MPS Logic:
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Contents

1 Ignored when BX01/BX02 Is Off, YAG01 Is In, or YAG02 Is In **20**
1.1 Toroid Comparator IM02/IM03 20

2 Ignored when BX01/BX02 Is On, YAG01 Is In, or YAG02 Is In **21**
2.1 BXS Status 21
2.2 Toroid Comparator IM02/IMS1 21

3 Ignored when BXG Is Off or YAG01 Is In **22**
3.1 Wakefield Shield Gun Spectrometer 22

4 Ignored when BXG Is On or YAG01 Is In **23**
4.1 Wakefield Shield Straight Ahead 23

5 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Diag Stopper XCS SB1 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XCS Is Not In Main Line, YAG01 Is In, or YAG02 Is In **24**
5.1 XCS SB1 VGC 02 Gate Valve Position 24
5.2 XCS SB2 VGC 01 Gate Valve Position 24

6 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper S5B Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In **25**
6.1 CXI Configuration 1 Summary 25
6.2 CXI Configuration 2 Summary 26
6.3 CXI Configuration 3 Summary 27
6.4 CXI Configuration 4 Summary 29
6.5 CXI Configuration 5 Summary 30
6.6 CXI Configuration 6 Summary 31
6.7 CXI Configuration 7 Summary 32
6.8 CXI KB2 VGC 02 Gate Valve Position 33
6.9 CXI MPS PLC Readiness Status 33
6.10 CXI User Patch Panel 1 Ready 34
6.11 CXI User Patch Panel 2 Ready 34
6.12 CXI:DG1:VGC:01 Gate Valve Open Position 34
6.13 CXI:DG1:VGC:02 Gate Valve Open Position 34
6.14 CXI:DG2:VGC:01 Gate Valve Position 35
6.15 CXI:DG2:VGC:02 Gate Valve Position 35
6.16 CXI:DG4:VGC:01 Gate Valve Position 35
6.17 CXI:DSC:VGC:01 Gate Valve Position 36

6.18 CXI:KB1:VGC:01 Gate Valve Open Position . . . 36
6.19 CXI:KB1:VGC:02 Gate Valve Open Position . . . 36
6.20 CXI:KB2:VGC:01 Gate Valve Open Position . . . 36
6.21 CXI:SC1:VGC:01 Gate Valve Position . . . 37
6.22 CXI:SC3:VGC:01 Be Gate Valve Position - Status from PLC . . . 37
6.23 HF4 LAM VGC 01 Gate Valve Position . . . 37

7 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XCS Is Not In Main Line, YAG01 Is In, or YAG02 Is In 38
7.1 XCS SB1 Diagnostic Stopper Position . . . 38
7.2 XCS SB1 VGC 01 Gate Valve Position . . . 38

8 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 39
8.1 CXI XRT Laser Reference Mirror Position . . . 39
8.2 HFA:SND:VGC:01 Gate Valve Open Position . . . 39
8.3 HFX:DIA:VGC:02 Gate Valve Open Position . . . 39
8.4 PPS Stopper S5B Position . . . 40
8.5 XRT HXRAY DIA Isolation Valve HXX-DIA-VGC-01 . . . 40

9 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 41
9.1 HFX:DG2:VGC:01 Gate Valve Position . . . 41
9.2 HFX:MON:VGC:01 Gate Valve Position . . . 41
9.3 HFX:MON:VGC:02 Gate Valve Position . . . 41
9.4 Stopper XRT S5 Position . . . 42

10 Ignored when Diag Stopper HFX UM6 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S6 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 43
10.1 MEC DV4 VCG 01 Gate Valve Position . . . 43
10.2 MEC DV5 VGC 01 Gate Valve Position . . . 43
10.3 MEC HXM VGC 01 Gate Valve Position . . . 43
10.4 MEC XT1 Reference Laser Position . . . 44
10.5 MEC XT1 VGC 01 Gate Valve Position . . . 44
10.6 MEC XT2 VGC 02 Gate Valve Position . . . 44
10.7 MEC XT2 VGC 03 Gate Valve Position . . . 44
10.8 MEC XT2 VGC 04 Gate Valve Position . . . 45
10.9 MEC XT2 VGC 05 Gate Valve Position . . . 45
10.10 MEC XT2 VGC 06 Gate Valve Position . . . 45

11 Ignored when Diag Stopper HFX UM6 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In **46**
11.1 DG2 Diagnostic Stopper Position . . . 46
11.2 MEC BXL VGC 01 Gate Valve Position . . . 46
11.3 MEC M3H Mirror and DG2 STP Fault . . . 46
11.4 MEC M3H Mirror Unknown Position Fault . . . 47
11.5 MEC XRT Attenuator Inspection Mirror Position . . . 47
11.6 MFX Gate Valves Not All Open - PLC Summary Status . . . 47
11.7 Stopper XRT S6 Position . . . 48
11.8 XRT HXRAY LOM Isolation Valve HXX-LOM-VGC-01 . . . 48
11.9 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:01 . . . 48
11.10 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:02 . . . 49
11.11 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:03 . . . 49
11.12 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:05 . . . 49

12 Ignored when Laser Heater Attenuator Is In **50**
12.1 Laser Heater Photodiode Shutter Position . . . 50
12.2 OTRH1 Position When LH Atten Not In . . . 50
12.3 OTRH2 Position When LH Atten Not In . . . 50

13 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper S1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In **51**
13.1 NEH AMO Laser Reference Mirror Position . . . 51
13.2 NEH AMO Valves Ok for Beam - Summary From PLC . . . 51
13.3 NEH1 Camera 1124 Position . . . 51
13.4 NEH1 XTOD S1 Isolation Valve Summary . . . 52

14 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper S2 Is In, Stopper S2B Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In **53**
14.1 NEH SXR Differential Pump Isolation Valve SXR-DFP-VGC-01 . . . 53
14.2 NEH SXR End Station Ready SXR-EXP-MPS-01 . . . 53
14.3 NEH SXR Intensity Monitor Isolation Valve SXR-FLX-VGC-01 . . . 54
14.4 NEH SXR KB Optics Isolation Valve SXR-KBO-VGC-01 . . . 54
14.5 NEH SXR Laser In-coupling Mirror Isolation Valve SXR-LIN-VGC-01 . . . 54

15 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper S2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In **55**
15.1 NEH Camera 2124 Position . . . 55
15.2 NEH SXR Collimator 3 Isolation Valve SXR-COL-VGC-01 . . . 55
15.3 NEH SXR Exit Slits Isolation Valve SXR-EXS-VGC-01 . . . 56
15.4 NEH SXR GMD VGC 01 Protection . . . 56
15.5 NEH SXR Monochromator Tank Isolation Valve SXR-MON-VGC-01 . . . 56
15.6 NEH SXR Photon Stoppers Isolation Valve SXR-PST-VGC-01 . . . 57
15.7 NEH SXR Transmission Sample System Isolation Valve SXR-TSS-VGC-01 . . . 57

15.8 NEH SXR Zero Order Interlock SXR-MON-MMS-06, SXR-EXS-MMS-01 57
15.9 NEH1 XTOD S2 Isolation Valve Summary 58

16 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 59
16.1 UM6 Diagnostic Stopper Position 59
16.2 XRT HXRAY UM6 Isolation Valve HXX-UM6-VGC-01 59
16.3 XRT UM6 Camera Position HXX-UM6-CVP-01 60

17 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XPP-NH3-POS-00 Beamline Is In, YAG01 Is In, or YAG02 Is In 61
17.1 NEH3 HXRAY DVD Isolation Valve HX3-DVD-VGC-01 61

18 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XPP-NH3-POS-00 Beamline Is Not In, YAG01 Is In, or YAG02 Is In 62
18.1 XPP SB2 VGC 01 Gate Valve Position 62
18.2 XPP SB2 VGC 02 Gate Valve Position 62
18.3 XPP SB2 VGC 03 Gate Valve Position 62

19 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 63
19.1 HX2 UVD VGC 01 Gate Valve Position 63
19.2 HX3 MON VGC 01 Gate Valve Position 63
19.3 NEH1 Camera 124 Position 63
19.4 NEH1 Camera 195 Position 64
19.5 NEH1 XTOD H Isolation Valve Summary 64
19.6 NEH2 HXRAY DVD Isolation Valve HX2-DVD-VGC-01 64
19.7 NEH3 HXRAY UVD Isolation Valve HX3-UVD-VGC-01 65

20 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 66
20.1 FEE Camera 1561 Position 66
20.2 FEE Camera 1692 Position 66
20.3 FEE Camera 1953 Position 66
20.4 FEE Camera 2953 Position 67
20.5 FEE Camera 852 Position 67
20.6 FEE Camera 913 Position 67
20.7 FEE Fast Shutter Valve and System Summary 68
20.8 FEE Gas Flow Aperture Summary 68
20.9 FEE Gas Flow Vacuum Isolation Valve Summary 68
20.10 FEE Instrument Vacuum Isolation Valve Summary 68
20.11 FEE Solid Attenuators - Gas Pressure Interlock 69
20.12 FEE Spectrometer Crystal - Beam Energy Too Low When Crystal Not Out 70

20.13 FEE XTOD H Isolation Valve Summary . . . 70
20.14 FEE XTOD S1 Isolation Valve Summary . . . 70
20.15 FEE XTOD S2 Isolation Valve Summary . . . 71
20.16 FEE1 M1S Mirror Beam Energy Upper Limit . . . 71
20.17 FEE1 M1S Mirror State . . . 71
20.18 HXR - Beam Energy Too Low With M1S Out . . . 72

21 Ignored when Stopper: BSY D2 Summary Is In 73
21.1 Stopper: ST1/ST2 Position . . . 73

22 Ignored when Stopper: BSY D2 Summary Is In or TDUND Is In 74
22.1 HXRSS Beamline Position . . . 74
22.2 HXRSS Chicane Bend Magnet Power Supply . . . 74
22.3 HXRSS Crystal Position . . . 74
22.4 HXRSS Crystal Valid Position . . . 75
22.5 HXRSS Mode State . . . 75
22.6 SXRSS Grating/M1 GRAT UND1 934 Position . . . 77
22.7 SXRSS M2 MIRR UND1 964 Position . . . 77
22.8 SXRSS M3 MIRR UND1 966 Position . . . 78
22.9 SXRSS Mode State . . . 78
22.10 SXRSS SLIT UND1 962 Position . . . 81
22.11 SXRSS Watchdog . . . 81

23 Ignored when Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 82
23.1 BCS LION LTU1 405 Threshold . . . 82
23.2 BCS LION LTU1 504 Threshold . . . 82
23.3 BCS LION LTU1 505 Threshold . . . 82
23.4 BCS LION LTU1 585 Threshold . . . 82
23.5 BCS LION LTU1 716 Threshold . . . 83
23.6 BCS LION LTU1 717 Threshold . . . 83
23.7 BCS LION LTU1 732 Threshold . . . 83
23.8 BCS LION LTU1 733 Threshold . . . 83
23.9 BCS LION LTU1 752 Threshold . . . 84
23.10 BCS LION LTU1 753 Threshold . . . 84
23.11 BCS LION LTU1 765 Threshold . . . 84
23.12 BCS LION LTU1 766 Threshold . . . 84
23.13 BOD UND1 1005 . . . 85
23.14 BOD UND1 1305 . . . 85
23.15 BYD Watchdog . . . 85
23.16 Magnet In Tolerance: QE31 . . . 85
23.17 Magnet In Tolerance: QUM1 . . . 86
23.18 Magnet In Tolerance: QUM2 . . . 86
23.19 Magnet In Tolerance: QUM3 . . . 86
23.20 Magnet In Tolerance: QUM4 . . . 86

23.21 Magnet Power: QE31 . . . 87
23.22 Magnet Power: QUM1 . . . 87
23.23 Magnet Power: QUM2 . . . 87
23.24 Magnet Power: QUM3 . . . 87
23.25 Magnet Power: QUM4 . . . 88
23.26 OTR30 LTU1 449 Position When TDUND Not In . . . 88
23.27 OTR33 Position When TDUND Not In . . . 88
23.28 PIC Raw Charge Thresholds: DMP1 698 . . . 89
23.29 PIC Raw Charge Thresholds: DMP1 699 . . . 89
23.30 Spoiler: SP0 DMP1 765 Position . . . 89
23.31 VVFS DMP1 107 Position . . . 90
23.32 VVMG DMP1 743 Position . . . 90
23.33 VVMG UND1 1645 Position . . . 90
23.34 VVMG UND1 1655 Position . . . 90
23.35 VVPG DMP1 355 Position . . . 91
23.36 YAG LTU1 743 Position When TDUND Not In (PSI Prof Mon) . . . 91

24 Ignored when Stopper: BSY D2 Summary Is In, TD11 Is In, YAG01 Is In, or YAG02 Is In 92
24.1 BCS PIC RAW Charge Threshold DMP 997 . . . 92
24.2 BCS PIC RAW Charge Threshold DMP 998 . . . 92
24.3 BLM Heartbeat: Dechirper LTU1 BLF545 . . . 92
24.4 BLM Pedestal Thresholds: Dechirper LTU1 BLF545 . . . 93
24.5 BLM Raw Charge Thresholds: Dechirper LTU1 BLF545 . . . 93
24.6 BYKIK 120 Hz Abort Trigger . . . 93
24.7 BYKIK 120 Hz Standby Trigger . . . 94
24.8 BYKIK 30 Hz Abort Trigger . . . 94
24.9 BYKIK 30 Hz Standby Trigger . . . 94
24.10 BYKIK Readback Signal . . . 94
24.11 LTU Dechirper - Horizontal Gap Too Small . . . 95
24.12 LTU Dechirper - Vertical Gap Too Small . . . 95
24.13 Magnet In Tolerance: BYD1 . . . 95
24.14 Magnet Power: BYD1 . . . 96
24.15 OTR30 LTU1 449 Position . . . 96
24.16 OTR33 Position . . . 96
24.17 TDUND Flow Switch Fault With TDUND Not Out . . . 97
24.18 TDUND Position . . . 97
24.19 Temperature RTD Summary: BSY Common Line Past D2 . . . 97
24.20 THZ-2 Position . . . 98
24.21 Undulator Beam Energy Lower Limit . . . 98
24.22 VVFS LTU1 102 Position . . . 98
24.23 VVMG LTU1 174 Position . . . 98
24.24 VVMG LTU1 355 Position . . . 99
24.25 VVMG LTU1 670 Position . . . 99
24.26 VVMG LTU1 742 Position . . . 99
24.27 VVMG LTU1 774 Position . . . 99

24.28 VVMG UND1 932 Position . . . 100
24.29 VVMG UND1 968 Position . . . 100
24.30 VVPG DMP1 103 Position . . . 100
24.31 VVPG DMP1 395 Position . . . 100
24.32 VVPG DMP1 700 Position . . . 101
24.33 VVPG LTU1 100 Position . . . 101
24.34 VVPG LTU1 265 Position . . . 101
24.35 VVPG LTU1 435 Position . . . 101
24.36 VVPG LTU1 580 Position . . . 102
24.37 VVPG LTU1 725 Position . . . 102
24.38 VVPG LTU1 757 Position . . . 102
24.39 VVPG LTU1 999 Position . . . 102
24.40 VVPG UND1 1000 Position . . . 103
24.41 VVPG UND1 2500 Position . . . 103
24.42 YAG LTU1 743 Position (PSI Prof Mon) . . . 103

25 Ignored when TD11 Is In 104
25.1 Test Temperature Logic Is Code . . . 104

26 Ignored when TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 105
26.1 BFW 1010 Position . . . 105
26.2 BFW 110 Position . . . 105
26.3 BFW 1110 Position . . . 105
26.4 BFW 1210 Position . . . 106
26.5 BFW 1310 Position . . . 106
26.6 BFW 1410 Position . . . 106
26.7 BFW 1510 Position . . . 107
26.8 BFW 1610 Position . . . 107
26.9 BFW 1710 Position . . . 107
26.10 BFW 1810 Position . . . 108
26.11 BFW 2010 Position . . . 108
26.12 BFW 210 Position . . . 108
26.13 BFW 2110 Position . . . 109
26.14 BFW 2210 Position . . . 109
26.15 BFW 2310 Position . . . 109
26.16 BFW 2410 Position . . . 110
26.17 BFW 2510 Position . . . 110
26.18 BFW 2610 Position . . . 110
26.19 BFW 2710 Position . . . 111
26.20 BFW 2810 Position . . . 111
26.21 BFW 2910 Position . . . 111
26.22 BFW 3010 Position . . . 112
26.23 BFW 310 Position . . . 112
26.24 BFW 3110 Position . . . 112
26.25 BFW 3210 Position . . . 113

26.26 BFW 3310 Position . . . 113
26.27 BFW 410 Position . . . 113
26.28 BFW 510 Position . . . 114
26.29 BFW 610 Position . . . 114
26.30 BFW 710 Position . . . 114
26.31 BFW 810 Position . . . 115
26.32 BFW 910 Position . . . 115
26.33 BFW Inserted Count . . . 115
26.34 BLM Argonne Heartbeat (LN32) . . . 117
26.35 BLM Argonne Heartbeat (LN33) . . . 117
26.36 BLM Argonne Heartbeat (LN35) . . . 117
26.37 BLM Argonne Heartbeat (LN36) . . . 118
26.38 BLM Argonne Heartbeat (LN37) . . . 118
26.39 BLM HVPS LTU1 762 . . . 118
26.40 BLM HVPS UND1 120 . . . 119
26.41 BLM HVPS UND1 1720 . . . 119
26.42 BLM HVPS UND1 2221 . . . 119
26.43 BLM HVPS UND1 2520 . . . 120
26.44 BLM HVPS UND1 3320 . . . 120
26.45 BLM HVPS UND1 920 . . . 120
26.46 BLM Pedestal Threshold: LTU1 722 . . . 121
26.47 BLM Pedestal Threshold: LTU1 732 . . . 121
26.48 BLM Pedestal Threshold: LTU1 762 . . . 121
26.49 BLM Pedestal Threshold: LTU1 772 . . . 122
26.50 BLM Pedestal Thresholds: LTU1 980 . . . 122
26.51 BLM Pedestal Thresholds: UND 1021 . . . 122
26.52 BLM Pedestal Thresholds: UND 1121 . . . 123
26.53 BLM Pedestal Thresholds: UND 120 . . . 123
26.54 BLM Pedestal Thresholds: UND 121 . . . 123
26.55 BLM Pedestal Thresholds: UND 1221 . . . 124
26.56 BLM Pedestal Thresholds: UND 1321 . . . 124
26.57 BLM Pedestal Thresholds: UND 1421 . . . 124
26.58 BLM Pedestal Thresholds: UND 1521 . . . 125
26.59 BLM Pedestal Thresholds: UND 1621 . . . 125
26.60 BLM Pedestal Thresholds: UND 1720 . . . 125
26.61 BLM Pedestal Thresholds: UND 1721 . . . 126
26.62 BLM Pedestal Thresholds: UND 1821 . . . 126
26.63 BLM Pedestal Thresholds: UND 1921 . . . 126
26.64 BLM Pedestal Thresholds: UND 2021 . . . 127
26.65 BLM Pedestal Thresholds: UND 2121 . . . 127
26.66 BLM Pedestal Thresholds: UND 221 . . . 127
26.67 BLM Pedestal Thresholds: UND 2221 . . . 128
26.68 BLM Pedestal Thresholds: UND 2321 . . . 128
26.69 BLM Pedestal Thresholds: UND 2421 . . . 128
26.70 BLM Pedestal Thresholds: UND 2520 . . . 129

26.71 BLM Pedestal Thresholds: UND 2521 . . . 129
26.72 BLM Pedestal Thresholds: UND 2621 . . . 129
26.73 BLM Pedestal Thresholds: UND 2721 . . . 130
26.74 BLM Pedestal Thresholds: UND 2821 . . . 130
26.75 BLM Pedestal Thresholds: UND 2921 . . . 130
26.76 BLM Pedestal Thresholds: UND 3021 . . . 131
26.77 BLM Pedestal Thresholds: UND 3121 . . . 131
26.78 BLM Pedestal Thresholds: UND 321 . . . 131
26.79 BLM Pedestal Thresholds: UND 3221 . . . 132
26.80 BLM Pedestal Thresholds: UND 3320 . . . 132
26.81 BLM Pedestal Thresholds: UND 3321 . . . 132
26.82 BLM Pedestal Thresholds: UND 421 . . . 133
26.83 BLM Pedestal Thresholds: UND 521 . . . 133
26.84 BLM Pedestal Thresholds: UND 621 . . . 133
26.85 BLM Pedestal Thresholds: UND 721 . . . 134
26.86 BLM Pedestal Thresholds: UND 821 . . . 134
26.87 BLM Pedestal Thresholds: UND 920 . . . 134
26.88 BLM Pedestal Thresholds: UND 921 . . . 135
26.89 BLM Pedestal Thresholds: UND BLF1 . . . 135
26.90 BLM Pedestal Thresholds: UND BLF17 . . . 135
26.91 BLM PEP Timing Check (LN30) . . . 136
26.92 BLM PEP Timing Check (LN32) . . . 136
26.93 BLM PEP Timing Check (LN33) . . . 136
26.94 BLM PEP Timing Check (LN35) . . . 137
26.95 BLM PEP Timing Check (LN36) . . . 137
26.96 BLM PEP Timing Check (LN37) . . . 137
26.97 BLM Raw Charge Thresholds: LTU1 722 . . . 138
26.98 BLM Raw Charge Thresholds: LTU1 732 . . . 138
26.99 BLM Raw Charge Thresholds: LTU1 762 . . . 138
26.100 BLM Raw Charge Thresholds: LTU1 772 . . . 139
26.101 BLM Raw Charge Thresholds: LTU1 980 . . . 139
26.102 BLM Raw Charge Thresholds: UND 1021 . . . 139
26.103 BLM Raw Charge Thresholds: UND 1121 . . . 140
26.104 BLM Raw Charge Thresholds: UND 120 . . . 140
26.105 BLM Raw Charge Thresholds: UND 121 . . . 140
26.106 BLM Raw Charge Thresholds: UND 1221 . . . 141
26.107 BLM Raw Charge Thresholds: UND 1321 . . . 141
26.108 BLM Raw Charge Thresholds: UND 1421 . . . 141
26.109 BLM Raw Charge Thresholds: UND 1521 . . . 142
26.110 BLM Raw Charge Thresholds: UND 1621 . . . 142
26.111 BLM Raw Charge Thresholds: UND 1720 . . . 142
26.112 BLM Raw Charge Thresholds: UND 1721 . . . 143
26.113 BLM Raw Charge Thresholds: UND 1821 . . . 143
26.114 BLM Raw Charge Thresholds: UND 1921 . . . 143
26.115 BLM Raw Charge Thresholds: UND 2021 . . . 144

