Tracking@LHC

- Introduction and basic concepts
- The challenge of tracking at LHC.
- ATLAS and CMS.
- Where we are now
- The next challenges: the alignment, the material, the pilot run
- New ideas for the future: L1 tracker trigger.

The challenge of tracking at LHC

Repeat in the most hostile hadronic environment (high luminosity, high multiplicity of charged tracks, high radiation flux) the success obtained with the sophisticated tracking systems introduced at LEP and the Tevatron Collider.

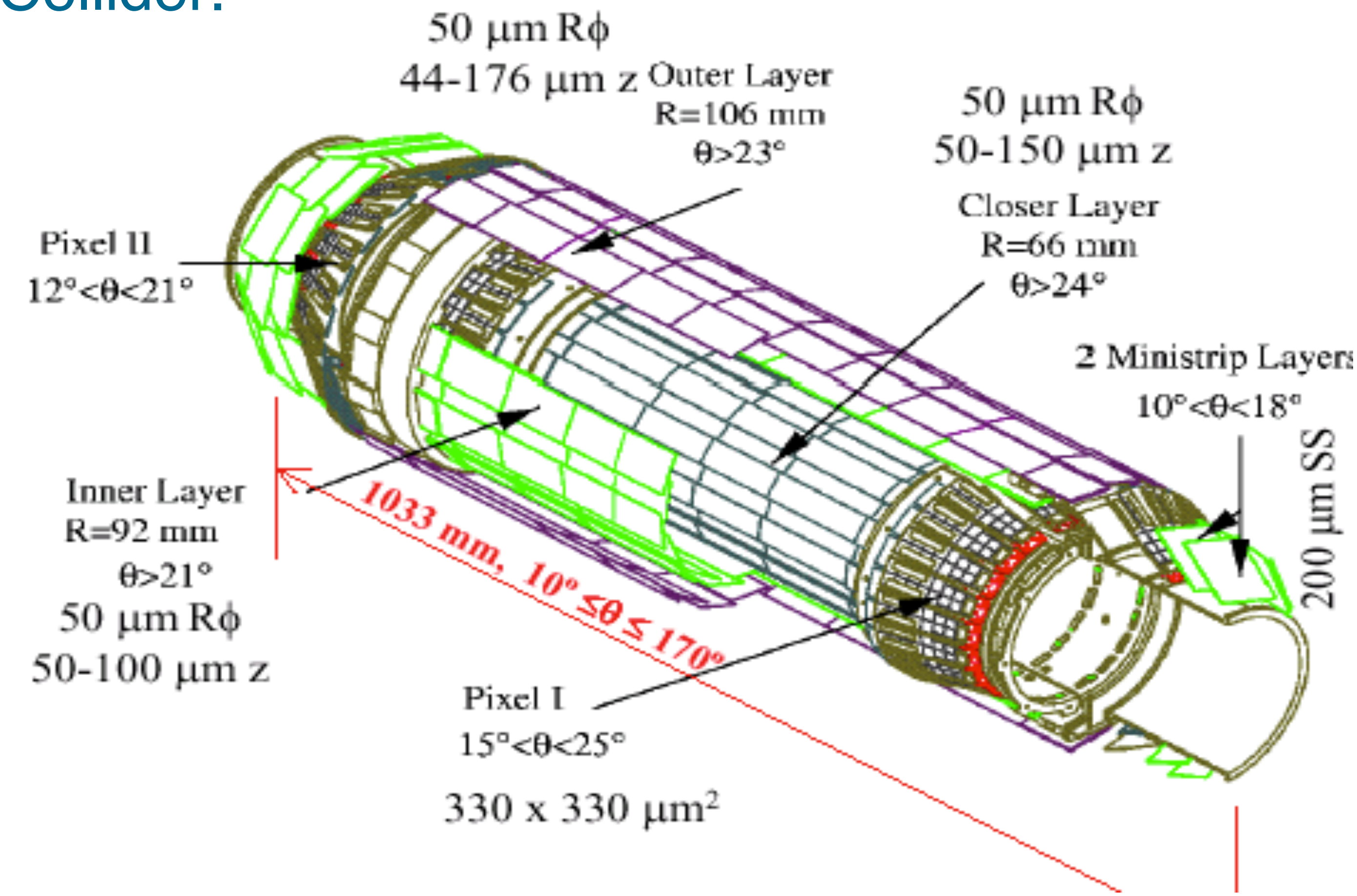
Delphi

Micro-vertex

