MPS Logic:
2018-03-21-a

Contents

1 Ignored when A-Line Kicker Is Not Enabled, A-Line SL10 Is Closed, TD11 Is In, YAG01 Is In, or YAG02 Is In **19**
1.1 Flowswitch: COLL BSYA 2060 (PC20) . . . 19
1.2 Flowswitch: COLL BSYA 2410 (COLL24H) . . . 19
1.3 Flowswitch: COLL BSYA 2410 (COLL24V) . . . 19
1.4 Flowswitch: COLL BSYA 2410 (PC24) . . . 19
1.5 Flowswitch: COLL BSYA 2600 (PC26) . . . 20
1.6 Flowswitch: COLL BSYA 2990 (PC29) . . . 20
1.7 Flowswitch: COLL BSYA 3710 (C37) . . . 20
1.8 Flowswitch: COLL BSYA 4120 (3C1A) . . . 20
1.9 PIC Raw Charge Thresholds: BSYA 2061 . . . 21
1.10 PIC Raw Charge Thresholds: BSYA 2120 . . . 21
1.11 PIC Raw Charge Thresholds: BSYA 2220 . . . 21
1.12 PIC Raw Charge Thresholds: BSYA 2321 . . . 22
1.13 PIC Raw Charge Thresholds: BSYA 2411 . . . 22
1.14 PIC Raw Charge Thresholds: BSYA 2472 . . . 22
1.15 PIC Raw Charge Thresholds: BSYA 2473 . . . 23
1.16 PIC Raw Charge Thresholds: BSYA 2474 . . . 23
1.17 PIC Raw Charge Thresholds: BSYA 2475 . . . 23
1.18 PIC Raw Charge Thresholds: BSYA 2520 . . . 24
1.19 PIC Raw Charge Thresholds: BSYA 2601 . . . 24
1.20 PIC Raw Charge Thresholds: BSYA 2861 . . . 24
1.21 PIC Raw Charge Thresholds: BSYA 2990 . . . 25
1.22 PIC Raw Charge Thresholds: BSYA 3320 . . . 25
1.23 PIC Raw Charge Thresholds: BSYA 3720 . . . 25
1.24 PIC Raw Charge Thresholds: BSYA 3721 . . . 26
1.25 PIC Raw Charge Thresholds: BSYA 3890 . . . 26
1.26 PIC Trigger Missed (LN42) . . . 26
1.27 Stopper BSYA 2275 (ST22) Position . . . 27
1.28 Stopper BSYA 2930 (ST29) Position . . . 27
1.29 Temperature RTD Summary: A-line Past SL10 . . . 27
1.30 Vac Valve BSYA 4005 (IV40) . . . 27
1.31 Vac Valve: VVFS BSYA 2855 (FV28) . . . 28
1.32 Vac Valve: VVPG BSYA 2635 (IV26) . . . 28
1.33 Vac Valve: VVPG ESA0 4195 POSITION (IV41) . . . 28

2 Ignored when A-Line Kicker Is Not Enabled, TD11 Is In, YAG01 Is In, or YAG02 Is In **29**
2.1 A-Line SL10 Position . . . 29
2.2 Flowswitch: BPM BSYA 1020 (BPM10) . . . 29
2.3 Flowswitch: BPM BSYA 1240 (BPM12) . . . 30

2.4 Flowswitch: COLL BSYA 1015 (PC10) . . . 30
2.5 Flowswitch: COLL BSYA 1230 (PC12) . . . 30
2.6 Flowswitch: COLL BSYA 1490 (PC14) . . . 30
2.7 Flowswitch: COLL BSYA 1700 (PC17) . . . 31
2.8 PIC Raw Charge Thresholds: BSYA 1016 . . . 31
2.9 PIC Raw Charge Thresholds: BSYA 1021 . . . 31
2.10 PIC Raw Charge Thresholds: BSYA 1120 . . . 32
2.11 PIC Raw Charge Thresholds: BSYA 1320 . . . 32
2.12 PIC Raw Charge Thresholds: BSYA 1520 . . . 32
2.13 PIC Raw Charge Thresholds: BSYA 1701A . . . 33
2.14 PIC Raw Charge Thresholds: BSYA 1701B . . . 33
2.15 PIC Raw Charge Thresholds: BSYA 1980 . . . 33
2.16 Temperature RTD Summary: A-Line Before SL10 . . . 34
2.17 Vac Valve: VVFS BSYA 1030 (FV10) . . . 34
2.18 Vac Valve: VVPG BSYA 1018 (IV10) . . . 34
2.19 VVPG BSYA 340 Position . . . 34

3 Ignored when BX01/BX02 Is Off, YAG01 Is In, or YAG02 Is In 35
3.1 Toroid Comparator Dogleg 1 (IM02 vs IM03) . . . 35

4 Ignored when BX01/BX02 Is On, YAG01 Is In, or YAG02 Is In 36
4.1 BXS Status . . . 36
4.2 Toroid Comparator Inj Spectrometer (IM02 vs IMS1) . . . 36

5 Ignored when BXG Is Off or YAG01 Is In 37
5.1 Wakefield Shield Gun Spectrometer . . . 37

6 Ignored when BXG Is On or YAG01 Is In 38
6.1 Wakefield Shield Straight Ahead . . . 38

7 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Diag Stopper XCS SB1 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XCS Is Not In Main Line, YAG01 Is In, or YAG02 Is In 39
7.1 XCS SB1 VGC 02 Gate Valve Position . . . 39
7.2 XCS SB2 VGC 01 Gate Valve Position . . . 39

8 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Stopper S5B Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 40
8.1 CXI Configuration 1 Summary . . . 40
8.2 CXI Configuration 2 Summary . . . 41
8.3 CXI Configuration 3 Summary . . . 42
8.4 CXI Configuration 4 Summary . . . 44
8.5 CXI Configuration 5 Summary . . . 45
8.6 CXI Configuration 6 Summary . . . 46

8.7 CXI Configuration 7 Summary . . . 47
8.8 CXI KB2 VGC 02 Gate Valve Position . . . 48
8.9 CXI MPS PLC Readiness Status . . . 48
8.10 CXI User Patch Panel 1 Ready . . . 49
8.11 CXI User Patch Panel 2 Ready . . . 49
8.12 CXI:DG1:VGC:01 Gate Valve Open Position . . . 49
8.13 CXI:DG1:VGC:02 Gate Valve Open Position . . . 49
8.14 CXI:DG2:VGC:01 Gate Valve Position . . . 50
8.15 CXI:DG2:VGC:02 Gate Valve Position . . . 50
8.16 CXI:DG4:VGC:01 Gate Valve Position . . . 50
8.17 CXI:DSC:VGC:01 Gate Valve Position . . . 51
8.18 CXI:KB1:VGC:01 Gate Valve Open Position . . . 51
8.19 CXI:KB1:VGC:02 Gate Valve Open Position . . . 51
8.20 CXI:KB2:VGC:01 Gate Valve Open Position . . . 51
8.21 CXI:SC1:VGC:01 Gate Valve Position . . . 52
8.22 CXI:SC3:VGC:01 Be Gate Valve Position - Status from PLC . . . 52
8.23 HF4 LAM VGC 01 Gate Valve Position . . . 52

9 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XCS Is Not In Main Line, YAG01 Is In, or YAG02 Is In 53
9.1 XCS SB1 Diagnostic Stopper Position . . . 53
9.2 XCS SB1 VGC 01 Gate Valve Position . . . 53

10 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 54
10.1 CXI XRT Laser Reference Mirror Position . . . 54
10.2 HFA:SND:VGC:01 Gate Valve Open Position . . . 54
10.3 HFX:DIA:VGC:02 Gate Valve Open Position . . . 54
10.4 PPS Stopper S5B Position . . . 55
10.5 XRT HXRAY DIA Isolation Valve HXX-DIA-VGC-01 . . . 55

11 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 56
11.1 HFX:DG2:VGC:01 Gate Valve Position . . . 56
11.2 HFX:MON:VGC:01 Gate Valve Position . . . 56
11.3 HFX:MON:VGC:02 Gate Valve Position . . . 56
11.4 Stopper XRT S5 Position . . . 57

12 Ignored when Diag Stopper HFX UM6 Is In, Stopper MFX S4.5 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 58
12.1 MFX MPS Summary - Downstream of Stopper 4.5 . . . 58

13 Ignored when Diag Stopper HFX UM6 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S6 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In **59**
13.1 MEC DV4 VCG 01 Gate Valve Position . . . 59
13.2 MEC DV5 VGC 01 Gate Valve Position . . . 59
13.3 MEC HXM VGC 01 Gate Valve Position . . . 59
13.4 MEC XT1 Reference Laser Position . . . 60
13.5 MEC XT1 VGC 01 Gate Valve Position . . . 60
13.6 MEC XT2 VGC 02 Gate Valve Position . . . 60
13.7 MEC XT2 VGC 03 Gate Valve Position . . . 60
13.8 MEC XT2 VGC 04 Gate Valve Position . . . 61
13.9 MEC XT2 VGC 05 Gate Valve Position . . . 61
13.10 MEC XT2 VGC 06 Gate Valve Position . . . 61

14 Ignored when Diag Stopper HFX UM6 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In **62**
14.1 DG2 Diagnostic Stopper Position . . . 62
14.2 MEC BXL VGC 01 Gate Valve Position . . . 62
14.3 MEC XRT Attenuator Inspection Mirror Position . . . 62
14.4 MFX Gate Valve Summary - Upstream of Stopper 4.5 . . . 63
14.5 Stopper MFX S4.5 Position . . . 63
14.6 Stopper XRT S6 Position . . . 63
14.7 XRT HXRAY LOM Isolation Valve HXX-LOM-VGC-01 . . . 64
14.8 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:01 . . . 64
14.9 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:02 . . . 64
14.10 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:03 . . . 65
14.11 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:05 . . . 65
14.12 XRT-M2 Mirror and DG2 STP Fault . . . 65

15 Ignored when Laser Heater Attenuator Is In **66**
15.1 Laser Heater Photodiode Shutter Position . . . 66
15.2 OTRH1 Position When LH Atten Not In . . . 66
15.3 OTRH2 Position When LH Atten Not In . . . 66

16 Ignored when Stopper S1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In **67**
16.1 NEH AMO Laser Reference Mirror Position . . . 67
16.2 NEH AMO Valves Ok for Beam - Summary From PLC . . . 67
16.3 NEH1 Camera 1124 Position . . . 67
16.4 NEH1 XTOD S1 Isolation Valve Summary . . . 68

17 Ignored when Stopper S2 Is In, Stopper S2B Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In **69**
17.1 NEH SXR Differential Pump Isolation Valve SXR-DFP-VGC-01 . . . 69
17.2 NEH SXR End Station Ready SXR-EXP-MPS-01 . . . 69

17.3 NEH SXR Intensity Monitor Isolation Valve SXR-FLX-VGC-01 69
17.4 NEH SXR KB Optics Isolation Valve SXR-KBO-VGC-01 70
17.5 NEH SXR Laser In-coupling Mirror Isolation Valve SXR-LIN-VGC-01 70

18 Ignored when Stopper S2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 71
18.1 NEH Camera 2124 Position 71
18.2 NEH SXR Collimator 3 Isolation Valve SXR-COL-VGC-01 71
18.3 NEH SXR Exit Slits Isolation Valve SXR-EXS-VGC-01 72
18.4 NEH SXR GMD VGC 01 Protection 72
18.5 NEH SXR Monochromator Tank Isolation Valve SXR-MON-VGC-01 72
18.6 NEH SXR Photon Stoppers Isolation Valve SXR-PST-VGC-01 73
18.7 NEH SXR Transmission Sample System Isolation Valve SXR-TSS-VGC-01 73
18.8 NEH SXR Zero Order Interlock SXR-MON-MMS-06, SXR-EXS-MMS-01 73
18.9 NEH1 XTOD S2 Isolation Valve Summary 74

19 Ignored when Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 75
19.1 UM6 Diagnostic Stopper Position 75
19.2 XRT HXRAY UM6 Isolation Valve HXX-UM6-VGC-01 75
19.3 XRT UM6 Camera Position HXX-UM6-CVP-01 76

20 Ignored when Stopper SH1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XPP-NH3-POS-00 Beamline Is In, YAG01 Is In, or YAG02 Is In 77
20.1 NEH3 HXRAY DVD Isolation Valve HX3-DVD-VGC-01 77

21 Ignored when Stopper SH1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XPP-NH3-POS-00 Beamline Is Not In, YAG01 Is In, or YAG02 Is In 78
21.1 XPP SB2 VGC 01 Gate Valve Position 78
21.2 XPP SB2 VGC 02 Gate Valve Position 78
21.3 XPP SB2 VGC 03 Gate Valve Position 78

22 Ignored when Stopper SH1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 79
22.1 HX2 UVD VGC 01 Gate Valve Position 79
22.2 HX3 MON VGC 01 Gate Valve Position 79
22.3 NEH HXTD Vacuum Valve Summary 79
22.4 NEH1 Camera 124 Position 80
22.5 NEH1 Camera 195 Position 80
22.6 NEH2 HXRAY DVD Isolation Valve HX2-DVD-VGC-01 80
22.7 NEH3 HXRAY UVD Isolation Valve HX3-UVD-VGC-01 81

23 Ignored when Stopper: BSY D2 Summary Is In or TDUND Is In 82
23.1 HXRSS Beamline Position 82
23.2 HXRSS Chicane Bend Magnet Power Supply 82
23.3 HXRSS Crystal Position 82

23.4 HXRSS Crystal Valid Position . . . 83
23.5 HXRSS Mode State . . . 83
23.6 SXRSS Grating/M1 GRAT UND1 934 Position . . . 85
23.7 SXRSS M2 MIRR UND1 964 Position . . . 85
23.8 SXRSS M3 MIRR UND1 966 Position . . . 86
23.9 SXRSS Mode State . . . 86
23.10 SXRSS SLIT UND1 962 Position . . . 89
23.11 SXRSS Watchdog . . . 89

24 Ignored when Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In 90
24.1 BCS PIC RAW Charge Threshold DMP 997 . . . 90
24.2 BCS PIC RAW Charge Threshold DMP 998 . . . 90
24.3 BFW 1010 Position . . . 90
24.4 BFW 110 Position . . . 91
24.5 BFW 1110 Position . . . 91
24.6 BFW 1210 Position . . . 91
24.7 BFW 1310 Position . . . 92
24.8 BFW 1410 Position . . . 92
24.9 BFW 1510 Position . . . 92
24.10 BFW 1610 Position . . . 93
24.11 BFW 1710 Position . . . 93
24.12 BFW 1810 Position . . . 93
24.13 BFW 1910 Position . . . 94
24.14 BFW 2010 Position . . . 94
24.15 BFW 210 Position . . . 94
24.16 BFW 2110 Position . . . 95
24.17 BFW 2210 Position . . . 95
24.18 BFW 2310 Position . . . 95
24.19 BFW 2410 Position . . . 96
24.20 BFW 2510 Position . . . 96
24.21 BFW 2610 Position . . . 96
24.22 BFW 2710 Position . . . 97
24.23 BFW 2810 Position . . . 97
24.24 BFW 2910 Position . . . 97
24.25 BFW 3010 Position . . . 98
24.26 BFW 310 Position . . . 98
24.27 BFW 3110 Position . . . 98
24.28 BFW 3210 Position . . . 99
24.29 BFW 3310 Position . . . 99
24.30 BFW 410 Position . . . 99
24.31 BFW 510 Position . . . 100
24.32 BFW 610 Position . . . 100
24.33 BFW 710 Position . . . 100
24.34 BFW 810 Position . . . 101

24.35 BFW 910 Position . . . 101
24.36 BFW Inserted Count . . . 101
24.37 BLM Argonne Heartbeat (LN32) . . . 103
24.38 BLM Argonne Heartbeat (LN33) . . . 103
24.39 BLM Argonne Heartbeat (LN35) . . . 103
24.40 BLM Argonne Heartbeat (LN36) . . . 104
24.41 BLM Argonne Heartbeat (LN37) . . . 104
24.42 BLM HVPS UND1 120 . . . 104
24.43 BLM HVPS UND1 1720 . . . 105
24.44 BLM HVPS UND1 2221 . . . 105
24.45 BLM HVPS UND1 2520 . . . 105
24.46 BLM HVPS UND1 3320 . . . 106
24.47 BLM HVPS UND1 920 . . . 106
24.48 BLM Pedestal Thresholds: LTU1 722 . . . 106
24.49 BLM Pedestal Thresholds: LTU1 732 . . . 107
24.50 BLM Pedestal Thresholds: LTU1 762 . . . 107
24.51 BLM Pedestal Thresholds: LTU1 772 . . . 107
24.52 BLM Pedestal Thresholds: LTU1 980 . . . 108
24.53 BLM Pedestal Thresholds: UND 1021 . . . 108
24.54 BLM Pedestal Thresholds: UND 1121 . . . 108
24.55 BLM Pedestal Thresholds: UND 120 . . . 109
24.56 BLM Pedestal Thresholds: UND 121 . . . 109
24.57 BLM Pedestal Thresholds: UND 1221 . . . 109
24.58 BLM Pedestal Thresholds: UND 1321 . . . 110
24.59 BLM Pedestal Thresholds: UND 1421 . . . 110
24.60 BLM Pedestal Thresholds: UND 1521 . . . 110
24.61 BLM Pedestal Thresholds: UND 1621 . . . 111
24.62 BLM Pedestal Thresholds: UND 1720 . . . 111
24.63 BLM Pedestal Thresholds: UND 1721 . . . 111
24.64 BLM Pedestal Thresholds: UND 1821 . . . 112
24.65 BLM Pedestal Thresholds: UND 1921 . . . 112
24.66 BLM Pedestal Thresholds: UND 2021 . . . 112
24.67 BLM Pedestal Thresholds: UND 2121 . . . 113
24.68 BLM Pedestal Thresholds: UND 221 . . . 113
24.69 BLM Pedestal Thresholds: UND 2221 . . . 113
24.70 BLM Pedestal Thresholds: UND 2321 . . . 114
24.71 BLM Pedestal Thresholds: UND 2421 . . . 114
24.72 BLM Pedestal Thresholds: UND 2520 . . . 114
24.73 BLM Pedestal Thresholds: UND 2521 . . . 115
24.74 BLM Pedestal Thresholds: UND 2621 . . . 115
24.75 BLM Pedestal Thresholds: UND 2721 . . . 115
24.76 BLM Pedestal Thresholds: UND 2821 . . . 116
24.77 BLM Pedestal Thresholds: UND 2921 . . . 116
24.78 BLM Pedestal Thresholds: UND 3021 . . . 116
24.79 BLM Pedestal Thresholds: UND 3121 . . . 117

24.80 BLM Pedestal Thresholds: UND 321 . . . 117
24.81 BLM Pedestal Thresholds: UND 3221 . . . 117
24.82 BLM Pedestal Thresholds: UND 3320 . . . 118
24.83 BLM Pedestal Thresholds: UND 3321 . . . 118
24.84 BLM Pedestal Thresholds: UND 421 . . . 118
24.85 BLM Pedestal Thresholds: UND 521 . . . 119
24.86 BLM Pedestal Thresholds: UND 621 . . . 119
24.87 BLM Pedestal Thresholds: UND 721 . . . 119
24.88 BLM Pedestal Thresholds: UND 821 . . . 120
24.89 BLM Pedestal Thresholds: UND 920 . . . 120
24.90 BLM Pedestal Thresholds: UND 921 . . . 120
24.91 BLM Pedestal Thresholds: UND BLF1 . . . 121
24.92 BLM Pedestal Thresholds: UND BLF17 . . . 121
24.93 BLM PEP Timing Check (LN32) . . . 121
24.94 BLM PEP Timing Check (LN33) . . . 122
24.95 BLM PEP Timing Check (LN35) . . . 122
24.96 BLM PEP Timing Check (LN36) . . . 122
24.97 BLM PEP Timing Check (LN37) . . . 123
24.98 BLM Raw Charge Thresholds: LTU1 722 . . . 123
24.99 BLM Raw Charge Thresholds: LTU1 732 . . . 123
24.100 BLM Raw Charge Thresholds: LTU1 762 . . . 124
24.101 BLM Raw Charge Thresholds: LTU1 772 . . . 124
24.102 BLM Raw Charge Thresholds: LTU1 980 . . . 124
24.103 BLM Raw Charge Thresholds: UND 1021 . . . 125
24.104 BLM Raw Charge Thresholds: UND 1121 . . . 125
24.105 BLM Raw Charge Thresholds: UND 120 . . . 125
24.106 BLM Raw Charge Thresholds: UND 121 . . . 126
24.107 BLM Raw Charge Thresholds: UND 1221 . . . 126
24.108 BLM Raw Charge Thresholds: UND 1321 . . . 126
24.109 BLM Raw Charge Thresholds: UND 1421 . . . 127
24.110 BLM Raw Charge Thresholds: UND 1521 . . . 127
24.111 BLM Raw Charge Thresholds: UND 1621 . . . 127
24.112 BLM Raw Charge Thresholds: UND 1720 . . . 128
24.113 BLM Raw Charge Thresholds: UND 1721 . . . 128
24.114 BLM Raw Charge Thresholds: UND 1821 . . . 128
24.115 BLM Raw Charge Thresholds: UND 1921 . . . 129
24.116 BLM Raw Charge Thresholds: UND 2021 . . . 129
24.117 BLM Raw Charge Thresholds: UND 2121 . . . 129
24.118 BLM Raw Charge Thresholds: UND 221 . . . 130
24.119 BLM Raw Charge Thresholds: UND 2221 . . . 130
24.120 BLM Raw Charge Thresholds: UND 2321 . . . 130
24.121 BLM Raw Charge Thresholds: UND 2421 . . . 131
24.122 BLM Raw Charge Thresholds: UND 2520 . . . 131
24.123 BLM Raw Charge Thresholds: UND 2521 . . . 131
24.124 BLM Raw Charge Thresholds: UND 2621 . . . 132