26.116 BLM Raw Charge Thresholds: UND 2121 . . . 144
26.117 BLM Raw Charge Thresholds: UND 221 . . . 144
26.118 BLM Raw Charge Thresholds: UND 2221 . . . 145
26.119 BLM Raw Charge Thresholds: UND 2321 . . . 145
26.120 BLM Raw Charge Thresholds: UND 2421 . . . 145
26.121 BLM Raw Charge Thresholds: UND 2520 . . . 146
26.122 BLM Raw Charge Thresholds: UND 2521 . . . 146
26.123 BLM Raw Charge Thresholds: UND 2621 . . . 146
26.124 BLM Raw Charge Thresholds: UND 2721 . . . 147
26.125 BLM Raw Charge Thresholds: UND 2821 . . . 147
26.126 BLM Raw Charge Thresholds: UND 2921 . . . 147
26.127 BLM Raw Charge Thresholds: UND 3021 . . . 148
26.128 BLM Raw Charge Thresholds: UND 3121 . . . 148
26.129 BLM Raw Charge Thresholds: UND 321 . . . 148
26.130 BLM Raw Charge Thresholds: UND 3221 . . . 149
26.131 BLM Raw Charge Thresholds: UND 3320 . . . 149
26.132 BLM Raw Charge Thresholds: UND 3321 . . . 149
26.133 BLM Raw Charge Thresholds: UND 421 . . . 150
26.134 BLM Raw Charge Thresholds: UND 521 . . . 150
26.135 BLM Raw Charge Thresholds: UND 621 . . . 150
26.136 BLM Raw Charge Thresholds: UND 721 . . . 151
26.137 BLM Raw Charge Thresholds: UND 821 . . . 151
26.138 BLM Raw Charge Thresholds: UND 920 . . . 151
26.139 BLM Raw Charge Thresholds: UND 921 . . . 152
26.140 BLM Raw Charge Thresholds: UND BLF1 . . . 152
26.141 BLM Raw Charge Thresholds: UND BLF17 . . . 152
26.142 BLM Timing Check (BLM:UND1:4) . . . 153
26.143 BLM Timing Check (LN30) . . . 153
26.144 BLM Trigger Missed (LN30) . . . 153
26.145 BLM Trigger Missed (LN32) . . . 153
26.146 BLM Trigger Missed (LN33) . . . 154
26.147 BLM Trigger Missed (LN35) . . . 154
26.148 BLM Trigger Missed (LN36) . . . 154
26.149 BLM Trigger Missed (LN37) . . . 154
26.150 BLM/PIC Watchdog: Downstream of TDUND . . . 155
26.151 BPM Summary (1-9) . . . 155
26.152 BPM Summary (10-18) . . . 155
26.153 BPM Summary (19-27) . . . 155
26.154 BPM Summary (28-36) . . . 156
26.155 OTR01 IN20 541 Position and TDUND Not In . . . 156
26.156 OTR02 IN20 571 Position and TDUND Not In . . . 156
26.157 OTR03 IN20 621 Position and TDUND Not In . . . 157
26.158 OTR04 IN20 711 Position and TDUND Not In . . . 157
26.159 OTR11 LI21 237 Position and TDUND Not In . . . 157
26.160 OTR12 LI21 291 Position and TDUND Not In . . . 158

26.161 OTR21 Position When TDUND Not In . . . 158
26.162 OTR22 Position When TDUND Not In . . . 158
26.163 OTRH1 Position When TDUND Not In . . . 159
26.164 OTRH2 Position When TDUND Not In . . . 159
26.165 PIC HVPS B921 - Location B921-2235 . . . 159
26.166 PIC Trigger Missed (LN34) . . . 159
26.167 THz Radiator Beryllium Foil . . . 160
26.168 Toroid Comparator (IMUNDI vs IMUNDO) . . . 160
26.169 Toroid Comparator (IMUNDO vs IMDUMP) . . . 160
26.170 Toroid Comparator Power Status (B921) . . . 161

27 Ignored when TD11 Is In, YAG01 Is In, or YAG02 Is In 162
27.1 A-Line SL10 Position . . . 162
27.2 BLM/PIC Watchdog BSY0/BSYA . . . 162
27.3 BLM/PIC Watchdog LI24 . . . 163
27.4 BLM/PIC Watchdog LI30 . . . 163
27.5 BSY GLAST Target Flow Switch . . . 163
27.6 BSY GLAST Target Klixon . . . 163
27.7 BSY GLAST Target Position . . . 164
27.8 Bunch Length Monitor BL21 Position . . . 164
27.9 Flowswitch: BPM BSYA 1020 (BPM10) . . . 164
27.10 Flowswitch: BPM BSYA 1240 (BPM12) . . . 165
27.11 Flowswitch: BSY PC320 . . . 165
27.12 Flowswitch: BSY PC90 . . . 165
27.13 Flowswitch: BSY RAD LCW Slit 10/30 . . . 165
27.14 Flowswitch: CE21 . . . 166
27.15 Flowswitch: COLL BSY0 16 (50PC20) . . . 166
27.16 Flowswitch: COLL BSY0 33 (50PC30) . . . 166
27.17 Flowswitch: COLL BSY0 45 (50PC-45) . . . 166
27.18 Flowswitch: COLL BSY0 59 (PC0119) . . . 167
27.19 Flowswitch: COLL BSY0 65 (PC0145) . . . 167
27.20 Flowswitch: COLL BSY0 67 (PC0155) . . . 167
27.21 Flowswitch: COLL BSY0 69 (PC0165) . . . 167
27.22 Flowswitch: COLL BSY0 71 (PC0175) . . . 168
27.23 Flowswitch: COLL BSY0 73 (PC0185) . . . 168
27.24 Flowswitch: COLL BSY0 75 (PC0195) . . . 168
27.25 Flowswitch: COLL BSYA 1015 (PC10) . . . 168
27.26 Flowswitch: COLL BSYA 1230 (PC12) . . . 169
27.27 Flowswitch: COLL BSYA 1490 (PC14) . . . 169
27.28 Flowswitch: COLL BSYA 1700 (PC17) . . . 169
27.29 Flowswitch: COLL BSYA 2060 (PC20) . . . 169
27.30 Flowswitch: COLL BSYA 2410 (COLL24H) . . . 170
27.31 Flowswitch: COLL BSYA 2410 (COLL24V) . . . 170
27.32 Flowswitch: COLL BSYA 2410 (PC24) . . . 170
27.33 Flowswitch: COLL BSYA 2600 (PC26) . . . 170

27.34 Flowswitch: COLL BSYA 2990 (PC29) . . . 171
27.35 Flowswitch: COLL BSYA 3710 (C37) . . . 171
27.36 Flowswitch: COLL BSYA 4120 (3C1A) . . . 171
27.37 Hydrogen Recombiner For BSY 1 Collimator . . . 171
27.38 Hydrogen Recombiner For BSY 2 Slit 10/30 . . . 172
27.39 Ion Chamber Gas Flowswitch BSY A . . . 172
27.40 Ion Chamber Gas Flowswitch BSY B . . . 172
27.41 Ion Chamber Gas Flowswitch BSY C . . . 172
27.42 KICK BSY0 66 PM1 State (A-Line Kicker) . . . 173
27.43 KICK BSY0 66 PM1 Trigger State (A-Line Kicker) . . . 173
27.44 KICK BSY0 66 PM2 State (A-Line Kicker) . . . 173
27.45 KICK BSY0 66 PM2 Trigger State (A-Line Kicker) . . . 174
27.46 OTR21 Position . . . 174
27.47 OTR22 Position . . . 174
27.48 PIC Gas Pressure LI24 . . . 175
27.49 PIC HVPS B911 - Location B911-2135 . . . 175
27.50 PIC HVPS B912 - Location B912-2135 . . . 175
27.51 PIC HVPS B913 - Location B913-2135 . . . 175
27.52 PIC HVPS BSY 1 - Location B005-3921 . . . 176
27.53 PIC HVPS BSY 2 - Location B005-3921 . . . 176
27.54 PIC HVPS BSY 3 - Location B005-3921 . . . 176
27.55 PIC HVPS BSY 4 - Location B005-3918 . . . 176
27.56 PIC HVPS BSY 5 - Location B005-3918 . . . 177
27.57 PIC HVPS BSY 6 - Location B005-3918 . . . 177
27.58 PIC HVPS LI24 - Location LKF24-0235 . . . 177
27.59 PIC Raw Charge Thresholds: BSYA 1016 . . . 177
27.60 PIC Raw Charge Thresholds: BSYA 1021 . . . 178
27.61 PIC Raw Charge Thresholds: BSYA 1120 . . . 178
27.62 PIC Raw Charge Thresholds: BSYA 1320 . . . 178
27.63 PIC Raw Charge Thresholds: BSYA 1520 . . . 179
27.64 PIC Raw Charge Thresholds: BSYA 1701A . . . 179
27.65 PIC Raw Charge Thresholds: BSYA 1701B . . . 179
27.66 PIC Raw Charge Thresholds: BSYA 1980 . . . 180
27.67 PIC Raw Charge Thresholds: BSYA 2061 . . . 180
27.68 PIC Raw Charge Thresholds: BSYA 2120 . . . 180
27.69 PIC Raw Charge Thresholds: BSYA 2220 . . . 181
27.70 PIC Raw Charge Thresholds: BSYA 2321 . . . 181
27.71 PIC Raw Charge Thresholds: BSYA 2411 . . . 181
27.72 PIC Raw Charge Thresholds: BSYA 2472 . . . 182
27.73 PIC Raw Charge Thresholds: BSYA 2473 . . . 182
27.74 PIC Raw Charge Thresholds: BSYA 2474 . . . 182
27.75 PIC Raw Charge Thresholds: BSYA 2475 . . . 183
27.76 PIC Raw Charge Thresholds: BSYA 2520 . . . 183
27.77 PIC Raw Charge Thresholds: BSYA 2601 . . . 183
27.78 PIC Raw Charge Thresholds: BSYA 2861 . . . 184

27.79 PIC Raw Charge Thresholds: BSYA 2990 . . . 184
27.80 PIC Raw Charge Thresholds: BSYA 3320 . . . 184
27.81 PIC Raw Charge Thresholds: BSYA 3720 . . . 185
27.82 PIC Raw Charge Thresholds: BSYA 3721 . . . 185
27.83 PIC Raw Charge Thresholds: BSYA 3890 . . . 185
27.84 PIC Raw Charge Thresholds: LTU1 220 . . . 186
27.85 PIC Raw Charge Thresholds: LTU1 252 . . . 186
27.86 PIC Raw Charge Thresholds: LTU1 280 . . . 186
27.87 PIC Raw Charge Thresholds: LTU1 420 . . . 187
27.88 PIC Raw Charge Thresholds: LTU1 450 . . . 187
27.89 PIC Raw Charge Thresholds: LTU1 480 . . . 187
27.90 PIC Raw Charge Thresholds: LTU1 722 . . . 188
27.91 PIC Raw Charge Thresholds: LTU1 732 . . . 188
27.92 PIC Raw Charge Thresholds: LTU1 762 . . . 188
27.93 PIC Raw Charge Thresholds: LTU1 772 . . . 189
27.94 PIC Trigger Missed (LN28) . . . 189
27.95 PIC Trigger Missed (LN29) . . . 189
27.96 PIC Trigger Missed (LN31) . . . 189
27.97 PIC Trigger Missed (LN42) . . . 190
27.98 Stopper BSYA 2275 (ST22) Position . . . 190
27.99 Stopper BSYA 2930 (ST29) Position . . . 190
27.100 Stopper: BSY D2, 60, 61 DM60 Summary . . . 190
27.101 Temperature RTD Summary: A-Line Before SL10 . . . 193
27.102 Temperature RTD Summary: A-line Past SL10 . . . 193
27.103 Temperature RTD Summary: BSY Common Line Before D2 . . . 194
27.104 Toroid Chassis IMBC2 . . . 194
27.105 Toroid Comparator IMBC2IN/IMBC2OUT . . . 194
27.106 Vac Valve BSYA 4005 (IV40) . . . 194
27.107 Vac Valve: VVFS BSYA 1030 (FV10) . . . 195
27.108 Vac Valve: VVFS BSYA 2855 (FV28) . . . 195
27.109 Vac Valve: VVPG BSYA 1018 (IV10) . . . 195
27.110 Vac Valve: VVPG BSYA 2635 (IV26) . . . 195
27.111 Vac Valve: VVPG ESA0 4195 POSITION (IV41) . . . 196
27.112 VVPG BSY0 IV2 Position . . . 196
27.113 VVPG BSY0 IV3 Position . . . 196
27.114 VVPG BSY0 IV4 Position . . . 196

28 Ignored when YAG01 Is In 197
28.1 BXG Status . . . 197
28.2 SONYA UND FAULT TEST . . . 197
28.3 Test Temperature Logic . . . 197
28.4 Toroid Peak Current Monitor IM01 . . . 198
28.5 YAG02 IN20 241 Position . . . 198

29 Ignored when YAG01 Is In or YAG02 Is In 199

29.1 BLM/PIC Watchdog: Upstream of TDUND . . . 199
29.2 BX01/BX02 Status . . . 199
29.3 Dump LI28 5879 Flowswitch . . . 199
29.4 Dump LI28 5879 Klixon . . . 199
29.5 Fast Shutter FV2 LI30 Position . . . 200
29.6 Fast Shutter FV2A LI30 Position . . . 200
29.7 Flowswitch: CE11 . . . 200
29.8 Flowswitch: COLL LI28-9 . . . 200
29.9 Flowswitch: COLL LI29-1 . . . 201
29.10 Flowswitch: COLL LI29-4 . . . 201
29.11 Flowswitch: COLL LI29-5 . . . 201
29.12 Flowswitch: COLL LI29-9 . . . 201
29.13 Flowswitch: COLL LI30-1 . . . 202
29.14 Flowswitch: COLL LI30-4 . . . 202
29.15 Flowswitch: COLL LI30-5 . . . 202
29.16 Flowswitch: TD11 . . . 202
29.17 Main Manifold Gauge: LI21 Station 5 . . . 203
29.18 Main Manifold Gauge: LI22 Station 5 . . . 203
29.19 Main Manifold Gauge: LI23 Station 5 . . . 203
29.20 Main Manifold Gauge: LI24 Station 5 . . . 203
29.21 Main Manifold Gauge: LI25 Station 5 . . . 204
29.22 Main Manifold Gauge: LI26 Station 5 . . . 204
29.23 Main Manifold Gauge: LI27 Station 5 . . . 204
29.24 Main Manifold Gauge: LI28 Station 5 . . . 204
29.25 Main Manifold Gauge: LI29 Station 5 . . . 205
29.26 Main Manifold Gauge: LI30 Station 5 . . . 205
29.27 Main Manifold Gauge: LI30 Station 9 . . . 205
29.28 Mirror BL11 Position . . . 205
29.29 OTR LI25 920 Position . . . 206
29.30 OTR01 IN20 541 Position . . . 206
29.31 OTR02 IN20 571 Position . . . 206
29.32 OTR03 IN20 621 Position . . . 207
29.33 OTR04 IN20 711 Position . . . 207
29.34 OTR11 LI21 237 Position . . . 207
29.35 OTR12 LI21 291 Position . . . 208
29.36 OTRH1 Position . . . 208
29.37 OTRH2 Position . . . 208
29.38 PIC HVPS LI30 - KG30-C1322 . . . 209
29.39 PIC Raw Charge Thresholds: LI24 791 . . . 209
29.40 PIC Raw Charge Thresholds: LI24 811 . . . 209
29.41 PIC Trigger Missed (LN16) . . . 209
29.42 Scraper Water LI21-9 (Station 22-1) . . . 210
29.43 Scraper Water LI22-9 (Station 23-1) . . . 210
29.44 Scraper Water LI23-9 (Station 24-1) . . . 210
29.45 Scraper Water LI24-9 (Station 25-1) . . . 210

29.46 Scraper Water LI25-9 (Station 26-1) . . . 211
29.47 Scraper Water LI26-9 (Station 27-1) . . . 211
29.48 Scraper Water LI27-9 (Station 28-1) . . . 211
29.49 Scraper Water LI28-9 (Station 29-1) . . . 211
29.50 Scraper Water LI29-9 (Station 30-1) . . . 212
29.51 Stopper LI28 950 and 960 Position . . . 212
29.52 Sub-booster Ready: LI21 . . . 212
29.53 Sub-booster Ready: LI22 . . . 212
29.54 Sub-booster Ready: LI25 . . . 213
29.55 Sub-booster Ready: LI26 . . . 213
29.56 Sub-booster Ready: LI27 . . . 213
29.57 Sub-booster Ready: LI28 . . . 213
29.58 Sub-booster Ready: LI29 . . . 214
29.59 Sub-booster Ready: LI30 . . . 214
29.60 TD11 Position . . . 214
29.61 Toroid Chassis IM11 . . . 214
29.62 Toroid Chassis IM12 . . . 215
29.63 Toroid Comparator IMBC1IN/IMBC1OUT . . . 215
29.64 VVFS LI21-9 Position (Station 22-1) . . . 215
29.65 VVFS LI22-9 Position (Station 23-1) . . . 215
29.66 VVFS LI23-9 Position (Station 24-1) . . . 216
29.67 VVFS LI24-9 Position (Station 25-1) . . . 216
29.68 VVFS LI25-9 Position (Station 26-1) . . . 216
29.69 VVFS LI26-9 Position (Station 27-1) . . . 216
29.70 VVFS LI27-9 Position (Station 28-1) . . . 217
29.71 VVFS LI28-9 Position (Station 29-1) . . . 217
29.72 VVFS LI29-9 Position (Station 30-1) . . . 217
29.73 VVFV IN20 785 Position . . . 217
29.74 VVMG LI21 195 Position . . . 218
29.75 VVMG LTU1 505 Position . . . 218
29.76 VVPG IN20 435 Position . . . 218
29.77 VVPG IN20 545 Position . . . 218
29.78 VVPG IN20 635 Position . . . 219
29.79 VVPG IN20 915 Position . . . 219
29.80 VVPG LI21-9 Position (Station 22-1) . . . 219
29.81 VVPG LI22-9 Position (Station 23-1) . . . 219
29.82 VVPG LI23-9 Position (Station 24-1) . . . 220
29.83 VVPG LI24 710 Position . . . 220
29.84 VVPG LI24 896 Position . . . 220
29.85 VVPG LI25-9 Position (Station 26-1) . . . 220
29.86 VVPG LI26-9 Position (Station 27-1) . . . 221
29.87 VVPG LI27-9 Position (Station 28-1) . . . 221
29.88 VVPG LI28-9 Position (Station 29-1) . . . 221
29.89 VVPG LI29-9 Position (Station 30-1) . . . 221
29.90 VVPG LI30-9 Position (Station 30-9) . . . 222

29.91 VVS Circuit Breaker: LI22 . . . 222
29.92 VVS Circuit Breaker: LI24 . . . 222
29.93 VVS Circuit Breaker: LI26 . . . 222
29.94 VVS Circuit Breaker: LI28 . . . 223
29.95 VVS Circuit Breaker: LI30 . . . 223
29.96 YAG03 IN20 351 Position . . . 223
29.97 YAGS1 IN20 921 Position . . . 223
29.98 YAGS2 LI21 995 Position . . . 224

30 Always Evaluated 225
30.1 Backward Beam Stopper (RST1) . . . 225
30.2 BLM/PIC Watchdog: IN20 . . . 225
30.3 Bypass Recover . . . 225
30.4 DPS Temperature LI30 . . . 225
30.5 Gun RF Peak Power 20-6 . . . 226
30.6 Gun Waveguide Vacuum Summary . . . 226
30.7 IOC-IN20-MP01 MPS Support IOC Heartbeat . . . 226
30.8 Laser Heater Attenuator Position . . . 226
30.9 MCC Emergency Radiation Stopper . . . 227
30.10 Mechanical Shutter Position . . . 227
30.11 Mirror AM01 Position . . . 227
30.12 MPS Beam Permit: BYKIK . . . 227
30.13 MPS Beam Permit: Gun RF . . . 228
30.14 MPS Beam Permit: Heater Shutter . . . 228
30.15 MPS Beam Permit: Mechanical Shutter . . . 228
30.16 MPS Mechanical Shutter Position . . . 228
30.17 PIC HVPS LI20 - Location LKG-1535 . . . 229
30.18 PIC Raw Charge Thresholds: BSY0 16 . . . 229
30.19 PIC Raw Charge Thresholds: BSY0 33 . . . 229
30.20 PIC Raw Charge Thresholds: BSY0 45 . . . 230
30.21 PIC Raw Charge Thresholds: BSY0 59 . . . 230
30.22 PIC Raw Charge Thresholds: BSY0 78A . . . 230
30.23 PIC Raw Charge Thresholds: BSY0 78B . . . 231
30.24 PIC Raw Charge Thresholds: IN20 185 . . . 231
30.25 PIC Raw Charge Thresholds: IN20 232 . . . 231
30.26 PIC Raw Charge Thresholds: IN20 245 . . . 232
30.27 PIC Raw Charge Thresholds: IN20 665 . . . 232
30.28 PIC Raw Charge Thresholds: IN20 775 . . . 232
30.29 PIC Raw Charge Thresholds: IN20 933 . . . 233
30.30 PIC Raw Charge Thresholds: LI28 916 . . . 233
30.31 PIC Raw Charge Thresholds: LI29 146 . . . 233
30.32 PIC Raw Charge Thresholds: LI29 446 . . . 234
30.33 PIC Raw Charge Thresholds: LI29 546 . . . 234
30.34 PIC Raw Charge Thresholds: LI29 801 . . . 234
30.35 PIC Raw Charge Thresholds: LI29 956 . . . 235

30.36 PIC Raw Charge Thresholds: LI30 146 . . . 235
30.37 PIC Raw Charge Thresholds: LI30 446 . . . 235
30.38 PIC Raw Charge Thresholds: LI30 546 . . . 236
30.39 PIC Raw Charge Thresholds: LI30 801 . . . 236
30.40 PIC Trigger Missed (LN11) . . . 236
30.41 PIC Trigger Missed (LN22) . . . 236
30.42 PIC Trigger Missed (LN25) . . . 237
30.43 Pockels Cell AND Gate 100 . . . 237
30.44 Pockels Cell AND Gate 200 . . . 237
30.45 Rate Request: BYKIK 1 Hz . . . 237
30.46 Rate Request: BYKIK 10 Hz . . . 238
30.47 Rate Request: BYKIK 30 Hz . . . 238
30.48 Rate Request: BYKIK 60 Hz . . . 238
30.49 Rate Request: BYKIK Burst . . . 238
30.50 Rate Request: BYKIK Single Shot . . . 239
30.51 Rate Request: Pockels Cell 1 Hz . . . 239
30.52 Rate Request: Pockels Cell 10 Hz . . . 239
30.53 Rate Request: Pockels Cell 30 Hz . . . 239
30.54 Rate Request: Pockels Cell 60 Hz . . . 240
30.55 Rate Request: Pockels Cell Burst . . . 240
30.56 Rate Request: Pockels Cell Single Shot . . . 240
30.57 VVMG IN20 175 Position . . . 240
30.58 VVPG IN20 155 Position . . . 241
30.59 VVS Circuit Breaker: LI20 . . . 241
30.60 YAG01 IN20 211 Position . . . 241
30.61 YAGG1 IN20 841 Position . . . 241