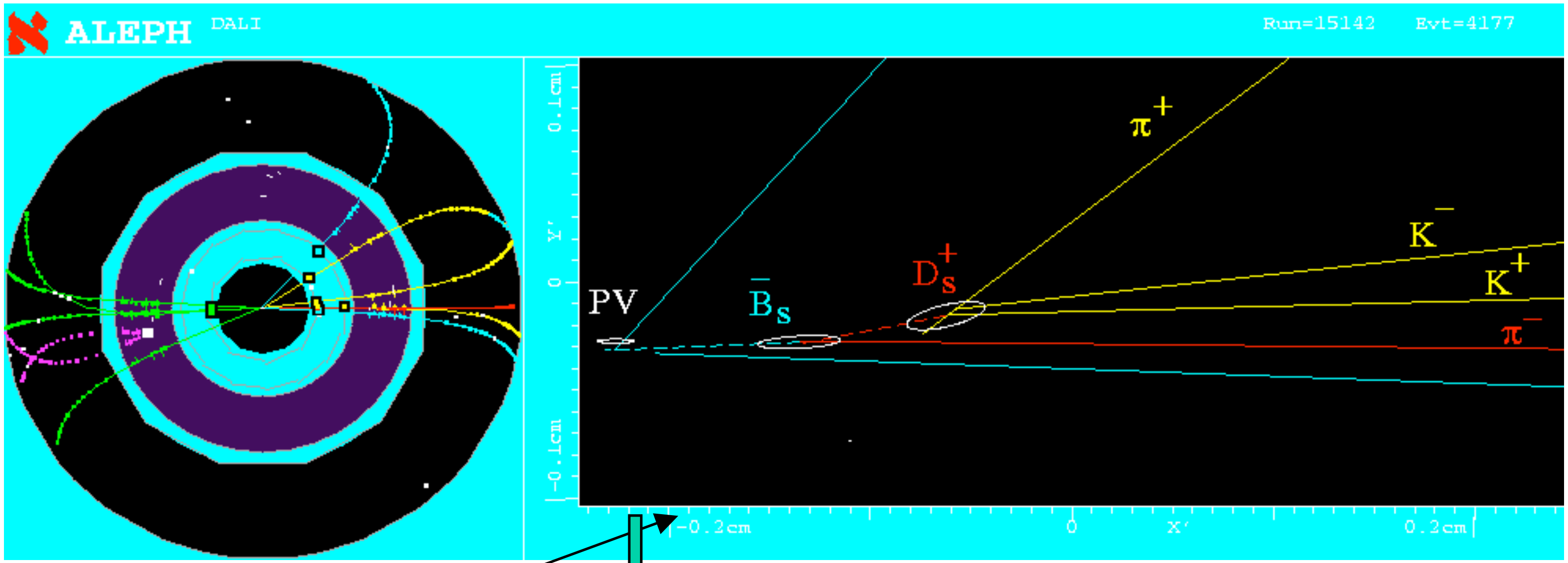
Detector

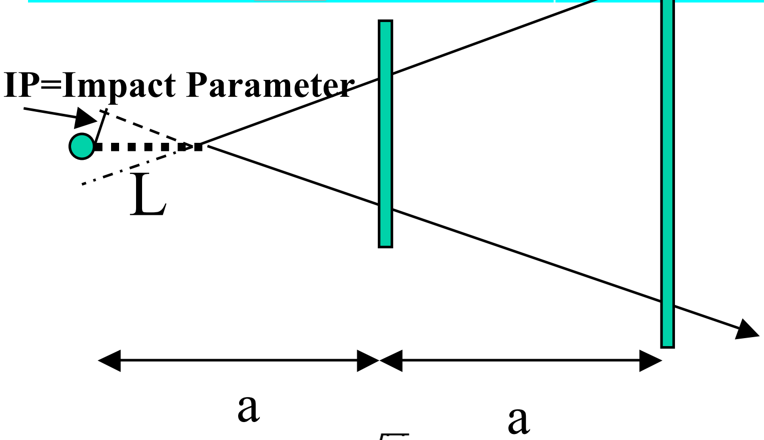
174 k μstrips

1.3 M pixel



Aleph: the importance of the impact parameter





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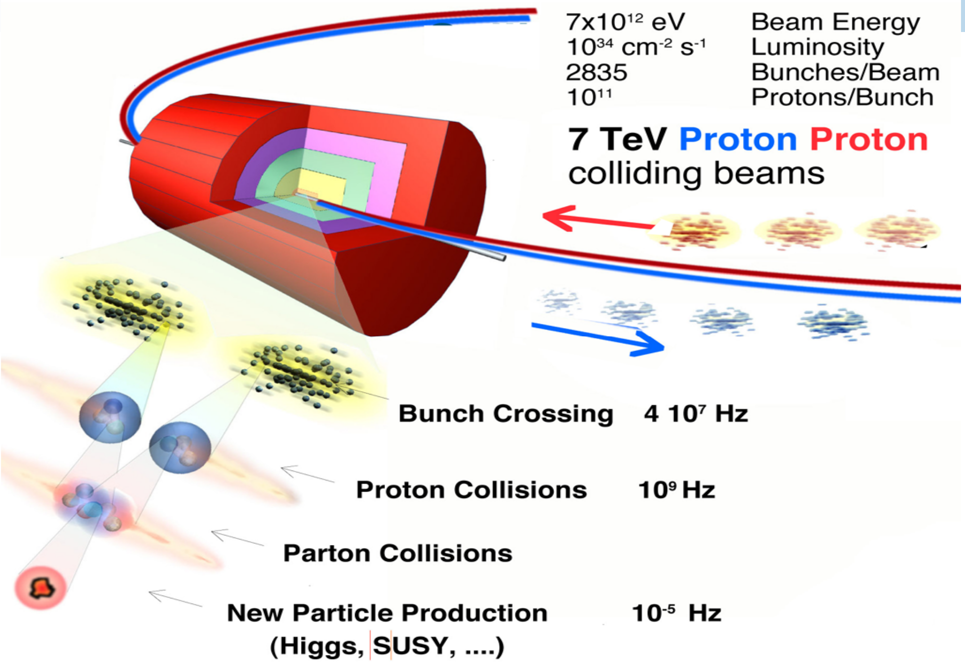
σ spatial resolution