24.125 BLM Raw Charge Thresholds: UND 2721 . . . 132
24.126 BLM Raw Charge Thresholds: UND 2821 . . . 132
24.127 BLM Raw Charge Thresholds: UND 2921 . . . 133
24.128 BLM Raw Charge Thresholds: UND 3021 . . . 133
24.129 BLM Raw Charge Thresholds: UND 3121 . . . 133
24.130 BLM Raw Charge Thresholds: UND 321 . . . 134
24.131 BLM Raw Charge Thresholds: UND 3221 . . . 134
24.132 BLM Raw Charge Thresholds: UND 3320 . . . 134
24.133 BLM Raw Charge Thresholds: UND 3321 . . . 135
24.134 BLM Raw Charge Thresholds: UND 421 . . . 135
24.135 BLM Raw Charge Thresholds: UND 521 . . . 135
24.136 BLM Raw Charge Thresholds: UND 621 . . . 136
24.137 BLM Raw Charge Thresholds: UND 721 . . . 136
24.138 BLM Raw Charge Thresholds: UND 821 . . . 136
24.139 BLM Raw Charge Thresholds: UND 920 . . . 137
24.140 BLM Raw Charge Thresholds: UND 921 . . . 137
24.141 BLM Raw Charge Thresholds: UND BLF1 . . . 137
24.142 BLM Raw Charge Thresholds: UND BLF17 . . . 138
24.143 BLM Trigger Missed (LN32) . . . 138
24.144 BLM Trigger Missed (LN33) . . . 138
24.145 BLM Trigger Missed (LN35) . . . 138
24.146 BLM Trigger Missed (LN36) . . . 139
24.147 BLM Trigger Missed (LN37) . . . 139
24.148 BLM/PIC Watchdog: Downstream of TDUND . . . 139
24.149 BOD UND1 1005 . . . 139
24.150 BOD UND1 1305 . . . 140
24.151 BPM Summary (1-9) - Status From IOC-UND1-BP01 . . . 140
24.152 BPM Summary (10-18) - Status From IOC-UND1-BP02 . . . 140
24.153 BPM Summary (19-27) - Status From IOC-UND1-BP03 . . . 140
24.154 BPM Summary (28-36) - Status From IOC-UND1-BP04 . . . 141
24.155 FEE Camera 1692 Position . . . 141
24.156 FEE Camera 1953 Position . . . 141
24.157 FEE Camera 2953 Position . . . 142
24.158 FEE Camera 852 Position Fault - Status From PLC . . . 142
24.159 FEE Camera 913 Position Fault - Status From PLC . . . 142
24.160 FEE Gas System Summary . . . 142
24.161 FEE HXTD Vacuum Valve Summary . . . 143
24.162 FEE M1S Mirror Beam Energy Upper Limit . . . 143
24.163 FEE M1S Mirror State . . . 143
24.164 FEE Spectrometer Crystal - Beam Energy Too Low When Crystal Not Out . . . 144
24.165 FEE Spectrometer Crystal - Pulse Energy Too High When Crystal Not Out . . . 144
24.166 FEE XTOD S1 Isolation Valve Summary . . . 144
24.167 FEE XTOD S2 Isolation Valve Summary . . . 145
24.168 Gas Detector Problem When FEE Spectrometer Crystal Not Out . . . 145
24.169 HXR - Beam Energy Too Low With M1S Out . . . 145

24.170 Magnet In Tolerance: QE31 . . . 146
24.171 Magnet In Tolerance: QUM1 . . . 146
24.172 Magnet In Tolerance: QUM2 . . . 146
24.173 Magnet In Tolerance: QUM3 . . . 146
24.174 Magnet In Tolerance: QUM4 . . . 147
24.175 Magnet Power: QE31 . . . 147
24.176 Magnet Power: QUM1 . . . 147
24.177 Magnet Power: QUM2 . . . 147
24.178 Magnet Power: QUM3 . . . 148
24.179 Magnet Power: QUM4 . . . 148
24.180 OTR01 IN20 541 Position and TDUND Not In . . . 148
24.181 OTR02 IN20 571 Position and TDUND Not In . . . 149
24.182 OTR03 IN20 621 Position and TDUND Not In . . . 149
24.183 OTR04 IN20 711 Position and TDUND Not In . . . 149
24.184 OTR11 LI21 237 Position and TDUND Not In . . . 150
24.185 OTR12 LI21 291 Position and TDUND Not In . . . 150
24.186 OTR21 Position When TDUND Not In . . . 150
24.187 OTR33 Position When TDUND Not In . . . 151
24.188 OTRH1 Position When TDUND Not In . . . 151
24.189 OTRH2 Position When TDUND Not In . . . 151
24.190 PIC HVPS B921 - Location B921-2235 . . . 152
24.191 PIC Raw Charge Thresholds: DMP1 698 . . . 152
24.192 PIC Raw Charge Thresholds: DMP1 699 . . . 152
24.193 PIC Trigger Missed (LN34) . . . 152
24.194 Toroid Comparator Dump (IMUNDO vs IMDUMP) . . . 153
24.195 Toroid Comparator Power Status (B921) . . . 153
24.196 Toroid Comparator Undulator (IMUNDI vs IMUNDO) . . . 153
24.197 VVFS DMP1 107 Position . . . 154
24.198 VVMG DMP1 743 Position . . . 154
24.199 VVMG UND1 1645 Position . . . 154
24.200 VVMG UND1 1655 Position . . . 154
24.201 VVPG DMP1 355 Position . . . 155
24.202 XLEAP PRXL1 - YAGS LTU1 844 Position and TDUND Not In . . . 155
24.203 XLEAP PRXL2 - YAGS LTU1 853 Position and TDUND Not In . . . 155
24.204 XLEAP PRXL3 - OTRS LTU1 858 Position and TDUND Not In . . . 156
24.205 YAG LTU1 743 Position When TDUND Not In (PSI Prof Mon) . . . 156

25 Ignored when Stopper: BSY D2 Summary Is In, TD11 Is In, YAG01 Is In, or YAG02 Is In 157
25.1 BCS LION LTU1 404 Threshold . . . 157
25.2 BCS LION LTU1 405 Threshold . . . 157
25.3 BCS LION LTU1 504 Threshold . . . 157
25.4 BCS LION LTU1 505 Threshold . . . 157
25.5 BCS LION LTU1 584 Threshold . . . 158
25.6 BCS LION LTU1 585 Threshold . . . 158
25.7 BCS LION LTU1 716 Threshold . . . 158

25.8 BCS LION LTU1 717 Threshold . . . 158
25.9 BCS LION LTU1 732 Threshold . . . 159
25.10 BCS LION LTU1 733 Threshold . . . 159
25.11 BCS LION LTU1 752 Threshold . . . 159
25.12 BCS LION LTU1 753 Threshold . . . 159
25.13 BCS LION LTU1 765 Threshold . . . 160
25.14 BCS LION LTU1 766 Threshold . . . 160
25.15 BLM Heartbeat: Dechirper LTU1 BLF545 . . . 160
25.16 BLM Heartbeat: XLEAP LTU1 BLF859 . . . 160
25.17 BLM HVPS LTU1 762 . . . 161
25.18 BLM Pedestal Thresholds: Dechirper LTU1 BLF545 . . . 161
25.19 BLM Pedestal Thresholds: XLEAP LTU1 BLF859 . . . 161
25.20 BLM PEP Timing Check (LN30) . . . 162
25.21 BLM Raw Charge Thresholds: Dechirper LTU1 BLF545 . . . 162
25.22 BLM Raw Charge Thresholds: XLEAP LTU1 BLF859 . . . 162
25.23 BLM Timing Check (LN30) . . . 163
25.24 BLM Trigger Missed (LN30) . . . 163
25.25 BYD Watchdog . . . 163
25.26 BYKIK 120 Hz Abort Trigger . . . 164
25.27 BYKIK 120 Hz Standby Trigger . . . 164
25.28 BYKIK 30 Hz Abort Trigger . . . 164
25.29 BYKIK 30 Hz Standby Trigger . . . 164
25.30 BYKIK Readback Signal . . . 165
25.31 LTU Dechirper - Horizontal Gap Too Small . . . 165
25.32 LTU Dechirper - Vertical Gap Too Small . . . 165
25.33 Magnet In Tolerance: BYD1 . . . 166
25.34 Magnet Power: BYD1 . . . 166
25.35 OTR33 Position . . . 166
25.36 PIC HVPS B911 - Location B911-2135 . . . 166
25.37 PIC HVPS B912 - Location B912-2135 . . . 167
25.38 PIC HVPS B913 - Location B913-2135 . . . 167
25.39 PIC Raw Charge Thresholds: LTU1 220 . . . 167
25.40 PIC Raw Charge Thresholds: LTU1 252 . . . 167
25.41 PIC Raw Charge Thresholds: LTU1 280 . . . 168
25.42 PIC Raw Charge Thresholds: LTU1 420 . . . 168
25.43 PIC Raw Charge Thresholds: LTU1 450 . . . 168
25.44 PIC Raw Charge Thresholds: LTU1 480 . . . 169
25.45 PIC Raw Charge Thresholds: LTU1 722 . . . 169
25.46 PIC Raw Charge Thresholds: LTU1 732 . . . 169
25.47 PIC Raw Charge Thresholds: LTU1 762 . . . 170
25.48 PIC Raw Charge Thresholds: LTU1 772 . . . 170
25.49 PIC Trigger Missed (LN28) . . . 170
25.50 PIC Trigger Missed (LN29) . . . 170
25.51 PIC Trigger Missed (LN31) . . . 171
25.52 TDUND Flow Switch Fault With TDUND Not Out . . . 171

25.53 TDUND Position . . . 171
25.54 THZ-2 Position . . . 172
25.55 Undulator Beam Energy Lower Limit . . . 172
25.56 VVFS LTU1 102 Position . . . 172
25.57 VVMG LTU1 174 Position . . . 172
25.58 VVMG LTU1 355 Position . . . 173
25.59 VVMG LTU1 505 Position . . . 173
25.60 VVMG LTU1 670 Position . . . 173
25.61 VVMG LTU1 742 Position . . . 173
25.62 VVMG LTU1 774 Position . . . 174
25.63 VVMG UND1 932 Position . . . 174
25.64 VVMG UND1 968 Position . . . 174
25.65 VVPG DMP1 103 Position . . . 174
25.66 VVPG DMP1 395 Position . . . 175
25.67 VVPG DMP1 700 Position . . . 175
25.68 VVPG LTU1 100 Position . . . 175
25.69 VVPG LTU1 265 Position . . . 175
25.70 VVPG LTU1 435 Position . . . 176
25.71 VVPG LTU1 580 Position . . . 176
25.72 VVPG LTU1 725 Position . . . 176
25.73 VVPG LTU1 757 Position . . . 176
25.74 VVPG LTU1 999 Position . . . 177
25.75 VVPG UND1 1000 Position . . . 177
25.76 VVPG UND1 2500 Position . . . 177
25.77 XLEAP MIRXL - MIRR LTU1 829 Position . . . 177
25.78 XLEAP PRXL1 - YAGS LTU1 844 Position . . . 178
25.79 XLEAP PRXL2 - YAGS LTU1 853 Position . . . 178
25.80 XLEAP PRXL3 - OTRS LTU1 858 Position . . . 178
25.81 XLEAP Wiggler - Downstream End Vertical Gap Too Small . . . 179
25.82 XLEAP Wiggler - Upstream End Vertical Gap Too Small . . . 179
25.83 YAG LTU1 743 Position (PSI Prof Mon) . . . 179

26 Ignored when TD11 Is In, YAG01 Is In, or YAG02 Is In 180
26.1 BLM/PIC Watchdog BSY0/BSYA . . . 180
26.2 BLM/PIC Watchdog LI24 . . . 180
26.3 BLM/PIC Watchdog LI30 . . . 180
26.4 Bunch Length Monitor BL21 Position . . . 181
26.5 Dump LI28 5879 Flowswitch . . . 181
26.6 Dump LI28 5879 Klixon . . . 181
26.7 Flowswitch: BSY RAD LCW Slit 10/30 . . . 181
26.8 Flowswitch: CE21 . . . 182
26.9 Flowswitch: COLL BSYH 479, 487, 495, 503 (PCAPM1-4) . . . 182
26.10 Flowswitch: COLL LI28-9 . . . 182
26.11 Flowswitch: COLL LI29-1 . . . 182
26.12 Flowswitch: COLL LI29-4 . . . 183

26.13 Flowswitch: COLL LI29-5 . . . 183
26.14 Flowswitch: COLL LI29-9 . . . 183
26.15 Flowswitch: COLL LI30-1 . . . 183
26.16 Flowswitch: COLL LI30-4 . . . 184
26.17 Flowswitch: COLL LI30-5 . . . 184
26.18 Hydrogen Recombiner For BSY 1 Collimator . . . 184
26.19 Hydrogen Recombiner For BSY 2 Slit 10/30 . . . 184
26.20 KICK BSYH 475 PM1 State (A-Line Kicker) . . . 185
26.21 KICK BSYH 475 PM1 Trigger State (A-Line Kicker) . . . 185
26.22 KICK BSYH 491 PM3 State (A-Line Kicker) . . . 185
26.23 KICK BSYH 491 PM3 Trigger State (A-Line Kicker) . . . 186
26.24 Main Manifold Gauge: LI22 Station 5 . . . 186
26.25 Main Manifold Gauge: LI23 Station 5 . . . 186
26.26 Main Manifold Gauge: LI24 Station 5 . . . 186
26.27 Main Manifold Gauge: LI25 Station 5 . . . 187
26.28 Main Manifold Gauge: LI26 Station 5 . . . 187
26.29 Main Manifold Gauge: LI27 Station 5 . . . 187
26.30 Main Manifold Gauge: LI28 Station 5 . . . 187
26.31 Main Manifold Gauge: LI29 Station 5 . . . 188
26.32 Main Manifold Gauge: LI30 Station 5 . . . 188
26.33 OTR LI25 920 Position . . . 188
26.34 OTR21 Position . . . 188
26.35 PIC Gas Pressure LI24 . . . 189
26.36 PIC HVPS BSY 1 - Location B005-3921 . . . 189
26.37 PIC HVPS BSY 2 - Location B005-3921 . . . 189
26.38 PIC HVPS BSY 3 - Location B005-3921 . . . 189
26.39 PIC HVPS BSY 4 - Location B005-3918 . . . 190
26.40 PIC HVPS BSY 5 - Location B005-3918 . . . 190
26.41 PIC HVPS BSY 6 - Location B005-3918 . . . 190
26.42 PIC HVPS LI24 - Location LKF24-0235 . . . 190
26.43 PIC HVPS LI30 - KG30-C1322 . . . 191
26.44 PIC Raw Charge Thresholds: BSYH 479 (PCAPM1) . . . 191
26.45 PIC Raw Charge Thresholds: BSYH 487 (PCAPM2) . . . 191
26.46 PIC Raw Charge Thresholds: BSYH 495 (PCAPM3) . . . 192
26.47 PIC Raw Charge Thresholds: BSYH 503 (PCAPM4) . . . 192
26.48 PIC Raw Charge Thresholds: BSYH 762 (PC90) . . . 192
26.49 PIC Raw Charge Thresholds: BSYH 836 (PC119) . . . 193
26.50 PIC Raw Charge Thresholds: LI24 791 . . . 193
26.51 PIC Raw Charge Thresholds: LI24 811 . . . 193
26.52 PIC Raw Charge Thresholds: LI28 916 . . . 194
26.53 PIC Raw Charge Thresholds: LI29 146 . . . 194
26.54 PIC Raw Charge Thresholds: LI29 446 . . . 194
26.55 PIC Raw Charge Thresholds: LI29 546 . . . 195
26.56 PIC Raw Charge Thresholds: LI29 801 . . . 195
26.57 PIC Raw Charge Thresholds: LI29 956 . . . 195

26.58 PIC Raw Charge Thresholds: LI30 146 . . . 196
26.59 PIC Raw Charge Thresholds: LI30 446 . . . 196
26.60 PIC Raw Charge Thresholds: LI30 546 . . . 196
26.61 PIC Raw Charge Thresholds: LI30 801 . . . 197
26.62 PIC Trigger Missed (LN16) . . . 197
26.63 PIC Trigger Missed (LN22) . . . 197
26.64 PIC Trigger Missed (LN25) . . . 197
26.65 Scraper Water LI21-9 (Station 22-1) . . . 198
26.66 Scraper Water LI22-9 (Station 23-1) . . . 198
26.67 Scraper Water LI23-9 (Station 24-1) . . . 198
26.68 Scraper Water LI24-9 (Station 25-1) . . . 198
26.69 Scraper Water LI25-9 (Station 26-1) . . . 199
26.70 Scraper Water LI26-9 (Station 27-1) . . . 199
26.71 Scraper Water LI27-9 (Station 28-1) . . . 199
26.72 Scraper Water LI28-9 (Station 29-1) . . . 199
26.73 Scraper Water LI29-9 (Station 30-1) . . . 200
26.74 Stopper LI28 950 and 960 Position . . . 200
26.75 Stopper: BSY D2, 60, 61 DM60 Summary . . . 200
26.76 Sub-booster Ready: LI22 . . . 203
26.77 Sub-booster Ready: LI25 . . . 203
26.78 Sub-booster Ready: LI26 . . . 203
26.79 Sub-booster Ready: LI27 . . . 203
26.80 Sub-booster Ready: LI28 . . . 204
26.81 Sub-booster Ready: LI29 . . . 204
26.82 Sub-booster Ready: LI30 . . . 204
26.83 Temperature RTD Summary: BSY Common Line . . . 204
26.84 Toroid Chassis LI24 IMBC2 . . . 205
26.85 Toroid Comparator BC2 (IMBC2IN vs IMBC2OUT) . . . 205
26.86 VVFS CLTH 101 Position . . . 205
26.87 VVFS LI21-9 Position (Station 22-1) . . . 205
26.88 VVFS LI22-9 Position (Station 23-1) . . . 206
26.89 VVFS LI23-9 Position (Station 24-1) . . . 206
26.90 VVFS LI24-9 Position (Station 25-1) . . . 206
26.91 VVFS LI25-9 Position (Station 26-1) . . . 206
26.92 VVFS LI26-9 Position (Station 27-1) . . . 207
26.93 VVFS LI27-9 Position (Station 28-1) . . . 207
26.94 VVFS LI28-9 Position (Station 29-1) . . . 207
26.95 VVFS LI29-9 Position (Station 30-1) . . . 207
26.96 VVPG BSYH 470 Position . . . 208
26.97 VVPG BSYH 541 Position . . . 208
26.98 VVPG BSYH 837 Position . . . 208
26.99 VVPG CLTH 178 Position . . . 208
26.100 VVPG CLTH 375 Position . . . 209
26.101 VVPG LI21-9 Position (Station 22-1) . . . 209
26.102 VVPG LI22-9 Position (Station 23-1) . . . 209

26.103 VVPG LI23-9 Position (Station 24-1) . . . 209
26.104 VVPG LI24 710 Position . . . 210
26.105 VVPG LI24 896 Position . . . 210
26.106 VVPG LI25-9 Position (Station 26-1) . . . 210
26.107 VVPG LI26-9 Position (Station 27-1) . . . 210
26.108 VVPG LI27-9 Position (Station 28-1) . . . 211
26.109 VVPG LI28-9 Position (Station 29-1) . . . 211
26.110 VVPG LI29-9 Position (Station 30-1) . . . 211
26.111 VVPG LI30-9 Position (Station 30-9) . . . 211

27 Ignored when YAG01 Is In 212
27.1 BXG Status . . . 212
27.2 Toroid Peak Current Monitor IM01 . . . 212
27.3 YAG02 IN20 241 Position . . . 212

28 Ignored when YAG01 Is In or YAG02 Is In 213
28.1 BLM/PIC Watchdog: Upstream of TDUND . . . 213
28.2 BX01/BX02 Status . . . 213
28.3 Flowswitch: CE11 . . . 213
28.4 Flowswitch: TD11 . . . 213
28.5 Main Manifold Gauge: LI21 Station 5 . . . 214
28.6 Mirror BL11 Position . . . 214
28.7 OTR01 IN20 541 Position . . . 214
28.8 OTR02 IN20 571 Position . . . 215
28.9 OTR03 IN20 621 Position . . . 215
28.10 OTR04 IN20 711 Position . . . 215
28.11 OTR11 LI21 237 Position . . . 216
28.12 OTR12 LI21 291 Position . . . 216
28.13 OTRH1 Position . . . 216
28.14 OTRH2 Position . . . 217
28.15 Sub-booster Ready: LI21 . . . 217
28.16 TD11 Position . . . 217
28.17 Toroid Chassis IN20 IM11 . . . 217
28.18 Toroid Chassis IN20 IM12 . . . 218
28.19 Toroid Comparator BC1 (IMBC1IN vs IMBC1OUT) . . . 218
28.20 VVFV IN20 785 Position . . . 218
28.21 VVMG LI21 195 Position . . . 219
28.22 VVPG IN20 435 Position . . . 219
28.23 VVPG IN20 545 Position . . . 219
28.24 VVPG IN20 635 Position . . . 219
28.25 VVPG IN20 915 Position . . . 220
28.26 VVS Circuit Breaker: LI22 . . . 220
28.27 VVS Circuit Breaker: LI24 . . . 220
28.28 VVS Circuit Breaker: LI26 . . . 220
28.29 VVS Circuit Breaker: LI28 . . . 221

28.30 VVS Circuit Breaker: LI30 . . . 221
28.31 YAG03 IN20 351 Position . . . 221
28.32 YAGS1 IN20 921 Position . . . 221
28.33 YAGS2 LI21 995 Position . . . 222

29 Always Evaluated **223**
29.1 Backward Beam Stopper (RST1) . . . 223
29.2 BLM/PIC Watchdog: IN20 . . . 223
29.3 Bypass Recover . . . 223
29.4 Gun RF Peak Power 20-6 . . . 223
29.5 Gun Waveguide Vacuum Summary . . . 224
29.6 IOC-IN20-MP01 MPS Support IOC Heartbeat . . . 224
29.7 Laser Heater Attenuator Position . . . 224
29.8 MCC Emergency Radiation Stopper . . . 224
29.9 Mechanical Shutter Position . . . 225
29.10 Mirror AM01 Position . . . 225
29.11 MPS Beam Permit: BYKIK . . . 225
29.12 MPS Beam Permit: Gun RF . . . 225
29.13 MPS Beam Permit: Heater Shutter . . . 226
29.14 MPS Beam Permit: Mechanical Shutter . . . 226
29.15 MPS Mechanical Shutter Position . . . 226
29.16 PIC HVPS LI20 - Location LKG-1535 . . . 226
29.17 PIC Raw Charge Thresholds: IN20 185 . . . 227
29.18 PIC Raw Charge Thresholds: IN20 232 . . . 227
29.19 PIC Raw Charge Thresholds: IN20 245 . . . 227
29.20 PIC Raw Charge Thresholds: IN20 665 . . . 228
29.21 PIC Raw Charge Thresholds: IN20 775 . . . 228
29.22 PIC Raw Charge Thresholds: IN20 933 . . . 228
29.23 PIC Trigger Missed (LN11) . . . 229
29.24 Pockels Cell AND Gate 100 . . . 229
29.25 Pockels Cell AND Gate 200 . . . 229
29.26 Rate Request: BYKIK 1 Hz . . . 229
29.27 Rate Request: BYKIK 10 Hz . . . 230
29.28 Rate Request: BYKIK 30 Hz . . . 230
29.29 Rate Request: BYKIK 60 Hz . . . 230
29.30 Rate Request: BYKIK Burst . . . 230
29.31 Rate Request: BYKIK Single Shot . . . 231
29.32 Rate Request: Pockels Cell 1 Hz . . . 231
29.33 Rate Request: Pockels Cell 10 Hz . . . 231
29.34 Rate Request: Pockels Cell 30 Hz . . . 231
29.35 Rate Request: Pockels Cell 60 Hz . . . 232
29.36 Rate Request: Pockels Cell Burst . . . 232
29.37 Rate Request: Pockels Cell Single Shot . . . 232
29.38 VVMG IN20 175 Position . . . 232
29.39 VVPG IN20 155 Position . . . 233

29.40 VVS Circuit Breaker: LI20 . . . 233
29.41 YAG01 IN20 211 Position . . . 233
29.42 YAGG1 IN20 841 Position . . . 233