31 Ignore Logic **243**
31.1 BX01/BX02 Is Off . . . 243
31.2 BX01/BX02 Is On . . . 243
31.3 BXG Is Off . . . 243
31.4 BXG Is On . . . 243
31.5 Diag Stopper HFX DG2 Is In . . . 244
31.6 Diag Stopper HFX UM6 Is In . . . 244
31.7 Diag Stopper XCS SB1 Is In . . . 244
31.8 Laser Heater Attenuator Is In . . . 244
31.9 LTU Dechirper Is Out . . . 244
31.10 M3H Mirror Is In Beam . . . 245
31.11 M3H Mirror Is Out of Beam . . . 245
31.12 Spoiler SP0 Is In . . . 245
31.13 ST1/ST2 Are In . . . 245
31.14 Stopper S1 Is In . . . 246
31.15 Stopper S2 Is In . . . 246
31.16 Stopper S2B Is In . . . 246
31.17 Stopper S5B Is In . . . 246

31.18 Stopper SH1 Is In . . . 246
31.19 Stopper SH2 Is In . . . 247
31.20 Stopper XRT S5 Is In . . . 247
31.21 Stopper XRT S6 Is In . . . 247
31.22 Stopper: BSY D2 Summary Is In . . . 247
31.23 TD11 Is In . . . 248
31.24 TDUND Is In . . . 248
31.25 XCS Is Not In Main Line . . . 248
31.26 XPP-NH3-POS-00 Beamline Is In . . . 248
31.27 XPP-NH3-POS-00 Beamline Is Not In . . . 248
31.28 YAG01 Is In . . . 249
31.29 YAG02 Is In . . . 249

1 Ignored when BX01/BX02 Is Off, YAG01 Is In, or YAG02 Is In

1.1 Toroid Comparator IM02/IM03

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Downstream > Upstream	F	T	0 Hz	0 Hz	0 Hz	–
Upstream > Downstream	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `TC203L1_STATE`,
B = `TC203L2_STATE`

2 Ignored when BX01/BX02 Is On, YAG01 Is In, or YAG02 Is In

2.1 BXS Status

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BEND_IN20_931_OK_STATE`

2.2 Toroid Comparator IM02/IMS1

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Downstream > Upstream	F	T	0 Hz	0 Hz	0 Hz	–
Upstream > Downstream	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `TC2S1L1_STATE`,
B = `TC2S1L2_STATE`

3 Ignored when BXG Is Off or YAG01 Is In

3.1 Wakefield Shield Gun Spectrometer

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	10 Hz	10 Hz	10 Hz	–

Where
A = `WL_BL231_IN_STATE`

4 Ignored when BXG Is On or YAG01 Is In

4.1 Wakefield Shield Straight Ahead

Name	A	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `WL_BL231_OUT_STATE`

5 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Diag Stopper XCS SB1 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XCS Is Not In Main Line, YAG01 Is In, or YAG02 Is In

5.1 XCS SB1 VGC 02 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `XCS_SB1_VGC_02_OPN_DI_POSITION`,
B = `XCS_SB1_VGC_02_CLS_DI_POSITION`

5.2 XCS SB2 VGC 01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `XCS_SB2_VGC_01_OPN_DI_POSITION`,
B = `XCS_SB2_VGC_01_CLS_DI_POSITION`

6 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper S5B Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

6.1 CXI Configuration 1 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigOne = -1;
{
        if ( CXI_MPS_CFG_1_CONFID ) /* EPS PLC asserts we are in config
            1 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                   state for Cfg 1 */
                if ((! CXI_DG1_MMS_03_A_POSITION) ||
                (! CXI_DG2_MMS_06_B_POSITION) ||
                (! CXI_SC1_VGC_02_OPN_DI_POSITION) )
                {
                        evalCXIConfigOne = 0;
                }
                else
                {
                        evalCXIConfigOne = 1;
                }
        }
}
```

```
switch( evalCXIConfigOne )
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
}
}
```

Name	State	PC	MS	BYKIK	LHS
Config 1 Fault	0	0 Hz	0 Hz	0 Hz	–
Config 1 Ok	1	120 Hz	120 Hz	120 Hz	–
Not In Config 1	2	120 Hz	120 Hz	120 Hz	–

6.2 CXI Configuration 2 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigTwo = -1;
{
        if ( CXI_MPS_CFG_2_CONFID ) /* EPS PLC asserts we are in config
            2 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                    state for Cfg 2 */
                if (    (! CXI_DG1_MMS_03_A_POSITION) ||
                        (! CXI_SC1_VGC_02_OPN_DI_POSITION) || /* If the
                            valve is not open, trip */
                        (       (! CXI_DIA_ATTEN_OK_POSITION) && /* DIA
                            attenuation */
                                (! (    CXI_DG1_MMS_08_B_POSITION &&
                                                CXI_DG1_MMS_08_B_POSITION
                                                    &&
```

```
                                                        CXI_DG2_MMS_08_B_POSITION
                                                              &&
                                                        CXI_DG2_MMS_09_B_POSITION
                                                              &&
                                                        CXI_DG2_MMS_10_B_POSITION
                                                              &&
                                                        CXI_DG4_MMS_05_B_POSITION
                                                              &&
                                                        CXI_DG4_MMS_03_B_POSITION

                                                    )
                                                )
                                        )
                                        )
                        {
                                evalCXIConfigTwo = 0;
                        }
                        else
                        {
                                evalCXIConfigTwo = 1;
                        }
        }
}

switch( evalCXIConfigTwo )
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
}
}
```

Name	State	PC	MS	BYKIK	LHS
Faulted	0	0 Hz	0 Hz	0 Hz	–
Ok	1	120 Hz	120 Hz	120 Hz	–
Not In Config 2	2	120 Hz	120 Hz	120 Hz	–

6.3 CXI Configuration 3 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
```

```
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigThree = -1;
{
        if ( CXI_MPS_CFG_3_CONFID ) /* EPS PLC asserts we are in config
            3 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                   state for Cfg 3 */
                if ((! CXI_DG1_MMS_03_A_POSITION) ||
                (! CXI_SC1_VGC_02_OPN_DI_POSITION) )
                {
                        evalCXIConfigThree = 0;
                }
                else
                {
                        evalCXIConfigThree = 1;
                }
        }
}

switch( evalCXIConfigThree )
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
}
}
```

Name	State	PC	MS	BYKIK	LHS
Faulted	0	0 Hz	0 Hz	0 Hz	–
Ok	1	120 Hz	120 Hz	120 Hz	–
Not in Config 3	2	120 Hz	120 Hz	120 Hz	–

6.4 CXI Configuration 4 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigFour = -1;
{
        if ( CXI_MPS_CFG_4_CONFID ) /* EPS PLC asserts we are in config
            4 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                   state for Cfg 4 */
                if ((! CXI_DG1_MMS_03_A_POSITION) ||
                (! CXI_SC1_VGC_02_OPN_DI_POSITION) )
                {
                        evalCXIConfigFour = 0;
                }
                else
                {
                        evalCXIConfigFour = 1;
                }
        }
}

switch( evalCXIConfigFour )
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
}
}
```

Name	State	PC	MS	BYKIK	LHS
Faulted	0	0 Hz	0 Hz	0 Hz	–
Ok	1	120 Hz	120 Hz	120 Hz	–
Not In Config 4	2	120 Hz	120 Hz	120 Hz	–

6.5 CXI Configuration 5 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigFive = -1;
{
        if ( CXI_MPS_CFG_5_CONFID ) /* EPS PLC asserts we are in config
            5 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                   state for Cfg 5 */
                if ((! CXI_DG1_MMS_03_A_POSITION) ||
                (! CXI_SC1_VGC_02_OPN_DI_POSITION) )
                {
                        evalCXIConfigFive = 0;
                }
                else
                {
                        evalCXIConfigFive = 1;
                }
        }
}

switch( evalCXIConfigFive )
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
```

```
}
}
```

Name	State	PC	MS	BYKIK	LHS
Faulted	0	0 Hz	0 Hz	0 Hz	–
Ok	1	120 Hz	120 Hz	120 Hz	–
Not In Config 5	2	120 Hz	120 Hz	120 Hz	–

6.6 CXI Configuration 6 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigSix = -1;
{
        if ( CXI_MPS_CFG_6_CONFID ) /* EPS PLC asserts we are in config
            6 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                   state for Cfg 6 */
                if ((! CXI_DG1_MMS_03_A_POSITION) ||
                        (! CXI_DG2_MMS_06_B_POSITION) ||
                (! CXI_SC2_VGC_02_OPN_DI_POSITION) )
                {
                        evalCXIConfigSix = 0;
                }
                else
                {
                        evalCXIConfigSix = 1;
                }
        }
}

switch( evalCXIConfigSix )
```

```
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
}
}
```

Name	State	PC	MS	BYKIK	LHS
Faulted	0	0 Hz	0 Hz	0 Hz	–
Ok	1	120 Hz	120 Hz	120 Hz	–
Not In Config 6	2	120 Hz	120 Hz	120 Hz	–

6.7 CXI Configuration 7 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigSeven = -1;
{
        if ( CXI_MPS_CFG_7_CONFID ) /* EPS PLC asserts we are in config
            7 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                   state for Cfg 7 */
                if ((! CXI_DG1_MMS_03_A_POSITION)       ||
                        (! CXI_SC1_VGC_02_OPN_DI_POSITION) ||
                (! CXI_SC2_VGC_02_OPN_DI_POSITION) )
                {
                        evalCXIConfigSeven = 0;
                }
                else
                {
                        evalCXIConfigSeven = 1;
                }
```

```
        }
}

switch( evalCXIConfigSeven )
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
}
}
```

Name	State	PC	MS	BYKIK	LHS
Faulted	0	0 Hz	0 Hz	0 Hz	–
Ok	1	120 Hz	120 Hz	120 Hz	–
Not In Config 7	2	120 Hz	120 Hz	120 Hz	–

6.8 CXI KB2 VGC 02 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CXI_KB2_VGC_02_OPN_DI_POSITION`,
B = `CXI_KB2_VGC_02_CLS_DI_POSITION`

6.9 CXI MPS PLC Readiness Status

Name	*A*	PC	MS	BYKIK	LHS
PLC Not OK	F	0 Hz	0 Hz	0 Hz	–
PLC OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_MPS_PLC_01_OK_STATUS`

6.10 CXI User Patch Panel 1 Ready

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_USR_01_MPSFAULT_STATUS`

6.11 CXI User Patch Panel 2 Ready

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_USR_02_MPSFAULT_STATUS`

6.12 CXI:DG1:VGC:01 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_DG1_VGC_01_OPN_DI_POSITION`

6.13 CXI:DG1:VGC:02 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_DG1_VGC_02_OPN_DI_POSITION`

6.14 CXI:DG2:VGC:01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CXI_DG2_VGC_01_OPN_DI_POSITION`,
B = `CXI_DG2_VGC_01_CLS_DI_POSITION`

6.15 CXI:DG2:VGC:02 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CXI_DG2_VGC_02_OPN_DI_POSITION`,
B = `CXI_DG2_VCG_02_CLS_DI_POSITION`

6.16 CXI:DG4:VGC:01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CXI_DG4_VGC_01_OPN_DI_POSITION`,
B = `CXI_DG4_VGC_01_CLS_DI_POSITION`

6.17 CXI:DSC:VGC:01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CXI_DSC_VGC_01_OPN_DI_POSITION`,
B = `CXI_DSC_VGC_01_CLS_DI_POSITION`

6.18 CXI:KB1:VGC:01 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_KB1_VGC_01_OPN_DI_POSITION`

6.19 CXI:KB1:VGC:02 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_KB1_VGC_02_OPN_DI_POSITION`

6.20 CXI:KB2:VGC:01 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = CXI_KB2_VGC_01_OPN_DI_POSITION

6.21 CXI:SC1:VGC:01 Gate Valve Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CXI_SC1_VGC_01_OPN_DI_POSITION,
B = CXI_SC1_VGC_01_CLS_DI_POSITION

6.22 CXI:SC3:VGC:01 Be Gate Valve Position - Status from PLC

Name	A	PC	MS	BYKIK	LHS
Moving or Broken	F	0 Hz	0 Hz	0 Hz	–
Open or Closed	T	120 Hz	120 Hz	120 Hz	–

Where
A = CXI_SC3_VGC_01_OPN_DI_POSITION

6.23 HF4 LAM VGC 01 Gate Valve Position

Name	A	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = HF4_LAM_VGC_01_OPN_DI_POSITION

7 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XCS Is Not In Main Line, YAG01 Is In, or YAG02 Is In

7.1 XCS SB1 Diagnostic Stopper Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `XCS_SB1_STP_01_OPN_DI_POSITION`,
B = `XCS_SB1_STP_01_CLS_DI_POSITION`

7.2 XCS SB1 VGC 01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `XCS_SB1_VGC_01_OPN_DI_POSITION`,
B = `XCS_SB1_VGC_01_CLS_DI_POSITION`

8 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

8.1 CXI XRT Laser Reference Mirror Position

Name	*A*	PC	MS	BYKIK	LHS
Mirror In Beam	F	0 Hz	0 Hz	0 Hz	–
Mirror Out of Beam	T	120 Hz	120 Hz	120 Hz	–

Where
A = `XRT_DIA_MMS_01_B_POSITION`

8.2 HFA:SND:VGC:01 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HFA_SND_VGC_01_OPN_DI_POSITION`

8.3 HFX:DIA:VGC:02 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HFX_DIA_VGC_02_OPN_DI_POSITION`

8.4 PPS Stopper S5B Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
In	F	T	–	–	–	–
Out	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `STPR_FEH1_5_S5BIN_POSITION`,
B = `STPR_FEH1_5_S5BOUT_POSITION`

8.5 XRT HXRAY DIA Isolation Valve HXX-DIA-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HXX_DIA_VGC_01_CLS_DI_STATE`,
B = `HXX_DIA_VGC_01_OPN_DI_STATE`

9 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

9.1 HFX:DG2:VGC:01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HFX_DG2_VGC_01_OPN_DI_POSITION`

9.2 HFX:MON:VGC:01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HFX_MON_VGC_01_OPN_DI_POSITION`

9.3 HFX:MON:VGC:02 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HFX_MON_VGC_02_OPN_DI_POSITION`

9.4 Stopper XRT S5 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `STPR_XRT1_1_S5OUT_POSITION`,
B = `STPR_XRT1_1_S5IN_POSITION`

10 Ignored when Diag Stopper HFX UM6 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S6 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

10.1 MEC DV4 VCG 01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_DV4_VGC_01_OPN_DI_POSITION`

10.2 MEC DV5 VGC 01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_DV5_VGC_01_OPN_DI_POSITION`

10.3 MEC HXM VGC 01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_HXM_VGC_01_OPN_DI_POSITION`

10.4 MEC XT1 Reference Laser Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_XT1_MMS_01_B_POSITION`

10.5 MEC XT1 VGC 01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_XT1_VGC_01_OPN_DI_POSITION`

10.6 MEC XT2 VGC 02 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_XT2_VGC_02_OPN_DI_POSITION`

10.7 MEC XT2 VGC 03 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_XT2_VGC_03_OPN_DI_POSITION`

10.8 MEC XT2 VGC 04 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_XT2_VGC_04_OPN_DI_POSITION`

10.9 MEC XT2 VGC 05 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `MEC_XT2_VGC_05_OPN_DI_POSITION`,
B = `MEC_XT2_VGC_05_CLS_DI_POSITION`

10.10 MEC XT2 VGC 06 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_XT2_VGC_06_OPN_DI_POSITION`

11 Ignored when Diag Stopper HFX UM6 Is In, Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

11.1 DG2 Diagnostic Stopper Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
In	F	T	–	–	–	–
Out	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HFX_DG2_STP_01_IN_DI_POSITION`,
B = `HFX_DG2_STP_01_OUT_DI_POSITION`

11.2 MEC BXL VGC 01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_BXL_VGC_01_OPN_DI_POSITION`

11.3 MEC M3H Mirror and DG2 STP Fault

Name	*B*	*A*	PC	MS	BYKIK	LHS
In Transit: DG2 STP Not In Beam, M3H Mirror Not Out	F	F	0 Hz	0 Hz	0 Hz	–
In Transit: DG2 STP Not In Beam, M3H Mirror Out	F	T	120 Hz	120 Hz	120 Hz	–
Safe: DG2 STP In Beam, M3H Mirror Not Out	T	F	120 Hz	120 Hz	120 Hz	–
Safe: DG2 STP In Beam, M3H Mirror Out	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HXX_HXM_MMS_01_B_POSITION,
B = HFX_DG2_STP_01_IN_DI_POSITION

11.4 MEC M3H Mirror Unknown Position Fault

Name	*B*	*A*	PC	MS	BYKIK	LHS
In Transit: M3H Mirror Neither In Nor Out	F	F	120 Hz	120 Hz	120 Hz	–
Out: M3H Mirror Out of Beam	F	T	120 Hz	120 Hz	120 Hz	–
In: M3H Mirror In Beam	T	F	120 Hz	120 Hz	120 Hz	–
Broken: M3H Mirror Both In And Out	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = HXX_HXM_MMS_01_B_POSITION,
B = HXX_HXM_MMS_01_INBEAM_POSITION

11.5 MEC XRT Attenuator Inspection Mirror Position

Name	*A*	PC	MS	BYKIK	LHS
Mirror Not Out	F	0 Hz	0 Hz	0 Hz	–
Mirror Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = MEC_HXM_MMS_04_B_POSITION

11.6 MFX Gate Valves Not All Open - PLC Summary Status

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = MFX_MPS_PLC_VAC_OK_STATUS

11.7 Stopper XRT S6 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
In	F	T	120 Hz	120 Hz	120 Hz	–
Out	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = STPR_XRT1_1_S6IN_POSITION,
B = STPR_XRT1_1_S6OUT_POSITION

11.8 XRT HXRAY LOM Isolation Valve HXX-LOM-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = HXX_LOM_VGC_01_CLS_DI_STATE,
B = HXX_LOM_VGC_01_OPN_DI_STATE

11.9 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:01

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = HXX_MXT_VGC_01_OPN_DI_POSITION

11.10 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:02

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HXX_MXT_VGC_02_OPN_DI_POSITION`

11.11 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:03

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HXX_MXT_VGC_03_CLS_DI_POSITION`,
B = `HXX_MXT_VGC_03_OPN_DI_POSITION`

11.12 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:05

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HXX_MXT_VGC_05_OPN_DI_POSITION`

12 Ignored when Laser Heater Attenuator Is In

12.1 Laser Heater Photodiode Shutter Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	–	–	–	0 Hz
Out	F	T	–	–	–	0 Hz
In	T	F	–	–	–	120 Hz
Broken	T	T	–	–	–	0 Hz

Where
A = LHPHD_OUT_LIMIT_STATE,
B = LHPHD_IN_LIMIT_STATE

12.2 OTRH1 Position When LH Atten Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	–	–	–	0 Hz
Out	F	T	–	–	–	120 Hz
In	T	F	–	–	–	0 Hz
Broken	T	T	–	–	–	0 Hz

Where
A = OTRH1_OUT_LIMIT_STATE,
B = OTRH1_IN_LIMIT_STATE

12.3 OTRH2 Position When LH Atten Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	–	–	–	0 Hz
Out	F	T	–	–	–	120 Hz
In	T	F	–	–	–	0 Hz
Broken	T	T	–	–	–	0 Hz

Where
A = OTRH2_OUT_LIMIT_STATE,
B = OTRH2_IN_LIMIT_STATE

13 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper S1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

13.1 NEH AMO Laser Reference Mirror Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = SAS_MMM_01_B_POSITION

13.2 NEH AMO Valves Ok for Beam - Summary From PLC

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = AMO_MPS_VAC_OK_SUM_STATE

13.3 NEH1 Camera 1124 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CAMR_NEH1_1124_OUT_STATE,
B = CAMR_NEH1_1124_IN_STATE

13.4 NEH1 XTOD S1 Isolation Valve Summary

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_NEH_703_ISOL_S1_STATE`

14 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper S2 Is In, Stopper S2B Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

14.1 NEH SXR Differential Pump Isolation Valve SXR-DFP-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_DFP_VGC_01_CLS_DI_STATE,
B = SXR_DFP_VGC_01_OPN_DI_STATE

14.2 NEH SXR End Station Ready SXR-EXP-MPS-01

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = SXR_EXP_MPS_01_STATE

14.3 NEH SXR Intensity Monitor Isolation Valve SXR-FLX-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_FLX_VGC_01_CLS_DI_STATE,
B = SXR_FLX_VGC_01_OPN_DI_STATE

14.4 NEH SXR KB Optics Isolation Valve SXR-KBO-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_KBO_VGC_01_CLS_DI_STATE,
B = SXR_KBO_VGC_01_OPN_DI_STATE

14.5 NEH SXR Laser In-coupling Mirror Isolation Valve SXR-LIN-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_LIN_VGC_01_CLS_DI_STATE,
B = SXR_LIN_VGC_01_OPN_DI_STATE

15 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper S2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

15.1 NEH Camera 2124 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CAMR_NEH1_2124_OUT_STATE`,
B = `CAMR_NEH1_2124_IN_STATE`

15.2 NEH SXR Collimator 3 Isolation Valve SXR-COL-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `SXR_COL_VGC_01_CLS_DI_STATE`,
B = `SXR_COL_VGC_01_OPN_DI_STATE`

15.3 NEH SXR Exit Slits Isolation Valve SXR-EXS-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_EXS_VGC_01_CLS_DI_STATE,
B = SXR_EXS_VGC_01_OPN_DI_STATE

15.4 NEH SXR GMD VGC 01 Protection

Name	*B*	*A*	PC	MS	BYKIK	LHS
In Transit: SXR GMD VGC 01 In Motion	F	F	0 Hz	0 Hz	0 Hz	–
Safe: SXR GMD VGC 01 Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed: SXR GMD VGC 01 Closed	T	F	0 Hz	0 Hz	0 Hz	–
Error: SXR GMD VGC 01 Open and Closed	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_GMD_VGC_01_OPN_DI_POSITION,
B = SXR_GMD_VGC_01_CLS_DI_POSITION

15.5 NEH SXR Monochromator Tank Isolation Valve SXR-MON-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_MON_VGC_01_CLS_DI_STATE,
B = SXR_MON_VGC_01_OPN_DI_STATE

15.6 NEH SXR Photon Stoppers Isolation Valve SXR-PST-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_PST_VGC_01_CLS_DI_STATE,
B = SXR_PST_VGC_01_OPN_DI_STATE

15.7 NEH SXR Transmission Sample System Isolation Valve SXR-TSS-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_TSS_VGC_01_CLS_DI_STATE,
B = SXR_TSS_VGC_01_OPN_DI_STATE

15.8 NEH SXR Zero Order Interlock SXR-MON-MMS-06, SXR-EXS-MMS-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Slits Not Open, No Zero Order	F	F	120 Hz	120 Hz	120 Hz	–
Slits Not Open, Zero Order Fault	F	T	0 Hz	0 Hz	0 Hz	–
Slits Open, No Zero Order	T	F	120 Hz	120 Hz	120 Hz	–
Slits Open, Zero Order	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = SXR_MON_MMS_06_B_STATE,
B = SXR_EXS_MMS_01_B_STATE

15.9 NEH1 XTOD S2 Isolation Valve Summary

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_NEH_703_ISOL_S2_STATE`

16 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

16.1 UM6 Diagnostic Stopper Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
In	F	T	–	–	–	–
Out	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HFX_UM6_STP_01_IN_DI_POSITION`,
B = `HFX_UM6_STP_01_OUT_DI_POSITION`

16.2 XRT HXRAY UM6 Isolation Valve HXX-UM6-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HXX_UM6_VGC_01_CLS_DI_STATE`,
B = `HXX_UM6_VGC_01_OPN_DI_STATE`

16.3 XRT UM6 Camera Position HXX-UM6-CVP-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = HXX_UM6_CVP_01_B_STATE,
B = HXX_UM6_CVP_01_A_STATE

17 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XPP-NH3-POS-00 Beamline Is In, YAG01 Is In, or YAG02 Is In

17.1 NEH3 HXRAY DVD Isolation Valve HX3-DVD-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = HX3_DVD_VGC_01_CLS_DI_STATE,
B = HX3_DVD_VGC_01_OPN_DI_STATE

18 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XPP-NH3-POS-00 Beamline Is Not In, YAG01 Is In, or YAG02 Is In

18.1 XPP SB2 VGC 01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `XPP_SB2_VGC_01_OPN_DI_POSITION`,
B = `XPP_SB2_VGC_01_CLS_DI_POSITION`

18.2 XPP SB2 VGC 02 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `XPP_SB2_VGC_02_OPN_DI_POSITION`

18.3 XPP SB2 VGC 03 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `XPP_SB2_VGC_03_OPN_DI_POSITION`

19 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper SH1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

19.1 HX2 UVD VGC 01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = HX2_SB1_VGC_01_OPN_DI_STATE,
B = HX2_SB1_VGC_01_CLS_DI_STATE

19.2 HX3 MON VGC 01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = HX3_MON_VGC_01_OPN_DI_POSITION,
B = HX3_MON_VGC_01_CLS_DI_POSITION

19.3 NEH1 Camera 124 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CAMR_NEH1_124_OUT_STATE,
B = CAMR_NEH1_124_IN_STATE

19.4 NEH1 Camera 195 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CAMR_NEH1_195_OUT_STATE,
B = CAMR_NEH1_195_IN_STATE

19.5 NEH1 XTOD H Isolation Valve Summary

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = VMPS_NEH_703_ISOL_H_STATE

19.6 NEH2 HXRAY DVD Isolation Valve HX2-DVD-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Fault	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = HX2_DVD_VGC_01_CLS_DI_STATE,
B = HX2_DVD_VGC_01_OPN_DI_STATE

19.7 NEH3 HXRAY UVD Isolation Valve HX3-UVD-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HX3_UVD_VGC_01_CLS_DI_STATE`,
B = `HX3_UVD_VGC_01_OPN_DI_STATE`

20 Ignored when Spoiler SP0 Is In, ST1/ST2 Are In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

20.1 FEE Camera 1561 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CAMR_FEE1_1561_OUT_STATE`,
B = `CAMR_FEE1_1561_IN_STATE`

20.2 FEE Camera 1692 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CAMR_FEE1_1692_OUT_STATE`,
B = `CAMR_FEE1_1692_IN_STATE`

20.3 FEE Camera 1953 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CAMR_FEE1_1953_OUT_STATE,
B = CAMR_FEE1_1953_IN_STATE

20.4 FEE Camera 2953 Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CAMR_FEE1_2953_OUT_STATE,
B = CAMR_FEE1_2953_IN_STATE

20.5 FEE Camera 852 Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CAMR_FEE1_852_OUT_STATE,
B = CAMR_FEE1_852_IN_STATE

20.6 FEE Camera 913 Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CAMR_FEE1_913_OUT_STATE,
B = CAMR_FEE1_913_IN_STATE

20.7 FEE Fast Shutter Valve and System Summary

Name	*A*	PC	MS	BYKIK	LHS
Not All Out And Ready	F	0 Hz	0 Hz	0 Hz	–
All Out And Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_FEE1_E101_FSHR_FAULT`

20.8 FEE Gas Flow Aperture Summary

Name	*A*	PC	MS	BYKIK	LHS
Not All Out Or In	F	0 Hz	0 Hz	0 Hz	–
All Out Or In	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_FEE1_E202_APRT_FAULT`

20.9 FEE Gas Flow Vacuum Isolation Valve Summary

Name	*A*	PC	MS	BYKIK	LHS
Not All Out	F	0 Hz	0 Hz	0 Hz	–
All Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_FEE1_E202_ISOV_FAULT`

20.10 FEE Instrument Vacuum Isolation Valve Summary

Name	*A*	PC	MS	BYKIK	LHS
Not All Out	F	0 Hz	0 Hz	0 Hz	–
All Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_FEE1_E101_ISOL_FAULT`

20.11 FEE Solid Attenuators - Gas Pressure Interlock

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/* Prevent beam if gas attenuator
* pressure is above a specified threshold,
* the gas valve is NOT CLOSED,
* AND interlocked solid attenuators are NOT OUT.
* Note that solid attenuators 3 and 4 are allowed to be in;
* they are not part of this logic.
*
* Gas pressure and valve status summary OK/Fault input comes from FEE
    PLC
* Dehong Zhang and Alex Wallace are contacts for this input
*/

state = (unsigned int) -1; /* Initialize to a guard value */

if (VMPS_FEE1_E202_NOGAS_THRESHOLD)
{
     state = 0; /* Gas attenuator interlock is OK (pressure is low
        enough and valve is closed), okay to run beam */
}

else if (SATT_FEE1_329_OUT_POSITION && SATT_FEE1_328_OUT_POSITION
        && SATT_FEE1_327_OUT_POSITION && SATT_FEE1_326_OUT_POSITION
        && SATT_FEE1_325_OUT_POSITION && SATT_FEE1_322_OUT_POSITION
        && SATT_FEE1_321_OUT_POSITION)
{
     state = 1; /* Interlocked solid attenuators are OUT, okay to run
        beam */
}

else
{
     state = 2; /* Interlocked solid attenuators are NOT ALL OUT, NOT
        okay to run beam */
}
```

