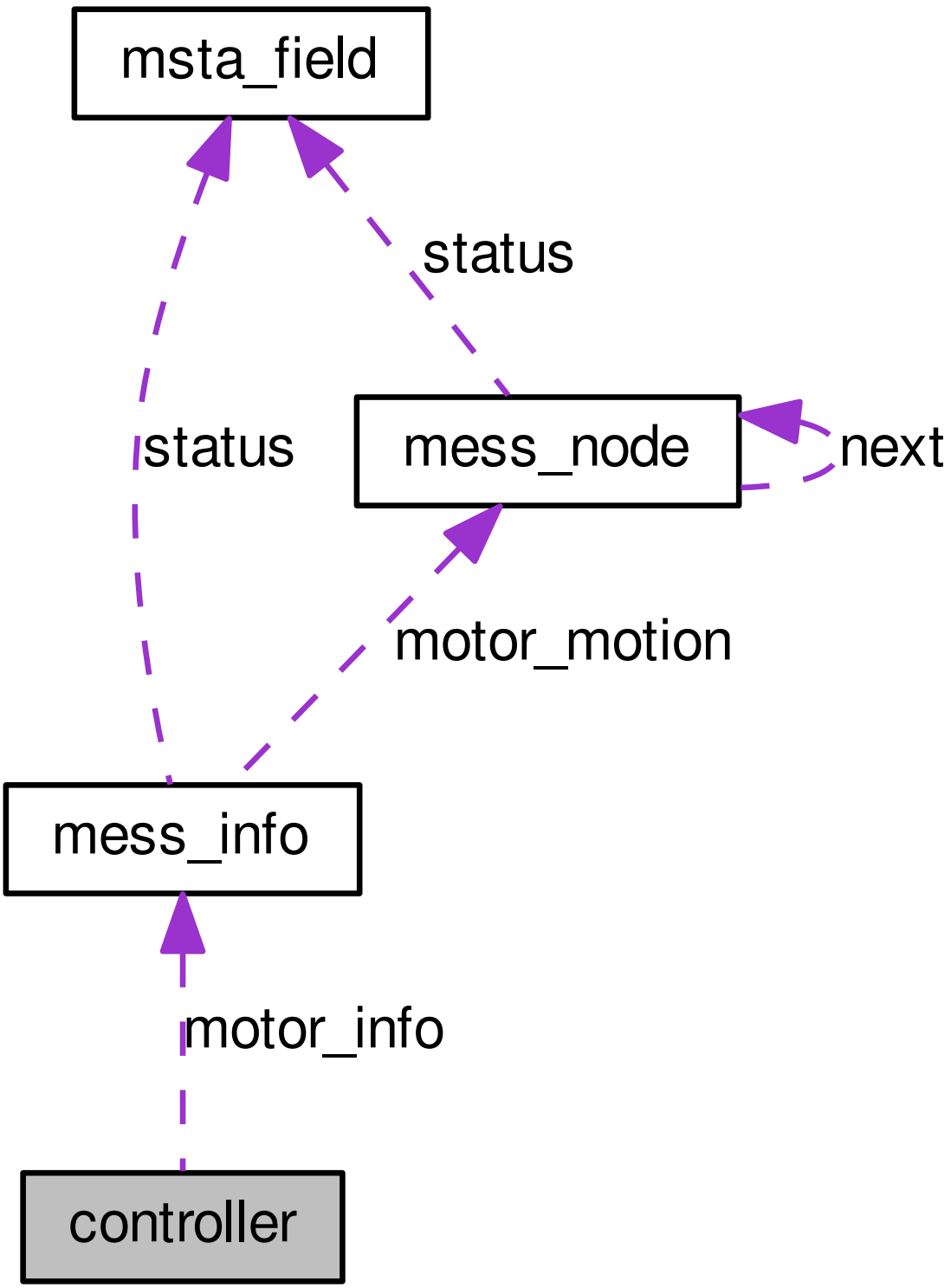
msta_field
status
status
mess_node
next
motor_motion
mess_info
motor_info
controller