30 Ignore Logic **235**
30.1 A-Line Kicker Is Not Enabled . . . 235
30.2 A-Line SL10 Is Closed . . . 235
30.3 BX01/BX02 Is Off . . . 235
30.4 BX01/BX02 Is On . . . 235
30.5 BXG Is Off . . . 236
30.6 BXG Is On . . . 236
30.7 Diag Stopper HFX DG2 Is In . . . 236
30.8 Diag Stopper HFX UM6 Is In . . . 236
30.9 Diag Stopper XCS SB1 Is In . . . 237
30.10 Laser Heater Attenuator Is In . . . 237
30.11 LTU Dechirper Is Out . . . 237
30.12 Stopper MFX S4.5 Is In . . . 237
30.13 Stopper S1 Is In . . . 238
30.14 Stopper S2 Is In . . . 238
30.15 Stopper S2B Is In . . . 238
30.16 Stopper S5B Is In . . . 238
30.17 Stopper SH1 Is In . . . 238
30.18 Stopper SH2 Is In . . . 239
30.19 Stopper XRT S5 Is In . . . 239
30.20 Stopper XRT S6 Is In . . . 239
30.21 Stopper: BSY D2 Summary Is In . . . 239
30.22 TD11 Is In . . . 240
30.23 TDUND Is In . . . 240
30.24 XCS Is Not In Main Line . . . 240
30.25 XPP-NH3-POS-00 Beamline Is In . . . 240
30.26 XPP-NH3-POS-00 Beamline Is Not In . . . 240
30.27 XRT-M2 Mirror Is Out of Beam . . . 241
30.28 YAG01 Is In . . . 241
30.29 YAG02 Is In . . . 241

1 Ignored when A-Line Kicker Is Not Enabled, A-Line SL10 Is Closed, TD11 Is In, YAG01 Is In, or YAG02 Is In

1.1 Flowswitch: COLL BSYA 2060 (PC20)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSYA_2060_FLOW_SW_STATE`

1.2 Flowswitch: COLL BSYA 2410 (COLL24H)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSYA_2470_H_FLOW_SW_STATE`

1.3 Flowswitch: COLL BSYA 2410 (COLL24V)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSYA_2470_V_FLOW_SW_STATE`

1.4 Flowswitch: COLL BSYA 2410 (PC24)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_BSYA_2410_FLOW_SW_STATE

1.5 Flowswitch: COLL BSYA 2600 (PC26)

Name	A	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_BSYA_2600_FLOW_SW_STATE

1.6 Flowswitch: COLL BSYA 2990 (PC29)

Name	A	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_BSYA_2990_FLOW_SW_STATE

1.7 Flowswitch: COLL BSYA 3710 (C37)

Name	A	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_BSYA_3710_FLOW_SW_STATE

1.8 Flowswitch: COLL BSYA 4120 (3C1A)

Name	A	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_ESA0_4120_FLOW_SW_STATE

1.9 PIC Raw Charge Thresholds: BSYA 2061

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2061_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2061_LOSSH_THRESHOLD`

1.10 PIC Raw Charge Thresholds: BSYA 2120

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2120_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2120_LOSSH_THRESHOLD`

1.11 PIC Raw Charge Thresholds: BSYA 2220

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2220_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2220_LOSSH_THRESHOLD`

1.12 PIC Raw Charge Thresholds: BSYA 2321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2321_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2321_LOSSH_THRESHOLD`

1.13 PIC Raw Charge Thresholds: BSYA 2411

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2411_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2411_LOSSH_THRESHOLD`

1.14 PIC Raw Charge Thresholds: BSYA 2472

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2472_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2472_LOSSH_THRESHOLD`

1.15 PIC Raw Charge Thresholds: BSYA 2473

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2473_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2473_LOSSH_THRESHOLD`

1.16 PIC Raw Charge Thresholds: BSYA 2474

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2474_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2474_LOSSH_THRESHOLD`

1.17 PIC Raw Charge Thresholds: BSYA 2475

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2475_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2475_LOSSH_THRESHOLD`

1.18 PIC Raw Charge Thresholds: BSYA 2520

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2520_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2520_LOSSH_THRESHOLD`

1.19 PIC Raw Charge Thresholds: BSYA 2601

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2601_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2601_LOSSH_THRESHOLD`

1.20 PIC Raw Charge Thresholds: BSYA 2861

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2861_LOSSL_THRESHOLD`,
B = `PICM_BSYA_2861_LOSSH_THRESHOLD`

1.21 PIC Raw Charge Thresholds: BSYA 2990

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSYA_2990_LOSSL_THRESHOLD,
B = PICM_BSYA_2990_LOSSH_THRESHOLD

1.22 PIC Raw Charge Thresholds: BSYA 3320

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSYA_3320_LOSSL_THRESHOLD,
B = PICM_BSYA_3320_LOSSH_THRESHOLD

1.23 PIC Raw Charge Thresholds: BSYA 3720

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSYA_3720_LOSSL_THRESHOLD,
B = PICM_BSYA_3720_LOSSH_THRESHOLD

1.24 PIC Raw Charge Thresholds: BSYA 3721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_3721_LOSSL_THRESHOLD`,
B = `PICM_BSYA_3721_LOSSH_THRESHOLD`

1.25 PIC Raw Charge Thresholds: BSYA 3890

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_3890_LOSSL_THRESHOLD`,
B = `PICM_BSYA_3890_LOSSH_THRESHOLD`

1.26 PIC Trigger Missed (LN42)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYA_2061_NO_TRIG_MISSED`

1.27 Stopper BSYA 2275 (ST22) Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
MOVING	F	F	0 Hz	0 Hz	0 Hz	–
OUT	F	T	120 Hz	120 Hz	120 Hz	–
IN	T	F	0 Hz	0 Hz	0 Hz	–
BROKEN	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = STPR_BSYA_2275_ST22_OUT_LIM_STATE,
B = STPR_BSYA_2275_ST22_IN_LIM_STATE

1.28 Stopper BSYA 2930 (ST29) Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
MOVING	F	F	0 Hz	0 Hz	0 Hz	–
OUT	F	T	120 Hz	120 Hz	120 Hz	–
IN	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = STPR_BSYA_2930_ST29_OUT_LIM_STATE,
B = STPR_BSYA_2930_ST29_IN_LIM_STATE

1.29 Temperature RTD Summary: A-line Past SL10

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = RTD_BSYA_2060_PASTSL10SUM_STATUS

1.30 Vac Valve BSYA 4005 (IV40)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_BSYA_4005_POSITION_STATE

1.31 Vac Valve: VVFS BSYA 2855 (FV28)

Name	A	PC	MS	BYKIK	LHS
NOT_OPEN	F	0 Hz	0 Hz	0 Hz	–
OPEN	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVFS_BSYA_2855_POSITION_STATE

1.32 Vac Valve: VVPG BSYA 2635 (IV26)

Name	A	PC	MS	BYKIK	LHS
NOT_OPEN	F	0 Hz	0 Hz	0 Hz	–
OPEN	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_BSYA_2635_POSITION_STATE

1.33 Vac Valve: VVPG ESA0 4195 POSITION (IV41)

Name	A	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_ESA0_4195_POSITION_STATE

2 Ignored when A-Line Kicker Is Not Enabled, TD11 Is In, YAG01 Is In, or YAG02 Is In

2.1 A-Line SL10 Position

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
state = (unsigned int) -1;

if ( SLIT_BSYA_2010_SL10_FB_IN_STATE &&
        SLIT_BSYA_2010_SL10_FT_IN_STATE &&
        SLIT_BSYA_2010_SL10_RB_IN_STATE &&
        SLIT_BSYA_2010_SL10_RT_IN_STATE )
{
    state = 0; /* SL10 is Closed */
}

else
{
    state = 1; /* SL10 is Not Closed */
}
```

Name	State	PC	MS	BYKIK	LHS
Closed	0	120 Hz	120 Hz	120 Hz	–
Not_Closed	1	120 Hz	120 Hz	120 Hz	–

2.2 Flowswitch: BPM BSYA 1020 (BPM10)

Name	*A*	PC	MS	BYKIK	LHS
IS_NOT_OK	F	0 Hz	0 Hz	–	–
OK	T	120 Hz	120 Hz	–	–

Where
A = `BPM_BSYA_1020_FLOW_SW_STATE`

2.3 Flowswitch: BPM BSYA 1240 (BPM12)

Name	*A*	PC	MS	BYKIK	LHS
IS_NOT_OK	F	0 Hz	0 Hz	–	–
OK	T	120 Hz	120 Hz	–	–

Where
A = `BPM_BSYA_1240_FLOW_SW_STATE`

2.4 Flowswitch: COLL BSYA 1015 (PC10)

Name	*A*	PC	MS	BYKIK	LHS
IS_NOT_OK	F	0 Hz	0 Hz	–	–
OK	T	120 Hz	120 Hz	–	–

Where
A = `COLL_BSYA_1015_FLOW_SW_STATE`

2.5 Flowswitch: COLL BSYA 1230 (PC12)

Name	*A*	PC	MS	BYKIK	LHS
IS_NOT_OK	F	0 Hz	0 Hz	–	–
OK	T	120 Hz	120 Hz	–	–

Where
A = `COLL_BSYA_1230_FLOW_SW_STATE`

2.6 Flowswitch: COLL BSYA 1490 (PC14)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSYA_1490_FLOW_SW_STATE`

2.7 Flowswitch: COLL BSYA 1700 (PC17)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = COLL_BSYA_1700_FLOW_SW_STATE

2.8 PIC Raw Charge Thresholds: BSYA 1016

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = PICM_BSYA_1016_LOSSL_THRESHOLD,
B = PICM_BSYA_1016_LOSSH_THRESHOLD

2.9 PIC Raw Charge Thresholds: BSYA 1021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = PICM_BSYA_1021_LOSSL_THRESHOLD,
B = PICM_BSYA_1021_LOSSH_THRESHOLD

2.10 PIC Raw Charge Thresholds: BSYA 1120

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = PICM_BSYA_1120_LOSSL_THRESHOLD,
B = PICM_BSYA_1120_LOSSH_THRESHOLD

2.11 PIC Raw Charge Thresholds: BSYA 1320

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = PICM_BSYA_1320_LOSSL_THRESHOLD,
B = PICM_BSYA_1320_LOSSH_THRESHOLD

2.12 PIC Raw Charge Thresholds: BSYA 1520

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = PICM_BSYA_1520_LOSSL_THRESHOLD,
B = PICM_BSYA_1520_LOSSH_THRESHOLD

2.13 PIC Raw Charge Thresholds: BSYA 1701A

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = `PICM_BSYA_1701A_LOSSL_THRESHOLD`,
B = `PICM_BSYA_1701A_LOSSH_THRESHOLD`

2.14 PIC Raw Charge Thresholds: BSYA 1701B

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = `PICM_BSYA_1701B_LOSSL_THRESHOLD`,
B = `PICM_BSYA_1701B_LOSSH_THRESHOLD`

2.15 PIC Raw Charge Thresholds: BSYA 1980

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	–	–
Over High Threshold	F	T	0 Hz	0 Hz	–	–
Under Low Threshold	T	F	0 Hz	0 Hz	–	–
OK	T	T	120 Hz	120 Hz	–	–

Where
A = `PICM_BSYA_1980_LOSSL_THRESHOLD`,
B = `PICM_BSYA_1980_LOSSH_THRESHOLD`

2.16 Temperature RTD Summary: A-Line Before SL10

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	–	–
OK	T	120 Hz	120 Hz	–	–

Where
A = `RTD_BSYA_1015_PRESL10SUM_STATUS`

2.17 Vac Valve: VVFS BSYA 1030 (FV10)

Name	*A*	PC	MS	BYKIK	LHS
NOT_OPEN	F	0 Hz	0 Hz	–	–
OPEN	T	120 Hz	120 Hz	–	–

Where
A = `VVFS_BSYA_1030_POSITION_STATE`

2.18 Vac Valve: VVPG BSYA 1018 (IV10)

Name	*A*	PC	MS	BYKIK	LHS
NOT_OPEN	F	0 Hz	0 Hz	–	–
OPEN	T	120 Hz	120 Hz	–	–

Where
A = `VVPG_BSYA_1018_POSITION_STATE`

2.19 VVPG BSYA 340 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVPG_BSYA_340_OPEN_LIMSW_POSITION`

3 Ignored when BX01/BX02 Is Off, YAG01 Is In, or YAG02 Is In

3.1 Toroid Comparator Dogleg 1 (IM02 vs IM03)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Downstream > Upstream	F	T	0 Hz	0 Hz	0 Hz	–
Upstream > Downstream	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `TC203L1_STATE`,
B = `TC203L2_STATE`

4 Ignored when BX01/BX02 Is On, YAG01 Is In, or YAG02 Is In

4.1 BXS Status

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BEND_IN20_931_OK_STATE`

4.2 Toroid Comparator Inj Spectrometer (IM02 vs IMS1)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Downstream > Upstream	F	T	0 Hz	0 Hz	0 Hz	–
Upstream > Downstream	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `TC2S1L1_STATE`,
B = `TC2S1L2_STATE`

5 Ignored when BXG Is Off or YAG01 Is In

5.1 Wakefield Shield Gun Spectrometer

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	10 Hz	10 Hz	10 Hz	–

Where
A = `WL_BL231_IN_STATE`

6 Ignored when BXG Is On or YAG01 Is In

6.1 Wakefield Shield Straight Ahead

Name	A	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `WL_BL231_OUT_STATE`

7 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Diag Stopper XCS SB1 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XCS Is Not In Main Line, YAG01 Is In, or YAG02 Is In

7.1 XCS SB1 VGC 02 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `XCS_SB1_VGC_02_OPN_DI_POSITION`,
B = `XCS_SB1_VGC_02_CLS_DI_POSITION`

7.2 XCS SB2 VGC 01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `XCS_SB2_VGC_01_OPN_DI_POSITION`,
B = `XCS_SB2_VGC_01_CLS_DI_POSITION`

8 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Stopper S5B Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

8.1 CXI Configuration 1 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigOne = -1;
{
        if ( CXI_MPS_CFG_1_CONFID ) /* EPS PLC asserts we are in config
            1 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                    state for Cfg 1 */
                if ((! CXI_DG1_MMS_03_A_POSITION) ||
                (! CXI_DG2_MMS_06_B_POSITION) ||
                (! CXI_SC1_VGC_02_OPN_DI_POSITION) )
                {
                        evalCXIConfigOne = 0;
                }
                else
                {
                        evalCXIConfigOne = 1;
                }
        }
}
```

```
switch( evalCXIConfigOne )
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
}
}
```

Name	State	PC	MS	BYKIK	LHS
Config 1 Fault	0	0 Hz	0 Hz	0 Hz	–
Config 1 Ok	1	120 Hz	120 Hz	120 Hz	–
Not In Config 1	2	120 Hz	120 Hz	120 Hz	–

8.2 CXI Configuration 2 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigTwo = -1;
{
        if ( CXI_MPS_CFG_2_CONFID ) /* EPS PLC asserts we are in config
            2 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                    state for Cfg 2 */
                if (    (! CXI_DG1_MMS_03_A_POSITION) ||
                        (! CXI_SC1_VGC_02_OPN_DI_POSITION) || /* If the
                            valve is not open, trip */
                        (       (! CXI_DIA_ATTEN_OK_POSITION) && /* DIA
                            attenuation */
                                (! (    CXI_DG1_MMS_08_B_POSITION &&
                                                CXI_DG1_MMS_08_B_POSITION
                                                    &&
```

```
                                                        CXI_DG2_MMS_08_B_POSITION
                                                            &&
                                                        CXI_DG2_MMS_09_B_POSITION
                                                            &&
                                                        CXI_DG2_MMS_10_B_POSITION
                                                            &&
                                                        CXI_DG4_MMS_05_B_POSITION
                                                            &&
                                                        CXI_DG4_MMS_03_B_POSITION

                                                    )
                                                )
                                            )
                                            )
                        {
                                evalCXIConfigTwo = 0;
                        }
                        else
                        {
                                evalCXIConfigTwo = 1;
                        }
        }
}

switch( evalCXIConfigTwo )
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
}
}
```

Name	State	PC	MS	BYKIK	LHS
Faulted	0	0 Hz	0 Hz	0 Hz	–
Ok	1	120 Hz	120 Hz	120 Hz	–
Not In Config 2	2	120 Hz	120 Hz	120 Hz	–

8.3 CXI Configuration 3 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
```

```
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigThree = -1;
{
        if ( CXI_MPS_CFG_3_CONFID ) /* EPS PLC asserts we are in config
            3 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                   state for Cfg 3 */
                if ((! CXI_DG1_MMS_03_A_POSITION) ||
                (! CXI_SC1_VGC_02_OPN_DI_POSITION) )
                {
                        evalCXIConfigThree = 0;
                }
                else
                {
                        evalCXIConfigThree = 1;
                }
        }
}

switch( evalCXIConfigThree )
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
}
}
```

Name	State	PC	MS	BYKIK	LHS
Faulted	0	0 Hz	0 Hz	0 Hz	–
Ok	1	120 Hz	120 Hz	120 Hz	–
Not in Config 3	2	120 Hz	120 Hz	120 Hz	–

8.4 CXI Configuration 4 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigFour = -1;
{
        if ( CXI_MPS_CFG_4_CONFID ) /* EPS PLC asserts we are in config
            4 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                   state for Cfg 4 */
                if ((! CXI_DG1_MMS_03_A_POSITION) ||
                (! CXI_SC1_VGC_02_OPN_DI_POSITION) )
                {
                        evalCXIConfigFour = 0;
                }
                else
                {
                        evalCXIConfigFour = 1;
                }
        }
}

switch( evalCXIConfigFour )
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
}
}
```

Name	State	PC	MS	BYKIK	LHS
Faulted	0	0 Hz	0 Hz	0 Hz	–
Ok	1	120 Hz	120 Hz	120 Hz	–
Not In Config 4	2	120 Hz	120 Hz	120 Hz	–

8.5 CXI Configuration 5 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigFive = -1;
{
        if ( CXI_MPS_CFG_5_CONFID ) /* EPS PLC asserts we are in config
            5 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                   state for Cfg 5 */
                if ((! CXI_DG1_MMS_03_A_POSITION) ||
                (! CXI_SC1_VGC_02_OPN_DI_POSITION) )
                {
                        evalCXIConfigFive = 0;
                }
                else
                {
                        evalCXIConfigFive = 1;
                }
        }
}

switch( evalCXIConfigFive )
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
```

```
}
}
```

Name	State	PC	MS	BYKIK	LHS
Faulted	0	0 Hz	0 Hz	0 Hz	–
Ok	1	120 Hz	120 Hz	120 Hz	–
Not In Config 5	2	120 Hz	120 Hz	120 Hz	–

8.6 CXI Configuration 6 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigSix = -1;
{
        if ( CXI_MPS_CFG_6_CONFID ) /* EPS PLC asserts we are in config
            6 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                   state for Cfg 6 */
                if ((! CXI_DG1_MMS_03_A_POSITION) ||
                        (! CXI_DG2_MMS_06_B_POSITION) ||
                (! CXI_SC2_VGC_02_OPN_DI_POSITION) )
                {
                        evalCXIConfigSix = 0;
                }
                else
                {
                        evalCXIConfigSix = 1;
                }
        }
}

switch( evalCXIConfigSix )
```

```
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
}
}
```

Name	State	PC	MS	BYKIK	LHS
Faulted	0	0 Hz	0 Hz	0 Hz	–
Ok	1	120 Hz	120 Hz	120 Hz	–
Not In Config 6	2	120 Hz	120 Hz	120 Hz	–

8.7 CXI Configuration 7 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
state = 0 beam dump
state = 1 beam allowed
state = 2 other, beam allowed
*/

/* Initialize to a guard value */
state = (unsigned int) -1;
{
int evalCXIConfigSeven = -1;
{
        if ( CXI_MPS_CFG_7_CONFID ) /* EPS PLC asserts we are in config
            7 */
        {
                /* Evaluate inputs to identify if we're in beam dump
                   state for Cfg 7 */
                if ((! CXI_DG1_MMS_03_A_POSITION)       ||
                        (! CXI_SC1_VGC_02_OPN_DI_POSITION) ||
                (! CXI_SC2_VGC_02_OPN_DI_POSITION) )
                {
                        evalCXIConfigSeven = 0;
                }
                else
                {
                        evalCXIConfigSeven = 1;
                }
```

```
        }
}

switch( evalCXIConfigSeven )
{
        case 0: state = 0; break;
        case 1: state = 1; break;
        default: state = 2; break;
}
}
```

Name	State	PC	MS	BYKIK	LHS
Faulted	0	0 Hz	0 Hz	0 Hz	–
Ok	1	120 Hz	120 Hz	120 Hz	–
Not In Config 7	2	120 Hz	120 Hz	120 Hz	–

8.8 CXI KB2 VGC 02 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CXI_KB2_VGC_02_OPN_DI_POSITION`,
B = `CXI_KB2_VGC_02_CLS_DI_POSITION`

8.9 CXI MPS PLC Readiness Status

Name	*A*	PC	MS	BYKIK	LHS
PLC Not OK	F	0 Hz	0 Hz	0 Hz	–
PLC OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_MPS_PLC_01_OK_STATUS`

8.10 CXI User Patch Panel 1 Ready

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_USR_01_MPSFAULT_STATUS`

8.11 CXI User Patch Panel 2 Ready

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_USR_02_MPSFAULT_STATUS`

8.12 CXI:DG1:VGC:01 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_DG1_VGC_01_OPN_DI_POSITION`

8.13 CXI:DG1:VGC:02 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_DG1_VGC_02_OPN_DI_POSITION`

8.14 CXI:DG2:VGC:01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CXI_DG2_VGC_01_OPN_DI_POSITION`,
B = `CXI_DG2_VGC_01_CLS_DI_POSITION`

8.15 CXI:DG2:VGC:02 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CXI_DG2_VGC_02_OPN_DI_POSITION`,
B = `CXI_DG2_VCG_02_CLS_DI_POSITION`

8.16 CXI:DG4:VGC:01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CXI_DG4_VGC_01_OPN_DI_POSITION`,
B = `CXI_DG4_VGC_01_CLS_DI_POSITION`

8.17 CXI:DSC:VGC:01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CXI_DSC_VGC_01_OPN_DI_POSITION`,
B = `CXI_DSC_VGC_01_CLS_DI_POSITION`

8.18 CXI:KB1:VGC:01 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_KB1_VGC_01_OPN_DI_POSITION`

8.19 CXI:KB1:VGC:02 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CXI_KB1_VGC_02_OPN_DI_POSITION`

8.20 CXI:KB2:VGC:01 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = CXI_KB2_VGC_01_OPN_DI_POSITION

8.21 CXI:SC1:VGC:01 Gate Valve Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CXI_SC1_VGC_01_OPN_DI_POSITION,
B = CXI_SC1_VGC_01_CLS_DI_POSITION

8.22 CXI:SC3:VGC:01 Be Gate Valve Position - Status from PLC

Name	A	PC	MS	BYKIK	LHS
Moving or Broken	F	0 Hz	0 Hz	0 Hz	–
Open or Closed	T	120 Hz	120 Hz	120 Hz	–

Where
A = CXI_SC3_VGC_01_OPN_DI_POSITION

8.23 HF4 LAM VGC 01 Gate Valve Position

Name	A	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = HF4_LAM_VGC_01_OPN_DI_POSITION

9 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XCS Is Not In Main Line, YAG01 Is In, or YAG02 Is In

9.1 XCS SB1 Diagnostic Stopper Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `XCS_SB1_STP_01_OPN_DI_POSITION`,
B = `XCS_SB1_STP_01_CLS_DI_POSITION`

9.2 XCS SB1 VGC 01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `XCS_SB1_VGC_01_OPN_DI_POSITION`,
B = `XCS_SB1_VGC_01_CLS_DI_POSITION`

10 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S5 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