Name	State	PC	MS	BYKIK	LHS
Gas Pressure Ok	0	120 Hz	120 Hz	120 Hz	–
Solid Att Out	1	120 Hz	120 Hz	120 Hz	–
Solid Att Not Out While Gas Pressure High	2	0 Hz	0 Hz	0 Hz	–

20.12 FEE Spectrometer Crystal - Beam Energy Too Low When Crystal Not Out

Name	*B*	*A*	PC	MS	BYKIK	LHS
Fault	F	F	0 Hz	0 Hz	0 Hz	–
Energy Ok	F	T	120 Hz	120 Hz	120 Hz	–
Crystal Out	T	F	120 Hz	120 Hz	120 Hz	–
Crystal Out	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `XTAL_FEE1_441_ENERGY_STATE`,
B = `XTAL_FEE1_441_OUT_LIMSW_POSITION`

20.13 FEE XTOD H Isolation Valve Summary

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_FEE1_703_ISOL_H_FAULT`

20.14 FEE XTOD S1 Isolation Valve Summary

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_FEE1_703_ISOL_S1_FAULT`

20.15 FEE XTOD S2 Isolation Valve Summary

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_FEE1_703_ISOL_S2_FAULT`

20.16 FEE1 M1S Mirror Beam Energy Upper Limit

Name	*B*	*A*	PC	MS	BYKIK	LHS
Fault	F	F	0 Hz	0 Hz	0 Hz	–
OK	F	T	120 Hz	120 Hz	120 Hz	–
OK	T	F	120 Hz	120 Hz	120 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MIRR_FEE1_1560_OUT_LIMIT1_POSITION`,
B = `MIRR_FEE1_1560_ENERGY_STATE`

20.17 FEE1 M1S Mirror State

Name	*B*	*A*	PC	MS	BYKIK	LHS
Not Out	F	F	120 Hz	120 Hz	120 Hz	–
Inconsistent	F	T	0 Hz	0 Hz	0 Hz	–
Inconsistent	T	F	0 Hz	0 Hz	0 Hz	–
Out	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MIRR_FEE1_1560_OUT_LIMIT1_POSITION`,
B = `MIRR_FEE1_1560_OUT_LIMIT2_POSITION`

20.18 HXR - Beam Energy Too Low With M1S Out

Name	*B*	*A*	PC	MS	BYKIK	LHS
Ok	F	F	120 Hz	120 Hz	120 Hz	–
Ok	F	T	120 Hz	120 Hz	120 Hz	–
Ok	T	F	120 Hz	120 Hz	120 Hz	–
Fault	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `MIRR_FEE1_1560_ENERGY_STATE`,
B = `MIRR_FEE1_1560_OUT_LIMIT1_POSITION`

21 Ignored when Stopper: BSY D2 Summary Is In

21.1 Stopper: ST1/ST2 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `STPR_FEE1_1_ST1ST2OUT_POSITION`,
B = `STPR_FEE1_1_ST1ST2IN_POSITION`

22 Ignored when Stopper: BSY D2 Summary Is In or TDUND Is In

22.1 HXRSS Beamline Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BMLN_UND1_1650_OUT_LMTSW_STATE`,
B = `BMLN_UND1_1650_IN_LMTSW_STATE`

22.2 HXRSS Chicane Bend Magnet Power Supply

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
ON	F	T	120 Hz	120 Hz	120 Hz	–
OFF	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BEND_UND1_1640_ON_STATE`,
B = `BEND_UND1_1640_OFF_STATE`

22.3 HXRSS Crystal Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = XTAL_UND1_1650_OUT_LMTSW_STATE,
B = XTAL_UND1_1650_IN_ENCDR_STATE

22.4 HXRSS Crystal Valid Position

Name	A	PC	MS	BYKIK	LHS
Not Valid	F	0 Hz	0 Hz	0 Hz	–
Valid	T	120 Hz	120 Hz	120 Hz	–

Where
A = XTAL_UND1_1650_POSITIONSTAT_STATE

22.5 HXRSS Mode State

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
 * state = 0 : full rate (120 Hz) beam allowed, HXRSS Seeded Mode
 * state = 1 : full rate (120 Hz) beam allowed, HXRSS SASE Mode
 * state = 2 : full rate (120 Hz) beam allowed, HXRSS Phase Shifter
    Mode
 * state = 3 : no beam allowed, HXRSS undefined state
*/

/* Initialize to a guard value */
state = (unsigned int) -1;

/*
 * Allow beam if HXRSS is ON, Seeded Mode: the raft is in;
 *                            the magnet is on in and tolerance;
 *                            the photon energy is OK;
 *                            the crystal is IN
 * Allow beam if HXRSS is OFF, SASE Mode: the raft is out;
 *                             the magnet is off;
 *                             the crystal is out
 * Allow beam if HXRSS is in Phase Shifter Mode: the raft is in;
 *                             the magnet is in ANY state;
 *                             the crystal is out
 * Otherwise, do not allow beam.
```

```
 */


/* Input Descriptions
*
* BEND_DMP1_400_INTOL_BRANGE_STATE= HXRSS Beam Energy OK when 10 GeV <
    E < 15 GeV
* XTAL_UND1_1650_OUT_LMTSW_STATE    = Crystal OUT Limit Switch
* XTAL_UND1_1650_IN_ENCDR_STATE      = Crystal IN Limit Switch, from
    encoder
* BMLN_UND1_1650_IN_LMTSW_STATE      = HXRSS Raft IN Limit Switch
* BMLN_UND1_1650_OUT_LMTSW_STATE    = HXRSS Raft OUT Limit Switch
* BEND_UND1_1640_INTOL_BMIN_STATE    = HXRSS Chicane Bend INTOL, greater
    than +0.6 kG-m
* BEND_UND1_1640_OFF_STATE                = HXRSS Chicane Bend String is
    OFF
* BEND_UND1_1640_ON_STATE                 = HXRSS Chicane Bend String is
    ON
*
*/

if ( BMLN_UND1_1650_IN_LMTSW_STATE &&
            BEND_UND1_1640_INTOL_BMIN_STATE &&
            BEND_UND1_1640_ON_STATE &&
            BEND_DMP1_400_INTOL_BRANGE_STATE &&
            ( XTAL_UND1_1650_IN_ENCDR_STATE   ) )
{
    state = 0; /* HXRSS ON, HXRSS Seeded Mode, okay to run beam */
}

else if ( BMLN_UND1_1650_OUT_LMTSW_STATE &&
            BEND_UND1_1640_OFF_STATE &&
            XTAL_UND1_1650_OUT_LMTSW_STATE )
{
    state = 1; /* HXRSS OFF,SASE Mode, okay to run beam */
}

else if ( BMLN_UND1_1650_IN_LMTSW_STATE &&
            XTAL_UND1_1650_OUT_LMTSW_STATE )
{
    state = 2; /* HXRSS in Phase Shifter Mode, okay to run beam */
}

else
{
```

```
    state = 3; /* HXRSS Undefined State, no beam allowed */
}
```

Name	State	PC	MS	BYKIK	LHS
HXRSS Seeded Mode	0	120 Hz	120 Hz	120 Hz	–
HXRSS SASE Mode	1	120 Hz	120 Hz	120 Hz	–
HXRSS Phase Shifter Mode	2	120 Hz	120 Hz	120 Hz	–
HXRSS Undefined State	3	0 Hz	0 Hz	0 Hz	–

22.6 SXRSS Grating/M1 GRAT UND1 934 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `GRAT_UND1_934_OUT_LIMIT_POSITION`,
B = `GRAT_UND1_934_IN_LIMIT_POSITION`

22.7 SXRSS M2 MIRR UND1 964 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `MIRR_UND1_964_OUT_LIMIT_POSITION`,
B = `MIRR_UND1_964_IN_LIMIT_POSITION`

22.8 SXRSS M3 MIRR UND1 966 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `MIRR_UND1_966_OUT_LIMIT_POSITION`,
B = `MIRR_UND1_966_IN_LIMIT_POSITION`

22.9 SXRSS Mode State

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/* Production MPS SXRSS Modes
 *
 * state = 0 : full rate (120 Hz) beam allowed, SXRSS Seeded Mode
 * state = 1 : full rate (120 Hz) beam allowed, SXRSS SASE Mode
 * state = 2 : full rate (120 Hz) beam allowed, Harmonic Mode
 * state = 3 : no beam allowed, SXRSS undefined state
 *
 * Allow beam if SXRSS is ON, Seeded Mode:
 *                              { grating/M1 is IN and M3 is IN or OUT
    }
 *                             OR
 *                             { slit is IN and grating/M1/M2/M3 are
   OUT }
 *                             chicane is ON;
 *                             e- beam position OK  [mm]
 *                             e- beam energy   OK [GeV]
 *                             upstream undulators IN OK
 * Allow beam if SXRSS is OFF, SASE Mode:
 *                              grating/M1 is OUT;
 *                              slit is OUT;
 *                             M2 is OUT;
 *                             M3 is OUT;
 *                             e- beam position    OK  [mm]
 * Allow beam if SXRSS is in Harmonic Mode:
 *                              grating/M1 is OUT;
 *                              slit is NOT_IN and NOT_OUT;
 *                             M2 is OUT;
```

```
*                                M3 is OUT;
*                                chicane is ON;
*                                e- beam position  OK  [mm]
*                                e- beam energy     OK       [GeV]
* Otherwise, do not allow beam.
*
* Input Descriptions
*
*  Link Node MPS PV Name                Link Node MPS Fault Name
                Desciption
* ------------------------------
   --------------------------------
   ------------------------------------------------
*  BEND:UND1:940:ON_MPS                =  BEND_UND1_940_ON_STATE
               =  Chicane power supply on
*  GRAT:UND1:934:IN_LIMIT_MPS          =  GRAT_UND1_934_IN_LIMIT_POSITION
      =  Grating/M1 IN limit switch
*  GRAT:UND1:934:OUT_LIMIT_MPS         =
   GRAT_UND1_934_OUT_LIMIT_POSITION    =  Grating/M1 OUT limit switch
*  SLIT:UND1:962:IN_LIMIT_MPS          =  SLIT_UND1_962_IN_LIMIT_POSITION
      =  Slit IN limit switch
*  SLIT:UND1:962:OUT_LIMIT_MPS         =
   SLIT_UND1_962_OUT_LIMIT_POSITION    =  Slit OUT limit switch
*  MIRR:UND1:964:IN_LIMIT_MPS          =  MIRR_UND1_964_IN_LIMIT_POSITION
      =  M2 IN limit switch
*  MIRR:UND1:964:OUT_LIMIT_MPS         =
   MIRR_UND1_964_OUT_LIMIT_POSITION    =  M2 OUT limit switch
*  MIRR:UND1:966:IN_LIMIT_MPS          =  MIRR_UND1_966_IN_LIMIT_POSITION
      =  M3 IN limit switch
*  MIRR:UND1:966:OUT_LIMIT_MPS         =
   MIRR_UND1_966_OUT_LIMIT_POSITION    =  M3 OUT limit switch
*  MPS:UND1:950:SX_HRMNC_ENERGY_MPS =
   MPS_UND1_950_SX_HRMNC_ENERGY_STATE =  e- beam energy safe for
   Harmonic mode
*  MPS:UND1:950:SX_HRMNC_X_MPS         =  MPS_UND1_950_SX_HRMNC_X_STATE
      =  e- beam position safe for Harmonic mode
*  MPS:UND1:950:SX_SASE_X_MPS          =  MPS_UND1_950_SX_SASE_X_STATE
       =  e- beam position safe for SASE mode
*  MPS:UND1:950:SX_SS_ENERGY_MPS       =  MPS_UND1_950_SX_SS_ENERGY_STATE
      =  e- beam energy safe for Seeded mode
*  MPS:UND1:950:SX_SS_UND_MPS          =  MPS_UND1_950_SX_SS_UND_STATE
       =  Inserted upstream undulators safe for Seeded mode
*  MPS:UND1:950:SX_SS_X_MPS            =  MPS_UND1_950_SX_SS_X_STATE
         =  e- beam position safe for Seeded mode
*/
```

```
/* Initialize to a guard value */
state = (unsigned int) -1;

if (     ((GRAT_UND1_934_IN_LIMIT_POSITION &&
         (MIRR_UND1_966_IN_LIMIT_POSITION ||
             MIRR_UND1_966_OUT_LIMIT_POSITION)) ||
          (SLIT_UND1_962_IN_LIMIT_POSITION  &&
              GRAT_UND1_934_OUT_LIMIT_POSITION &&
            MIRR_UND1_964_OUT_LIMIT_POSITION &&
                MIRR_UND1_966_OUT_LIMIT_POSITION)) &&
         BEND_UND1_940_ON_STATE &&
         MPS_UND1_950_SX_SS_X_STATE &&
         MPS_UND1_950_SX_SS_ENERGY_STATE &&
         MPS_UND1_950_SX_SS_UND_STATE )
{
    state = 0; /* SXRSS Seeded Mode, okay to run beam */
}

else if ( GRAT_UND1_934_OUT_LIMIT_POSITION &&
         SLIT_UND1_962_OUT_LIMIT_POSITION &&
         MIRR_UND1_964_OUT_LIMIT_POSITION &&
         MIRR_UND1_966_OUT_LIMIT_POSITION &&
         MPS_UND1_950_SX_SASE_X_STATE )
{
    state = 1; /* SXRSS SASE Mode, okay to run beam */
}

else if ( GRAT_UND1_934_OUT_LIMIT_POSITION &&
         !SLIT_UND1_962_IN_LIMIT_POSITION && !
             SLIT_UND1_962_OUT_LIMIT_POSITION &&
         MIRR_UND1_964_OUT_LIMIT_POSITION &&
         MIRR_UND1_966_OUT_LIMIT_POSITION &&
         BEND_UND1_940_ON_STATE &&
         MPS_UND1_950_SX_HRMNC_X_STATE &&
         MPS_UND1_950_SX_HRMNC_ENERGY_STATE )
{
    state = 2; /* SXRSS Harmonic Mode, okay to run beam */
}

else
{
    state = 3; /* SXRSS Undefined State, no beam allowed */
}
```

Name	State	PC	MS	BYKIK	LHS
SXRSS Seeded Mode	0	120 Hz	120 Hz	120 Hz	–
SXRSS SASE Mode	1	120 Hz	120 Hz	120 Hz	–
SXRSS Harmonic Mode	2	120 Hz	120 Hz	120 Hz	–
SXRSS Undefined State	3	0 Hz	0 Hz	0 Hz	–

22.10 SXRSS SLIT UND1 962 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	120 Hz	120 Hz	120 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `SLIT_UND1_962_OUT_LIMIT_POSITION`,
B = `SLIT_UND1_962_IN_LIMIT_POSITION`

22.11 SXRSS Watchdog

Name	*A*	PC	MS	BYKIK	LHS
NOT_OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_UND1_950_SXRSS_WDOG_STATE`

23 Ignored when Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

23.1 BCS LION LTU1 405 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION405_STATE`

23.2 BCS LION LTU1 504 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION504_STATE`

23.3 BCS LION LTU1 505 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION505_STATE`

23.4 BCS LION LTU1 585 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = LION585_STATE

23.5 BCS LION LTU1 716 Threshold

Name	A	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = LION716_STATE

23.6 BCS LION LTU1 717 Threshold

Name	A	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = LION717_STATE

23.7 BCS LION LTU1 732 Threshold

Name	A	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = LION732_STATE

23.8 BCS LION LTU1 733 Threshold

Name	A	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = LION733_STATE

23.9 BCS LION LTU1 752 Threshold

Name	A	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION752_STATE`

23.10 BCS LION LTU1 753 Threshold

Name	A	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION753_STATE`

23.11 BCS LION LTU1 765 Threshold

Name	A	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION765_STATE`

23.12 BCS LION LTU1 766 Threshold

Name	A	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION766_STATE`

23.13 BOD UND1 1005

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BOD_UND1_1005_OUT_LIMIT_POSITION,
B = BOD_UND1_1005_IN_LIMIT_POSITION

23.14 BOD UND1 1305

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BOD_UND1_1305_OUT_LIMIT_POSITION,
B = BOD_UND1_1305_IN_LIMIT_POSITION

23.15 BYD Watchdog

Name	*A*	PC	MS	BYKIK	LHS
NOT_OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = BEND_DMP1_400_BACT_WDOG_STATE

23.16 Magnet In Tolerance: QE31

Name	*A*	PC	MS	BYKIK	LHS
No	F	0 Hz	0 Hz	0 Hz	–
Yes	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_720_INTOL_STATUS