cτ (B) ~ 500 μm

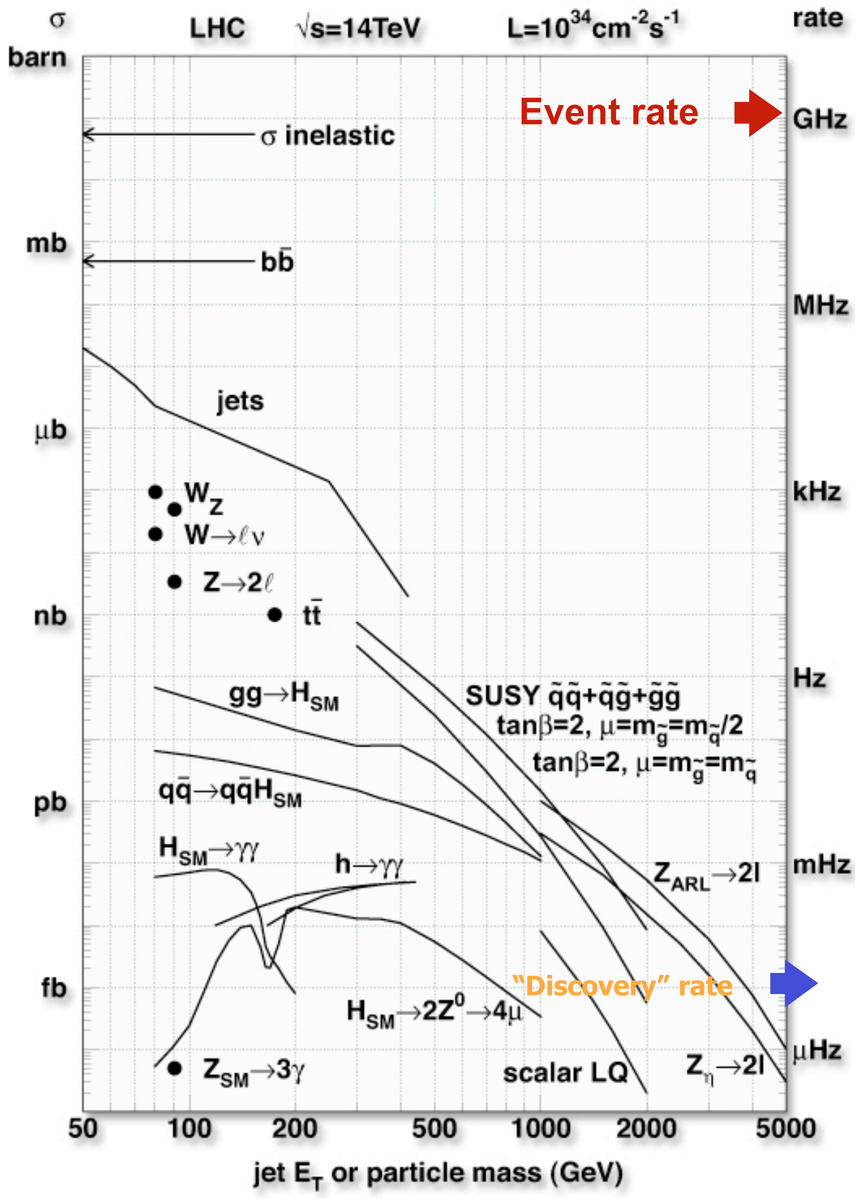
cτ (τ) ~ 100 μm

LHC main parameters



Collision frequency	**40 MHz**
Event frequency	**~10^9 Hz**
Max LV1 Trigger	**100 kHz**
Event size	**~1 Mbyte**
Readout network	**1 Terabit/s**
#livelli di trigger	**2**
Rejection factor %	**99.9997% (100 Hz from 40 MHz)**
Dead-time	**~ %**
Event selection:	**~$1/10^{13}$**

LHC



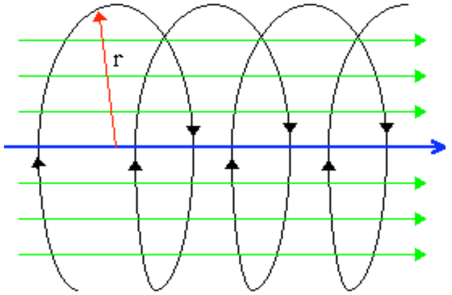
- σ_{INE}=100mb implies $R_{INE}=10^9$ ev/s
- 25 inelastic events per crossing
  20 MB events per crossing
- About 1000 soft tracks per crossi
  (+loopers due to the solenoidal fie
- Very difficult pattern recognition
- Detectors and electronics capabl
  single bunch crossing identificatio
  (25ns) and radiation resistant.

Basic tracking concepts

Very useful lectures by F. Ragusa
http://www.le.infn.it/lhcschool/talks/Ragusa.pdf

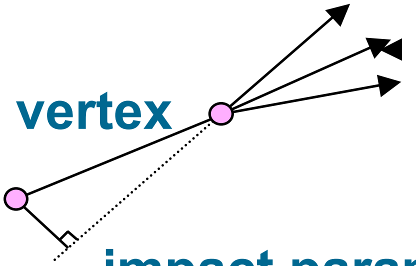
Tracking means reconstruction of charged particles trajectory to perform several measurements

momentum (magnetic field)