10.1 CXI XRT Laser Reference Mirror Position

Name	*A*	PC	MS	BYKIK	LHS
Mirror In Beam	F	0 Hz	0 Hz	0 Hz	–
Mirror Out of Beam	T	120 Hz	120 Hz	120 Hz	–

Where
A = `XRT_DIA_MMS_01_B_POSITION`

10.2 HFA:SND:VGC:01 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HFA_SND_VGC_01_OPN_DI_POSITION`

10.3 HFX:DIA:VGC:02 Gate Valve Open Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HFX_DIA_VGC_02_OPN_DI_POSITION`

10.4 PPS Stopper S5B Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
In	F	T	–	–	–	–
Out	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `STPR_FEH1_5_S5BIN_POSITION`,
B = `STPR_FEH1_5_S5BOUT_POSITION`

10.5 XRT HXRAY DIA Isolation Valve HXX-DIA-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HXX_DIA_VGC_01_CLS_DI_STATE`,
B = `HXX_DIA_VGC_01_OPN_DI_STATE`

11 Ignored when Diag Stopper HFX DG2 Is In, Diag Stopper HFX UM6 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

11.1 HFX:DG2:VGC:01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HFX_DG2_VGC_01_OPN_DI_POSITION`

11.2 HFX:MON:VGC:01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HFX_MON_VGC_01_OPN_DI_POSITION`

11.3 HFX:MON:VGC:02 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HFX_MON_VGC_02_OPN_DI_POSITION`

11.4 Stopper XRT S5 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `STPR_XRT1_1_S5OUT_POSITION`,
B = `STPR_XRT1_1_S5IN_POSITION`

12 Ignored when Diag Stopper HFX UM6 Is In, Stopper MFX S4.5 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

12.1 MFX MPS Summary - Downstream of Stopper 4.5

Name	*A*	PC	MS	BYKIK	LHS
Not Ok	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MFX_MPS_1_SUM_STATE`

13 Ignored when Diag Stopper HFX UM6 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper XRT S6 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

13.1 MEC DV4 VCG 01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_DV4_VGC_01_OPN_DI_POSITION`

13.2 MEC DV5 VGC 01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_DV5_VGC_01_OPN_DI_POSITION`

13.3 MEC HXM VGC 01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_HXM_VGC_01_OPN_DI_POSITION`

13.4 MEC XT1 Reference Laser Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_XT1_MMS_01_B_POSITION`

13.5 MEC XT1 VGC 01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_XT1_VGC_01_OPN_DI_POSITION`

13.6 MEC XT2 VGC 02 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_XT2_VGC_02_OPN_DI_POSITION`

13.7 MEC XT2 VGC 03 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_XT2_VGC_03_OPN_DI_POSITION`

13.8 MEC XT2 VGC 04 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_XT2_VGC_04_OPN_DI_POSITION`

13.9 MEC XT2 VGC 05 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `MEC_XT2_VGC_05_OPN_DI_POSITION`,
B = `MEC_XT2_VGC_05_CLS_DI_POSITION`

13.10 MEC XT2 VGC 06 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_XT2_VGC_06_OPN_DI_POSITION`

14 Ignored when Diag Stopper HFX UM6 Is In, Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

14.1 DG2 Diagnostic Stopper Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
In	F	T	–	–	–	–
Out	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HFX_DG2_STP_01_IN_DI_POSITION`,
B = `HFX_DG2_STP_01_OUT_DI_POSITION`

14.2 MEC BXL VGC 01 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_BXL_VGC_01_OPN_DI_POSITION`

14.3 MEC XRT Attenuator Inspection Mirror Position

Name	*A*	PC	MS	BYKIK	LHS
Mirror Not Out	F	0 Hz	0 Hz	0 Hz	–
Mirror Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MEC_HXM_MMS_04_B_POSITION`

14.4 MFX Gate Valve Summary - Upstream of Stopper 4.5

Name	*A*	PC	MS	BYKIK	LHS
Not All Out	F	0 Hz	0 Hz	0 Hz	–
All Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MFX_XRT_VGC_OUT_SUM_STATE`

14.5 Stopper MFX S4.5 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `STPR_XRT_1_S45OUT_STATE`,
B = `STPR_XRT_1_S45IN_STATE`

14.6 Stopper XRT S6 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
In	F	T	120 Hz	120 Hz	120 Hz	–
Out	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `STPR_XRT1_1_S6IN_POSITION`,
B = `STPR_XRT1_1_S6OUT_POSITION`

14.7 XRT HXRAY LOM Isolation Valve HXX-LOM-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = HXX_LOM_VGC_01_CLS_DI_STATE,
B = HXX_LOM_VGC_01_OPN_DI_STATE

14.8 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:01

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = HXX_MXT_VGC_01_OPN_DI_POSITION

14.9 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:02

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = HXX_MXT_VGC_02_OPN_DI_POSITION

14.10 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:03

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HXX_MXT_VGC_03_CLS_DI_POSITION`,
B = `HXX_MXT_VGC_03_OPN_DI_POSITION`

14.11 XRT HXRAY MXT Gate Valve HXX:MXT:VGC:05

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HXX_MXT_VGC_05_OPN_DI_POSITION`

14.12 XRT-M2 Mirror and DG2 STP Fault

Name	*B*	*A*	PC	MS	BYKIK	LHS
In Transit: DG2 STP Not In Beam, XRT-M2 Mirror Not Out	F	F	0 Hz	0 Hz	0 Hz	–
In Transit: DG2 STP Not In Beam, XRT-M2 Mirror Out	F	T	120 Hz	120 Hz	120 Hz	–
Safe: DG2 STP In Beam, XRT-M2 Mirror Not Out	T	F	120 Hz	120 Hz	120 Hz	–
Safe: DG2 STP In Beam, XRT-M2 Mirror Out	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HXX_HXM_MMS_01_B_POSITION`,
B = `HFX_DG2_STP_01_IN_DI_POSITION`

15 Ignored when Laser Heater Attenuator Is In

15.1 Laser Heater Photodiode Shutter Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	–	–	–	0 Hz
Out	F	T	–	–	–	0 Hz
In	T	F	–	–	–	120 Hz
Broken	T	T	–	–	–	0 Hz

Where
A = `LHPHD_OUT_LIMIT_STATE`,
B = `LHPHD_IN_LIMIT_STATE`

15.2 OTRH1 Position When LH Atten Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	–	–	–	0 Hz
Out	F	T	–	–	–	120 Hz
In	T	F	–	–	–	0 Hz
Broken	T	T	–	–	–	0 Hz

Where
A = `OTRH1_OUT_LIMIT_STATE`,
B = `OTRH1_IN_LIMIT_STATE`

15.3 OTRH2 Position When LH Atten Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	–	–	–	0 Hz
Out	F	T	–	–	–	120 Hz
In	T	F	–	–	–	0 Hz
Broken	T	T	–	–	–	0 Hz

Where
A = `OTRH2_OUT_LIMIT_STATE`,
B = `OTRH2_IN_LIMIT_STATE`

16 Ignored when Stopper S1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

16.1 NEH AMO Laser Reference Mirror Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = SAS_MMM_01_B_POSITION

16.2 NEH AMO Valves Ok for Beam - Summary From PLC

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = AMO_MPS_VAC_OK_SUM_STATE

16.3 NEH1 Camera 1124 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CAMR_NEH1_1124_OUT_STATE,
B = CAMR_NEH1_1124_IN_STATE

16.4 NEH1 XTOD S1 Isolation Valve Summary

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_NEH_703_ISOL_S1_STATE`

17 Ignored when Stopper S2 Is In, Stopper S2B Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

17.1 NEH SXR Differential Pump Isolation Valve SXR-DFP-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_DFP_VGC_01_CLS_DI_STATE,
B = SXR_DFP_VGC_01_OPN_DI_STATE

17.2 NEH SXR End Station Ready SXR-EXP-MPS-01

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = SXR_EXP_MPS_01_STATE

17.3 NEH SXR Intensity Monitor Isolation Valve SXR-FLX-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_FLX_VGC_01_CLS_DI_STATE,
B = SXR_FLX_VGC_01_OPN_DI_STATE

17.4 NEH SXR KB Optics Isolation Valve SXR-KBO-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_KBO_VGC_01_CLS_DI_STATE,
B = SXR_KBO_VGC_01_OPN_DI_STATE

17.5 NEH SXR Laser In-coupling Mirror Isolation Valve SXR-LIN-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_LIN_VGC_01_CLS_DI_STATE,
B = SXR_LIN_VGC_01_OPN_DI_STATE

18 Ignored when Stopper S2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

18.1 NEH Camera 2124 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CAMR_NEH1_2124_OUT_STATE`,
B = `CAMR_NEH1_2124_IN_STATE`

18.2 NEH SXR Collimator 3 Isolation Valve SXR-COL-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `SXR_COL_VGC_01_CLS_DI_STATE`,
B = `SXR_COL_VGC_01_OPN_DI_STATE`

18.3 NEH SXR Exit Slits Isolation Valve SXR-EXS-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_EXS_VGC_01_CLS_DI_STATE,
B = SXR_EXS_VGC_01_OPN_DI_STATE

18.4 NEH SXR GMD VGC 01 Protection

Name	*B*	*A*	PC	MS	BYKIK	LHS
In Transit: SXR GMD VGC 01 In Motion	F	F	0 Hz	0 Hz	0 Hz	–
Safe: SXR GMD VGC 01 Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed: SXR GMD VGC 01 Closed	T	F	0 Hz	0 Hz	0 Hz	–
Error: SXR GMD VGC 01 Open and Closed	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_GMD_VGC_01_OPN_DI_POSITION,
B = SXR_GMD_VGC_01_CLS_DI_POSITION

18.5 NEH SXR Monochromator Tank Isolation Valve SXR-MON-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_MON_VGC_01_CLS_DI_STATE,
B = SXR_MON_VGC_01_OPN_DI_STATE

18.6 NEH SXR Photon Stoppers Isolation Valve SXR-PST-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_PST_VGC_01_CLS_DI_STATE,
B = SXR_PST_VGC_01_OPN_DI_STATE

18.7 NEH SXR Transmission Sample System Isolation Valve SXR-TSS-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = SXR_TSS_VGC_01_CLS_DI_STATE,
B = SXR_TSS_VGC_01_OPN_DI_STATE

18.8 NEH SXR Zero Order Interlock SXR-MON-MMS-06, SXR-EXS-MMS-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Slits Not Open, No Zero Order	F	F	120 Hz	120 Hz	120 Hz	–
Slits Not Open, Zero Order Fault	F	T	0 Hz	0 Hz	0 Hz	–
Slits Open, No Zero Order	T	F	120 Hz	120 Hz	120 Hz	–
Slits Open, Zero Order	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = SXR_MON_MMS_06_B_STATE,
B = SXR_EXS_MMS_01_B_STATE

18.9 NEH1 XTOD S2 Isolation Valve Summary

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_NEH_703_ISOL_S2_STATE`

19 Ignored when Stopper SH1 Is In, Stopper SH2 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

19.1 UM6 Diagnostic Stopper Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
In	F	T	–	–	–	–
Out	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = HFX_UM6_STP_01_IN_DI_POSITION,
B = HFX_UM6_STP_01_OUT_DI_POSITION

19.2 XRT HXRAY UM6 Isolation Valve HXX-UM6-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = HXX_UM6_VGC_01_CLS_DI_STATE,
B = HXX_UM6_VGC_01_OPN_DI_STATE

19.3 XRT UM6 Camera Position HXX-UM6-CVP-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HXX_UM6_CVP_01_B_STATE`,
B = `HXX_UM6_CVP_01_A_STATE`

20 Ignored when Stopper SH1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XPP-NH3-POS-00 Beamline Is In, YAG01 Is In, or YAG02 Is In

20.1 NEH3 HXRAY DVD Isolation Valve HX3-DVD-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HX3_DVD_VGC_01_CLS_DI_STATE`,
B = `HX3_DVD_VGC_01_OPN_DI_STATE`

21 Ignored when Stopper SH1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, XPP-NH3-POS-00 Beamline Is Not In, YAG01 Is In, or YAG02 Is In

21.1 XPP SB2 VGC 01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `XPP_SB2_VGC_01_OPN_DI_POSITION`,
B = `XPP_SB2_VGC_01_CLS_DI_POSITION`

21.2 XPP SB2 VGC 02 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `XPP_SB2_VGC_02_OPN_DI_POSITION`

21.3 XPP SB2 VGC 03 Gate Valve Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `XPP_SB2_VGC_03_OPN_DI_POSITION`

22 Ignored when Stopper SH1 Is In, Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

22.1 HX2 UVD VGC 01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HX2_SB1_VGC_01_OPN_DI_STATE`,
B = `HX2_SB1_VGC_01_CLS_DI_STATE`

22.2 HX3 MON VGC 01 Gate Valve Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HX3_MON_VGC_01_OPN_DI_POSITION`,
B = `HX3_MON_VGC_01_CLS_DI_POSITION`

22.3 NEH HXTD Vacuum Valve Summary

Name	*A*	PC	MS	BYKIK	LHS
Not All Open	F	0 Hz	0 Hz	0 Hz	–
All Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_NEH1_HXTD_SUM_FAULT`

22.4 NEH1 Camera 124 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CAMR_NEH1_124_OUT_STATE,
B = CAMR_NEH1_124_IN_STATE

22.5 NEH1 Camera 195 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CAMR_NEH1_195_OUT_STATE,
B = CAMR_NEH1_195_IN_STATE

22.6 NEH2 HXRAY DVD Isolation Valve HX2-DVD-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Fault	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = HX2_DVD_VGC_01_CLS_DI_STATE,
B = HX2_DVD_VGC_01_OPN_DI_STATE

22.7 NEH3 HXRAY UVD Isolation Valve HX3-UVD-VGC-01

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Closed	F	T	0 Hz	0 Hz	0 Hz	–
Open	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `HX3_UVD_VGC_01_CLS_DI_STATE`,
B = `HX3_UVD_VGC_01_OPN_DI_STATE`

23 Ignored when Stopper: BSY D2 Summary Is In or TDUND Is In

23.1 HXRSS Beamline Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BMLN_UND1_1650_OUT_LMTSW_STATE`,
B = `BMLN_UND1_1650_IN_LMTSW_STATE`

23.2 HXRSS Chicane Bend Magnet Power Supply

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
ON	F	T	120 Hz	120 Hz	120 Hz	–
OFF	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BEND_UND1_1640_ON_STATE`,
B = `BEND_UND1_1640_OFF_STATE`

23.3 HXRSS Crystal Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = XTAL_UND1_1650_OUT_LMTSW_STATE,
B = XTAL_UND1_1650_IN_ENCDR_STATE

23.4 HXRSS Crystal Valid Position

Name	A	PC	MS	BYKIK	LHS
Not Valid	F	0 Hz	0 Hz	0 Hz	–
Valid	T	120 Hz	120 Hz	120 Hz	–

Where
A = XTAL_UND1_1650_POSITIONSTAT_STATE

23.5 HXRSS Mode State

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
 * state = 0 : full rate (120 Hz) beam allowed, HXRSS Seeded Mode
 * state = 1 : full rate (120 Hz) beam allowed, HXRSS SASE Mode
 * state = 2 : full rate (120 Hz) beam allowed, HXRSS Phase Shifter
    Mode
 * state = 3 : no beam allowed, HXRSS undefined state
*/

/* Initialize to a guard value */
state = (unsigned int) -1;

/*
 * Allow beam if HXRSS is ON, Seeded Mode: the raft is in;
 *                            the magnet is on in and tolerance;
 *                            the photon energy is OK;
 *                            the crystal is IN
 * Allow beam if HXRSS is OFF, SASE Mode: the raft is out;
 *                             the magnet is off;
 *                             the crystal is out
 * Allow beam if HXRSS is in Phase Shifter Mode: the raft is in;
 *                             the magnet is in ANY state;
 *                             the crystal is out
 * Otherwise, do not allow beam.
```

```
 */


/* Input Descriptions
*
* BEND_DMP1_400_INTOL_BRANGE_STATE= HXRSS Beam Energy OK when 10 GeV <
    E < 15 GeV
* XTAL_UND1_1650_OUT_LMTSW_STATE    = Crystal OUT Limit Switch
* XTAL_UND1_1650_IN_ENCDR_STATE      = Crystal IN Limit Switch, from
    encoder
* BMLN_UND1_1650_IN_LMTSW_STATE      = HXRSS Raft IN Limit Switch
* BMLN_UND1_1650_OUT_LMTSW_STATE    = HXRSS Raft OUT Limit Switch
* BEND_UND1_1640_INTOL_BMIN_STATE    = HXRSS Chicane Bend INTOL, greater
    than +0.6 kG-m
* BEND_UND1_1640_OFF_STATE                = HXRSS Chicane Bend String is
    OFF
* BEND_UND1_1640_ON_STATE                 = HXRSS Chicane Bend String is
    ON
*
*/

if ( BMLN_UND1_1650_IN_LMTSW_STATE &&
            BEND_UND1_1640_INTOL_BMIN_STATE &&
            BEND_UND1_1640_ON_STATE &&
            BEND_DMP1_400_INTOL_BRANGE_STATE &&
            ( XTAL_UND1_1650_IN_ENCDR_STATE   ) )
{
    state = 0; /* HXRSS ON, HXRSS Seeded Mode, okay to run beam */
}

else if ( BMLN_UND1_1650_OUT_LMTSW_STATE &&
            BEND_UND1_1640_OFF_STATE &&
            XTAL_UND1_1650_OUT_LMTSW_STATE )
{
    state = 1; /* HXRSS OFF,SASE Mode, okay to run beam */
}

else if ( BMLN_UND1_1650_IN_LMTSW_STATE &&
            XTAL_UND1_1650_OUT_LMTSW_STATE )
{
    state = 2; /* HXRSS in Phase Shifter Mode, okay to run beam */
}

else
{
```

```
    state = 3; /* HXRSS Undefined State, no beam allowed */
}
```

Name	State	PC	MS	BYKIK	LHS
HXRSS Seeded Mode	0	120 Hz	120 Hz	120 Hz	–
HXRSS SASE Mode	1	120 Hz	120 Hz	120 Hz	–
HXRSS Phase Shifter Mode	2	120 Hz	120 Hz	120 Hz	–
HXRSS Undefined State	3	0 Hz	0 Hz	0 Hz	–

23.6 SXRSS Grating/M1 GRAT UND1 934 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `GRAT_UND1_934_OUT_LIMIT_POSITION`,
B = `GRAT_UND1_934_IN_LIMIT_POSITION`

23.7 SXRSS M2 MIRR UND1 964 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `MIRR_UND1_964_OUT_LIMIT_POSITION`,
B = `MIRR_UND1_964_IN_LIMIT_POSITION`

23.8 SXRSS M3 MIRR UND1 966 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `MIRR_UND1_966_OUT_LIMIT_POSITION`,
B = `MIRR_UND1_966_IN_LIMIT_POSITION`

23.9 SXRSS Mode State

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/* Production MPS SXRSS Modes
 *
 * state = 0 : full rate (120 Hz) beam allowed, SXRSS Seeded Mode
 * state = 1 : full rate (120 Hz) beam allowed, SXRSS SASE Mode
 * state = 2 : full rate (120 Hz) beam allowed, Harmonic Mode
 * state = 3 : no beam allowed, SXRSS undefined state
 *
 * Allow beam if SXRSS is ON, Seeded Mode:
 *                              { grating/M1 is IN and M3 is IN or OUT
    }
 *                             OR
 *                             { slit is IN and grating/M1/M2/M3 are
    OUT }
 *                             chicane is ON;
 *                             e- beam position OK  [mm]
 *                             e- beam energy   OK [GeV]
 *                             upstream undulators IN OK
 * Allow beam if SXRSS is OFF, SASE Mode:
 *                              grating/M1 is OUT;
 *                              slit is OUT;
 *                             M2 is OUT;
 *                             M3 is OUT;
 *                             e- beam position    OK  [mm]
 * Allow beam if SXRSS is in Harmonic Mode:
 *                              grating/M1 is OUT;
 *                              slit is NOT_IN and NOT_OUT;
 *                             M2 is OUT;
```

```
*                                M3 is OUT;
*                                chicane is ON;
*                                e- beam position  OK  [mm]
*                                e- beam energy     OK       [GeV]
* Otherwise, do not allow beam.
*
* Input Descriptions
*
*  Link Node MPS PV Name                  Link Node MPS Fault Name
                Desciption
* ------------------------------
   --------------------------------
   ------------------------------------------------
*  BEND:UND1:940:ON_MPS                =  BEND_UND1_940_ON_STATE
               =  Chicane power supply on
*  GRAT:UND1:934:IN_LIMIT_MPS          =  GRAT_UND1_934_IN_LIMIT_POSITION
      =  Grating/M1 IN limit switch
*  GRAT:UND1:934:OUT_LIMIT_MPS         =
   GRAT_UND1_934_OUT_LIMIT_POSITION    =  Grating/M1 OUT limit switch
*  SLIT:UND1:962:IN_LIMIT_MPS          =  SLIT_UND1_962_IN_LIMIT_POSITION
      =  Slit IN limit switch
*  SLIT:UND1:962:OUT_LIMIT_MPS         =
   SLIT_UND1_962_OUT_LIMIT_POSITION    =  Slit OUT limit switch
*  MIRR:UND1:964:IN_LIMIT_MPS          =  MIRR_UND1_964_IN_LIMIT_POSITION
      =  M2 IN limit switch
*  MIRR:UND1:964:OUT_LIMIT_MPS         =
   MIRR_UND1_964_OUT_LIMIT_POSITION    =  M2 OUT limit switch
*  MIRR:UND1:966:IN_LIMIT_MPS          =  MIRR_UND1_966_IN_LIMIT_POSITION
      =  M3 IN limit switch
*  MIRR:UND1:966:OUT_LIMIT_MPS         =
   MIRR_UND1_966_OUT_LIMIT_POSITION    =  M3 OUT limit switch
*  MPS:UND1:950:SX_HRMNC_ENERGY_MPS =
   MPS_UND1_950_SX_HRMNC_ENERGY_STATE =  e- beam energy safe for
   Harmonic mode
*  MPS:UND1:950:SX_HRMNC_X_MPS         =  MPS_UND1_950_SX_HRMNC_X_STATE
      =  e- beam position safe for Harmonic mode
*  MPS:UND1:950:SX_SASE_X_MPS          =  MPS_UND1_950_SX_SASE_X_STATE
      =  e- beam position safe for SASE mode
*  MPS:UND1:950:SX_SS_ENERGY_MPS       =  MPS_UND1_950_SX_SS_ENERGY_STATE
      =  e- beam energy safe for Seeded mode
*  MPS:UND1:950:SX_SS_UND_MPS          =  MPS_UND1_950_SX_SS_UND_STATE
      =  Inserted upstream undulators safe for Seeded mode
*  MPS:UND1:950:SX_SS_X_MPS            =  MPS_UND1_950_SX_SS_X_STATE
      =  e- beam position safe for Seeded mode
*/
```

```
/* Initialize to a guard value */
state = (unsigned int) -1;

if (     ((GRAT_UND1_934_IN_LIMIT_POSITION &&
         (MIRR_UND1_966_IN_LIMIT_POSITION ||
             MIRR_UND1_966_OUT_LIMIT_POSITION)) ||
          (SLIT_UND1_962_IN_LIMIT_POSITION  &&
              GRAT_UND1_934_OUT_LIMIT_POSITION &&
            MIRR_UND1_964_OUT_LIMIT_POSITION &&
                MIRR_UND1_966_OUT_LIMIT_POSITION)) &&
         BEND_UND1_940_ON_STATE &&
         MPS_UND1_950_SX_SS_X_STATE &&
         MPS_UND1_950_SX_SS_ENERGY_STATE &&
         MPS_UND1_950_SX_SS_UND_STATE )
{
    state = 0; /* SXRSS Seeded Mode, okay to run beam */
}

else if ( GRAT_UND1_934_OUT_LIMIT_POSITION &&
         SLIT_UND1_962_OUT_LIMIT_POSITION &&
         MIRR_UND1_964_OUT_LIMIT_POSITION &&
         MIRR_UND1_966_OUT_LIMIT_POSITION &&
         MPS_UND1_950_SX_SASE_X_STATE )
{
    state = 1; /* SXRSS SASE Mode, okay to run beam */
}

else if ( GRAT_UND1_934_OUT_LIMIT_POSITION &&
         !SLIT_UND1_962_IN_LIMIT_POSITION && !
             SLIT_UND1_962_OUT_LIMIT_POSITION &&
         MIRR_UND1_964_OUT_LIMIT_POSITION &&
         MIRR_UND1_966_OUT_LIMIT_POSITION &&
         BEND_UND1_940_ON_STATE &&
         MPS_UND1_950_SX_HRMNC_X_STATE &&
         MPS_UND1_950_SX_HRMNC_ENERGY_STATE )
{
    state = 2; /* SXRSS Harmonic Mode, okay to run beam */
}

else
{
    state = 3; /* SXRSS Undefined State, no beam allowed */
}
```