23.17 Magnet In Tolerance: QUM1

Name	A	PC	MS	BYKIK	LHS
No	F	0 Hz	0 Hz	0 Hz	–
Yes	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_820_INTOL_STATUS

23.18 Magnet In Tolerance: QUM2

Name	A	PC	MS	BYKIK	LHS
No	F	0 Hz	0 Hz	0 Hz	–
Yes	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_840_INTOL_STATUS

23.19 Magnet In Tolerance: QUM3

Name	A	PC	MS	BYKIK	LHS
No	F	0 Hz	0 Hz	0 Hz	–
Yes	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_860_INTOL_STATUS

23.20 Magnet In Tolerance: QUM4

Name	A	PC	MS	BYKIK	LHS
No	F	0 Hz	0 Hz	0 Hz	–
Yes	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_880_INTOL_STATUS

23.21 Magnet Power: QE31

Name	*A*	PC	MS	BYKIK	LHS
Off	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_720_STATE_STATUS

23.22 Magnet Power: QUM1

Name	*A*	PC	MS	BYKIK	LHS
Off	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_820_STATE_STATUS

23.23 Magnet Power: QUM2

Name	*A*	PC	MS	BYKIK	LHS
Off	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_840_STATE_STATUS

23.24 Magnet Power: QUM3

Name	*A*	PC	MS	BYKIK	LHS
Off	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_860_STATE_STATUS

23.25 Magnet Power: QUM4

Name	*A*	PC	MS	BYKIK	LHS
Off	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_880_STATE_STATUS

23.26 OTR30 LTU1 449 Position When TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_LTU1_449_OUT_LMTSW_STATE,
B = OTRS_LTU1_449_IN_LMTSW_STATE

23.27 OTR33 Position When TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTR33_0745_OUT_STATE,
B = OTR33_0745_IN_STATE

23.28 PIC Raw Charge Thresholds: DMP1 698

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_DMP1_100_LOSSL_THRESHOLD,
B = PICS_DMP1_100_LOSSH_THRESHOLD

23.29 PIC Raw Charge Thresholds: DMP1 699

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_DMP2_200_LOSSL_THRESHOLD,
B = PICS_DMP2_200_LOSSH_THRESHOLD

23.30 Spoiler: SP0 DMP1 765 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
In	F	T	120 Hz	120 Hz	120 Hz	–
Out	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SPLR_DMP1_765_IN_LIMSW_POSITION,
B = SPLR_DMP1_765_OUT_LIMSW_POSITION

23.31 VVFS DMP1 107 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVFS_DMP1_107_OPEN_LMTSW_STATE

23.32 VVMG DMP1 743 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVMG_DMP1_743_POSITION_STATE

23.33 VVMG UND1 1645 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVMG_UND1_1645_OPEN_LMTSW_STATE

23.34 VVMG UND1 1655 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVMG_UND1_1655_OPEN_LMTSW_STATE

23.35 VVPG DMP1 355 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = VVPG_DMP1_355_OPENSTATUS_STATE,
B = VVPG_DMP1_355_CLOSEDSTATUS_STATE

23.36 YAG LTU1 743 Position When TDUND Not In (PSI Prof Mon)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = YAGS_LTU1_743_OUT_LIMIT_POSITION,
B = YAGS_LTU1_743_IN_LIMIT_POSITION

24 Ignored when Stopper: BSY D2 Summary Is In, TD11 Is In, YAG01 Is In, or YAG02 Is In

24.1 BCS PIC RAW Charge Threshold DMP 997

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PIC997_STATE`

24.2 BCS PIC RAW Charge Threshold DMP 998

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PIC998_STATE`

24.3 BLM Heartbeat: Dechirper LTU1 BLF545

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_BLF545_TEST_L_THRESHOLD`,
B = `BLM_LTU1_BLF545_TEST_H_THRESHOLD`

24.4 BLM Pedestal Thresholds: Dechirper LTU1 BLF545

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_BLF545_PED_L_THRESHOLD`,
B = `BLM_LTU1_BLF545_PED_H_THRESHOLD`

24.5 BLM Raw Charge Thresholds: Dechirper LTU1 BLF545

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_BLF545_LOSS_L_THRESHOLD`,
B = `BLM_LTU1_BLF545_LOSS_H_THRESHOLD`

24.6 BYKIK 120 Hz Abort Trigger

Name	*A*	PC	MS	BYKIK	LHS
Missed Trigger	F	0 Hz	0 Hz	0 Hz	–
Stable	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BYKIK_120HZ_ABRT_TRIG_MISSED`

24.7 BYKIK 120 Hz Standby Trigger

Name	*A*	PC	MS	BYKIK	LHS
Missed Trigger	F	0 Hz	0 Hz	0 Hz	–
Stable	T	120 Hz	120 Hz	120 Hz	–

Where
A = BYKIK_120HZ_STBY_TRIG_MISSED

24.8 BYKIK 30 Hz Abort Trigger

Name	*A*	PC	MS	BYKIK	LHS
Missed Trigger	F	0 Hz	0 Hz	0 Hz	–
Stable	T	120 Hz	120 Hz	120 Hz	–

Where
A = BYKIK_30HZ_ABRT_TRIG_MISSED

24.9 BYKIK 30 Hz Standby Trigger

Name	*A*	PC	MS	BYKIK	LHS
Missed Trigger	F	0 Hz	0 Hz	0 Hz	–
Stable	T	120 Hz	120 Hz	120 Hz	–

Where
A = BYKIK_30HZ_STBY_TRIG_MISSED

24.10 BYKIK Readback Signal

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BYKIK_THRESHOLD_UNDER_FAULT,
B = BYKIK_THRESHOLD_OVER_FAULT

24.11 LTU Dechirper - Horizontal Gap Too Small

Name	*B*	*A*	PC	MS	BYKIK	LHS
Both ends gap too small	F	F	0 Hz	0 Hz	0 Hz	–
Downstream end gap too small	F	T	0 Hz	0 Hz	0 Hz	–
Upstream end gap too small	T	F	0 Hz	0 Hz	0 Hz	–
Gap ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `DCHP_LTU1_555_GAP_LIMSW_NEGZ_POSITION`,
B = `DCHP_LTU1_555_GAP_LIMSW_POSZ_POSITION`

24.12 LTU Dechirper - Vertical Gap Too Small

Name	*B*	*A*	PC	MS	BYKIK	LHS
Both ends gap too small	F	F	0 Hz	0 Hz	0 Hz	–
Downstream end gap too small	F	T	0 Hz	0 Hz	0 Hz	–
Upstream end gap too small	T	F	0 Hz	0 Hz	0 Hz	–
Gap ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `DCHP_LTU1_545_GAP_LIMSW_NEGZ_POSITION`,
B = `DCHP_LTU1_545_GAP_LIMSW_POSZ_POSITION`

24.13 Magnet In Tolerance: BYD1

Name	*A*	PC	MS	BYKIK	LHS
No	F	0 Hz	0 Hz	0 Hz	–
Yes	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BEND_DMP1_400_INTOL_STATUS`

24.14 Magnet Power: BYD1

Name	*A*	PC	MS	BYKIK	LHS
Off	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = BEND_DMP1_400_STATE_STATUS

24.15 OTR30 LTU1 449 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_LTU1_449_OUT_LMTSW_STATE,
B = OTRS_LTU1_449_IN_LMTSW_STATE

24.16 OTR33 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTR33_0745_OUT_STATE,
B = OTR33_0745_IN_STATE

24.17 TDUND Flow Switch Fault With TDUND Not Out

Name	*B*	*A*	PC	MS	BYKIK	LHS
Fault	F	F	0 Hz	0 Hz	0 Hz	–
Ok	F	T	120 Hz	120 Hz	120 Hz	–
Ok, TDUND Out	T	F	120 Hz	120 Hz	120 Hz	–
Ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `TDUND_FS_STATE`,
B = `DUMP_LTU1_970_TDUND_OUT_POSITION`

24.18 TDUND Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `DUMP_LTU1_970_TDUND_OUT_POSITION`,
B = `DUMP_LTU1_970_TDUND_IN_POSITION`

24.19 Temperature RTD Summary: BSY Common Line Past D2

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `RTD_BSY0_89_PASTD2SUM_STATUS`

24.20 THZ-2 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `THZR_LTU1_741_OUT_LIMSW_POSITION`,
B = `THZR_LTU1_741_IN_LIMSW_POSITION`

24.21 Undulator Beam Energy Lower Limit

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BEND_DMP1_400_INTOL_BMIN_STATE`

24.22 VVFS LTU1 102 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACFS_LTU1_102_STATE`

24.23 VVMG LTU1 174 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACV_LTU1_174_STATE`

24.24 VVMG LTU1 355 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACV_LTU1_355_STATE`

24.25 VVMG LTU1 670 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVPG_0670_STATE`

24.26 VVMG LTU1 742 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVPG_0742_STATE`

24.27 VVMG LTU1 774 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVPG_0774_STATE`

24.28 VVMG UND1 932 Position

Name	*A*	PC	MS	BYKIK	LHS
NOT_OUT	F	0 Hz	0 Hz	0 Hz	–
OUT	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVMG_UND1_932_OUT_LIMIT_POSITION

24.29 VVMG UND1 968 Position

Name	*A*	PC	MS	BYKIK	LHS
NOT_OUT	F	0 Hz	0 Hz	0 Hz	–
OUT	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVMG_UND1_968_OUT_LIMIT_POSITION

24.30 VVPG DMP1 103 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VACV_DMP_100_STATE

24.31 VVPG DMP1 395 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VACV_DMP_395_STATE

24.32 VVPG DMP1 700 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACV_DMP_700_STATE`

24.33 VVPG LTU1 100 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACV_LTU1_100_STATE`

24.34 VVPG LTU1 265 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACV_LTU1_265_STATE`

24.35 VVPG LTU1 435 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVPG_0435_STATE`

24.36 VVPG LTU1 580 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0580_STATE

24.37 VVPG LTU1 725 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0725_STATE

24.38 VVPG LTU1 757 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0757_STATE

24.39 VVPG LTU1 999 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0999_STATE

24.40 VVPG UND1 1000 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACV_LTU0_1000_OPEN_STATE`

24.41 VVPG UND1 2500 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACV_UND_2500_STATE`

24.42 YAG LTU1 743 Position (PSI Prof Mon)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `YAGS_LTU1_743_OUT_LIMIT_POSITION`,
B = `YAGS_LTU1_743_IN_LIMIT_POSITION`

25 Ignored when TD11 Is In

25.1 Test Temperature Logic Is Code

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/* Initialize to a guard value */
state = (unsigned int) -1;

if ( SONYA_BSY0_1_TEMPSUM_THRESHOLD)
{
    state = 1; /* Ok */
}

else
{
    state = 0; /* Fault */
}
```

Name	State	PC	MS	BYKIK	LHS
Fault	0	0 Hz	0 Hz	0 Hz	–
Ok	1	120 Hz	120 Hz	120 Hz	–

26 Ignored when TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

26.1 BFW 1010 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1010_OUT_STATE,
B = BFW_UND1_1010_IN_STATE

26.2 BFW 110 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_110_OUT_STATE,
B = BFW_UND1_110_IN_STATE

26.3 BFW 1110 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1110_OUT_STATE,
B = BFW_UND1_1110_IN_STATE

26.4 BFW 1210 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1211_OUT_STATE,
B = BFW_UND1_1211_IN_STATE

26.5 BFW 1310 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1310_OUT_STATE,
B = BFW_UND1_1310_IN_STATE

26.6 BFW 1410 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1410_OUT_STATE,
B = BFW_UND1_1410_IN_STATE

26.7 BFW 1510 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1510_OUT_STATE,
B = BFW_UND1_1510_IN_STATE

26.8 BFW 1610 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1610_OUT_STATE,
B = BFW_UND1_1610_IN_STATE

26.9 BFW 1710 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1710_OUT_STATE,
B = BFW_UND1_1710_IN_STATE

26.10 BFW 1810 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1810_OUT_STATE,
B = BFW_UND1_1810_IN_STATE

26.11 BFW 2010 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2010_OUT_STATE,
B = BFW_UND1_2010_IN_STATE

26.12 BFW 210 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_210_OUT_STATE,
B = BFW_UND1_210_IN_STATE

26.13 BFW 2110 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2110_OUT_STATE,
B = BFW_UND1_2110_IN_STATE

26.14 BFW 2210 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2210_OUT_STATE,
B = BFW_UND1_2210_IN_STATE

26.15 BFW 2310 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2310_OUT_STATE,
B = BFW_UND1_2310_IN_STATE

26.16 BFW 2410 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2410_OUT_STATE,
B = BFW_UND1_2410_IN_STATE

26.17 BFW 2510 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2510_OUT_STATE,
B = BFW_UND1_2510_IN_STATE

26.18 BFW 2610 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2610_OUT_STATE,
B = BFW_UND1_2610_IN_STATE

26.19 BFW 2710 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2710_OUT_STATE,
B = BFW_UND1_2710_IN_STATE

26.20 BFW 2810 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2810_OUT_STATE,
B = BFW_UND1_2810_IN_STATE

26.21 BFW 2910 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2910_OUT_STATE,
B = BFW_UND1_2910_IN_STATE

26.22 BFW 3010 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_3010_OUT_STATE,
B = BFW_UND1_3010_IN_STATE

26.23 BFW 310 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_310_OUT_STATE,
B = BFW_UND1_310_IN_STATE

26.24 BFW 3110 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_3110_OUT_STATE,
B = BFW_UND1_3110_IN_STATE

26.25 BFW 3210 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_3210_OUT_STATE,
B = BFW_UND1_3210_IN_STATE

26.26 BFW 3310 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_3310_OUT_STATE,
B = BFW_UND1_3310_IN_STATE

26.27 BFW 410 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_410_OUT_STATE,
B = BFW_UND1_410_IN_STATE

26.28 BFW 510 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_510_OUT_STATE,
B = BFW_UND1_510_IN_STATE

26.29 BFW 610 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_610_OUT_STATE,
B = BFW_UND1_610_IN_STATE

26.30 BFW 710 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_710_OUT_STATE,
B = BFW_UND1_710_IN_STATE

26.31 BFW 810 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BFW_UND1_810_OUT_STATE`,
B = `BFW_UND1_810_IN_STATE`

26.32 BFW 910 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BFW_UND1_910_OUT_STATE`,
B = `BFW_UND1_910_IN_STATE`

26.33 BFW Inserted Count

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
unsigned int beamFinderWireInCount = 0;

/* "BFW UND1 XXX" is IN when BFW_UND1_XXX_OUT_STATE == 0 */
if (!( BFW_UND1_110_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_210_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_310_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_410_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_510_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_610_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_710_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_810_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_910_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1010_OUT_STATE)) { beamFinderWireInCount++; }
```

```
if (!(BFW_UND1_1110_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1211_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1310_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1410_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1510_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1610_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1710_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1810_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1910_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2010_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2110_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2210_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2310_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2410_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2510_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2610_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2710_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2810_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2910_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_3010_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_3110_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_3210_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_3310_OUT_STATE)) { beamFinderWireInCount++; }

switch(beamFinderWireInCount)
{
    case 0:  state = 0; break; /* No BFWs in */
    case 1:  state = 1; break; /* One BFW in */
    default: state = 2; break; /* More than one BFW in */
}
```

Name	State	PC	MS	BYKIK	LHS
No BFWs In	0	120 Hz	120 Hz	120 Hz	–
One BFW In	1	10 Hz	10 Hz	10 Hz	–
More Than One BFW In	2	0 Hz	0 Hz	0 Hz	–

26.34 BLM Argonne Heartbeat (LN32)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_120_TEST_L_THRESHOLD,
B = BLM_UND1_120_TEST_H_THRESHOLD

26.35 BLM Argonne Heartbeat (LN33)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_920_TEST_L_THRESHOLD,
B = BLM_UND1_920_TEST_H_THRESHOLD

26.36 BLM Argonne Heartbeat (LN35)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1720_TEST_L_THRESHOLD,
B = BLM_UND1_1720_TEST_H_THRESHOLD

26.37 BLM Argonne Heartbeat (LN36)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2520_QTL_THRESHOLD,
B = BLM_2520_QTH_THRESHOLD

26.38 BLM Argonne Heartbeat (LN37)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_3320_TEST_L_THRESHOLD,
B = BLM_UND1_3320_TEST_H_THRESHOLD

26.39 BLM HVPS LTU1 762

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_LTU1_762_LOW_FAULT,
B = HVPS_LTU1_762_HIGH_FAULT

26.40 BLM HVPS UND1 120

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_UND1_120_LOW_FAULT,
B = HVPS_UND1_120_HIGH_FAULT

26.41 BLM HVPS UND1 1720

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_UND1_1720_LOW_FAULT,
B = HVPS_UND1_1720_HIGH_FAULT

26.42 BLM HVPS UND1 2221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_UND1_2221_LOW_FAULT,
B = HVPS_UND1_2221_HIGH_FAULT

26.43 BLM HVPS UND1 2520

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_UND1_2520_LOW_FAULT,
B = HVPS_UND1_2520_HIGH_FAULT

26.44 BLM HVPS UND1 3320

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_UND1_3320_LOW_FAULT,
B = HVPS_UND1_3320_HIGH_FAULT

26.45 BLM HVPS UND1 920

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_UND1_920_LOW_FAULT,
B = HVPS_UND1_920_HIGH_FAULT

26.46 BLM Pedestal Threshold: LTU1 722

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_722_PED_L_THRESHOLD`,
B = `BLM_LTU1_722_PED_H_THRESHOLD`

26.47 BLM Pedestal Threshold: LTU1 732

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_732_PED_L_THRESHOLD`,
B = `BLM_LTU1_732_PED_H_THRESHOLD`

26.48 BLM Pedestal Threshold: LTU1 762

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_762_PED_L_THRESHOLD`,
B = `BLM_LTU1_762_PED_H_THRESHOLD`

26.49 BLM Pedestal Threshold: LTU1 772

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_772_PED_L_THRESHOLD`,
B = `BLM_LTU1_772_PED_H_THRESHOLD`

26.50 BLM Pedestal Thresholds: LTU1 980

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_980_PED_L_THRESHOLD`,
B = `BLM_LTU1_980_PED_H_THRESHOLD`

26.51 BLM Pedestal Thresholds: UND 1021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1021_PED_L_THRESHOLD`,
B = `BLM_UND1_1021_PED_H_THRESHOLD`

26.52 BLM Pedestal Thresholds: UND 1121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1121_PED_L_THRESHOLD,
B = BLM_UND1_1121_PED_H_THRESHOLD

26.53 BLM Pedestal Thresholds: UND 120

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_120_PED_L_THRESHOLD,
B = BLM_UND1_120_PED_H_THRESHOLD

26.54 BLM Pedestal Thresholds: UND 121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_121_PED_L_THRESHOLD,
B = BLM_UND1_121_PED_H_THRESHOLD

26.55 BLM Pedestal Thresholds: UND 1221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1221_PED_L_THRESHOLD`,
B = `BLM_UND1_1221_PED_H_THRESHOLD`

26.56 BLM Pedestal Thresholds: UND 1321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1321_PED_L_THRESHOLD`,
B = `BLM_UND1_1321_PED_H_THRESHOLD`

26.57 BLM Pedestal Thresholds: UND 1421

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1421_PED_L_THRESHOLD`,
B = `BLM_UND1_1421_PED_H_THRESHOLD`

26.58 BLM Pedestal Thresholds: UND 1521

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1521_PED_L_THRESHOLD`,
B = `BLM_UND1_1521_PED_H_THRESHOLD`

26.59 BLM Pedestal Thresholds: UND 1621

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1621_PED_L_THRESHOLD`,
B = `BLM_UND1_1621_PED_H_THRESHOLD`

26.60 BLM Pedestal Thresholds: UND 1720

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1720_PED_L_THRESHOLD`,
B = `BLM_UND1_1720_PED_H_THRESHOLD`

26.61 BLM Pedestal Thresholds: UND 1721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1721_PED_L_THRESHOLD`,
B = `BLM_UND1_1721_PED_H_THRESHOLD`

26.62 BLM Pedestal Thresholds: UND 1821

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1821_PED_L_THRESHOLD`,
B = `BLM_UND1_1821_PED_H_THRESHOLD`

26.63 BLM Pedestal Thresholds: UND 1921

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1921_PED_L_THRESHOLD`,
B = `BLM_UND1_1921_PED_H_THRESHOLD`

26.64 BLM Pedestal Thresholds: UND 2021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_2021_PED_L_THRESHOLD,
B = BLM_UND1_2021_PED_H_THRESHOLD

26.65 BLM Pedestal Thresholds: UND 2121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_2121_PED_L_THRESHOLD,
B = BLM_UND1_2121_PED_H_THRESHOLD

26.66 BLM Pedestal Thresholds: UND 221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_221_PED_L_THRESHOLD,
B = BLM_UND1_221_PED_H_THRESHOLD

26.67 BLM Pedestal Thresholds: UND 2221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2220_QBLL_THRESHOLD`,
B = `BLM_2220_QBLH_THRESHOLD`

26.68 BLM Pedestal Thresholds: UND 2321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2320_QBLL_THRESHOLD`,
B = `BLM_2320_QBLH_THRESHOLD`

26.69 BLM Pedestal Thresholds: UND 2421

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2420_QBLL_THRESHOLD`,
B = `BLM_2420_QBLH_THRESHOLD`

26.70 BLM Pedestal Thresholds: UND 2520

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2520_QBLL_THRESHOLD,
B = BLM_2520_QBLH_THRESHOLD

26.71 BLM Pedestal Thresholds: UND 2521

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_2521_PED_L_THRESHOLD,
B = BLM_UND1_2521_PED_H_THRESHOLD

26.72 BLM Pedestal Thresholds: UND 2621

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2620_QBLL_THRESHOLD,
B = BLM_2620_QBLH_THRESHOLD

26.73 BLM Pedestal Thresholds: UND 2721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2720_QBLL_THRESHOLD,
B = BLM_2720_QBLH_THRESHOLD

26.74 BLM Pedestal Thresholds: UND 2821

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2820_QBLL_THRESHOLD,
B = BLM_2820_QBLH_THRESHOLD

26.75 BLM Pedestal Thresholds: UND 2921

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2920_QBLL_THRESHOLD,
B = BLM_2920_QBLH_THRESHOLD

26.76 BLM Pedestal Thresholds: UND 3021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_3021_PED_L_THRESHOLD`,
B = `BLM_UND1_3021_PED_H_THRESHOLD`

26.77 BLM Pedestal Thresholds: UND 3121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_3121_PED_L_THRESHOLD`,
B = `BLM_UND1_3121_PED_H_THRESHOLD`

26.78 BLM Pedestal Thresholds: UND 321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_321_PED_L_THRESHOLD`,
B = `BLM_UND1_321_PED_H_THRESHOLD`

26.79 BLM Pedestal Thresholds: UND 3221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_3221_PED_L_THRESHOLD`,
B = `BLM_UND1_3221_PED_H_THRESHOLD`

26.80 BLM Pedestal Thresholds: UND 3320

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_3320_PED_L_THRESHOLD`,
B = `BLM_UND1_3320_PED_H_THRESHOLD`

