demagnetization cycle can be used. We can further optimize from the cycle used in the main text by ending at a small but nonzero applied field. This allows us to avoid the heating event near zero field, and also to stop before the cooling power from adiabatic demagnetization tends toward zero. This can be seen in Fig. S7(b). In the simple model developed above, the quantity (S.4) remains constant during an adiabatic process. Differentiating with respect to B, it follows that

$$\frac{dT}{dB} = \frac{\frac{g\mu_0 N}{C_V} \left(\frac{g\mu_0 B}{k_B T}\right) \operatorname{sech}^2 \left(\frac{g\mu_0 B}{k_B T}\right)}{\frac{k_B N}{C_V} \left(\frac{g\mu_0 B}{k_B T}\right)^2 \operatorname{sech}^2 \left(\frac{g\mu_0 B}{k_B T}\right) + 1} = \frac{g\mu_0 N}{C_V} \left(\frac{g\mu_0 B}{k_B T}\right) + \mathcal{O}\left(\left(\frac{g\mu_0 B}{k_B T}\right)^2\right).$$
(S.5)

Since T remains nonzero, $dT/dB \rightarrow 0$ as B approaches zero, so it is advantageous to stop the adiabatic demagnetization at a nonzero field before the heat load overwhelms the cooling power.

We performed a demagnetization cycle beginning and ending at H = -15 mT and report ρ_{xx} , σ_{xy} , and the inferred temperature from the Arrhenius fit (Fig. S8). Following a previous demagnetization, the cycle starts with the film at an inferred temperature of 30 mK, still below the equilibrium temperature of 35 mK. In a rough approximation of isothermal magnetization, the magnitude of the applied field is then slowly increased until H = -110 mT, where the film is allowed to cool after heating from the magnetization. Here, the field is changed at an average rate of about 0.011 mT/s, roughly 20% slower than the corresponding step in the cycle de-



FIG. S9. High field measurements. (a), Longitudinal and Hall resistivities during field sweep over magnet's full range, -14 T to 14 T. (b), Smaller range of same data, showing resistivities as applied field approaches and crosses zero. (c), Arrhenius plots of σ_{xx} versus inverse temperature at three applied fields. The lines are exponential fits with characteristic temperatures as labelled. (d), Parametric plot of σ_{xx} versus σ_{xy} as the sample is warmed at three different applied field. The gray lines are calculated renormalization group flow lines. The plots for 0 T and 0.1 T applied fields are indistinguishable.

scribed in the main text in order to decrease the amount of heating. The adiabatic demagnetization step is then performed by sweeping H from -110 mT to -15 mT at an average rate of 0.042 mT/s. By comparison, the corresponding step in cycle from the main text was performed at approximately the same rate from -110 mT to -30 mT, and then at 0.013 mT/s from -30 mT to 0. After reaching -15 mT, ρ_{xx} is around 4 Ω . However, upon waiting a short time, the film cools further and ρ_{xx} drops below 1 Ω .

High-field measurements

Although the main emphasis of this paper is the QAHE at low applied fields, the system has surprising behavior at higher fields. A sweep over the magnet's full field range, from -14 T to 14 T (Fig. S9(a)), demonstrates that ρ_{xx} becomes sizable and ρ_{yx} departs substantially from quantization above ± 3 T. This was not the case in previous measurements performed by some of us [6], but we have in several cases observed that as samples age they become more resistive at high field. (This effect is even more acute in samples without good quantization.) The device measured in this paper was made from a film that had been grown six months earlier.

Some large resistivity features appear during the sweep, such as between -5 T and -2T (Fig. S9(b)). Under the main interpretation proposed in this paper, these would be seen as heating events, but they persist over many hours of sweeping time. The feature near +2 T, on the other hand, coincides with a temporary spike in the temperature of the mixing chamber plate thermometer.

When repeating the high-temperature measurements at nonzero applied field, the energy scale of the thermal activation decreases (Fig. S9(c)), suggesting a closing exchange gap. The system's trajectory in conductivity space shifts as well between 0 and 1 T (Fig. S9(d)), though the 0.1 T trajectory is indistinguishable from that at zero field.

Hysteresis loops at higher temperatures

In a previous device made from the same material (also different from that in Kou *et al.* [6]), hysteresis loops



FIG. S10. Hysteresis loops at higher temperatures. (a), Hall resistance of a different sample made from the same material, in ferromagnetic hysteresis loops, at a range of temperatures. The calibration in these data is less precise and the magnet sweep rate is much faster (1 mT/second, except 30 mK sweeps, which are 0.4 mT/second) than for all other figures. (b), Longitudinal resistance during same measurements. For clarity, only half of the loop is shown.

were taken at a variety of temperatures (Fig. S10(a)-(b)). These measurements were less careful: the calibration was performed to a known resistor rather than a more precise quantum Hall plateau, the lock-in amplifier's excitation frequency was higher (leading to substantial phase offsets between excitation and measurement), and the magnetic field sweep rate was much faster (leading to some heating in cryostat elements due to eddy currents). Nonetheless, they add useful information to our understanding of the ferromagnetism in the film.

As is the case elsewhere, raising the temperature to 100 mK quickly increases the value of R_{xx} and degrades quantization in R_{yx} . Between 317 mK and 486 mK we observe several changes: the hysteresis loop becomes much less sharp, the coercive field starts to decrease, and the demagnetization effect is no longer visible in R_{xx} . Further study is warranted in this temperature range to understand if these are related effects.

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