Name	State	PC	MS	BYKIK	LHS
SXRSS Seeded Mode	0	120 Hz	120 Hz	120 Hz	–
SXRSS SASE Mode	1	120 Hz	120 Hz	120 Hz	–
SXRSS Harmonic Mode	2	120 Hz	120 Hz	120 Hz	–
SXRSS Undefined State	3	0 Hz	0 Hz	0 Hz	–

23.10 SXRSS SLIT UND1 962 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	120 Hz	120 Hz	120 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `SLIT_UND1_962_OUT_LIMIT_POSITION`,
B = `SLIT_UND1_962_IN_LIMIT_POSITION`

23.11 SXRSS Watchdog

Name	*A*	PC	MS	BYKIK	LHS
NOT_OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_UND1_950_SXRSS_WDOG_STATE`

24 Ignored when Stopper: BSY D2 Summary Is In, TD11 Is In, TDUND Is In, YAG01 Is In, or YAG02 Is In

24.1 BCS PIC RAW Charge Threshold DMP 997

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PIC997_STATE`

24.2 BCS PIC RAW Charge Threshold DMP 998

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PIC998_STATE`

24.3 BFW 1010 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BFW_UND1_1010_OUT_STATE`,
B = `BFW_UND1_1010_IN_STATE`

24.4 BFW 110 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_110_OUT_STATE,
B = BFW_UND1_110_IN_STATE

24.5 BFW 1110 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1110_OUT_STATE,
B = BFW_UND1_1110_IN_STATE

24.6 BFW 1210 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1210_OUT_STATE,
B = BFW_UND1_1210_IN_STATE

24.7 BFW 1310 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1310_OUT_STATE,
B = BFW_UND1_1310_IN_STATE

24.8 BFW 1410 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1410_OUT_STATE,
B = BFW_UND1_1410_IN_STATE

24.9 BFW 1510 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1510_OUT_STATE,
B = BFW_UND1_1510_IN_STATE

24.10 BFW 1610 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1610_OUT_STATE,
B = BFW_UND1_1610_IN_STATE

24.11 BFW 1710 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1710_OUT_STATE,
B = BFW_UND1_1710_IN_STATE

24.12 BFW 1810 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1810_OUT_STATE,
B = BFW_UND1_1810_IN_STATE

24.13 BFW 1910 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_1910_OUT_STATE,
B = BFW_UND1_1910_IN_STATE

24.14 BFW 2010 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2010_OUT_STATE,
B = BFW_UND1_2010_IN_STATE

24.15 BFW 210 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_210_OUT_STATE,
B = BFW_UND1_210_IN_STATE

24.16 BFW 2110 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2110_OUT_STATE,
B = BFW_UND1_2110_IN_STATE

24.17 BFW 2210 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2210_OUT_STATE,
B = BFW_UND1_2210_IN_STATE

24.18 BFW 2310 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2310_OUT_STATE,
B = BFW_UND1_2310_IN_STATE

24.19 BFW 2410 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2410_OUT_STATE,
B = BFW_UND1_2410_IN_STATE

24.20 BFW 2510 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2510_OUT_STATE,
B = BFW_UND1_2510_IN_STATE

24.21 BFW 2610 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2610_OUT_STATE,
B = BFW_UND1_2610_IN_STATE

24.22 BFW 2710 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2710_OUT_STATE,
B = BFW_UND1_2710_IN_STATE

24.23 BFW 2810 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2810_OUT_STATE,
B = BFW_UND1_2810_IN_STATE

24.24 BFW 2910 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_2910_OUT_STATE,
B = BFW_UND1_2910_IN_STATE

24.25 BFW 3010 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_3010_OUT_STATE,
B = BFW_UND1_3010_IN_STATE

24.26 BFW 310 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_310_OUT_STATE,
B = BFW_UND1_310_IN_STATE

24.27 BFW 3110 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_3110_OUT_STATE,
B = BFW_UND1_3110_IN_STATE

24.28 BFW 3210 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_3210_OUT_STATE,
B = BFW_UND1_3210_IN_STATE

24.29 BFW 3310 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_3310_OUT_STATE,
B = BFW_UND1_3310_IN_STATE

24.30 BFW 410 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BFW_UND1_410_OUT_STATE,
B = BFW_UND1_410_IN_STATE

24.31 BFW 510 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BFW_UND1_510_OUT_STATE`,
B = `BFW_UND1_510_IN_STATE`

24.32 BFW 610 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BFW_UND1_610_OUT_STATE`,
B = `BFW_UND1_610_IN_STATE`

24.33 BFW 710 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BFW_UND1_710_OUT_STATE`,
B = `BFW_UND1_710_IN_STATE`

24.34 BFW 810 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BFW_UND1_810_OUT_STATE`,
B = `BFW_UND1_810_IN_STATE`

24.35 BFW 910 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BFW_UND1_910_OUT_STATE`,
B = `BFW_UND1_910_IN_STATE`

24.36 BFW Inserted Count

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
unsigned int beamFinderWireInCount = 0;

/* "BFW UND1 XXX" is IN when BFW_UND1_XXX_OUT_STATE == 0 */
if (!( BFW_UND1_110_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_210_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_310_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_410_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_510_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_610_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_710_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_810_OUT_STATE)) { beamFinderWireInCount++; }
if (!( BFW_UND1_910_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1010_OUT_STATE)) { beamFinderWireInCount++; }
```

```
if (!(BFW_UND1_1110_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1210_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1310_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1410_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1510_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1610_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1710_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1810_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_1910_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2010_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2110_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2210_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2310_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2410_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2510_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2610_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2710_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2810_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_2910_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_3010_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_3110_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_3210_OUT_STATE)) { beamFinderWireInCount++; }
if (!(BFW_UND1_3310_OUT_STATE)) { beamFinderWireInCount++; }