26.81 BLM Pedestal Thresholds: UND 3321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_3321_PED_L_THRESHOLD`,
B = `BLM_UND1_3321_PED_H_THRESHOLD`

26.82 BLM Pedestal Thresholds: UND 421

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_421_PED_L_THRESHOLD`,
B = `BLM_UND1_421_PED_H_THRESHOLD`

26.83 BLM Pedestal Thresholds: UND 521

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_521_PED_L_THRESHOLD`,
B = `BLM_UND1_521_PED_H_THRESHOLD`

26.84 BLM Pedestal Thresholds: UND 621

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_621_PED_L_THRESHOLD`,
B = `BLM_UND1_621_PED_H_THRESHOLD`

26.85 BLM Pedestal Thresholds: UND 721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_721_PED_L_THRESHOLD,
B = BLM_UND1_721_PED_H_THRESHOLD

26.86 BLM Pedestal Thresholds: UND 821

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_821_PED_L_THRESHOLD,
B = BLM_UND1_821_PED_H_THRESHOLD

26.87 BLM Pedestal Thresholds: UND 920

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_920_PED_L_THRESHOLD,
B = BLM_UND1_920_PED_H_THRESHOLD

26.88 BLM Pedestal Thresholds: UND 921

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_921_PED_L_THRESHOLD`,
B = `BLM_UND1_921_PED_H_THRESHOLD`

26.89 BLM Pedestal Thresholds: UND BLF1

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_BLF1_PED_L_THRESHOLD`,
B = `BLM_UND1_BLF1_PED_H_THRESHOLD`

26.90 BLM Pedestal Thresholds: UND BLF17

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_BLF17_PED_L_THRESHOLD`,
B = `BLM_UND1_BLF17_PED_H_THRESHOLD`

26.91 BLM PEP Timing Check (LN30)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_722_TEST_L_THRESHOLD,
B = BLM_LTU1_722_TEST_H_THRESHOLD

26.92 BLM PEP Timing Check (LN32)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_762_TEST_L_THRESHOLD,
B = BLM_LTU1_762_TEST_H_THRESHOLD

26.93 BLM PEP Timing Check (LN33)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_621_TEST_L_THRESHOLD,
B = BLM_UND1_621_TEST_H_THRESHOLD

26.94 BLM PEP Timing Check (LN35)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1421_TEST_L_THRESHOLD,
B = BLM_UND1_1421_TEST_H_THRESHOLD

26.95 BLM PEP Timing Check (LN36)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2220_QTL_THRESHOLD,
B = BLM_2220_QTH_THRESHOLD

26.96 BLM PEP Timing Check (LN37)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_3021_TEST_L_THRESHOLD,
B = BLM_UND1_3021_TEST_H_THRESHOLD

26.97 BLM Raw Charge Thresholds: LTU1 722

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_722_LOSS_L_THRESHOLD`,
B = `BLM_LTU1_722_LOSS_H_THRESHOLD`

26.98 BLM Raw Charge Thresholds: LTU1 732

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_732_LOSS_L_THRESHOLD`,
B = `BLM_LTU1_732_LOSS_H_THRESHOLD`

26.99 BLM Raw Charge Thresholds: LTU1 762

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_762_LOSS_L_THRESHOLD`,
B = `BLM_LTU1_762_LOSS_H_THRESHOLD`

26.100 BLM Raw Charge Thresholds: LTU1 772

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_772_LOSS_L_THRESHOLD`,
B = `BLM_LTU1_772_LOSS_H_THRESHOLD`

26.101 BLM Raw Charge Thresholds: LTU1 980

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_980_LOSS_L_THRESHOLD`,
B = `BLM_LTU1_980_LOSS_H_THRESHOLD`

26.102 BLM Raw Charge Thresholds: UND 1021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1021_LOSS_L_THRESHOLD`,
B = `BLM_UND1_1021_LOSS_H_THRESHOLD`

26.103 BLM Raw Charge Thresholds: UND 1121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1121_LOSS_L_THRESHOLD,
B = BLM_UND1_1121_LOSS_H_THRESHOLD

26.104 BLM Raw Charge Thresholds: UND 120

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_120_LOSS_L_THRESHOLD,
B = BLM_UND1_120_LOSS_H_THRESHOLD

26.105 BLM Raw Charge Thresholds: UND 121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_121_LOSS_L_THRESHOLD,
B = BLM_UND1_121_LOSS_H_THRESHOLD

26.106 BLM Raw Charge Thresholds: UND 1221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1221_LOSS_L_THRESHOLD,
B = BLM_UND1_1221_LOSS_H_THRESHOLD

26.107 BLM Raw Charge Thresholds: UND 1321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1321_LOSS_L_THRESHOLD,
B = BLM_UND1_1321_LOSS_H_THRESHOLD

26.108 BLM Raw Charge Thresholds: UND 1421

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1421_LOSS_L_THRESHOLD,
B = BLM_UND1_1421_LOSS_H_THRESHOLD

26.109 BLM Raw Charge Thresholds: UND 1521

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1521_LOSS_L_THRESHOLD,
B = BLM_UND1_1521_LOSS_H_THRESHOLD

26.110 BLM Raw Charge Thresholds: UND 1621

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1621_LOSS_L_THRESHOLD,
B = BLM_UND1_1621_LOSS_H_THRESHOLD

26.111 BLM Raw Charge Thresholds: UND 1720

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1720_LOSS_L_THRESHOLD,
B = BLM_UND1_1720_LOSS_H_THRESHOLD

26.112 BLM Raw Charge Thresholds: UND 1721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1721_LOSS_L_THRESHOLD,
B = BLM_UND1_1721_LOSS_H_THRESHOLD

26.113 BLM Raw Charge Thresholds: UND 1821

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1821_LOSS_L_THRESHOLD,
B = BLM_UND1_1821_LOSS_H_THRESHOLD

26.114 BLM Raw Charge Thresholds: UND 1921

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1921_LOSS_L_THRESHOLD,
B = BLM_UND1_1921_LOSS_H_THRESHOLD

26.115 BLM Raw Charge Thresholds: UND 2021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_2021_LOSS_L_THRESHOLD,
B = BLM_UND1_2021_LOSS_H_THRESHOLD

26.116 BLM Raw Charge Thresholds: UND 2121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_2121_LOSS_L_THRESHOLD,
B = BLM_UND1_2121_LOSS_H_THRESHOLD

26.117 BLM Raw Charge Thresholds: UND 221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_221_LOSS_L_THRESHOLD,
B = BLM_UND1_221_LOSS_H_THRESHOLD

26.118 BLM Raw Charge Thresholds: UND 2221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2220_QBL_THRESHOLD`,
B = `BLM_2220_QBH_THRESHOLD`

26.119 BLM Raw Charge Thresholds: UND 2321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2320_QBL_THRESHOLD`,
B = `BLM_2320_QBH_THRESHOLD`

26.120 BLM Raw Charge Thresholds: UND 2421

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2420_QBL_THRESHOLD`,
B = `BLM_2420_QBH_THRESHOLD`

26.121 BLM Raw Charge Thresholds: UND 2520

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2520_QBL_THRESHOLD,
B = BLM_2520_QBH_THRESHOLD

26.122 BLM Raw Charge Thresholds: UND 2521

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_2521_LOSS_L_THRESHOLD,
B = BLM_UND1_2521_LOSS_H_THRESHOLD

26.123 BLM Raw Charge Thresholds: UND 2621

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2620_QBL_THRESHOLD,
B = BLM_2620_QBH_THRESHOLD

26.124 BLM Raw Charge Thresholds: UND 2721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2720_QBL_THRESHOLD`,
B = `BLM_2720_QBH_THRESHOLD`

26.125 BLM Raw Charge Thresholds: UND 2821

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2820_QBL_THRESHOLD`,
B = `BLM_2820_QBH_THRESHOLD`

26.126 BLM Raw Charge Thresholds: UND 2921

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2920_QBL_THRESHOLD`,
B = `BLM_2920_QBH_THRESHOLD`

26.127 BLM Raw Charge Thresholds: UND 3021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_3021_LOSS_L_THRESHOLD,
B = BLM_UND1_3021_LOSS_H_THRESHOLD

26.128 BLM Raw Charge Thresholds: UND 3121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_3121_LOSS_L_THRESHOLD,
B = BLM_UND1_3121_LOSS_H_THRESHOLD

26.129 BLM Raw Charge Thresholds: UND 321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_321_LOSS_L_THRESHOLD,
B = BLM_UND1_321_LOSS_H_THRESHOLD

26.130 BLM Raw Charge Thresholds: UND 3221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_3221_LOSS_L_THRESHOLD,
B = BLM_UND1_3221_LOSS_H_THRESHOLD

26.131 BLM Raw Charge Thresholds: UND 3320

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_3320_LOSS_L_THRESHOLD,
B = BLM_UND1_3320_LOSS_H_THRESHOLD

26.132 BLM Raw Charge Thresholds: UND 3321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_3321_LOSS_L_THRESHOLD,
B = BLM_UND1_3321_LOSS_H_THRESHOLD

26.133 BLM Raw Charge Thresholds: UND 421

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_421_LOSS_L_THRESHOLD`,
B = `BLM_UND1_421_LOSS_H_THRESHOLD`

26.134 BLM Raw Charge Thresholds: UND 521

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_521_LOSS_L_THRESHOLD`,
B = `BLM_UND1_521_LOSS_H_THRESHOLD`

26.135 BLM Raw Charge Thresholds: UND 621

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_621_LOSS_L_THRESHOLD`,
B = `BLM_UND1_621_LOSS_H_THRESHOLD`

26.136 BLM Raw Charge Thresholds: UND 721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_721_LOSS_L_THRESHOLD,
B = BLM_UND1_721_LOSS_H_THRESHOLD

26.137 BLM Raw Charge Thresholds: UND 821

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_821_LOSS_L_THRESHOLD,
B = BLM_UND1_821_LOSS_H_THRESHOLD

26.138 BLM Raw Charge Thresholds: UND 920

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_920_LOSS_L_THRESHOLD,
B = BLM_UND1_920_LOSS_H_THRESHOLD

26.139 BLM Raw Charge Thresholds: UND 921

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_921_LOSS_L_THRESHOLD,
B = BLM_UND1_921_LOSS_H_THRESHOLD

26.140 BLM Raw Charge Thresholds: UND BLF1

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_BLF1_LOSS_L_THRESHOLD,
B = BLM_UND1_BLF1_LOSS_H_THRESHOLD

26.141 BLM Raw Charge Thresholds: UND BLF17

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_BLF17_LOSS_L_THRESHOLD,
B = BLM_UND1_BLF17_LOSS_H_THRESHOLD

26.142 BLM Timing Check (BLM:UND1:4)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Bad Timing	F	F	0 Hz	0 Hz	0 Hz	–
Bad Timing High	F	T	0 Hz	0 Hz	0 Hz	–
Bad Timing Low	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_4_TIMING_L_THRESHOLD`,
B = `BLM_UND1_4_TIMING_H_THRESHOLD`

26.143 BLM Timing Check (LN30)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Bad Timing	F	F	0 Hz	0 Hz	0 Hz	–
Bad Timing High	F	T	0 Hz	0 Hz	0 Hz	–
Bad Timing Low	T	F	0 Hz	0 Hz	0 Hz	–
All OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_4_TIMING_L_THRESHOLD`,
B = `BLM_UND1_4_TIMING_H_THRESHOLD`

26.144 BLM Trigger Missed (LN30)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_722_NO_TRIG_MISSED`

26.145 BLM Trigger Missed (LN32)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_762_NO_TRIG_MISSED

26.146 BLM Trigger Missed (LN33)

Name	A	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_6_NO_TRIG_MISSED

26.147 BLM Trigger Missed (LN35)

Name	A	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_14_NO_TRIG_MISSED

26.148 BLM Trigger Missed (LN36)

Name	A	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_TRIG_MISSED

26.149 BLM Trigger Missed (LN37)

Name	A	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_30_NO_TRIG_MISSED

26.150 BLM/PIC Watchdog: Downstream of TDUND

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MCC0_2_PICBLM_WD_STATUS`

26.151 BPM Summary (1-9)

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `IOC_UND1_BP01_MPSSTAT_STATE`

26.152 BPM Summary (10-18)

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `IOC_UND1_BP02_MPSSTAT_STATE`

26.153 BPM Summary (19-27)

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `IOC_UND1_BP03_MPSSTAT_STATE`

26.154 BPM Summary (28-36)

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = IOC_UND1_BP04_MPSSTAT_STATE

26.155 OTR01 IN20 541 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_IN20_541_OUT_LMTSW_STATE,
B = OTRS_IN20_541_IN_LMTSW_STATE

26.156 OTR02 IN20 571 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_IN20_571_OUT_LMTSW_STATE,
B = OTRS_IN20_571_IN_LMTSW_STATE

26.157 OTR03 IN20 621 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_IN20_621_OUT_LMTSW_STATE`,
B = `OTRS_IN20_621_IN_LMTSW_STATE`

26.158 OTR04 IN20 711 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_IN20_711_OUT_LMTSW_STATE`,
B = `OTRS_IN20_711_IN_LMTSW_STATE`

26.159 OTR11 LI21 237 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_LI21_237_OUT_LMTSW_STATE`,
B = `OTRS_LI21_237_IN_LMTSW_STATE`

26.160 OTR12 LI21 291 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_LI21_291_OUT_LMTSW_STATE,
B = OTRS_LI21_291_IN_LMTSW_STATE

26.161 OTR21 Position When TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_LI24_807_OUT_LMTSW_STATE,
B = OTRS_LI24_807_IN_LMTSW_STATE

26.162 OTR22 Position When TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_LI25_342_OUT_LMTSW_STATE,
B = OTRS_LI25_342_IN_LMTSW_STATE

26.163 OTRH1 Position When TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRH1_OUT_LIMIT_STATE`,
B = `OTRH1_IN_LIMIT_STATE`

26.164 OTRH2 Position When TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRH2_OUT_LIMIT_STATE`,
B = `OTRH2_IN_LIMIT_STATE`

26.165 PIC HVPS B921 - Location B921-2235

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_DMP1_B921_HV_PWR_STATE`

26.166 PIC Trigger Missed (LN34)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_DMP1_100_NO_TRIG_MISSED

26.167 THz Radiator Beryllium Foil

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = THZR_DMP1_350_OUT_LIMIT_POSITION,
B = THZR_DMP1_350_IN_LIMIT_POSITION

26.168 Toroid Comparator (IMUNDI vs IMUNDO)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
3E8 ppb Gain	F	T	0 Hz	0 Hz	0 Hz	–
3E8 ppb Loss	T	F	0 Hz	0 Hz	0 Hz	–
Under 3E8 ppb Loss	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = IMUNDI_COMP_L1_STATE,
B = IMUNDI_COMP_L2_STATE

26.169 Toroid Comparator (IMUNDO vs IMDUMP)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
3E8 ppb Gain	F	T	0 Hz	0 Hz	0 Hz	–
3E8 ppb Loss	T	F	0 Hz	0 Hz	0 Hz	–
Under 3E8 ppb Loss	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = IMUNDO_COMP_L1_STATE,
B = IMUNDO_COMP_L2_STATE

26.170 Toroid Comparator Power Status (B921)

Name	A	PC	MS	BYKIK	LHS
Powered Off	F	0 Hz	0 Hz	0 Hz	–
Powered On	T	120 Hz	120 Hz	120 Hz	–

Where
A = COMP_STAT_ON_STATE

27 Ignored when TD11 Is In, YAG01 Is In, or YAG02 Is In

27.1 A-Line SL10 Position

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
state = (unsigned int) -1;

if ( SLIT_BSYA_2010_SL10_FB_IN_STATE &&
        SLIT_BSYA_2010_SL10_FT_IN_STATE &&
        SLIT_BSYA_2010_SL10_RB_IN_STATE &&
        SLIT_BSYA_2010_SL10_RT_IN_STATE )
{
    state = 0; /* SL10 is Closed */
}

else
{
    state = 1; /* SL10 is Not Closed */
}
```

Name	State	PC	MS	BYKIK	LHS
Closed	0	120 Hz	120 Hz	120 Hz	–
Not_Closed	1	120 Hz	120 Hz	120 Hz	–

27.2 BLM/PIC Watchdog BSY0/BSYA

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_BSY0_1_PICBLM_WD_STATUS`

27.3 BLM/PIC Watchdog LI24

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_LI24_1_PICBLM_WD_STATUS`

27.4 BLM/PIC Watchdog LI30

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_LI30_1_PICBLM_WD_STATUS`

27.5 BSY GLAST Target Flow Switch

Name	*B*	*A*	PC	MS	BYKIK	LHS
Faulted	F	F	0 Hz	0 Hz	0 Hz	–
Ok	F	T	120 Hz	120 Hz	120 Hz	–
Faulted but Target Out	T	F	120 Hz	120 Hz	120 Hz	–
Ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `TRGT_BSY0_70_FLOW_SW_STATE`,
B = `TRGT_BSY0_70_OUT_LIMSW_POSITION`

27.6 BSY GLAST Target Klixon

Name	*B*	*A*	PC	MS	BYKIK	LHS
Faulted	F	F	0 Hz	0 Hz	0 Hz	–
Ok	F	T	120 Hz	120 Hz	120 Hz	–
Faulted but Target Out	T	F	120 Hz	120 Hz	120 Hz	–
Ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = GL_KLIXON_STATE,
B = TRGT_BSY0_70_OUT_LIMSW_POSITION

27.7 BSY GLAST Target Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
In	F	T	120 Hz	120 Hz	120 Hz	–
Out	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = TRGT_BSY0_70_IN_LIMSW_POSITION,
B = TRGT_BSY0_70_OUT_LIMSW_POSITION

27.8 Bunch Length Monitor BL21 Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BL22_OUT_STATE,
B = BL22_IN_STATE

27.9 Flowswitch: BPM BSYA 1020 (BPM10)

Name	A	PC	MS	BYKIK	LHS
IS_NOT_OK	F	0 Hz	0 Hz	–	–
OK	T	120 Hz	120 Hz	–	–

Where
A = BPM_BSYA_1020_FLOW_SW_STATE

27.10 Flowswitch: BPM BSYA 1240 (BPM12)

Name	*A*	PC	MS	BYKIK	LHS
IS_NOT_OK	F	0 Hz	0 Hz	–	–
OK	T	120 Hz	120 Hz	–	–

Where
A = `BPM_BSYA_1240_FLOW_SW_STATE`

27.11 Flowswitch: BSY PC320

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PC320_FS_STATE`

27.12 Flowswitch: BSY PC90

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PC90_FS_STATE`

27.13 Flowswitch: BSY RAD LCW Slit 10/30

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HTEXCH2_STATE`

27.14 Flowswitch: CE21

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COL_805_FLOSW_STATE`

27.15 Flowswitch: COLL BSY0 16 (50PC20)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSY0_16_FLOW_SW_STATE`

27.16 Flowswitch: COLL BSY0 33 (50PC30)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSY0_33_FLOW_SW_STATE`

27.17 Flowswitch: COLL BSY0 45 (50PC-45)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSY0_45_FLOW_SW_STATE`

27.18 Flowswitch: COLL BSY0 59 (PC0119)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSY0_59_FLOW_SW_STATE`

27.19 Flowswitch: COLL BSY0 65 (PC0145)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSY0_65_FLOW_SW_STATE`

27.20 Flowswitch: COLL BSY0 67 (PC0155)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSY0_67_FLOW_SW_STATE`

27.21 Flowswitch: COLL BSY0 69 (PC0165)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSY0_69_FLOW_SW_STATE`

27.22 Flowswitch: COLL BSY0 71 (PC0175)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSY0_71_FLOW_SW_STATE`

27.23 Flowswitch: COLL BSY0 73 (PC0185)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSY0_73_FLOW_SW_STATE`

27.24 Flowswitch: COLL BSY0 75 (PC0195)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSY0_75_FLOW_SW_STATE`

27.25 Flowswitch: COLL BSYA 1015 (PC10)

Name	*A*	PC	MS	BYKIK	LHS
IS_NOT_OK	F	0 Hz	0 Hz	–	–
OK	T	120 Hz	120 Hz	–	–

Where
A = `COLL_BSYA_1015_FLOW_SW_STATE`

27.26 Flowswitch: COLL BSYA 1230 (PC12)

Name	*A*	PC	MS	BYKIK	LHS
IS_NOT_OK	F	0 Hz	0 Hz	–	–
OK	T	120 Hz	120 Hz	–	–

Where
A = `COLL_BSYA_1230_FLOW_SW_STATE`

27.27 Flowswitch: COLL BSYA 1490 (PC14)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSYA_1490_FLOW_SW_STATE`

27.28 Flowswitch: COLL BSYA 1700 (PC17)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSYA_1700_FLOW_SW_STATE`

27.29 Flowswitch: COLL BSYA 2060 (PC20)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSYA_2060_FLOW_SW_STATE`

27.30 Flowswitch: COLL BSYA 2410 (COLL24H)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_BSYA_2470_H_FLOW_SW_STATE

27.31 Flowswitch: COLL BSYA 2410 (COLL24V)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_BSYA_2470_V_FLOW_SW_STATE

27.32 Flowswitch: COLL BSYA 2410 (PC24)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_BSYA_2410_FLOW_SW_STATE

27.33 Flowswitch: COLL BSYA 2600 (PC26)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_BSYA_2600_FLOW_SW_STATE

27.34 Flowswitch: COLL BSYA 2990 (PC29)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_BSYA_2990_FLOW_SW_STATE

27.35 Flowswitch: COLL BSYA 3710 (C37)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_BSYA_3710_FLOW_SW_STATE

27.36 Flowswitch: COLL BSYA 4120 (3C1A)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_ESA0_4120_FLOW_SW_STATE

27.37 Hydrogen Recombiner For BSY 1 Collimator

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = HYDRECM1_STATE

27.38 Hydrogen Recombiner For BSY 2 Slit 10/30

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = HYDRECM2_STATE

27.39 Ion Chamber Gas Flowswitch BSY A

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = A_IC_GAS_STATE

27.40 Ion Chamber Gas Flowswitch BSY B

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = B_IC_GAS_STATE

27.41 Ion Chamber Gas Flowswitch BSY C

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = C_IC_GAS_STATE

27.42 KICK BSY0 66 PM1 State (A-Line Kicker)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Inconsistent	F	F	0 Hz	0 Hz	0 Hz	–
Is_OFF	F	T	120 Hz	120 Hz	120 Hz	–
Is_ON	T	F	120 Hz	120 Hz	120 Hz	–
Inconsistent	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = KICK_BSY0_66_PM1_OFF_STATUS,
B = KICK_BSY0_66_PM1_ON_STATUS

27.43 KICK BSY0 66 PM1 Trigger State (A-Line Kicker)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Inconsistent	F	F	0 Hz	0 Hz	0 Hz	–
Is_Triggered	F	T	120 Hz	120 Hz	120 Hz	–
Is_Trig_Disabled	T	F	120 Hz	120 Hz	120 Hz	–
Inconsistent	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = KICK_BSY0_66_PM1_TRIG_ENB_STATUS,
B = KICK_BSY0_66_PM1_TRIG_LOCK_STATUS

27.44 KICK BSY0 66 PM2 State (A-Line Kicker)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Inconsistent	F	F	0 Hz	0 Hz	0 Hz	–
Is_OFF	F	T	120 Hz	120 Hz	120 Hz	–
Is_ON	T	F	120 Hz	120 Hz	120 Hz	–
Inconsistent	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = KICK_BSY0_66_PM2_OFF_STATUS,
B = KICK_BSY0_66_PM2_ON_STATUS

27.45 KICK BSY0 66 PM2 Trigger State (A-Line Kicker)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Inconsistent	F	F	0 Hz	0 Hz	0 Hz	–
Is_Triggered	F	T	120 Hz	120 Hz	120 Hz	–
Is_Trig_Disabled	T	F	120 Hz	120 Hz	120 Hz	–
Inconsistent	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = KICK_BSY0_66_PM2_TRIG_ENB_STATUS,
B = KICK_BSY0_66_PM2_TRIG_LOCK_STATUS

27.46 OTR21 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_LI24_807_OUT_LMTSW_STATE,
B = OTRS_LI24_807_IN_LMTSW_STATE

27.47 OTR22 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_LI25_342_OUT_LMTSW_STATE,
B = OTRS_LI25_342_IN_LMTSW_STATE

27.48 PIC Gas Pressure LI24

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PIC_GAS_PRESS_STATE

27.49 PIC HVPS B911 - Location B911-2135

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LTU1_B911_HV_PWR_STATE

27.50 PIC HVPS B912 - Location B912-2135

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LTU1_B912_HV_PWR_STATE

27.51 PIC HVPS B913 - Location B913-2135

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LTU1_B913_HV_PWR_STATE

27.52 PIC HVPS BSY 1 - Location B005-3921

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSY0_1_HV_PWR_STATE`

27.53 PIC HVPS BSY 2 - Location B005-3921

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSY0_2_HV_PWR_STATE`

27.54 PIC HVPS BSY 3 - Location B005-3921

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSY0_3_HV_PWR_STATE`

27.55 PIC HVPS BSY 4 - Location B005-3918

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSY0_4_HV_PWR_STATE`

27.56 PIC HVPS BSY 5 - Location B005-3918

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSY0_5_HV_PWR_STATE

27.57 PIC HVPS BSY 6 - Location B005-3918

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSY0_6_HV_PWR_STATE

27.58 PIC HVPS LI24 - Location LKF24-0235

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI24_1_HV_PWR_STATE

27.59 PIC Raw Charge Thresholds: BSYA 1016

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = PICM_BSYA_1016_LOSSL_THRESHOLD,
B = PICM_BSYA_1016_LOSSH_THRESHOLD

27.60 PIC Raw Charge Thresholds: BSYA 1021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = `PICM_BSYA_1021_LOSSL_THRESHOLD`,
B = `PICM_BSYA_1021_LOSSH_THRESHOLD`

27.61 PIC Raw Charge Thresholds: BSYA 1120

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = `PICM_BSYA_1120_LOSSL_THRESHOLD`,
B = `PICM_BSYA_1120_LOSSH_THRESHOLD`

27.62 PIC Raw Charge Thresholds: BSYA 1320

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = `PICM_BSYA_1320_LOSSL_THRESHOLD`,
B = `PICM_BSYA_1320_LOSSH_THRESHOLD`

27.63 PIC Raw Charge Thresholds: BSYA 1520

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = `PICM_BSYA_1520_LOSSL_THRESHOLD`,
B = `PICM_BSYA_1520_LOSSH_THRESHOLD`

27.64 PIC Raw Charge Thresholds: BSYA 1701A

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = `PICM_BSYA_1701A_LOSSL_THRESHOLD`,
B = `PICM_BSYA_1701A_LOSSH_THRESHOLD`

27.65 PIC Raw Charge Thresholds: BSYA 1701B

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = `PICM_BSYA_1701B_LOSSL_THRESHOLD`,
B = `PICM_BSYA_1701B_LOSSH_THRESHOLD`

27.66 PIC Raw Charge Thresholds: BSYA 1980

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = `PICM_BSYA_1980_LOSSL_THRESHOLD`,
B = `PICM_BSYA_1980_LOSSH_THRESHOLD`

27.67 PIC Raw Charge Thresholds: BSYA 2061

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2061_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2061_LOSSH_THRESHOLD`

27.68 PIC Raw Charge Thresholds: BSYA 2120

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2120_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2120_LOSSH_THRESHOLD`

27.69 PIC Raw Charge Thresholds: BSYA 2220

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2220_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2220_LOSSH_THRESHOLD`

27.70 PIC Raw Charge Thresholds: BSYA 2321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2321_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2321_LOSSH_THRESHOLD`

27.71 PIC Raw Charge Thresholds: BSYA 2411

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2411_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2411_LOSSH_THRESHOLD`

27.72 PIC Raw Charge Thresholds: BSYA 2472

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2472_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2472_LOSSH_THRESHOLD`

27.73 PIC Raw Charge Thresholds: BSYA 2473

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2473_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2473_LOSSH_THRESHOLD`

27.74 PIC Raw Charge Thresholds: BSYA 2474

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2474_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2474_LOSSH_THRESHOLD`

27.75 PIC Raw Charge Thresholds: BSYA 2475

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2475_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2475_LOSSH_THRESHOLD`

27.76 PIC Raw Charge Thresholds: BSYA 2520

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2520_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2520_LOSSH_THRESHOLD`

27.77 PIC Raw Charge Thresholds: BSYA 2601

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2601_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2601_LOSSH_THRESHOLD`

27.78 PIC Raw Charge Thresholds: BSYA 2861

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2861_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2861_LOSSH_THRESHOLD`

27.79 PIC Raw Charge Thresholds: BSYA 2990

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2990_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2990_LOSSH_THRESHOLD`

27.80 PIC Raw Charge Thresholds: BSYA 3320

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_3320_LOSSL_THRESHOLD`,
B = `PICM_BSYA_3320_LOSSH_THRESHOLD`

27.81 PIC Raw Charge Thresholds: BSYA 3720

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSYA_3720_LOSSL_THRESHOLD,
B = PICM_BSYA_3720_LOSSH_THRESHOLD

27.82 PIC Raw Charge Thresholds: BSYA 3721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSYA_3721_LOSSL_THRESHOLD,
B = PICM_BSYA_3721_LOSSH_THRESHOLD

27.83 PIC Raw Charge Thresholds: BSYA 3890

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSYA_3890_LOSSL_THRESHOLD,
B = PICM_BSYA_3890_LOSSH_THRESHOLD

27.84 PIC Raw Charge Thresholds: LTU1 220

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_220_LOSSL_THRESHOLD,
B = PICS_LTU1_220_LOSSH_THRESHOLD

27.85 PIC Raw Charge Thresholds: LTU1 252

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_252_LOSSL_THRESHOLD,
B = PICS_LTU1_252_LOSSH_THRESHOLD

27.86 PIC Raw Charge Thresholds: LTU1 280

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_280_LOSSL_THRESHOLD,
B = PICS_LTU1_280_LOSSH_THRESHOLD

27.87 PIC Raw Charge Thresholds: LTU1 420

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_420_LOSSL_THRESHOLD,
B = PICS_LTU1_420_LOSSH_THRESHOLD

27.88 PIC Raw Charge Thresholds: LTU1 450

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_450_LOSSL_THRESHOLD,
B = PICS_LTU1_450_LOSSH_THRESHOLD

27.89 PIC Raw Charge Thresholds: LTU1 480

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_480_LOSSL_THRESHOLD,
B = PICS_LTU1_480_LOSSH_THRESHOLD

27.90 PIC Raw Charge Thresholds: LTU1 722

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_722_LOSSL_THRESHOLD,
B = PICS_LTU1_722_LOSSH_THRESHOLD

27.91 PIC Raw Charge Thresholds: LTU1 732

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LTU1_732_LOSSL_THRESHOLD,
B = PICM_LTU1_732_LOSSH_THRESHOLD

27.92 PIC Raw Charge Thresholds: LTU1 762

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_762_LOSSL_THRESHOLD,
B = PICS_LTU1_762_LOSSH_THRESHOLD

27.93 PIC Raw Charge Thresholds: LTU1 772

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_772_LOSSL_THRESHOLD,
B = PICS_LTU1_772_LOSSH_THRESHOLD

27.94 PIC Trigger Missed (LN28)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_220_NO_TRIG_MISSED

27.95 PIC Trigger Missed (LN29)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_480_NO_TRIG_MISSED

27.96 PIC Trigger Missed (LN31)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_762_NO_TRIG_MISSED

27.97 PIC Trigger Missed (LN42)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2061_NO_TRIG_MISSED`

27.98 Stopper BSYA 2275 (ST22) Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
MOVING	F	F	0 Hz	0 Hz	0 Hz	–
OUT	F	T	120 Hz	120 Hz	120 Hz	–
IN	T	F	0 Hz	0 Hz	0 Hz	–
BROKEN	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `STPR_BSYA_2275_ST22_OUT_LIM_STATE`,
B = `STPR_BSYA_2275_ST22_IN_LIM_STATE`

27.99 Stopper BSYA 2930 (ST29) Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
MOVING	F	F	0 Hz	0 Hz	0 Hz	–
OUT	F	T	120 Hz	120 Hz	120 Hz	–
IN	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `STPR_BSYA_2930_ST29_OUT_LIM_STATE`,
B = `STPR_BSYA_2930_ST29_IN_LIM_STATE`

27.100 Stopper: BSY D2, 60, 61 DM60 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
 * state = 0 : full rate (120 Hz) beam allowed, ALL OUT
```

```
 * state = 1 : full rate (120 Hz) beam allowed, ALL IN
 * state = 2 : do not allow beam, Moving or Inconsistant
*/

/* Initialize to a guard value */
state = (unsigned int) -1;

/*
 * Stopper: BSY D2, 60, 61 DM60 Summary
 * Status given from PPS Stopper chassis very close to limit switches
    and CNTRL and passed to MPS via
 * opto's to insure fasts possible response. BTM60 has been documented
    to move at 200 msec from OUT to IN
 * Allow beam if ALL OUT
 * Allow beam if ALL IN
 * Otherwise, do not allow beam, Moving or Inconsistant
 */


/* Input Descriptions
*    INPUT_NAME                                                    ,
   FAULT_NAME (low)      , OK_NAME          , DESC
*       STPR_BSY0_89_IN_LIMSW_A_POSITION          , "IS_NOT_IN"
              , "IS_IN"      , "ST60 IN LIMSW CHAN A"
*       STPR_BSY0_89_IN_LIMSW_B_POSITION          , "IS_NOT_IN"
              , "IS_IN"      , "ST60 IN LIMSW CHAN B"
*       STPR_BSY0_89_OUT_LIMSW_A_POSITION         , "IS_NOT_OUT"
             , "IS_OUT"     , "ST60 OUT LIMSW CHAN A"
*       STPR_BSY0_89_OUT_LIMSW_B_POSITION         , "IS_NOT_OUT"
             , "IS_OUT"     , "ST60 OUT LIMSW CHAN B"
*       STPR_BSY0_90_IN_LIMSW_A_POSITION          , "IS_NOT_IN"
              , "IS_IN"      , "ST61 IN LIMSW CHAN A"
*       STPR_BSY0_90_IN_LIMSW_B_POSITION          , "IS_NOT_IN"
              , "IS_IN"      , "ST61 IN LIMSW CHAN B"
*       STPR_BSY0_90_OUT_LIMSW_A_POSITION         , "IS_NOT_OUT"
             , "IS_OUT"     , "ST61 OUT LIMSW CHAN A"
*       STPR_BSY0_90_OUT_LIMSW_B_POSITION         , "IS_NOT_OUT"
             , "IS_OUT"     , "ST61 OUT LIMSW CHAN B"
*       STPR_BSY0_88_IN_LIMSW_A_POSITION          , "IS_NOT_IN"
              , "IS_IN"      , "D2 IN LIMSW CHAN A"
*       STPR_BSY0_88_IN_LIMSW_B_POSITION          , "IS_NOT_IN"
              , "IS_IN"      , "D2 IN LIMSW CHAN B"
*       STPR_BSY0_88_OUT_LIMSW_A_POSITION         , "IS_NOT_OUT"
             , "IS_OUT"     , "D2 OUT LIMSW CHAN A"
*       BTM_BSY0_89_IN_LIMSW_A_POSITION           , "IS_NOT_IN"
```

```
                , "IS_IN"       , "BTM60 IN LIMSW CHAN A"
*       BTM_BSY0_89_IN_LIMSW_B_POSITION       , "IS_NOT_IN"          , "
    IS_IN"       , "BTM60 IN LIMSW CHAN B"
*       BTM_BSY0_89_OUT_LIMSW_A_POSITION           , "IS_NOT_OUT"
              , "IS_OUT"      , "BTM60 OUT LIMSW CHAN A"
*       BTM_BSY0_89_OUT_CNTRL_A_PPS_CNTRL          , "IS_NOT_OUT_RQ"
            , "IS_OUT_RQ"  , "BTM60 OUT SOLN CNTRL CHAN A"
*       BTM_BSY0_89_OUT_CNTRL_B_PPS_CNTRL          , "IS_NOT_OUT_RQ"
            , "IS_OUT_RQ"  , "BTM60 OUT SOLN CNTRL CHAN B2"
*
*/

if ( STPR_BSY0_89_OUT_LIMSW_A_POSITION &&
    STPR_BSY0_89_OUT_LIMSW_B_POSITION &&
            STPR_BSY0_90_OUT_LIMSW_A_POSITION &&
                STPR_BSY0_90_OUT_LIMSW_B_POSITION &&
            STPR_BSY0_88_OUT_LIMSW_A_POSITION &&
                BTM_BSY0_89_OUT_LIMSW_A_POSITION &&
            BTM_BSY0_89_OUT_CNTRL_A_PPS_CNTRL &&
                BTM_BSY0_89_OUT_CNTRL_B_PPS_CNTRL &&
            !( STPR_BSY0_89_IN_LIMSW_A_POSITION ||
                STPR_BSY0_89_IN_LIMSW_B_POSITION ||
                STPR_BSY0_90_IN_LIMSW_A_POSITION ||
                    STPR_BSY0_90_IN_LIMSW_B_POSITION ||
                STPR_BSY0_88_IN_LIMSW_A_POSITION ||
                    STPR_BSY0_88_IN_LIMSW_B_POSITION ||
                BTM_BSY0_89_IN_LIMSW_A_POSITION ||
                    BTM_BSY0_89_IN_LIMSW_B_POSITION ) )
{
     state = 0; /* ALL OUT, and NOT IN, okay to run beam */
}

else if ( STPR_BSY0_89_IN_LIMSW_A_POSITION  &&
    STPR_BSY0_89_IN_LIMSW_B_POSITION &&
              STPR_BSY0_90_IN_LIMSW_A_POSITION &&
                  STPR_BSY0_90_IN_LIMSW_B_POSITION &&
              STPR_BSY0_88_IN_LIMSW_A_POSITION &&
                  STPR_BSY0_88_IN_LIMSW_B_POSITION &&
              BTM_BSY0_89_IN_LIMSW_A_POSITION &&
                  BTM_BSY0_89_IN_LIMSW_B_POSITION  &&
              !(STPR_BSY0_89_OUT_LIMSW_A_POSITION ||
                  STPR_BSY0_89_OUT_LIMSW_B_POSITION ||
                STPR_BSY0_90_OUT_LIMSW_A_POSITION ||
                    STPR_BSY0_90_OUT_LIMSW_B_POSITION ||
                STPR_BSY0_88_OUT_LIMSW_A_POSITION ||
```

```
                    BTM_BSY0_89_OUT_LIMSW_A_POSITION    ||
                BTM_BSY0_89_OUT_CNTRL_A_PPS_CNTRL  ||
                    BTM_BSY0_89_OUT_CNTRL_B_PPS_CNTRL  ) )
{
    state = 1; /* ALL IN and NOT OUT okay to run beam */
}

else
{
    state = 2; /* do not allow beam, Moving or Inconsistent */
}
```

Name	State	PC	MS	BYKIK	LHS
IS_OUT	0	120 Hz	120 Hz	120 Hz	–
IS_IN	1	10 Hz	10 Hz	10 Hz	–
Moving or Inconsistent	2	0 Hz	0 Hz	0 Hz	–

27.101 Temperature RTD Summary: A-Line Before SL10

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	–	–
OK	T	120 Hz	120 Hz	–	–

Where
A = `RTD_BSYA_1015_PRESL10SUM_STATUS`

27.102 Temperature RTD Summary: A-line Past SL10

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `RTD_BSYA_2060_PASTSL10SUM_STATUS`

27.103 Temperature RTD Summary: BSY Common Line Before D2

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `RTD_BSY0_16_CLINESUM_STATUS`

27.104 Toroid Chassis IMBC2

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CHASIMB2_STATE`

27.105 Toroid Comparator IMBC2IN/IMBC2OUT

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Downstream > Upstream	F	T	0 Hz	0 Hz	0 Hz	–
Upstream > Downstream	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `TCBC2L1_STATE`,
B = `TCBC2L2_STATE`

27.106 Vac Valve BSYA 4005 (IV40)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_BSYA_4005_POSITION_STATE

27.107 Vac Valve: VVFS BSYA 1030 (FV10)

Name	A	PC	MS	BYKIK	LHS
NOT_OPEN	F	0 Hz	0 Hz	–	–
OPEN	T	120 Hz	120 Hz	–	–

Where
A = VVFS_BSYA_1030_POSITION_STATE

27.108 Vac Valve: VVFS BSYA 2855 (FV28)

Name	A	PC	MS	BYKIK	LHS
NOT_OPEN	F	0 Hz	0 Hz	0 Hz	–
OPEN	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVFS_BSYA_2855_POSITION_STATE

27.109 Vac Valve: VVPG BSYA 1018 (IV10)

Name	A	PC	MS	BYKIK	LHS
NOT_OPEN	F	0 Hz	0 Hz	–	–
OPEN	T	120 Hz	120 Hz	–	–

Where
A = VVPG_BSYA_1018_POSITION_STATE

27.110 Vac Valve: VVPG BSYA 2635 (IV26)

Name	A	PC	MS	BYKIK	LHS
NOT_OPEN	F	0 Hz	0 Hz	0 Hz	–
OPEN	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_BSYA_2635_POSITION_STATE

27.111 Vac Valve: VVPG ESA0 4195 POSITION (IV41)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVPG_ESA0_4195_POSITION_STATE`

27.112 VVPG BSY0 IV2 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `IV2_OPEN_STATE`

27.113 VVPG BSY0 IV3 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `IV3_OPEN_STATE`

27.114 VVPG BSY0 IV4 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `IV4_OPEN_STATE`

28 Ignored when YAG01 Is In

28.1 BXG Status

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Off	F	T	120 Hz	120 Hz	120 Hz	–
On	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BEND_IN20_231_OFF_STATE,
B = BEND_IN20_231_OK_STATE

28.2 SONYA UND FAULT TEST

Name	*B*	*A*	PC	MS	BYKIK	LHS
FAULT	F	F	0 Hz	0 Hz	0 Hz	–
UND OK	F	T	120 Hz	120 Hz	120 Hz	–
BSY OK	T	F	120 Hz	120 Hz	120 Hz	–
BOTH OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = SONYA_UND1_1_FAULT_THRESHOLD,
B = SONYA_BSY0_1_TEMPSUM_THRESHOLD

28.3 Test Temperature Logic

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = SONYA_BSY0_1_TEMPSUM_THRESHOLD

28.4 Toroid Peak Current Monitor IM01

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `TR_BL215_STATE`

28.5 YAG02 IN20 241 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `YAGS_IN20_241_OUT_LMTSW_STATE`,
B = `YAGS_IN20_241_IN_LMTSW_STATE`

29 Ignored when YAG01 Is In or YAG02 Is In

29.1 BLM/PIC Watchdog: Upstream of TDUND

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MCC0_1_PICBLM_WD_STATUS`

29.2 BX01/BX02 Status

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Off	F	T	120 Hz	120 Hz	120 Hz	–
On	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BEND_IN20_751_OFF_STATE`,
B = `BEND_IN20_751_OK_STATE`

29.3 Dump LI28 5879 Flowswitch

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `DUMP_5879_FLOW_SW_STATE`

29.4 Dump LI28 5879 Klixon

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = DUMP_5879_KLIXON_OK_STATE

29.5 Fast Shutter FV2 LI30 Position

Name	A	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_SHUTTER_FV2_OK_OPEN_STATE

29.6 Fast Shutter FV2A LI30 Position

Name	A	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_SHUTTER_FV2A_OK_OPEN_STATE

29.7 Flowswitch: CE11

Name	A	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_LI21_235_OPEN_STATE

29.8 Flowswitch: COLL LI28-9

Name	A	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FLOW_SW_28_9_STATE

29.9 Flowswitch: COLL LI29-1

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FLOW_SW_29_1_STATE

29.10 Flowswitch: COLL LI29-4

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FLOW_SW_29_4_STATE

29.11 Flowswitch: COLL LI29-5

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FLOW_SW_29_5_STATE

29.12 Flowswitch: COLL LI29-9

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FLOW_SW_29_9_STATE

29.13 Flowswitch: COLL LI30-1

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FLOW_SW_30_1_STATE

29.14 Flowswitch: COLL LI30-4

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FLOW_SW_30_4_STATE

29.15 Flowswitch: COLL LI30-5

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FLOW_SW_30_5_STATE

29.16 Flowswitch: TD11

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FS_BL305_STATE

29.17 Main Manifold Gauge: LI21 Station 5

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_LI21_STATE`

29.18 Main Manifold Gauge: LI22 Station 5

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_LI22_STATE`

29.19 Main Manifold Gauge: LI23 Station 5

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_LI23_STATE`

29.20 Main Manifold Gauge: LI24 Station 5

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_LI24_STATE`

29.21 Main Manifold Gauge: LI25 Station 5

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_LI25_STATE`

29.22 Main Manifold Gauge: LI26 Station 5

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_LI26_STATE`

29.23 Main Manifold Gauge: LI27 Station 5

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_LI27_STATE`

29.24 Main Manifold Gauge: LI28 Station 5

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_LI28_STATE`

29.25 Main Manifold Gauge: LI29 Station 5

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_STATE`

29.26 Main Manifold Gauge: LI30 Station 5

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_30_5_OK_STATE`

29.27 Main Manifold Gauge: LI30 Station 9

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_30_9_OK_STATE`

29.28 Mirror BL11 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `MIR_BL11_OUT_STATE`,
B = `MIR_BL11_IN_STATE`

29.29 OTR LI25 920 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTR_TCAV_OUT_STATE`,
B = `OTR_TCAV_IN_STATE`

29.30 OTR01 IN20 541 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_IN20_541_OUT_LMTSW_STATE`,
B = `OTRS_IN20_541_IN_LMTSW_STATE`