switch(beamFinderWireInCount)
{
    case 0:  state = 0; break; /* No BFWs in */
    case 1:  state = 1; break; /* One BFW in */
    default: state = 2; break; /* More than one BFW in */
}
```

Name	State	PC	MS	BYKIK	LHS
No BFWs In	0	120 Hz	120 Hz	120 Hz	–
One BFW In	1	10 Hz	10 Hz	10 Hz	–
More Than One BFW In	2	0 Hz	0 Hz	0 Hz	–

24.37 BLM Argonne Heartbeat (LN32)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_120_TEST_L_THRESHOLD,
B = BLM_UND1_120_TEST_H_THRESHOLD

24.38 BLM Argonne Heartbeat (LN33)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_920_TEST_L_THRESHOLD,
B = BLM_UND1_920_TEST_H_THRESHOLD

24.39 BLM Argonne Heartbeat (LN35)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1720_TEST_L_THRESHOLD,
B = BLM_UND1_1720_TEST_H_THRESHOLD

24.40 BLM Argonne Heartbeat (LN36)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2520_QTL_THRESHOLD,
B = BLM_2520_QTH_THRESHOLD

24.41 BLM Argonne Heartbeat (LN37)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_3320_TEST_L_THRESHOLD,
B = BLM_UND1_3320_TEST_H_THRESHOLD

24.42 BLM HVPS UND1 120

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_UND1_120_LOW_FAULT,
B = HVPS_UND1_120_HIGH_FAULT

24.43 BLM HVPS UND1 1720

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_UND1_1720_LOW_FAULT,
B = HVPS_UND1_1720_HIGH_FAULT

24.44 BLM HVPS UND1 2221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_UND1_2221_LOW_FAULT,
B = HVPS_UND1_2221_HIGH_FAULT

24.45 BLM HVPS UND1 2520

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_UND1_2520_LOW_FAULT,
B = HVPS_UND1_2520_HIGH_FAULT

24.46 BLM HVPS UND1 3320

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_UND1_3320_LOW_FAULT,
B = HVPS_UND1_3320_HIGH_FAULT

24.47 BLM HVPS UND1 920

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_UND1_920_LOW_FAULT,
B = HVPS_UND1_920_HIGH_FAULT

24.48 BLM Pedestal Thresholds: LTU1 722

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_722_PED_L_THRESHOLD,
B = BLM_LTU1_722_PED_H_THRESHOLD

24.49 BLM Pedestal Thresholds: LTU1 732

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_732_PED_L_THRESHOLD`,
B = `BLM_LTU1_732_PED_H_THRESHOLD`

24.50 BLM Pedestal Thresholds: LTU1 762

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_762_PED_L_THRESHOLD`,
B = `BLM_LTU1_762_PED_H_THRESHOLD`

24.51 BLM Pedestal Thresholds: LTU1 772

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_772_PED_L_THRESHOLD`,
B = `BLM_LTU1_772_PED_H_THRESHOLD`

24.52 BLM Pedestal Thresholds: LTU1 980

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_980_PED_L_THRESHOLD`,
B = `BLM_LTU1_980_PED_H_THRESHOLD`

24.53 BLM Pedestal Thresholds: UND 1021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1021_PED_L_THRESHOLD`,
B = `BLM_UND1_1021_PED_H_THRESHOLD`

24.54 BLM Pedestal Thresholds: UND 1121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1121_PED_L_THRESHOLD`,
B = `BLM_UND1_1121_PED_H_THRESHOLD`

24.55 BLM Pedestal Thresholds: UND 120

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_120_PED_L_THRESHOLD,
B = BLM_UND1_120_PED_H_THRESHOLD

24.56 BLM Pedestal Thresholds: UND 121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_121_PED_L_THRESHOLD,
B = BLM_UND1_121_PED_H_THRESHOLD

24.57 BLM Pedestal Thresholds: UND 1221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1221_PED_L_THRESHOLD,
B = BLM_UND1_1221_PED_H_THRESHOLD

24.58 BLM Pedestal Thresholds: UND 1321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1321_PED_L_THRESHOLD`,
B = `BLM_UND1_1321_PED_H_THRESHOLD`

24.59 BLM Pedestal Thresholds: UND 1421

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1421_PED_L_THRESHOLD`,
B = `BLM_UND1_1421_PED_H_THRESHOLD`

24.60 BLM Pedestal Thresholds: UND 1521

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1521_PED_L_THRESHOLD`,
B = `BLM_UND1_1521_PED_H_THRESHOLD`

24.61 BLM Pedestal Thresholds: UND 1621

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1621_PED_L_THRESHOLD`,
B = `BLM_UND1_1621_PED_H_THRESHOLD`

24.62 BLM Pedestal Thresholds: UND 1720

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1720_PED_L_THRESHOLD`,
B = `BLM_UND1_1720_PED_H_THRESHOLD`

24.63 BLM Pedestal Thresholds: UND 1721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1721_PED_L_THRESHOLD`,
B = `BLM_UND1_1721_PED_H_THRESHOLD`

24.64 BLM Pedestal Thresholds: UND 1821

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1821_PED_L_THRESHOLD,
B = BLM_UND1_1821_PED_H_THRESHOLD

24.65 BLM Pedestal Thresholds: UND 1921

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1921_PED_L_THRESHOLD,
B = BLM_UND1_1921_PED_H_THRESHOLD

24.66 BLM Pedestal Thresholds: UND 2021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_2021_PED_L_THRESHOLD,
B = BLM_UND1_2021_PED_H_THRESHOLD

24.67 BLM Pedestal Thresholds: UND 2121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_2121_PED_L_THRESHOLD,
B = BLM_UND1_2121_PED_H_THRESHOLD

24.68 BLM Pedestal Thresholds: UND 221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_221_PED_L_THRESHOLD,
B = BLM_UND1_221_PED_H_THRESHOLD

24.69 BLM Pedestal Thresholds: UND 2221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2220_QBLL_THRESHOLD,
B = BLM_2220_QBLH_THRESHOLD

24.70 BLM Pedestal Thresholds: UND 2321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2320_QBLL_THRESHOLD`,
B = `BLM_2320_QBLH_THRESHOLD`

24.71 BLM Pedestal Thresholds: UND 2421

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2420_QBLL_THRESHOLD`,
B = `BLM_2420_QBLH_THRESHOLD`

24.72 BLM Pedestal Thresholds: UND 2520

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2520_QBLL_THRESHOLD`,
B = `BLM_2520_QBLH_THRESHOLD`

24.73 BLM Pedestal Thresholds: UND 2521

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_2521_PED_L_THRESHOLD`,
B = `BLM_UND1_2521_PED_H_THRESHOLD`

24.74 BLM Pedestal Thresholds: UND 2621

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2620_QBLL_THRESHOLD`,
B = `BLM_2620_QBLH_THRESHOLD`

24.75 BLM Pedestal Thresholds: UND 2721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2720_QBLL_THRESHOLD`,
B = `BLM_2720_QBLH_THRESHOLD`

24.76 BLM Pedestal Thresholds: UND 2821

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2820_QBLL_THRESHOLD,
B = BLM_2820_QBLH_THRESHOLD

24.77 BLM Pedestal Thresholds: UND 2921

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2920_QBLL_THRESHOLD,
B = BLM_2920_QBLH_THRESHOLD

24.78 BLM Pedestal Thresholds: UND 3021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_3021_PED_L_THRESHOLD,
B = BLM_UND1_3021_PED_H_THRESHOLD

24.79 BLM Pedestal Thresholds: UND 3121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_3121_PED_L_THRESHOLD`,
B = `BLM_UND1_3121_PED_H_THRESHOLD`

24.80 BLM Pedestal Thresholds: UND 321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_321_PED_L_THRESHOLD`,
B = `BLM_UND1_321_PED_H_THRESHOLD`

24.81 BLM Pedestal Thresholds: UND 3221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_3221_PED_L_THRESHOLD`,
B = `BLM_UND1_3221_PED_H_THRESHOLD`

24.82 BLM Pedestal Thresholds: UND 3320

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_3320_PED_L_THRESHOLD`,
B = `BLM_UND1_3320_PED_H_THRESHOLD`

24.83 BLM Pedestal Thresholds: UND 3321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_3321_PED_L_THRESHOLD`,
B = `BLM_UND1_3321_PED_H_THRESHOLD`

24.84 BLM Pedestal Thresholds: UND 421

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_421_PED_L_THRESHOLD`,
B = `BLM_UND1_421_PED_H_THRESHOLD`

24.85 BLM Pedestal Thresholds: UND 521

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_521_PED_L_THRESHOLD`,
B = `BLM_UND1_521_PED_H_THRESHOLD`

24.86 BLM Pedestal Thresholds: UND 621

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_621_PED_L_THRESHOLD`,
B = `BLM_UND1_621_PED_H_THRESHOLD`

24.87 BLM Pedestal Thresholds: UND 721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_721_PED_L_THRESHOLD`,
B = `BLM_UND1_721_PED_H_THRESHOLD`

24.88 BLM Pedestal Thresholds: UND 821

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_821_PED_L_THRESHOLD,
B = BLM_UND1_821_PED_H_THRESHOLD

24.89 BLM Pedestal Thresholds: UND 920

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_920_PED_L_THRESHOLD,
B = BLM_UND1_920_PED_H_THRESHOLD

24.90 BLM Pedestal Thresholds: UND 921

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_921_PED_L_THRESHOLD,
B = BLM_UND1_921_PED_H_THRESHOLD

24.91 BLM Pedestal Thresholds: UND BLF1

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_BLF1_PED_L_THRESHOLD`,
B = `BLM_UND1_BLF1_PED_H_THRESHOLD`

24.92 BLM Pedestal Thresholds: UND BLF17

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_BLF17_PED_L_THRESHOLD`,
B = `BLM_UND1_BLF17_PED_H_THRESHOLD`

24.93 BLM PEP Timing Check (LN32)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_762_TEST_L_THRESHOLD`,
B = `BLM_LTU1_762_TEST_H_THRESHOLD`

24.94 BLM PEP Timing Check (LN33)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_621_TEST_L_THRESHOLD,
B = BLM_UND1_621_TEST_H_THRESHOLD

24.95 BLM PEP Timing Check (LN35)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1421_TEST_L_THRESHOLD,
B = BLM_UND1_1421_TEST_H_THRESHOLD

24.96 BLM PEP Timing Check (LN36)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2220_QTL_THRESHOLD,
B = BLM_2220_QTH_THRESHOLD

24.97 BLM PEP Timing Check (LN37)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_3021_TEST_L_THRESHOLD,
B = BLM_UND1_3021_TEST_H_THRESHOLD

24.98 BLM Raw Charge Thresholds: LTU1 722

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_722_LOSS_L_THRESHOLD,
B = BLM_LTU1_722_LOSS_H_THRESHOLD

24.99 BLM Raw Charge Thresholds: LTU1 732

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_732_LOSS_L_THRESHOLD,
B = BLM_LTU1_732_LOSS_H_THRESHOLD

24.100 BLM Raw Charge Thresholds: LTU1 762

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_762_LOSS_L_THRESHOLD`,
B = `BLM_LTU1_762_LOSS_H_THRESHOLD`

24.101 BLM Raw Charge Thresholds: LTU1 772

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_772_LOSS_L_THRESHOLD`,
B = `BLM_LTU1_772_LOSS_H_THRESHOLD`

24.102 BLM Raw Charge Thresholds: LTU1 980

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_980_LOSS_L_THRESHOLD`,
B = `BLM_LTU1_980_LOSS_H_THRESHOLD`

24.103 BLM Raw Charge Thresholds: UND 1021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1021_LOSS_L_THRESHOLD,
B = BLM_UND1_1021_LOSS_H_THRESHOLD

24.104 BLM Raw Charge Thresholds: UND 1121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1121_LOSS_L_THRESHOLD,
B = BLM_UND1_1121_LOSS_H_THRESHOLD

24.105 BLM Raw Charge Thresholds: UND 120

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_120_LOSS_L_THRESHOLD,
B = BLM_UND1_120_LOSS_H_THRESHOLD

24.106 BLM Raw Charge Thresholds: UND 121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_121_LOSS_L_THRESHOLD`,
B = `BLM_UND1_121_LOSS_H_THRESHOLD`

24.107 BLM Raw Charge Thresholds: UND 1221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1221_LOSS_L_THRESHOLD`,
B = `BLM_UND1_1221_LOSS_H_THRESHOLD`

24.108 BLM Raw Charge Thresholds: UND 1321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_1321_LOSS_L_THRESHOLD`,
B = `BLM_UND1_1321_LOSS_H_THRESHOLD`

24.109 BLM Raw Charge Thresholds: UND 1421

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1421_LOSS_L_THRESHOLD,
B = BLM_UND1_1421_LOSS_H_THRESHOLD

24.110 BLM Raw Charge Thresholds: UND 1521

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1521_LOSS_L_THRESHOLD,
B = BLM_UND1_1521_LOSS_H_THRESHOLD

24.111 BLM Raw Charge Thresholds: UND 1621

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1621_LOSS_L_THRESHOLD,
B = BLM_UND1_1621_LOSS_H_THRESHOLD

24.112 BLM Raw Charge Thresholds: UND 1720

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1720_LOSS_L_THRESHOLD,
B = BLM_UND1_1720_LOSS_H_THRESHOLD

24.113 BLM Raw Charge Thresholds: UND 1721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1721_LOSS_L_THRESHOLD,
B = BLM_UND1_1721_LOSS_H_THRESHOLD

24.114 BLM Raw Charge Thresholds: UND 1821

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1821_LOSS_L_THRESHOLD,
B = BLM_UND1_1821_LOSS_H_THRESHOLD

24.115 BLM Raw Charge Thresholds: UND 1921

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_1921_LOSS_L_THRESHOLD,
B = BLM_UND1_1921_LOSS_H_THRESHOLD

24.116 BLM Raw Charge Thresholds: UND 2021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_2021_LOSS_L_THRESHOLD,
B = BLM_UND1_2021_LOSS_H_THRESHOLD

24.117 BLM Raw Charge Thresholds: UND 2121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_2121_LOSS_L_THRESHOLD,
B = BLM_UND1_2121_LOSS_H_THRESHOLD

24.118 BLM Raw Charge Thresholds: UND 221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_221_LOSS_L_THRESHOLD,
B = BLM_UND1_221_LOSS_H_THRESHOLD

24.119 BLM Raw Charge Thresholds: UND 2221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2220_QBL_THRESHOLD,
B = BLM_2220_QBH_THRESHOLD

24.120 BLM Raw Charge Thresholds: UND 2321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2320_QBL_THRESHOLD,
B = BLM_2320_QBH_THRESHOLD

24.121 BLM Raw Charge Thresholds: UND 2421

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2420_QBL_THRESHOLD,
B = BLM_2420_QBH_THRESHOLD

24.122 BLM Raw Charge Thresholds: UND 2520

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2520_QBL_THRESHOLD,
B = BLM_2520_QBH_THRESHOLD

24.123 BLM Raw Charge Thresholds: UND 2521

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_2521_LOSS_L_THRESHOLD,
B = BLM_UND1_2521_LOSS_H_THRESHOLD

24.124 BLM Raw Charge Thresholds: UND 2621

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2620_QBL_THRESHOLD`,
B = `BLM_2620_QBH_THRESHOLD`

24.125 BLM Raw Charge Thresholds: UND 2721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2720_QBL_THRESHOLD`,
B = `BLM_2720_QBH_THRESHOLD`

24.126 BLM Raw Charge Thresholds: UND 2821

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_2820_QBL_THRESHOLD`,
B = `BLM_2820_QBH_THRESHOLD`

24.127 BLM Raw Charge Thresholds: UND 2921

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_2920_QBL_THRESHOLD,
B = BLM_2920_QBH_THRESHOLD

24.128 BLM Raw Charge Thresholds: UND 3021

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_3021_LOSS_L_THRESHOLD,
B = BLM_UND1_3021_LOSS_H_THRESHOLD

24.129 BLM Raw Charge Thresholds: UND 3121

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_3121_LOSS_L_THRESHOLD,
B = BLM_UND1_3121_LOSS_H_THRESHOLD

24.130 BLM Raw Charge Thresholds: UND 321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_321_LOSS_L_THRESHOLD`,
B = `BLM_UND1_321_LOSS_H_THRESHOLD`

24.131 BLM Raw Charge Thresholds: UND 3221

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_3221_LOSS_L_THRESHOLD`,
B = `BLM_UND1_3221_LOSS_H_THRESHOLD`

24.132 BLM Raw Charge Thresholds: UND 3320

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_3320_LOSS_L_THRESHOLD`,
B = `BLM_UND1_3320_LOSS_H_THRESHOLD`

24.133 BLM Raw Charge Thresholds: UND 3321

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_3321_LOSS_L_THRESHOLD,
B = BLM_UND1_3321_LOSS_H_THRESHOLD

24.134 BLM Raw Charge Thresholds: UND 421

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_421_LOSS_L_THRESHOLD,
B = BLM_UND1_421_LOSS_H_THRESHOLD

24.135 BLM Raw Charge Thresholds: UND 521

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_521_LOSS_L_THRESHOLD,
B = BLM_UND1_521_LOSS_H_THRESHOLD

24.136 BLM Raw Charge Thresholds: UND 621

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_621_LOSS_L_THRESHOLD`,
B = `BLM_UND1_621_LOSS_H_THRESHOLD`

24.137 BLM Raw Charge Thresholds: UND 721

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_721_LOSS_L_THRESHOLD`,
B = `BLM_UND1_721_LOSS_H_THRESHOLD`

24.138 BLM Raw Charge Thresholds: UND 821

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_821_LOSS_L_THRESHOLD`,
B = `BLM_UND1_821_LOSS_H_THRESHOLD`

24.139 BLM Raw Charge Thresholds: UND 920

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_920_LOSS_L_THRESHOLD`,
B = `BLM_UND1_920_LOSS_H_THRESHOLD`

24.140 BLM Raw Charge Thresholds: UND 921

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_921_LOSS_L_THRESHOLD`,
B = `BLM_UND1_921_LOSS_H_THRESHOLD`

24.141 BLM Raw Charge Thresholds: UND BLF1

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_UND1_BLF1_LOSS_L_THRESHOLD`,
B = `BLM_UND1_BLF1_LOSS_H_THRESHOLD`

24.142 BLM Raw Charge Thresholds: UND BLF17

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_BLF17_LOSS_L_THRESHOLD,
B = BLM_UND1_BLF17_LOSS_H_THRESHOLD

24.143 BLM Trigger Missed (LN32)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_762_NO_TRIG_MISSED

24.144 BLM Trigger Missed (LN33)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_6_NO_TRIG_MISSED

24.145 BLM Trigger Missed (LN35)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_14_NO_TRIG_MISSED

24.146 BLM Trigger Missed (LN36)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_TRIG_MISSED

24.147 BLM Trigger Missed (LN37)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_UND1_30_NO_TRIG_MISSED

24.148 BLM/PIC Watchdog: Downstream of TDUND

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_MCC0_2_PICBLM_WD_STATUS

24.149 BOD UND1 1005

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BOD_UND1_1005_OUT_LIMIT_POSITION,
B = BOD_UND1_1005_IN_LIMIT_POSITION

24.150 BOD UND1 1305

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BOD_UND1_1305_OUT_LIMIT_POSITION,
B = BOD_UND1_1305_IN_LIMIT_POSITION

24.151 BPM Summary (1-9) - Status From IOC-UND1-BP01

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = IOC_UND1_BP01_MPSSTAT_STATE

24.152 BPM Summary (10-18) - Status From IOC-UND1-BP02

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = IOC_UND1_BP02_MPSSTAT_STATE

24.153 BPM Summary (19-27) - Status From IOC-UND1-BP03

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = IOC_UND1_BP03_MPSSTAT_STATE

24.154 BPM Summary (28-36) - Status From IOC-UND1-BP04

Name	A	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = IOC_UND1_BP04_MPSSTAT_STATE

24.155 FEE Camera 1692 Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CAMR_FEE1_1692_OUT_STATE,
B = CAMR_FEE1_1692_IN_STATE

24.156 FEE Camera 1953 Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = CAMR_FEE1_1953_OUT_STATE,
B = CAMR_FEE1_1953_IN_STATE

24.157 FEE Camera 2953 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `CAMR_FEE1_2953_OUT_STATE`,
B = `CAMR_FEE1_2953_IN_STATE`

24.158 FEE Camera 852 Position Fault - Status From PLC

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CAMR_FEE1_852_STATUS_FAULT`

24.159 FEE Camera 913 Position Fault - Status From PLC

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CAMR_FEE1_913_STATUS_FAULT`

24.160 FEE Gas System Summary

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = VMPS_FEE1_GAS_SUM_FAULT

24.161 FEE HXTD Vacuum Valve Summary

Name	A	PC	MS	BYKIK	LHS
Not All Open	F	0 Hz	0 Hz	0 Hz	–
All Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = VMPS_FEE1_HXTD_SUM_FAULT

24.162 FEE M1S Mirror Beam Energy Upper Limit

Name	B	A	PC	MS	BYKIK	LHS
Fault	F	F	0 Hz	0 Hz	0 Hz	–
Mirror Out	F	T	120 Hz	120 Hz	120 Hz	–
Energy Ok	T	F	120 Hz	120 Hz	120 Hz	–
Mirror Out and Energy Ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = MIRR_FEE1_1560_OUT_LIMIT1_POSITION,
B = MIRR_FEE1_1560_ENERGY_STATE

24.163 FEE M1S Mirror State

Name	B	A	PC	MS	BYKIK	LHS
Not Out	F	F	120 Hz	120 Hz	120 Hz	–
Inconsistent	F	T	0 Hz	0 Hz	0 Hz	–
Inconsistent	T	F	0 Hz	0 Hz	0 Hz	–
Out	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = MIRR_FEE1_1560_OUT_LIMIT1_POSITION,
B = MIRR_FEE1_1560_OUT_LIMIT2_POSITION

24.164 FEE Spectrometer Crystal - Beam Energy Too Low When Crystal Not Out

Name	*B*	*A*	PC	MS	BYKIK	LHS
Fault	F	F	0 Hz	0 Hz	0 Hz	–
Energy Ok	F	T	120 Hz	120 Hz	120 Hz	–
Crystal Out	T	F	120 Hz	120 Hz	120 Hz	–
Crystal Out and Energy Ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `XTAL_FEE1_441_ENERGY_STATE`,
B = `XTAL_FEE1_441_OUT_LIMSW_POSITION`

24.165 FEE Spectrometer Crystal - Pulse Energy Too High When Crystal Not Out

Name	*B*	*A*	PC	MS	BYKIK	LHS
Fault	F	F	0 Hz	0 Hz	0 Hz	–
Pulse Energy Ok	F	T	120 Hz	120 Hz	120 Hz	–
Crystal Out	T	F	120 Hz	120 Hz	120 Hz	–
Crystal Out and Pulse Energy Ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `XTAL_FEE1_441_PULSEENERGY_THRESHOLD`,
B = `XTAL_FEE1_441_OUT_LIMSW_POSITION`

24.166 FEE XTOD S1 Isolation Valve Summary

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_FEE1_703_ISOL_S1_FAULT`

24.167 FEE XTOD S2 Isolation Valve Summary

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VMPS_FEE1_703_ISOL_S2_FAULT`

24.168 Gas Detector Problem When FEE Spectrometer Crystal Not Out

Name	*B*	*A*	PC	MS	BYKIK	LHS
Fault	F	F	0 Hz	0 Hz	0 Hz	–
Gas Detector Ok	F	T	120 Hz	120 Hz	120 Hz	–
Crystal Out	T	F	120 Hz	120 Hz	120 Hz	–
Crystal Out and Gas Detector Ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `GDET_FEE1_1_CAL_OK_STATE`,
B = `XTAL_FEE1_441_OUT_LIMSW_POSITION`

24.169 HXR - Beam Energy Too Low With M1S Out

Name	*B*	*A*	PC	MS	BYKIK	LHS
Ok	F	F	120 Hz	120 Hz	120 Hz	–
Ok	F	T	120 Hz	120 Hz	120 Hz	–
Ok	T	F	120 Hz	120 Hz	120 Hz	–
Fault	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `MIRR_FEE1_1560_ENERGY_STATE`,
B = `MIRR_FEE1_1560_OUT_LIMIT1_POSITION`

24.170 Magnet In Tolerance: QE31

Name	*A*	PC	MS	BYKIK	LHS
No	F	0 Hz	0 Hz	0 Hz	–
Yes	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_720_INTOL_STATUS

24.171 Magnet In Tolerance: QUM1

Name	*A*	PC	MS	BYKIK	LHS
No	F	0 Hz	0 Hz	0 Hz	–
Yes	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_820_INTOL_STATUS

24.172 Magnet In Tolerance: QUM2

Name	*A*	PC	MS	BYKIK	LHS
No	F	0 Hz	0 Hz	0 Hz	–
Yes	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_840_INTOL_STATUS

24.173 Magnet In Tolerance: QUM3

Name	*A*	PC	MS	BYKIK	LHS
No	F	0 Hz	0 Hz	0 Hz	–
Yes	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_860_INTOL_STATUS

24.174 Magnet In Tolerance: QUM4

Name	*A*	PC	MS	BYKIK	LHS
No	F	0 Hz	0 Hz	0 Hz	–
Yes	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_880_INTOL_STATUS

24.175 Magnet Power: QE31

Name	*A*	PC	MS	BYKIK	LHS
Off	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_720_STATE_STATUS

24.176 Magnet Power: QUM1

Name	*A*	PC	MS	BYKIK	LHS
Off	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_820_STATE_STATUS

24.177 Magnet Power: QUM2

Name	*A*	PC	MS	BYKIK	LHS
Off	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_840_STATE_STATUS

24.178 Magnet Power: QUM3

Name	*A*	PC	MS	BYKIK	LHS
Off	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_860_STATE_STATUS

24.179 Magnet Power: QUM4

Name	*A*	PC	MS	BYKIK	LHS
Off	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = QUAD_LTU1_880_STATE_STATUS

24.180 OTR01 IN20 541 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_IN20_541_OUT_LMTSW_STATE,
B = OTRS_IN20_541_IN_LMTSW_STATE

24.181 OTR02 IN20 571 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_IN20_571_OUT_LMTSW_STATE,
B = OTRS_IN20_571_IN_LMTSW_STATE

24.182 OTR03 IN20 621 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_IN20_621_OUT_LMTSW_STATE,
B = OTRS_IN20_621_IN_LMTSW_STATE

24.183 OTR04 IN20 711 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_IN20_711_OUT_LMTSW_STATE,
B = OTRS_IN20_711_IN_LMTSW_STATE

24.184 OTR11 LI21 237 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_LI21_237_OUT_LMTSW_STATE`,
B = `OTRS_LI21_237_IN_LMTSW_STATE`

24.185 OTR12 LI21 291 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_LI21_291_OUT_LMTSW_STATE`,
B = `OTRS_LI21_291_IN_LMTSW_STATE`

24.186 OTR21 Position When TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_LI24_807_OUT_LMTSW_STATE`,
B = `OTRS_LI24_807_IN_LMTSW_STATE`

24.187 OTR33 Position When TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTR33_0745_OUT_STATE`,
B = `OTR33_0745_IN_STATE`

24.188 OTRH1 Position When TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRH1_OUT_LIMIT_STATE`,
B = `OTRH1_IN_LIMIT_STATE`

24.189 OTRH2 Position When TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRH2_OUT_LIMIT_STATE`,
B = `OTRH2_IN_LIMIT_STATE`

24.190 PIC HVPS B921 - Location B921-2235

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_DMP1_B921_HV_PWR_STATE

24.191 PIC Raw Charge Thresholds: DMP1 698

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_DMP1_100_LOSSL_THRESHOLD,
B = PICS_DMP1_100_LOSSH_THRESHOLD

24.192 PIC Raw Charge Thresholds: DMP1 699

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_DMP2_200_LOSSL_THRESHOLD,
B = PICS_DMP2_200_LOSSH_THRESHOLD

24.193 PIC Trigger Missed (LN34)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_DMP1_100_NO_TRIG_MISSED

24.194 Toroid Comparator Dump (IMUNDO vs IMDUMP)

Name	B	A	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
3E8 ppb Gain	F	T	0 Hz	0 Hz	0 Hz	–
3E8 ppb Loss	T	F	0 Hz	0 Hz	0 Hz	–
Under 3E8 ppb Loss	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = IMUNDO_COMP_L1_STATE,
B = IMUNDO_COMP_L2_STATE

24.195 Toroid Comparator Power Status (B921)

Name	A	PC	MS	BYKIK	LHS
Powered Off	F	0 Hz	0 Hz	0 Hz	–
Powered On	T	120 Hz	120 Hz	120 Hz	–

Where
A = COMP_STAT_ON_STATE

24.196 Toroid Comparator Undulator (IMUNDI vs IMUNDO)

Name	B	A	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
3E8 ppb Gain	F	T	0 Hz	0 Hz	0 Hz	–
3E8 ppb Loss	T	F	0 Hz	0 Hz	0 Hz	–
Under 3E8 ppb Loss	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = IMUNDI_COMP_L1_STATE,
B = IMUNDI_COMP_L2_STATE

24.197 VVFS DMP1 107 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVFS_DMP1_107_OPEN_LMTSW_STATE`

24.198 VVMG DMP1 743 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVMG_DMP1_743_POSITION_STATE`

24.199 VVMG UND1 1645 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVMG_UND1_1645_OPEN_LMTSW_STATE`

24.200 VVMG UND1 1655 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVMG_UND1_1655_OPEN_LMTSW_STATE`

24.201 VVPG DMP1 355 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Open	F	T	120 Hz	120 Hz	120 Hz	–
Closed	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `VVPG_DMP1_355_OPENSTATUS_STATE`,
B = `VVPG_DMP1_355_CLOSEDSTATUS_STATE`

24.202 XLEAP PRXL1 - YAGS LTU1 844 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `YAGS_LTU1_844_OUT_LIMSW_POSITION`,
B = `YAGS_LTU1_844_IN_LIMSW_POSITION`

24.203 XLEAP PRXL2 - YAGS LTU1 853 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `YAGS_LTU1_853_OUT_LIMSW_POSITION`,
B = `YAGS_LTU1_853_IN_LIMSW_POSITION`

24.204 XLEAP PRXL3 - OTRS LTU1 858 Position and TDUND Not In

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_LTU1_858_OUT_LIMSW_POSITION`,
B = `OTRS_LTU1_858_IN_LIMSW_POSITION`

24.205 YAG LTU1 743 Position When TDUND Not In (PSI Prof Mon)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `YAGS_LTU1_743_OUT_LIMIT_POSITION`,
B = `YAGS_LTU1_743_IN_LIMIT_POSITION`

25 Ignored when Stopper: BSY D2 Summary Is In, TD11 Is In, YAG01 Is In, or YAG02 Is In

25.1 BCS LION LTU1 404 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION404_STATE`

25.2 BCS LION LTU1 405 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION405_STATE`

25.3 BCS LION LTU1 504 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION504_STATE`

25.4 BCS LION LTU1 505 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = LION505_STATE

25.5 BCS LION LTU1 584 Threshold

Name	A	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = LION584_STATE

25.6 BCS LION LTU1 585 Threshold

Name	A	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = LION585_STATE

25.7 BCS LION LTU1 716 Threshold

Name	A	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = LION716_STATE

25.8 BCS LION LTU1 717 Threshold

Name	A	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = LION717_STATE

25.9 BCS LION LTU1 732 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION732_STATE`

25.10 BCS LION LTU1 733 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION733_STATE`

25.11 BCS LION LTU1 752 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION752_STATE`

25.12 BCS LION LTU1 753 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION753_STATE`

25.13 BCS LION LTU1 765 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION765_STATE`

25.14 BCS LION LTU1 766 Threshold

Name	*A*	PC	MS	BYKIK	LHS
Exceeded	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `LION766_STATE`

25.15 BLM Heartbeat: Dechirper LTU1 BLF545

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BLM_LTU1_BLF545_TEST_L_THRESHOLD`,
B = `BLM_LTU1_BLF545_TEST_H_THRESHOLD`

25.16 BLM Heartbeat: XLEAP LTU1 BLF859

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_BLF859_TEST_L_THRESHOLD,
B = BLM_LTU1_BLF859_TEST_H_THRESHOLD

25.17 BLM HVPS LTU1 762

Name	B	A	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = HVPS_LTU1_762_LOW_FAULT,
B = HVPS_LTU1_762_HIGH_FAULT

25.18 BLM Pedestal Thresholds: Dechirper LTU1 BLF545

Name	B	A	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_BLF545_PED_L_THRESHOLD,
B = BLM_LTU1_BLF545_PED_H_THRESHOLD

25.19 BLM Pedestal Thresholds: XLEAP LTU1 BLF859

Name	B	A	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_BLF859_PED_L_THRESHOLD,
B = BLM_LTU1_BLF859_PED_H_THRESHOLD

25.20 BLM PEP Timing Check (LN30)

Name	B	A	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_722_TEST_L_THRESHOLD,
B = BLM_LTU1_722_TEST_H_THRESHOLD

25.21 BLM Raw Charge Thresholds: Dechirper LTU1 BLF545

Name	B	A	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_BLF545_LOSS_L_THRESHOLD,
B = BLM_LTU1_BLF545_LOSS_H_THRESHOLD

25.22 BLM Raw Charge Thresholds: XLEAP LTU1 BLF859

Name	B	A	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_BLF859_LOSS_L_THRESHOLD,
B = BLM_LTU1_BLF859_LOSS_H_THRESHOLD

25.23 BLM Timing Check (LN30)

Name	B	A	PC	MS	BYKIK	LHS
Bad Timing	F	F	0 Hz	0 Hz	0 Hz	–
Bad Timing High	F	T	0 Hz	0 Hz	0 Hz	–
Bad Timing Low	T	F	0 Hz	0 Hz	0 Hz	–
All OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_BLF859_TEST_L_THRESHOLD,
B = BLM_LTU1_BLF859_TEST_H_THRESHOLD

25.24 BLM Trigger Missed (LN30)

Name	A	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = BLM_LTU1_722_NO_TRIG_MISSED

25.25 BYD Watchdog

Name	A	PC	MS	BYKIK	LHS
NOT_OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = BEND_DMP1_400_BACT_WDOG_STATE

25.26 BYKIK 120 Hz Abort Trigger

Name	*A*	PC	MS	BYKIK	LHS
Missed Trigger	F	0 Hz	0 Hz	0 Hz	–
Stable	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BYKIK_120HZ_ABRT_TRIG_MISSED`

25.27 BYKIK 120 Hz Standby Trigger

Name	*A*	PC	MS	BYKIK	LHS
Missed Trigger	F	0 Hz	0 Hz	0 Hz	–
Stable	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BYKIK_120HZ_STBY_TRIG_MISSED`

25.28 BYKIK 30 Hz Abort Trigger

Name	*A*	PC	MS	BYKIK	LHS
Missed Trigger	F	0 Hz	0 Hz	0 Hz	–
Stable	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BYKIK_30HZ_ABRT_TRIG_MISSED`

25.29 BYKIK 30 Hz Standby Trigger

Name	*A*	PC	MS	BYKIK	LHS
Missed Trigger	F	0 Hz	0 Hz	0 Hz	–
Stable	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BYKIK_30HZ_STBY_TRIG_MISSED`

25.30 BYKIK Readback Signal

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = BYKIK_THRESHOLD_UNDER_FAULT,
B = BYKIK_THRESHOLD_OVER_FAULT

25.31 LTU Dechirper - Horizontal Gap Too Small

Name	*B*	*A*	PC	MS	BYKIK	LHS
Both ends gap too small	F	F	0 Hz	0 Hz	0 Hz	–
Downstream end gap too small	F	T	0 Hz	0 Hz	0 Hz	–
Upstream end gap too small	T	F	0 Hz	0 Hz	0 Hz	–
Gap ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = DCHP_LTU1_555_GAP_LIMSW_NEGZ_POSITION,
B = DCHP_LTU1_555_GAP_LIMSW_POSZ_POSITION

25.32 LTU Dechirper - Vertical Gap Too Small

Name	*B*	*A*	PC	MS	BYKIK	LHS
Both ends gap too small	F	F	0 Hz	0 Hz	0 Hz	–
Downstream end gap too small	F	T	0 Hz	0 Hz	0 Hz	–
Upstream end gap too small	T	F	0 Hz	0 Hz	0 Hz	–
Gap ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = DCHP_LTU1_545_GAP_LIMSW_NEGZ_POSITION,
B = DCHP_LTU1_545_GAP_LIMSW_POSZ_POSITION

25.33 Magnet In Tolerance: BYD1

Name	*A*	PC	MS	BYKIK	LHS
No	F	0 Hz	0 Hz	0 Hz	–
Yes	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BEND_DMP1_400_INTOL_STATUS`

25.34 Magnet Power: BYD1

Name	*A*	PC	MS	BYKIK	LHS
Off	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BEND_DMP1_400_STATE_STATUS`

25.35 OTR33 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTR33_0745_OUT_STATE`,
B = `OTR33_0745_IN_STATE`

25.36 PIC HVPS B911 - Location B911-2135

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LTU1_B911_HV_PWR_STATE`

25.37 PIC HVPS B912 - Location B912-2135

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LTU1_B912_HV_PWR_STATE

25.38 PIC HVPS B913 - Location B913-2135

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LTU1_B913_HV_PWR_STATE

25.39 PIC Raw Charge Thresholds: LTU1 220

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_220_LOSSL_THRESHOLD,
B = PICS_LTU1_220_LOSSH_THRESHOLD

25.40 PIC Raw Charge Thresholds: LTU1 252

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_252_LOSSL_THRESHOLD,
B = PICS_LTU1_252_LOSSH_THRESHOLD

25.41 PIC Raw Charge Thresholds: LTU1 280

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_280_LOSSL_THRESHOLD,
B = PICS_LTU1_280_LOSSH_THRESHOLD

25.42 PIC Raw Charge Thresholds: LTU1 420

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_420_LOSSL_THRESHOLD,
B = PICS_LTU1_420_LOSSH_THRESHOLD

25.43 PIC Raw Charge Thresholds: LTU1 450

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_450_LOSSL_THRESHOLD,
B = PICS_LTU1_450_LOSSH_THRESHOLD

25.44 PIC Raw Charge Thresholds: LTU1 480

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_480_LOSSL_THRESHOLD,
B = PICS_LTU1_480_LOSSH_THRESHOLD

25.45 PIC Raw Charge Thresholds: LTU1 722

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_722_LOSSL_THRESHOLD,
B = PICS_LTU1_722_LOSSH_THRESHOLD

25.46 PIC Raw Charge Thresholds: LTU1 732

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LTU1_732_LOSSL_THRESHOLD,
B = PICM_LTU1_732_LOSSH_THRESHOLD

25.47 PIC Raw Charge Thresholds: LTU1 762

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_762_LOSSL_THRESHOLD,
B = PICS_LTU1_762_LOSSH_THRESHOLD

25.48 PIC Raw Charge Thresholds: LTU1 772

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_772_LOSSL_THRESHOLD,
B = PICS_LTU1_772_LOSSH_THRESHOLD

25.49 PIC Trigger Missed (LN28)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_220_NO_TRIG_MISSED

25.50 PIC Trigger Missed (LN29)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_480_NO_TRIG_MISSED

25.51 PIC Trigger Missed (LN31)

Name	A	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICS_LTU1_762_NO_TRIG_MISSED

25.52 TDUND Flow Switch Fault With TDUND Not Out

Name	B	A	PC	MS	BYKIK	LHS
Fault	F	F	0 Hz	0 Hz	0 Hz	–
Ok	F	T	120 Hz	120 Hz	120 Hz	–
Ok, TDUND Out	T	F	120 Hz	120 Hz	120 Hz	–
Ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = TDUND_FS_STATE,
B = DUMP_LTU1_970_TDUND_OUT_POSITION

25.53 TDUND Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = DUMP_LTU1_970_TDUND_OUT_POSITION,
B = DUMP_LTU1_970_TDUND_IN_POSITION

25.54 THZ-2 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `THZR_LTU1_741_OUT_LIMSW_POSITION`,
B = `THZR_LTU1_741_IN_LIMSW_POSITION`

25.55 Undulator Beam Energy Lower Limit

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BEND_DMP1_400_INTOL_BMIN_STATE`

25.56 VVFS LTU1 102 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACFS_LTU1_102_STATE`

25.57 VVMG LTU1 174 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACV_LTU1_174_STATE`

25.58 VVMG LTU1 355 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VACV_LTU1_355_STATE

25.59 VVMG LTU1 505 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0505_STATE

25.60 VVMG LTU1 670 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0670_STATE

25.61 VVMG LTU1 742 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0742_STATE

25.62 VVMG LTU1 774 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0774_STATE

25.63 VVMG UND1 932 Position

Name	*A*	PC	MS	BYKIK	LHS
NOT_OUT	F	0 Hz	0 Hz	0 Hz	–
OUT	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVMG_UND1_932_OUT_LIMIT_POSITION

25.64 VVMG UND1 968 Position

Name	*A*	PC	MS	BYKIK	LHS
NOT_OUT	F	0 Hz	0 Hz	0 Hz	–
OUT	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVMG_UND1_968_OUT_LIMIT_POSITION

25.65 VVPG DMP1 103 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VACV_DMP_100_STATE

25.66 VVPG DMP1 395 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACV_DMP_395_STATE`

25.67 VVPG DMP1 700 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACV_DMP_700_STATE`

25.68 VVPG LTU1 100 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACV_LTU1_100_STATE`

25.69 VVPG LTU1 265 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VACV_LTU1_265_STATE`

25.70 VVPG LTU1 435 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0435_STATE

25.71 VVPG LTU1 580 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0580_STATE

25.72 VVPG LTU1 725 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0725_STATE

25.73 VVPG LTU1 757 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0757_STATE

25.74 VVPG LTU1 999 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_0999_STATE

25.75 VVPG UND1 1000 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VACV_LTU0_1000_OPEN_STATE

25.76 VVPG UND1 2500 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VACV_UND_2500_STATE

25.77 XLEAP MIRXL - MIRR LTU1 829 Position

Name	*C*	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	F	T	120 Hz	120 Hz	120 Hz	–
3 mm Aperture	F	T	F	120 Hz	120 Hz	120 Hz	–
Broken	F	T	T	0 Hz	0 Hz	0 Hz	–
5 mm Aperture	T	F	F	120 Hz	120 Hz	120 Hz	–
Broken	T	F	T	0 Hz	0 Hz	0 Hz	–
Broken	T	T	F	0 Hz	0 Hz	0 Hz	–
Broken	T	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = MIRR_LTU1_829_OUT_LIMSW_POSITION,
B = MIRR_LTU1_829_APERTURE_3MM_POSITION,
C = MIRR_LTU1_829_APERTURE_5MM_POSITION

25.78 XLEAP PRXL1 - YAGS LTU1 844 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = YAGS_LTU1_844_OUT_LIMSW_POSITION,
B = YAGS_LTU1_844_IN_LIMSW_POSITION

25.79 XLEAP PRXL2 - YAGS LTU1 853 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = YAGS_LTU1_853_OUT_LIMSW_POSITION,
B = YAGS_LTU1_853_IN_LIMSW_POSITION

25.80 XLEAP PRXL3 - OTRS LTU1 858 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_LTU1_858_OUT_LIMSW_POSITION,
B = OTRS_LTU1_858_IN_LIMSW_POSITION

25.81 XLEAP Wiggler - Downstream End Vertical Gap Too Small

Name	*B*	*A*	PC	MS	BYKIK	LHS
Gap too small	F	F	0 Hz	0 Hz	0 Hz	–
Gap too small (bottom switch)	F	T	0 Hz	0 Hz	0 Hz	–
Gap too small (top switch)	T	F	0 Hz	0 Hz	0 Hz	–
Gap ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `WIGG_LTU1_849_GAP_LIMSW_POSZ_TOP_POSITION`,
B = `WIGG_LTU1_849_GAP_LIMSW_POSZ_BOT_POSITION`

25.82 XLEAP Wiggler - Upstream End Vertical Gap Too Small

Name	*B*	*A*	PC	MS	BYKIK	LHS
Gap too small	F	F	0 Hz	0 Hz	0 Hz	–
Gap too small (bottom switch)	F	T	0 Hz	0 Hz	0 Hz	–
Gap too small (top switch)	T	F	0 Hz	0 Hz	0 Hz	–
Gap ok	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `WIGG_LTU1_849_GAP_LIMSW_NEGZ_TOP_POSITION`,
B = `WIGG_LTU1_849_GAP_LIMSW_NEGZ_BOT_POSITION`

25.83 YAG LTU1 743 Position (PSI Prof Mon)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `YAGS_LTU1_743_OUT_LIMIT_POSITION`,
B = `YAGS_LTU1_743_IN_LIMIT_POSITION`

26 Ignored when TD11 Is In, YAG01 Is In, or YAG02 Is In

26.1 BLM/PIC Watchdog BSY0/BSYA

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_BSY0_1_PICBLM_WD_STATUS`

26.2 BLM/PIC Watchdog LI24

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_LI24_1_PICBLM_WD_STATUS`

26.3 BLM/PIC Watchdog LI30

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_LI30_1_PICBLM_WD_STATUS`

26.4 Bunch Length Monitor BL21 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BL22_OUT_STATE,
B = BL22_IN_STATE

26.5 Dump LI28 5879 Flowswitch

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = DUMP_5879_FLOW_SW_STATE

26.6 Dump LI28 5879 Klixon

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = DUMP_5879_KLIXON_OK_STATE

26.7 Flowswitch: BSY RAD LCW Slit 10/30

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = HTEXCH2_STATE

26.8 Flowswitch: CE21

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COL_805_FLOSW_STATE`

26.9 Flowswitch: COLL BSYH 479, 487, 495, 503 (PCAPM1-4)

Name	*A*	PC	MS	BYKIK	LHS
FAULT	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_BSYH_479_PCAPM_FLOW_SW_STATE`

26.10 Flowswitch: COLL LI28-9

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `FLOW_SW_28_9_STATE`

26.11 Flowswitch: COLL LI29-1

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `FLOW_SW_29_1_STATE`

26.12 Flowswitch: COLL LI29-4

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FLOW_SW_29_4_STATE

26.13 Flowswitch: COLL LI29-5

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FLOW_SW_29_5_STATE

26.14 Flowswitch: COLL LI29-9

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FLOW_SW_29_9_STATE

26.15 Flowswitch: COLL LI30-1

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FLOW_SW_30_1_STATE

26.16 Flowswitch: COLL LI30-4

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `FLOW_SW_30_4_STATE`

26.17 Flowswitch: COLL LI30-5

Name	*A*	PC	MS	BYKIK	LHS
No Flow	F	0 Hz	0 Hz	0 Hz	–
Flow OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `FLOW_SW_30_5_STATE`

26.18 Hydrogen Recombiner For BSY 1 Collimator

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HYDRECM1_STATE`

26.19 Hydrogen Recombiner For BSY 2 Slit 10/30

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
Ok	T	120 Hz	120 Hz	120 Hz	–

Where
A = `HYDRECM2_STATE`

26.20 KICK BSYH 475 PM1 State (A-Line Kicker)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Inconsistent	F	F	0 Hz	0 Hz	0 Hz	–
Is_OFF	F	T	120 Hz	120 Hz	120 Hz	–
Is_ON	T	F	120 Hz	120 Hz	120 Hz	–
Inconsistent	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = KICK_BSY0_66_PM1_OFF_STATUS,
B = KICK_BSY0_66_PM1_ON_STATUS

26.21 KICK BSYH 475 PM1 Trigger State (A-Line Kicker)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Inconsistent	F	F	0 Hz	0 Hz	0 Hz	–
Is_Triggered	F	T	120 Hz	120 Hz	120 Hz	–
Is_Trig_Disabled	T	F	120 Hz	120 Hz	120 Hz	–
Inconsistent	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = KICK_BSY0_66_PM1_TRIG_ENB_STATUS,
B = KICK_BSY0_66_PM1_TRIG_LOCK_STATUS

26.22 KICK BSYH 491 PM3 State (A-Line Kicker)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Inconsistent	F	F	0 Hz	0 Hz	0 Hz	–
Is_OFF	F	T	120 Hz	120 Hz	120 Hz	–
Is_ON	T	F	120 Hz	120 Hz	120 Hz	–
Inconsistent	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = KICK_BSY0_66_PM2_OFF_STATUS,
B = KICK_BSY0_66_PM2_ON_STATUS

26.23 KICK BSYH 491 PM3 Trigger State (A-Line Kicker)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Inconsistent	F	F	0 Hz	0 Hz	0 Hz	–
Is_Triggered	F	T	120 Hz	120 Hz	120 Hz	–
Is_Trig_Disabled	T	F	120 Hz	120 Hz	120 Hz	–
Inconsistent	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = KICK_BSY0_66_PM2_TRIG_ENB_STATUS,
B = KICK_BSY0_66_PM2_TRIG_LOCK_STATUS

26.24 Main Manifold Gauge: LI22 Station 5

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_MM_GAUGE_OK_LI22_STATE

26.25 Main Manifold Gauge: LI23 Station 5

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_MM_GAUGE_OK_LI23_STATE

26.26 Main Manifold Gauge: LI24 Station 5

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_MM_GAUGE_OK_LI24_STATE

26.27 Main Manifold Gauge: LI25 Station 5

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_LI25_STATE`

26.28 Main Manifold Gauge: LI26 Station 5

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_LI26_STATE`

26.29 Main Manifold Gauge: LI27 Station 5

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_LI27_STATE`

26.30 Main Manifold Gauge: LI28 Station 5

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_LI28_STATE`

26.31 Main Manifold Gauge: LI29 Station 5

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_OK_STATE`

26.32 Main Manifold Gauge: LI30 Station 5

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MM_GAUGE_30_5_OK_STATE`

26.33 OTR LI25 920 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTR_TCAV_OUT_STATE`,
B = `OTR_TCAV_IN_STATE`

26.34 OTR21 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_LI24_807_OUT_LMTSW_STATE,
B = OTRS_LI24_807_IN_LMTSW_STATE

26.35 PIC Gas Pressure LI24

Name	A	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PIC_GAS_PRESS_STATE

26.36 PIC HVPS BSY 1 - Location B005-3921

Name	A	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSY0_1_HV_PWR_STATE

26.37 PIC HVPS BSY 2 - Location B005-3921

Name	A	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSY0_2_HV_PWR_STATE

26.38 PIC HVPS BSY 3 - Location B005-3921

Name	A	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSY0_3_HV_PWR_STATE

26.39 PIC HVPS BSY 4 - Location B005-3918

Name	A	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSY0_4_HV_PWR_STATE

26.40 PIC HVPS BSY 5 - Location B005-3918

Name	A	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSY0_5_HV_PWR_STATE

26.41 PIC HVPS BSY 6 - Location B005-3918

Name	A	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSY0_6_HV_PWR_STATE

26.42 PIC HVPS LI24 - Location LKF24-0235

Name	A	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI24_1_HV_PWR_STATE

26.43 PIC HVPS LI30 - KG30-C1322

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI30_1_HV_PWR_STATE

26.44 PIC Raw Charge Thresholds: BSYH 479 (PCAPM1)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSYH_479_LOSSL_THRESHOLD,
B = PICM_BSYH_479_LOSSH_THRESHOLD

26.45 PIC Raw Charge Thresholds: BSYH 487 (PCAPM2)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSYH_487_LOSSL_THRESHOLD,
B = PICM_BSYH_487_LOSSH_THRESHOLD

26.46 PIC Raw Charge Thresholds: BSYH 495 (PCAPM3)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYH_495_LOSSL_THRESHOLD`,
B = `PICM_BSYH_495_LOSSH_THRESHOLD`

26.47 PIC Raw Charge Thresholds: BSYH 503 (PCAPM4)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYH_503_LOSSL_THRESHOLD`,
B = `PICM_BSYH_503_LOSSH_THRESHOLD`

26.48 PIC Raw Charge Thresholds: BSYH 762 (PC90)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYH_762_LOSSL_THRESHOLD`,
B = `PICM_BSYH_762_LOSSH_THRESHOLD`

26.49 PIC Raw Charge Thresholds: BSYH 836 (PC119)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_BSYH_836_LOSSL_THRESHOLD`,
B = `PICM_BSYH_836_LOSSH_THRESHOLD`

26.50 PIC Raw Charge Thresholds: LI24 791

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI24_791_LOSSL_THRESHOLD`,
B = `PICM_LI24_791_LOSSH_THRESHOLD`

26.51 PIC Raw Charge Thresholds: LI24 811

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI24_811_LOSSL_THRESHOLD`,
B = `PICM_LI24_811_LOSSH_THRESHOLD`

26.52 PIC Raw Charge Thresholds: LI28 916

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI28_916_LOSSL_THRESHOLD`,
B = `PICM_LI28_916_LOSSH_THRESHOLD`

26.53 PIC Raw Charge Thresholds: LI29 146

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI29_146_LOSSL_THRESHOLD`,
B = `PICM_LI29_146_LOSSH_THRESHOLD`

26.54 PIC Raw Charge Thresholds: LI29 446

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI29_446_LOSSL_THRESHOLD`,
B = `PICM_LI29_446_LOSSH_THRESHOLD`

26.55 PIC Raw Charge Thresholds: LI29 546

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI29_546_LOSSL_THRESHOLD`,
B = `PICM_LI29_546_LOSSH_THRESHOLD`

26.56 PIC Raw Charge Thresholds: LI29 801

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI29_801_LOSSL_THRESHOLD`,
B = `PICM_LI29_801_LOSSH_THRESHOLD`

26.57 PIC Raw Charge Thresholds: LI29 956

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI29_956_LOSSL_THRESHOLD`,
B = `PICM_LI29_956_LOSSH_THRESHOLD`

26.58 PIC Raw Charge Thresholds: LI30 146

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI30_146_LOSSL_THRESHOLD`,
B = `PICM_LI30_146_LOSSH_THRESHOLD`

26.59 PIC Raw Charge Thresholds: LI30 446

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI30_446_LOSSL_THRESHOLD`,
B = `PICM_LI30_446_LOSSH_THRESHOLD`

26.60 PIC Raw Charge Thresholds: LI30 546

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_LI30_546_LOSSL_THRESHOLD`,
B = `PICM_LI30_546_LOSSH_THRESHOLD`

26.61 PIC Raw Charge Thresholds: LI30 801

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI30_801_LOSSL_THRESHOLD,
B = PICM_LI30_801_LOSSH_THRESHOLD

26.62 PIC Trigger Missed (LN16)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI24_791_NO_TRIG_MISSED

26.63 PIC Trigger Missed (LN22)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI28_916_NO_TRIG_MISSED

26.64 PIC Trigger Missed (LN25)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_BSY0_16_NO_TRIG_MISSED

26.65 Scraper Water LI21-9 (Station 22-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI22_STATE

26.66 Scraper Water LI22-9 (Station 23-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI23_STATE

26.67 Scraper Water LI23-9 (Station 24-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI24_STATE

26.68 Scraper Water LI24-9 (Station 25-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI25_STATE

26.69 Scraper Water LI25-9 (Station 26-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI26_STATE

26.70 Scraper Water LI26-9 (Station 27-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI27_STATE

26.71 Scraper Water LI27-9 (Station 28-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI28_STATE

26.72 Scraper Water LI28-9 (Station 29-1)

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SCRAPPER_FLOW_OK_LI29_STATE

26.73 Scraper Water LI29-9 (Station 30-1)

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_SCRAPPER_FLOW_OK_LI30_STATE`

26.74 Stopper LI28 950 and 960 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `BASII_STOPPER_OUT_STATE`

26.75 Stopper: BSY D2, 60, 61 DM60 Summary

The following code assigns the truth table's state number to the `unsigned int` variable `state`.