29.31 OTR02 IN20 571 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_IN20_571_OUT_LMTSW_STATE`,
B = `OTRS_IN20_571_IN_LMTSW_STATE`

29.32 OTR03 IN20 621 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_IN20_621_OUT_LMTSW_STATE`,
B = `OTRS_IN20_621_IN_LMTSW_STATE`

29.33 OTR04 IN20 711 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_IN20_711_OUT_LMTSW_STATE`,
B = `OTRS_IN20_711_IN_LMTSW_STATE`

29.34 OTR11 LI21 237 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_LI21_237_OUT_LMTSW_STATE`,
B = `OTRS_LI21_237_IN_LMTSW_STATE`

29.35 OTR12 LI21 291 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_LI21_291_OUT_LMTSW_STATE`,
B = `OTRS_LI21_291_IN_LMTSW_STATE`

29.36 OTRH1 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRH1_OUT_LIMIT_STATE`,
B = `OTRH1_IN_LIMIT_STATE`

29.37 OTRH2 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRH2_OUT_LIMIT_STATE`,
B = `OTRH2_IN_LIMIT_STATE`

29.38 PIC HVPS LI30 - KG30-C1322

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI30_1_HV_PWR_STATE

29.39 PIC Raw Charge Thresholds: LI24 791

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI24_791_LOSSL_THRESHOLD,
B = PICM_LI24_791_LOSSH_THRESHOLD

29.40 PIC Raw Charge Thresholds: LI24 811

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI24_811_LOSSL_THRESHOLD,
B = PICM_LI24_811_LOSSH_THRESHOLD

29.41 PIC Trigger Missed (LN16)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI24_791_NO_TRIG_MISSED

29.42 Scraper Water LI21-9 (Station 22-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI22_STATE

29.43 Scraper Water LI22-9 (Station 23-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI23_STATE

29.44 Scraper Water LI23-9 (Station 24-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI24_STATE

29.45 Scraper Water LI24-9 (Station 25-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI25_STATE

29.46 Scraper Water LI25-9 (Station 26-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI26_STATE

29.47 Scraper Water LI26-9 (Station 27-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI27_STATE

29.48 Scraper Water LI27-9 (Station 28-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI28_STATE

29.49 Scraper Water LI28-9 (Station 29-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI29_STATE

29.50 Scraper Water LI29-9 (Station 30-1)

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI30_STATE

29.51 Stopper LI28 950 and 960 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = BASII_STOPPER_OUT_STATE

29.52 Sub-booster Ready: LI21

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SBST_OK_READY_LI21_STATE

29.53 Sub-booster Ready: LI22

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SBST_OK_READY_LI22_STATE

29.54 Sub-booster Ready: LI25

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_SBST_OK_READY_LI25_STATE`

29.55 Sub-booster Ready: LI26

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_SBST_OK_READY_LI26_STATE`

29.56 Sub-booster Ready: LI27

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_SBST_OK_READY_LI27_STATE`

29.57 Sub-booster Ready: LI28

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_SBST_OK_READY_LI28_STATE`

29.58 Sub-booster Ready: LI29

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SBST_OK_READY_LI29_STATE

29.59 Sub-booster Ready: LI30

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SBST_OK_READY_LI30_STATE

29.60 TD11 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	–	–
Out	F	T	120 Hz	120 Hz	–	–
In	T	F	120 Hz	120 Hz	–	–
Broken	T	T	0 Hz	0 Hz	–	–

Where
A = TD11_OUT_LIMIT_STATE,
B = TD11_IN_LIMIT_STATE

29.61 Toroid Chassis IM11

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = CHASIM11_STATE

29.62 Toroid Chassis IM12

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CHASIM12_STATE`

29.63 Toroid Comparator IMBC1IN/IMBC1OUT

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Downstream - Upstream > 50 pC	F	T	0 Hz	0 Hz	0 Hz	–
Upstream - Downstream > 200 pC	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `TCBC1L1_STATE`,
B = `TCBC1L2_STATE`

29.64 VVFS LI21-9 Position (Station 22-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `FAST_VLV_OPEN_LI22_STATE`

29.65 VVFS LI22-9 Position (Station 23-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `FAST_VLV_OPEN_LI23_STATE`

29.66 VVFS LI23-9 Position (Station 24-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI24_STATE

29.67 VVFS LI24-9 Position (Station 25-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI25_STATE

29.68 VVFS LI25-9 Position (Station 26-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI26_STATE

29.69 VVFS LI26-9 Position (Station 27-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI27_STATE

29.70 VVFS LI27-9 Position (Station 28-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI28_STATE

29.71 VVFS LI28-9 Position (Station 29-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI29_STATE

29.72 VVFS LI29-9 Position (Station 30-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI30_STATE

29.73 VVFV IN20 785 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVFV_IN20_785_OPEN_LMTSW_POSITION

29.74 VVMG LI21 195 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VV_BL195_STATE

29.75 VVMG LTU1 505 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0505_STATE

29.76 VVPG IN20 435 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VV_BL435_STATE

29.77 VVPG IN20 545 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VV_BL545_STATE

29.78 VVPG IN20 635 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VV_BL635_STATE

29.79 VVPG IN20 915 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VV_IS915_STATE

29.80 VVPG LI21-9 Position (Station 22-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI22_STATE

29.81 VVPG LI22-9 Position (Station 23-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI23_STATE

29.82 VVPG LI23-9 Position (Station 24-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI24_STATE

29.83 VVPG LI24 710 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VV21_STATE

29.84 VVPG LI24 896 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VV22_STATE

29.85 VVPG LI25-9 Position (Station 26-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI26_STATE

29.86 VVPG LI26-9 Position (Station 27-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI27_STATE

29.87 VVPG LI27-9 Position (Station 28-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI28_STATE

29.88 VVPG LI28-9 Position (Station 29-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI29_STATE

29.89 VVPG LI29-9 Position (Station 30-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI30_STATE

29.90 VVPG LI30-9 Position (Station 30-9)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_30_9_OK_OPEN_STATE

29.91 VVS Circuit Breaker: LI22

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVS_BRKR_OK_READY_LI22_STATE

29.92 VVS Circuit Breaker: LI24

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVS_BRKR_OK_READY_LI24_STATE

29.93 VVS Circuit Breaker: LI26

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVS_BRKR_OK_READY_LI26_STATE

29.94 VVS Circuit Breaker: LI28

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVS_BRKR_OK_READY_LI28_STATE

29.95 VVS Circuit Breaker: LI30

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVS_BRKR_OK_READY_LI30_STATE

29.96 YAG03 IN20 351 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = YAGS_IN20_351_OUT_LMTSW_STATE,
B = YAGS_IN20_351_IN_LMTSW_STATE

29.97 YAGS1 IN20 921 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = YAGS_IN20_921_OUT_LMTSW_STATE,
B = YAGS_IN20_921_IN_LMTSW_STATE

29.98 YAGS2 LI21 995 Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = YAGS_LI21_995_OUT_LMTSW_STATE,
B = YAGS_LI21_995_IN_LMTSW_STATE

30 Always Evaluated

30.1 Backward Beam Stopper (RST1)

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `ST_BL551_STATE`

30.2 BLM/PIC Watchdog: IN20

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_IN20_1_PICBLM_WD_STATUS`

30.3 Bypass Recover

Name	*A*	PC	MS	BYKIK	LHS
Recovering	F	0 Hz	0 Hz	0 Hz	0 Hz
OK	T	120 Hz	120 Hz	120 Hz	120 Hz

Where
A = `LP_BYPASS_RECOVER`

30.4 DPS Temperature LI30

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `DPS_TEMP_STATE`

30.5 Gun RF Peak Power 20-6

Name	*A*	PC	MS	BYKIK	LHS
OK	F	120 Hz	120 Hz	120 Hz	–
Fault	T	0 Hz	0 Hz	0 Hz	–

Where
A = FLT_20_6_TRP_STATE

30.6 Gun Waveguide Vacuum Summary

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = WGVACGUN_STATE

30.7 IOC-IN20-MP01 MPS Support IOC Heartbeat

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MN_HEART_STATE

30.8 Laser Heater Attenuator Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	–	–	–	0 Hz
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	–	–	–	0 Hz

Where
A = LHATTEN_OUT_LIMIT_STATE,
B = LHATTEN_IN_LIMIT_STATE

30.9 MCC Emergency Radiation Stopper

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `EMG_RAD_STOP_STATE`

30.10 Mechanical Shutter Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	–	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	–	0 Hz	–

Where
A = `MPS_IN20_200_MSHT1_OUT_FAULT`,
B = `MPS_IN20_200_MSHT1_IN_FAULT`

30.11 Mirror AM01 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MR_BL191_STATE`

30.12 MPS Beam Permit: BYKIK

Name	*A*	PC	MS	BYKIK	LHS
Not Permitted	F	–	–	0 Hz	–
Permitted	T	–	–	120 Hz	–

Where
A = `LP_ALLOWS_BEAM_BYKIK`

30.13 MPS Beam Permit: Gun RF

Name	*A*	PC	MS	BYKIK	LHS
Not Permitted	F	0 Hz	–	–	–
Permitted	T	120 Hz	–	–	–

Where
A = LP_ALLOWS_BEAM_POCKELS_CELL

30.14 MPS Beam Permit: Heater Shutter

Name	*A*	PC	MS	BYKIK	LHS
Not Permitted	F	–	–	–	0 Hz
Permitted	T	–	–	–	120 Hz

Where
A = LP_ALLOWS_BEAM_LH_SHUT

30.15 MPS Beam Permit: Mechanical Shutter

Name	*A*	PC	MS	BYKIK	LHS
Not Permitted	F	–	0 Hz	–	–
Permitted	T	–	120 Hz	–	–

Where
A = LP_ALLOWS_BEAM_MECH_SHUT

30.16 MPS Mechanical Shutter Position

Name	*A*	PC	MS	BYKIK	LHS
OK	F	120 Hz	120 Hz	120 Hz	–
Readback Does Not Match	T	0 Hz	0 Hz	0 Hz	–

Where
A = SHFLT_STATE

30.17 PIC HVPS LI20 - Location LKG-1535

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI20_1_HV_PWR_STATE

30.18 PIC Raw Charge Thresholds: BSY0 16

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSY0_16_LOSSL_THRESHOLD,
B = PICM_BSY0_16_LOSSH_THRESHOLD

30.19 PIC Raw Charge Thresholds: BSY0 33

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSY0_33_LOSSL_THRESHOLD,
B = PICM_BSY0_33_LOSSH_THRESHOLD

30.20 PIC Raw Charge Thresholds: BSY0 45

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSY0_45_LOSSL_THRESHOLD`,
B = `PICM_BSY0_45_LOSSH_THRESHOLD`

30.21 PIC Raw Charge Thresholds: BSY0 59

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSY0_59_LOSSL_THRESHOLD`,
B = `PICM_BSY0_59_LOSSH_THRESHOLD`

30.22 PIC Raw Charge Thresholds: BSY0 78A

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSY0_78A_LOSSL_THRESHOLD`,
B = `PICM_BSY0_78A_LOSSH_THRESHOLD`

30.23 PIC Raw Charge Thresholds: BSY0 78B

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSY0_78B_LOSSL_THRESHOLD`,
B = `PICM_BSY0_78B_LOSSH_THRESHOLD`

30.24 PIC Raw Charge Thresholds: IN20 185

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_IN20_185_LOSSL_THRESHOLD`,
B = `PICM_IN20_185_LOSSH_THRESHOLD`

30.25 PIC Raw Charge Thresholds: IN20 232

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_IN20_232_LOSSL_THRESHOLD`,
B = `PICM_IN20_232_LOSSH_THRESHOLD`

30.26 PIC Raw Charge Thresholds: IN20 245

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_IN20_245_LOSSL_THRESHOLD,
B = PICM_IN20_245_LOSSH_THRESHOLD

30.27 PIC Raw Charge Thresholds: IN20 665

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_IN20_665_LOSSL_THRESHOLD,
B = PICM_IN20_665_LOSSH_THRESHOLD

30.28 PIC Raw Charge Thresholds: IN20 775

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_IN20_775_LOSSL_THRESHOLD,
B = PICM_IN20_775_LOSSH_THRESHOLD

30.29 PIC Raw Charge Thresholds: IN20 933

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_IN20_933_LOSSL_THRESHOLD`,
B = `PICM_IN20_933_LOSSH_THRESHOLD`

30.30 PIC Raw Charge Thresholds: LI28 916

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI28_916_LOSSL_THRESHOLD`,
B = `PICM_LI28_916_LOSSH_THRESHOLD`

30.31 PIC Raw Charge Thresholds: LI29 146

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI29_146_LOSSL_THRESHOLD`,
B = `PICM_LI29_146_LOSSH_THRESHOLD`

30.32 PIC Raw Charge Thresholds: LI29 446

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI29_446_LOSSL_THRESHOLD,
B = PICM_LI29_446_LOSSH_THRESHOLD

30.33 PIC Raw Charge Thresholds: LI29 546

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI29_546_LOSSL_THRESHOLD,
B = PICM_LI29_546_LOSSH_THRESHOLD

30.34 PIC Raw Charge Thresholds: LI29 801

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI29_801_LOSSL_THRESHOLD,
B = PICM_LI29_801_LOSSH_THRESHOLD

30.35 PIC Raw Charge Thresholds: LI29 956

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI29_956_LOSSL_THRESHOLD`,
B = `PICM_LI29_956_LOSSH_THRESHOLD`

30.36 PIC Raw Charge Thresholds: LI30 146

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI30_146_LOSSL_THRESHOLD`,
B = `PICM_LI30_146_LOSSH_THRESHOLD`

30.37 PIC Raw Charge Thresholds: LI30 446

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI30_446_LOSSL_THRESHOLD`,
B = `PICM_LI30_446_LOSSH_THRESHOLD`

30.38 PIC Raw Charge Thresholds: LI30 546

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI30_546_LOSSL_THRESHOLD,
B = PICM_LI30_546_LOSSH_THRESHOLD

30.39 PIC Raw Charge Thresholds: LI30 801

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI30_801_LOSSL_THRESHOLD,
B = PICM_LI30_801_LOSSH_THRESHOLD

30.40 PIC Trigger Missed (LN11)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_IN20_665_NO_TRIG_MISSED

30.41 PIC Trigger Missed (LN22)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI28_916_NO_TRIG_MISSED

30.42 PIC Trigger Missed (LN25)

Name	A	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSY0_16_NO_TRIG_MISSED

30.43 Pockels Cell AND Gate 100

Name	A	PC	MS	BYKIK	LHS
Bypassed	F	0 Hz	0 Hz	0 Hz	–
Active	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_IN20_100_ANDALLACTV_STATE

30.44 Pockels Cell AND Gate 200

Name	A	PC	MS	BYKIK	LHS
Bypassed	F	0 Hz	0 Hz	0 Hz	–
Active	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_IN20_200_ANDALLACTV_STATE

30.45 Rate Request: BYKIK 1 Hz

Name	A	PC	MS	BYKIK	LHS
Not Requested	F	–	–	120 Hz	–
Requested	T	–	–	1 Hz	–

Where
A = LP_MAX_RATE_BYKIK_1_HZ

30.46 Rate Request: BYKIK 10 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	–	–	120 Hz	–
Requested	T	–	–	10 Hz	–

Where
A = LP_MAX_RATE_BYKIK_10_HZ

30.47 Rate Request: BYKIK 30 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	–	–	120 Hz	–
Requested	T	–	–	30 Hz	–

Where
A = LP_MAX_RATE_BYKIK_30_HZ

30.48 Rate Request: BYKIK 60 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	–	–	120 Hz	–
Requested	T	–	–	60 Hz	–

Where
A = LP_MAX_RATE_BYKIK_60_HZ

30.49 Rate Request: BYKIK Burst

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	–	–	120 Hz	–
Requested	T	–	–	Burst Mode	–

Where
A = LP_MAX_RATE_BYKIK_BURST

30.50 Rate Request: BYKIK Single Shot

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	–	–	120 Hz	–
Requested	T	–	–	Single Shot	–

Where
A = LP_MAX_RATE_BYKIK_SINGLE_SHOT

30.51 Rate Request: Pockels Cell 1 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	120 Hz	–	–	–
Requested	T	1 Hz	–	–	–

Where
A = LP_MAX_RATE_PC_1_HZ

30.52 Rate Request: Pockels Cell 10 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	120 Hz	–	–	–
Requested	T	10 Hz	–	–	–

Where
A = LP_MAX_RATE_PC_10_HZ

30.53 Rate Request: Pockels Cell 30 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	120 Hz	–	–	–
Requested	T	30 Hz	–	–	–

Where
A = LP_MAX_RATE_PC_30_HZ

30.54 Rate Request: Pockels Cell 60 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	120 Hz	–	–	–
Requested	T	60 Hz	–	–	–

Where
A = LP_MAX_RATE_PC_60_HZ

30.55 Rate Request: Pockels Cell Burst

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	120 Hz	–	–	–
Requested	T	Burst Mode	–	–	–

Where
A = LP_MAX_RATE_PC_BURST

30.56 Rate Request: Pockels Cell Single Shot

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	120 Hz	–	–	–
Requested	T	Single Shot	–	–	–

Where
A = LP_MAX_RATE_PC_SINGLE_SHOT

30.57 VVMG IN20 175 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VV_BL175_STATE

30.58 VVPG IN20 155 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VV_BL155_STATE

30.59 VVS Circuit Breaker: LI20

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVS_BRKR_OK_READY_LI20_STATE

30.60 YAG01 IN20 211 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = YAGS_IN20_211_OUT_LMTSW_STATE,
B = YAGS_IN20_211_IN_LMTSW_STATE

30.61 YAGG1 IN20 841 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = YAGS_IN20_841_OUT_LMTSW_STATE,
B = YAGS_IN20_841_IN_LMTSW_STATE

31 Ignore Logic

31.1 BX01/BX02 Is Off

Name	*B*	*A*	PC	MS	BYKIK	LHS
Off	F	T	–	–	–	–

Where
A = BEND_IN20_751_OFF_STATE,
B = BEND_IN20_751_OK_STATE

31.2 BX01/BX02 Is On

Name	*B*	*A*	PC	MS	BYKIK	LHS
On	T	F	–	–	–	–

Where
A = BEND_IN20_751_OFF_STATE,
B = BEND_IN20_751_OK_STATE

31.3 BXG Is Off

Name	*B*	*A*	PC	MS	BYKIK	LHS
Off	F	T	–	–	–	–

Where
A = BEND_IN20_231_OFF_STATE,
B = BEND_IN20_231_OK_STATE

31.4 BXG Is On

Name	*B*	*A*	PC	MS	BYKIK	LHS
On	T	F	–	–	–	–

Where
A = BEND_IN20_231_OFF_STATE,
B = BEND_IN20_231_OK_STATE

31.5 Diag Stopper HFX DG2 Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = HFX_DG2_STP_01_IN_DI_POSITION

31.6 Diag Stopper HFX UM6 Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = HFX_UM6_STP_01_IN_DI_POSITION

31.7 Diag Stopper XCS SB1 Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = XCS_SB1_STP_01_CLS_DI_POSITION

31.8 Laser Heater Attenuator Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = LHATTEN_IN_LIMIT_STATE

31.9 LTU Dechirper Is Out

Name	*D*	*C*	*B*	*A*	PC	MS	BYKIK	LHS
Out	T	T	T	T	–	–	–	–

Where
A = DCHP_LTU1_545_OUT_LIMSW_NEGY_POSITION,
B = DCHP_LTU1_545_OUT_LIMSW_POSY_POSITION,
C = DCHP_LTU1_555_OUT_LIMSW_NEGX_POSITION,
D = DCHP_LTU1_555_OUT_LIMSW_POSX_POSITION

31.10 M3H Mirror Is In Beam

Name	*A*	PC	MS	BYKIK	LHS
Is_IN	T	–	–	–	–

Where
A = HXX_HXM_MMS_01_INBEAM_POSITION

31.11 M3H Mirror Is Out of Beam

Name	*A*	PC	MS	BYKIK	LHS
IS_OUT	T	–	–	–	–

Where
A = HXX_HXM_MMS_01_B_POSITION

31.12 Spoiler SP0 Is In

Name	*A*	PC	MS	BYKIK	LHS
Is In	T	–	–	–	–

Where
A = SPLR_DMP1_765_IN_LIMSW_POSITION

31.13 ST1/ST2 Are In

Name	*B*	*A*	PC	MS	BYKIK	LHS
In	T	F	–	–	–	–

Where
A = STPR_FEE1_1_ST1ST2OUT_POSITION,
B = STPR_FEE1_1_ST1ST2IN_POSITION

31.14 Stopper S1 Is In

Name	*A*	PC	MS	BYKIK	LHS
Is In	T	–	–	–	–

Where
A = STPR_FEE1_1_S1IN_POSITION

31.15 Stopper S2 Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = STPR_FEE1_1_S2IN_STATE

31.16 Stopper S2B Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = STPR_FEE1_1_S2BIN_STATE

31.17 Stopper S5B Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = STPR_FEH1_5_S5BIN_POSITION

31.18 Stopper SH1 Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = STPR_FEE1_1_SH1IN_STATE

31.19 Stopper SH2 Is In

Name	B	A	PC	MS	BYKIK	LHS
In	T	F	–	–	–	–

Where
A = STPR_XRT1_1_SH2OUT_STATE,
B = STPR_XRT1_1_SH2IN_STATE

31.20 Stopper XRT S5 Is In

Name	A	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = STPR_XRT1_1_S5IN_POSITION

31.21 Stopper XRT S6 Is In

Name	A	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = STPR_XRT1_1_S6IN_POSITION

31.22 Stopper: BSY D2 Summary Is In

Name	B	A	PC	MS	BYKIK	LHS
In	T	T	–	–	–	–

Where
A = STPR_BSY0_88_IN_LIMSW_A_POSITION,
B = STPR_BSY0_88_IN_LIMSW_B_POSITION

31.23 TD11 Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = TD11_IN_LIMIT_STATE

31.24 TDUND Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = DUMP_LTU1_970_TDUND_IN_POSITION

31.25 XCS Is Not In Main Line

Name	*A*	PC	MS	BYKIK	LHS
Not in	F	–	–	–	–

Where
A = XCS_SB_POS_HARD_POSITION

31.26 XPP-NH3-POS-00 Beamline Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = XPP_NH3_POS_00_IN_STATE

31.27 XPP-NH3-POS-00 Beamline Is Not In

Name	*A*	PC	MS	BYKIK	LHS
Not_IN	F	–	–	–	–

Where
A = XPP_NH3_POS_00_IN_STATE

31.28 YAG01 Is In

Name	B	A	PC	MS	BYKIK	LHS
In	T	F	–	–	–	–

Where
A = YAGS_IN20_211_OUT_LMTSW_STATE,
B = YAGS_IN20_211_IN_LMTSW_STATE

31.29 YAG02 Is In

Name	A	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = YAGS_IN20_241_IN_LMTSW_STATE