```
/*
 * state = 0 : full rate (120 Hz) beam allowed, ALL OUT
 * state = 1 : full rate (120 Hz) beam allowed, ALL IN
 * state = 2 : do not allow beam, Moving or Inconsistant
*/

/* Initialize to a guard value */
state = (unsigned int) -1;

/*
 * Stopper: BSY D2, 60, 61 DM60 Summary
 * Status given from PPS Stopper chassis very close to limit switches
    and CNTRL and passed to MPS via
 * opto's to insure fasts possible response. BTM60 has been documented
    to move at 200 msec from OUT to IN
 * Allow beam if ALL OUT
 * Allow beam if ALL IN
 * Otherwise, do not allow beam, Moving or Inconsistant
 */
```

```
/* Input Descriptions
*    INPUT_NAME                                                    ,
   FAULT_NAME (low)       , OK_NAME            , DESC
*       STPR_BSY0_89_IN_LIMSW_A_POSITION          , "IS_NOT_IN"
              , "IS_IN"       , "ST60 IN LIMSW CHAN A"
*       STPR_BSY0_89_IN_LIMSW_B_POSITION          , "IS_NOT_IN"
              , "IS_IN"       , "ST60 IN LIMSW CHAN B"
*       STPR_BSY0_89_OUT_LIMSW_A_POSITION         , "IS_NOT_OUT"
             , "IS_OUT"      , "ST60 OUT LIMSW CHAN A"
*       STPR_BSY0_89_OUT_LIMSW_B_POSITION         , "IS_NOT_OUT"
             , "IS_OUT"      , "ST60 OUT LIMSW CHAN B"
*       STPR_BSY0_90_IN_LIMSW_A_POSITION          , "IS_NOT_IN"
              , "IS_IN"       , "ST61 IN LIMSW CHAN A"
*       STPR_BSY0_90_IN_LIMSW_B_POSITION          , "IS_NOT_IN"
              , "IS_IN"       , "ST61 IN LIMSW CHAN B"
*       STPR_BSY0_90_OUT_LIMSW_A_POSITION         , "IS_NOT_OUT"
             , "IS_OUT"      , "ST61 OUT LIMSW CHAN A"
*       STPR_BSY0_90_OUT_LIMSW_B_POSITION         , "IS_NOT_OUT"
             , "IS_OUT"      , "ST61 OUT LIMSW CHAN B"
*       STPR_BSY0_88_IN_LIMSW_A_POSITION          , "IS_NOT_IN"
              , "IS_IN"       , "D2 IN LIMSW CHAN A"
*       STPR_BSY0_88_IN_LIMSW_B_POSITION          , "IS_NOT_IN"
              , "IS_IN"       , "D2 IN LIMSW CHAN B"
*       STPR_BSY0_88_OUT_LIMSW_A_POSITION         , "IS_NOT_OUT"
             , "IS_OUT"      , "D2 OUT LIMSW CHAN A"
*       BTM_BSY0_89_IN_LIMSW_A_POSITION           , "IS_NOT_IN"
              , "IS_IN"       , "BTM60 IN LIMSW CHAN A"
*       BTM_BSY0_89_IN_LIMSW_B_POSITION       , "IS_NOT_IN"          , "
   IS_IN"       , "BTM60 IN LIMSW CHAN B"
*       BTM_BSY0_89_OUT_LIMSW_A_POSITION          , "IS_NOT_OUT"
             , "IS_OUT"      , "BTM60 OUT LIMSW CHAN A"
*       BTM_BSY0_89_OUT_CNTRL_A_PPS_CNTRL         , "IS_NOT_OUT_RQ"
          , "IS_OUT_RQ" , "BTM60 OUT SOLN CNTRL CHAN A"
*       BTM_BSY0_89_OUT_CNTRL_B_PPS_CNTRL         , "IS_NOT_OUT_RQ"
          , "IS_OUT_RQ" , "BTM60 OUT SOLN CNTRL CHAN B2"
*
*/

if ( STPR_BSY0_89_OUT_LIMSW_A_POSITION &&
   STPR_BSY0_89_OUT_LIMSW_B_POSITION &&
            STPR_BSY0_90_OUT_LIMSW_A_POSITION &&
                STPR_BSY0_90_OUT_LIMSW_B_POSITION &&
            STPR_BSY0_88_OUT_LIMSW_A_POSITION &&
```

```
                BTM_BSY0_89_OUT_LIMSW_A_POSITION &&
            BTM_BSY0_89_OUT_CNTRL_A_PPS_CNTRL &&
                BTM_BSY0_89_OUT_CNTRL_B_PPS_CNTRL &&
            !( STPR_BSY0_89_IN_LIMSW_A_POSITION ||
                STPR_BSY0_89_IN_LIMSW_B_POSITION ||
                STPR_BSY0_90_IN_LIMSW_A_POSITION ||
                    STPR_BSY0_90_IN_LIMSW_B_POSITION ||
                STPR_BSY0_88_IN_LIMSW_A_POSITION ||
                    STPR_BSY0_88_IN_LIMSW_B_POSITION ||
                BTM_BSY0_89_IN_LIMSW_A_POSITION ||
                    BTM_BSY0_89_IN_LIMSW_B_POSITION ) )
{
    state = 0; /* ALL OUT, and NOT IN, okay to run beam */
}

else if ( STPR_BSY0_89_IN_LIMSW_A_POSITION &&
   STPR_BSY0_89_IN_LIMSW_B_POSITION &&
            STPR_BSY0_90_IN_LIMSW_A_POSITION &&
                STPR_BSY0_90_IN_LIMSW_B_POSITION &&
            STPR_BSY0_88_IN_LIMSW_A_POSITION &&
                STPR_BSY0_88_IN_LIMSW_B_POSITION &&
            BTM_BSY0_89_IN_LIMSW_A_POSITION &&
                BTM_BSY0_89_IN_LIMSW_B_POSITION &&
            !(STPR_BSY0_89_OUT_LIMSW_A_POSITION ||
                STPR_BSY0_89_OUT_LIMSW_B_POSITION ||
              STPR_BSY0_90_OUT_LIMSW_A_POSITION ||
                  STPR_BSY0_90_OUT_LIMSW_B_POSITION ||
              STPR_BSY0_88_OUT_LIMSW_A_POSITION ||
                  BTM_BSY0_89_OUT_LIMSW_A_POSITION ||
              BTM_BSY0_89_OUT_CNTRL_A_PPS_CNTRL ||
                  BTM_BSY0_89_OUT_CNTRL_B_PPS_CNTRL ) )
{
    state = 1; /* ALL IN and NOT OUT okay to run beam */
}

else
{
    state = 2; /* do not allow beam, Moving or Inconsistent */
}
```

Name	State	PC	MS	BYKIK	LHS
IS_OUT	0	120 Hz	120 Hz	120 Hz	–
IS_IN	1	120 Hz	120 Hz	120 Hz	–
Moving or Inconsistent	2	0 Hz	0 Hz	0 Hz	–

26.76 Sub-booster Ready: LI22

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_SBST_OK_READY_LI22_STATE`

26.77 Sub-booster Ready: LI25

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_SBST_OK_READY_LI25_STATE`

26.78 Sub-booster Ready: LI26

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_SBST_OK_READY_LI26_STATE`

26.79 Sub-booster Ready: LI27

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_SBST_OK_READY_LI27_STATE`

26.80 Sub-booster Ready: LI28

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SBST_OK_READY_LI28_STATE

26.81 Sub-booster Ready: LI29

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SBST_OK_READY_LI29_STATE

26.82 Sub-booster Ready: LI30

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_SBST_OK_READY_LI30_STATE

26.83 Temperature RTD Summary: BSY Common Line

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = RTD_BSY0_16_CLINESUM_STATUS

26.84 Toroid Chassis LI24 IMBC2

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `CHASIMB2_STATE`

26.85 Toroid Comparator BC2 (IMBC2IN vs IMBC2OUT)

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Downstream > Upstream	F	T	0 Hz	0 Hz	0 Hz	–
Upstream > Downstream	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `TCBC2L1_STATE`,
B = `TCBC2L2_STATE`

26.86 VVFS CLTH 101 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVFS_CLTH_101_OPEN_LIMSW_POSITION`

26.87 VVFS LI21-9 Position (Station 22-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `FAST_VLV_OPEN_LI22_STATE`

26.88 VVFS LI22-9 Position (Station 23-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI23_STATE

26.89 VVFS LI23-9 Position (Station 24-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI24_STATE

26.90 VVFS LI24-9 Position (Station 25-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI25_STATE

26.91 VVFS LI25-9 Position (Station 26-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI26_STATE

26.92 VVFS LI26-9 Position (Station 27-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI27_STATE

26.93 VVFS LI27-9 Position (Station 28-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI28_STATE

26.94 VVFS LI28-9 Position (Station 29-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI29_STATE

26.95 VVFS LI29-9 Position (Station 30-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = FAST_VLV_OPEN_LI30_STATE

26.96 VVPG BSYH 470 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVPG_BSYH_470_OPEN_LIMSW_POSITION`

26.97 VVPG BSYH 541 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVPG_BSYH_541_OPEN_LIMSW_POSITION`

26.98 VVPG BSYH 837 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVPG_BSYH_837_OPEN_LIMSW_POSITION`

26.99 VVPG CLTH 178 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVPG_CLTH_178_OPEN_LIMSW_POSITION`

26.100 VVPG CLTH 375 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVPG_CLTH_375_OPEN_LIMSW_POSITION

26.101 VVPG LI21-9 Position (Station 22-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI22_STATE

26.102 VVPG LI22-9 Position (Station 23-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI23_STATE

26.103 VVPG LI23-9 Position (Station 24-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI24_STATE

26.104 VVPG LI24 710 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VV21_STATE`

26.105 VVPG LI24 896 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VV22_STATE`

26.106 VVPG LI25-9 Position (Station 26-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `SLOW_VLV_OPEN_LI26_STATE`

26.107 VVPG LI26-9 Position (Station 27-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = `SLOW_VLV_OPEN_LI27_STATE`

26.108 VVPG LI27-9 Position (Station 28-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI28_STATE

26.109 VVPG LI28-9 Position (Station 29-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI29_STATE

26.110 VVPG LI29-9 Position (Station 30-1)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_OPEN_LI30_STATE

26.111 VVPG LI30-9 Position (Station 30-9)

Name	*A*	PC	MS	BYKIK	LHS
Not Open	F	0 Hz	0 Hz	0 Hz	–
Open	T	120 Hz	120 Hz	120 Hz	–

Where
A = SLOW_VLV_30_9_OK_OPEN_STATE

27 Ignored when YAG01 Is In

27.1 BXG Status

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Off	F	T	120 Hz	120 Hz	120 Hz	–
On	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = BEND_IN20_231_OFF_STATE,
B = BEND_IN20_231_OK_STATE

27.2 Toroid Peak Current Monitor IM01

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = TR_BL215_STATE

27.3 YAG02 IN20 241 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = YAGS_IN20_241_OUT_LMTSW_STATE,
B = YAGS_IN20_241_IN_LMTSW_STATE

28 Ignored when YAG01 Is In or YAG02 Is In

28.1 BLM/PIC Watchdog: Upstream of TDUND

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_MCC0_1_PICBLM_WD_STATUS`

28.2 BX01/BX02 Status

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Off	F	T	120 Hz	120 Hz	120 Hz	–
On	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `BEND_IN20_751_OFF_STATE`,
B = `BEND_IN20_751_OK_STATE`

28.3 Flowswitch: CE11

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `COLL_LI21_235_OPEN_STATE`

28.4 Flowswitch: TD11

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = FS_BL305_STATE

28.5 Main Manifold Gauge: LI21 Station 5

Name	A	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_MM_GAUGE_OK_LI21_STATE

28.6 Mirror BL11 Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	120 Hz	120 Hz	120 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = MIR_BL11_OUT_STATE,
B = MIR_BL11_IN_STATE

28.7 OTR01 IN20 541 Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = OTRS_IN20_541_OUT_LMTSW_STATE,
B = OTRS_IN20_541_IN_LMTSW_STATE

28.8 OTR02 IN20 571 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_IN20_571_OUT_LMTSW_STATE`,
B = `OTRS_IN20_571_IN_LMTSW_STATE`

28.9 OTR03 IN20 621 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_IN20_621_OUT_LMTSW_STATE`,
B = `OTRS_IN20_621_IN_LMTSW_STATE`

28.10 OTR04 IN20 711 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_IN20_711_OUT_LMTSW_STATE`,
B = `OTRS_IN20_711_IN_LMTSW_STATE`

28.11 OTR11 LI21 237 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_LI21_237_OUT_LMTSW_STATE`,
B = `OTRS_LI21_237_IN_LMTSW_STATE`

28.12 OTR12 LI21 291 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRS_LI21_291_OUT_LMTSW_STATE`,
B = `OTRS_LI21_291_IN_LMTSW_STATE`

28.13 OTRH1 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRH1_OUT_LIMIT_STATE`,
B = `OTRH1_IN_LIMIT_STATE`

28.14 OTRH2 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `OTRH2_OUT_LIMIT_STATE`,
B = `OTRH2_IN_LIMIT_STATE`

28.15 Sub-booster Ready: LI21

Name	*A*	PC	MS	BYKIK	LHS
Not Ready	F	0 Hz	0 Hz	0 Hz	–
Ready	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_SBST_OK_READY_LI21_STATE`

28.16 TD11 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	–	–
Out	F	T	120 Hz	120 Hz	–	–
In	T	F	120 Hz	120 Hz	–	–
Broken	T	T	0 Hz	0 Hz	–	–

Where
A = `TD11_OUT_LIMIT_STATE`,
B = `TD11_IN_LIMIT_STATE`

28.17 Toroid Chassis IN20 IM11

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = CHASIM11_STATE

28.18 Toroid Chassis IN20 IM12

Name	A	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = CHASIM12_STATE

28.19 Toroid Comparator BC1 (IMBC1IN vs IMBC1OUT)

Name	B	A	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Downstream - Upstream > 50 pC	F	T	0 Hz	0 Hz	0 Hz	–
Upstream - Downstream > 200 pC	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = TCBC1L1_STATE,
B = TCBC1L2_STATE

28.20 VVFV IN20 785 Position

Name	A	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVFV_IN20_785_OPEN_LMTSW_POSITION

28.21 VVMG LI21 195 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VV_BL195_STATE`

28.22 VVPG IN20 435 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VV_BL435_STATE`

28.23 VVPG IN20 545 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VV_BL545_STATE`

28.24 VVPG IN20 635 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VV_BL635_STATE`

28.25 VVPG IN20 915 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VV_IS915_STATE

28.26 VVS Circuit Breaker: LI22

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVS_BRKR_OK_READY_LI22_STATE

28.27 VVS Circuit Breaker: LI24

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVS_BRKR_OK_READY_LI24_STATE

28.28 VVS Circuit Breaker: LI26

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVS_BRKR_OK_READY_LI26_STATE

28.29 VVS Circuit Breaker: LI28

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVS_BRKR_OK_READY_LI28_STATE

28.30 VVS Circuit Breaker: LI30

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = VVS_BRKR_OK_READY_LI30_STATE

28.31 YAG03 IN20 351 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = YAGS_IN20_351_OUT_LMTSW_STATE,
B = YAGS_IN20_351_IN_LMTSW_STATE

28.32 YAGS1 IN20 921 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = YAGS_IN20_921_OUT_LMTSW_STATE,
B = YAGS_IN20_921_IN_LMTSW_STATE

28.33 YAGS2 LI21 995 Position

Name	B	A	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = YAGS_LI21_995_OUT_LMTSW_STATE,
B = YAGS_LI21_995_IN_LMTSW_STATE

29 Always Evaluated

29.1 Backward Beam Stopper (RST1)

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `ST_BL551_STATE`

29.2 BLM/PIC Watchdog: IN20

Name	*A*	PC	MS	BYKIK	LHS
Faulted	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MPS_IN20_1_PICBLM_WD_STATUS`

29.3 Bypass Recover

Name	*A*	PC	MS	BYKIK	LHS
Recovering	F	0 Hz	0 Hz	0 Hz	0 Hz
OK	T	120 Hz	120 Hz	120 Hz	120 Hz

Where
A = `LP_BYPASS_RECOVER`

29.4 Gun RF Peak Power 20-6

Name	*A*	PC	MS	BYKIK	LHS
OK	F	120 Hz	120 Hz	120 Hz	–
Fault	T	0 Hz	0 Hz	0 Hz	–

Where
A = `FLT_20_6_TRP_STATE`

29.5 Gun Waveguide Vacuum Summary

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `WGVACGUN_STATE`

29.6 IOC-IN20-MP01 MPS Support IOC Heartbeat

Name	*A*	PC	MS	BYKIK	LHS
Fault	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MN_HEART_STATE`

29.7 Laser Heater Attenuator Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	–	–	–	0 Hz
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	–	–	–	0 Hz

Where
A = `LHATTEN_OUT_LIMIT_STATE`,
B = `LHATTEN_IN_LIMIT_STATE`

29.8 MCC Emergency Radiation Stopper

Name	*A*	PC	MS	BYKIK	LHS
Not OK	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = `EMG_RAD_STOP_STATE`

29.9 Mechanical Shutter Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	–	0 Hz	–
Out	F	T	–	–	–	–
In	T	F	–	–	–	–
Broken	T	T	0 Hz	–	0 Hz	–

Where
A = `MPS_IN20_200_MSHT1_OUT_FAULT`,
B = `MPS_IN20_200_MSHT1_IN_FAULT`

29.10 Mirror AM01 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `MR_BL191_STATE`

29.11 MPS Beam Permit: BYKIK

Name	*A*	PC	MS	BYKIK	LHS
Not Permitted	F	–	–	0 Hz	–
Permitted	T	–	–	120 Hz	–

Where
A = `LP_ALLOWS_BEAM_BYKIK`

29.12 MPS Beam Permit: Gun RF

Name	*A*	PC	MS	BYKIK	LHS
Not Permitted	F	0 Hz	–	–	–
Permitted	T	120 Hz	–	–	–

Where
A = `LP_ALLOWS_BEAM_POCKELS_CELL`

29.13 MPS Beam Permit: Heater Shutter

Name	*A*	PC	MS	BYKIK	LHS
Not Permitted	F	–	–	–	0 Hz
Permitted	T	–	–	–	120 Hz

Where
A = LP_ALLOWS_BEAM_LH_SHUT

29.14 MPS Beam Permit: Mechanical Shutter

Name	*A*	PC	MS	BYKIK	LHS
Not Permitted	F	–	0 Hz	–	–
Permitted	T	–	120 Hz	–	–

Where
A = LP_ALLOWS_BEAM_MECH_SHUT

29.15 MPS Mechanical Shutter Position

Name	*A*	PC	MS	BYKIK	LHS
OK	F	120 Hz	120 Hz	120 Hz	–
Readback Does Not Match	T	0 Hz	0 Hz	0 Hz	–

Where
A = SHFLT_STATE

29.16 PIC HVPS LI20 - Location LKG-1535

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_LI20_1_HV_PWR_STATE

29.17 PIC Raw Charge Thresholds: IN20 185

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_IN20_185_LOSSL_THRESHOLD`,
B = `PICM_IN20_185_LOSSH_THRESHOLD`

29.18 PIC Raw Charge Thresholds: IN20 232

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_IN20_232_LOSSL_THRESHOLD`,
B = `PICM_IN20_232_LOSSH_THRESHOLD`

29.19 PIC Raw Charge Thresholds: IN20 245

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_IN20_245_LOSSL_THRESHOLD`,
B = `PICM_IN20_245_LOSSH_THRESHOLD`

29.20 PIC Raw Charge Thresholds: IN20 665

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_IN20_665_LOSSL_THRESHOLD`,
B = `PICM_IN20_665_LOSSH_THRESHOLD`

29.21 PIC Raw Charge Thresholds: IN20 775

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_IN20_775_LOSSL_THRESHOLD`,
B = `PICM_IN20_775_LOSSH_THRESHOLD`

29.22 PIC Raw Charge Thresholds: IN20 933

Name	*B*	*A*	PC	MS	BYKIK	LHS
Broken	F	F	0 Hz	0 Hz	0 Hz	–
Over High Threshold	F	T	0 Hz	0 Hz	0 Hz	–
Under Low Threshold	T	F	0 Hz	0 Hz	0 Hz	–
OK	T	T	120 Hz	120 Hz	120 Hz	–

Where
A = `PICM_IN20_933_LOSSL_THRESHOLD`,
B = `PICM_IN20_933_LOSSH_THRESHOLD`

29.23 PIC Trigger Missed (LN11)

Name	*A*	PC	MS	BYKIK	LHS
Missed	F	0 Hz	0 Hz	0 Hz	–
OK	T	120 Hz	120 Hz	120 Hz	–

Where
A = PICM_IN20_665_NO_TRIG_MISSED

29.24 Pockels Cell AND Gate 100

Name	*A*	PC	MS	BYKIK	LHS
Bypassed	F	0 Hz	0 Hz	0 Hz	–
Active	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_IN20_100_ANDALLACTV_STATE

29.25 Pockels Cell AND Gate 200

Name	*A*	PC	MS	BYKIK	LHS
Bypassed	F	0 Hz	0 Hz	0 Hz	–
Active	T	120 Hz	120 Hz	120 Hz	–

Where
A = MPS_IN20_200_ANDALLACTV_STATE

29.26 Rate Request: BYKIK 1 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	–	–	120 Hz	–
Requested	T	–	–	1 Hz	–

Where
A = LP_MAX_RATE_BYKIK_1_HZ

29.27 Rate Request: BYKIK 10 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	–	–	120 Hz	–
Requested	T	–	–	10 Hz	–

Where
A = `LP_MAX_RATE_BYKIK_10_HZ`

29.28 Rate Request: BYKIK 30 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	–	–	120 Hz	–
Requested	T	–	–	30 Hz	–

Where
A = `LP_MAX_RATE_BYKIK_30_HZ`

29.29 Rate Request: BYKIK 60 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	–	–	120 Hz	–
Requested	T	–	–	60 Hz	–

Where
A = `LP_MAX_RATE_BYKIK_60_HZ`

29.30 Rate Request: BYKIK Burst

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	–	–	120 Hz	–
Requested	T	–	–	Burst Mode	–

Where
A = `LP_MAX_RATE_BYKIK_BURST`

29.31 Rate Request: BYKIK Single Shot

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	–	–	120 Hz	–
Requested	T	–	–	Single Shot	–

Where
A = LP_MAX_RATE_BYKIK_SINGLE_SHOT

29.32 Rate Request: Pockels Cell 1 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	120 Hz	–	–	–
Requested	T	1 Hz	–	–	–

Where
A = LP_MAX_RATE_PC_1_HZ

29.33 Rate Request: Pockels Cell 10 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	120 Hz	–	–	–
Requested	T	10 Hz	–	–	–

Where
A = LP_MAX_RATE_PC_10_HZ

29.34 Rate Request: Pockels Cell 30 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	120 Hz	–	–	–
Requested	T	30 Hz	–	–	–

Where
A = LP_MAX_RATE_PC_30_HZ

29.35 Rate Request: Pockels Cell 60 Hz

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	120 Hz	–	–	–
Requested	T	60 Hz	–	–	–

Where
A = LP_MAX_RATE_PC_60_HZ

29.36 Rate Request: Pockels Cell Burst

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	120 Hz	–	–	–
Requested	T	Burst Mode	–	–	–

Where
A = LP_MAX_RATE_PC_BURST

29.37 Rate Request: Pockels Cell Single Shot

Name	*A*	PC	MS	BYKIK	LHS
Not Requested	F	120 Hz	–	–	–
Requested	T	Single Shot	–	–	–

Where
A = LP_MAX_RATE_PC_SINGLE_SHOT

29.38 VVMG IN20 175 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = VV_BL175_STATE

29.39 VVPG IN20 155 Position

Name	*A*	PC	MS	BYKIK	LHS
Not Out	F	0 Hz	0 Hz	0 Hz	–
Out	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VV_BL155_STATE`

29.40 VVS Circuit Breaker: LI20

Name	*A*	PC	MS	BYKIK	LHS
Not On	F	0 Hz	0 Hz	0 Hz	–
On	T	120 Hz	120 Hz	120 Hz	–

Where
A = `VVS_BRKR_OK_READY_LI20_STATE`

29.41 YAG01 IN20 211 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = `YAGS_IN20_211_OUT_LMTSW_STATE`,
B = `YAGS_IN20_211_IN_LMTSW_STATE`

29.42 YAGG1 IN20 841 Position

Name	*B*	*A*	PC	MS	BYKIK	LHS
Moving	F	F	0 Hz	0 Hz	0 Hz	–
Out	F	T	120 Hz	120 Hz	120 Hz	–
In	T	F	10 Hz	10 Hz	10 Hz	–
Broken	T	T	0 Hz	0 Hz	0 Hz	–

Where
A = YAGS_IN20_841_OUT_LMTSW_STATE,
B = YAGS_IN20_841_IN_LMTSW_STATE

30 Ignore Logic

30.1 A-Line Kicker Is Not Enabled

Name	*B*	*A*	PC	MS	BYKIK	LHS
Is Not Enabled	F	F	–	–	–	–

Where
A = KICK_BSY0_66_PM1_TRIG_ENB_STATUS,
B = KICK_BSY0_66_PM2_TRIG_ENB_STATUS

30.2 A-Line SL10 Is Closed

Name	*D*	*C*	*B*	*A*	PC	MS	BYKIK	LHS
Closed	T	T	T	T	–	–	–	–

Where
A = SLIT_BSYA_2010_SL10_FB_IN_STATE,
B = SLIT_BSYA_2010_SL10_FT_IN_STATE,
C = SLIT_BSYA_2010_SL10_RB_IN_STATE,
D = SLIT_BSYA_2010_SL10_RT_IN_STATE

30.3 BX01/BX02 Is Off

Name	*B*	*A*	PC	MS	BYKIK	LHS
Off	F	T	–	–	–	–

Where
A = BEND_IN20_751_OFF_STATE,
B = BEND_IN20_751_OK_STATE

30.4 BX01/BX02 Is On

Name	*B*	*A*	PC	MS	BYKIK	LHS
On	T	F	–	–	–	–

Where
A = BEND_IN20_751_OFF_STATE,
B = BEND_IN20_751_OK_STATE

30.5 BXG Is Off

Name	B	A	PC	MS	BYKIK	LHS
Off	F	T	–	–	–	–

Where
A = BEND_IN20_231_OFF_STATE,
B = BEND_IN20_231_OK_STATE

30.6 BXG Is On

Name	B	A	PC	MS	BYKIK	LHS
On	T	F	–	–	–	–

Where
A = BEND_IN20_231_OFF_STATE,
B = BEND_IN20_231_OK_STATE

30.7 Diag Stopper HFX DG2 Is In

Name	A	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = HFX_DG2_STP_01_IN_DI_POSITION

30.8 Diag Stopper HFX UM6 Is In

Name	A	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = HFX_UM6_STP_01_IN_DI_POSITION

30.9 Diag Stopper XCS SB1 Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = XCS_SB1_STP_01_CLS_DI_POSITION

30.10 Laser Heater Attenuator Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = LHATTEN_IN_LIMIT_STATE

30.11 LTU Dechirper Is Out

Name	*D*	*C*	*B*	*A*	PC	MS	BYKIK	LHS
Out	T	T	T	T	–	–	–	–

Where
A = DCHP_LTU1_545_OUT_LIMSW_NEGY_POSITION,
B = DCHP_LTU1_545_OUT_LIMSW_POSY_POSITION,
C = DCHP_LTU1_555_OUT_LIMSW_NEGX_POSITION,
D = DCHP_LTU1_555_OUT_LIMSW_POSX_POSITION

30.12 Stopper MFX S4.5 Is In

Name	*A*	PC	MS	BYKIK	LHS
Is In	T	–	–	–	–

Where
A = STPR_XRT_1_S45IN_STATE

30.13 Stopper S1 Is In

Name	*A*	PC	MS	BYKIK	LHS
Is In	T	–	–	–	–

Where
A = STPR_FEE1_1_S1IN_POSITION

30.14 Stopper S2 Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = STPR_FEE1_1_S2IN_STATE

30.15 Stopper S2B Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = STPR_FEE1_1_S2BIN_STATE

30.16 Stopper S5B Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = STPR_FEH1_5_S5BIN_POSITION

30.17 Stopper SH1 Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = STPR_FEE1_1_SH1IN_STATE

30.18 Stopper SH2 Is In

Name	B	A	PC	MS	BYKIK	LHS
In	T	F	–	–	–	–

Where
A = STPR_XRT1_1_SH2OUT_STATE,
B = STPR_XRT1_1_SH2IN_STATE

30.19 Stopper XRT S5 Is In

Name	A	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = STPR_XRT1_1_S5IN_POSITION

30.20 Stopper XRT S6 Is In

Name	A	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = STPR_XRT1_1_S6IN_POSITION

30.21 Stopper: BSY D2 Summary Is In

Name	B	A	PC	MS	BYKIK	LHS
In	T	T	–	–	–	–

Where
A = STPR_BSY0_88_IN_LIMSW_A_POSITION,
B = STPR_BSY0_88_IN_LIMSW_B_POSITION

30.22 TD11 Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = TD11_IN_LIMIT_STATE

30.23 TDUND Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = DUMP_LTU1_970_TDUND_IN_POSITION

30.24 XCS Is Not In Main Line

Name	*A*	PC	MS	BYKIK	LHS
Not in	F	–	–	–	–

Where
A = XCS_SB_POS_HARD_POSITION

30.25 XPP-NH3-POS-00 Beamline Is In

Name	*A*	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = XPP_NH3_POS_00_IN_STATE

30.26 XPP-NH3-POS-00 Beamline Is Not In

Name	*A*	PC	MS	BYKIK	LHS
Not_IN	F	–	–	–	–

Where
A = XPP_NH3_POS_00_IN_STATE

30.27 XRT-M2 Mirror Is Out of Beam

Name	A	PC	MS	BYKIK	LHS
IS_OUT	T	–	–	–	–

Where
A = HXX_HXM_MMS_01_B_POSITION

30.28 YAG01 Is In

Name	B	A	PC	MS	BYKIK	LHS
In	T	F	–	–	–	–

Where
A = YAGS_IN20_211_OUT_LMTSW_STATE,
B = YAGS_IN20_211_IN_LMTSW_STATE

30.29 YAG02 Is In

Name	A	PC	MS	BYKIK	LHS
In	T	–	–	–	–

Where
A = YAGS_IN20_241_IN_LMTSW_STATE