$p = 0.3 \cdot B \cdot R$

vertexing

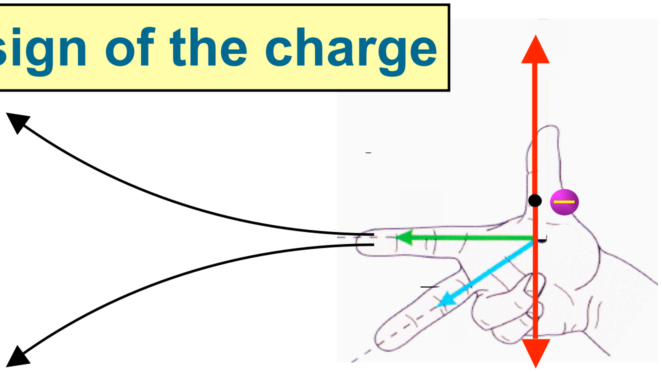


secondary vertex

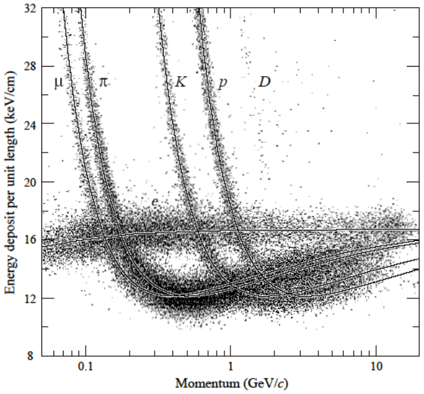
primary vertex

impact parameter

the sign of the charge



particle ID (mass), not necessarily with the same detector



$p = m_o \gamma \beta$

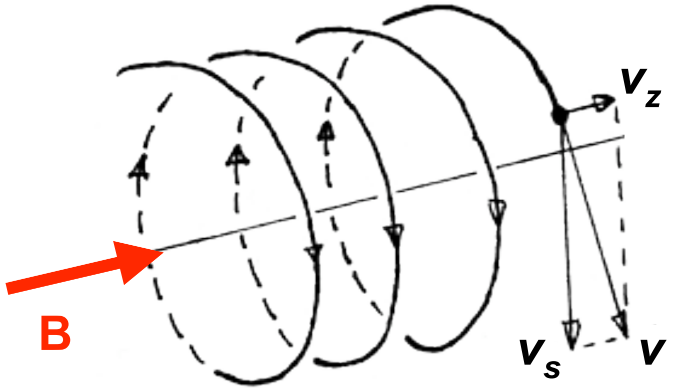
Basic concepts: motion in Magnetic Field

In a magnetic field the motion of a char-ged particle is determined by the Lorentz force. For homogenous B (solenoidal field) the trajectory is given by an helix

$$x(s) = x_o + R\left[\cos\left(\Phi_o + \frac{hs\cos\lambda}{R}\right) - \cos\Phi_o\right]$$

$$y(s) = y_o + R\left[\sin\left(\Phi_o + \frac{hs\cos\lambda}{R}\right) - \sin\Phi_o\right]$$

$$z(s) = z_o + s\sin\lambda$$

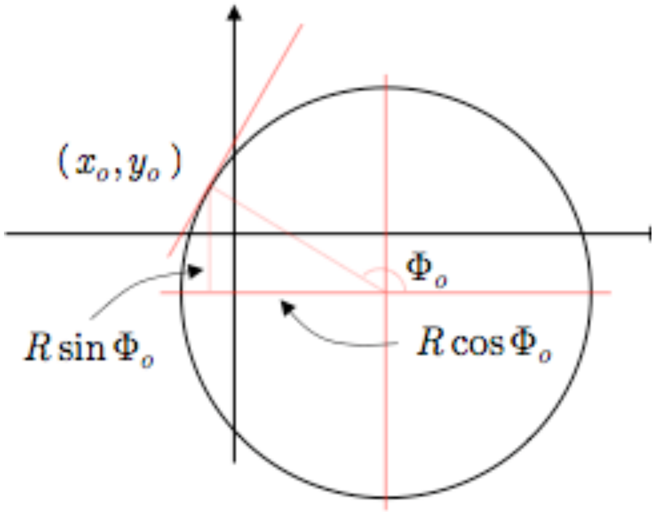


Where λ is the dip angle and h=±1 is the sense of rotation.

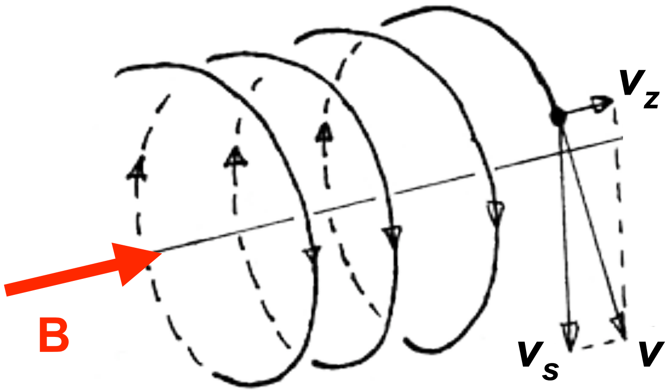
The projection of the helix

In the transverse plane (x,y) is a circle

$$(x - x_o + R\cos\Phi_o)^2 + (y - y_o + R\sin\Phi_o)^2 = R^2$$



Basic concepts: radius of curvature



$$\boxed{R(m) = \frac{p_\perp(GeV)}{0.3B(T)}}$$

Important to dimension the tracking system and to calculate the number of measuring points for a given transverse momentum (cut-off in pt).

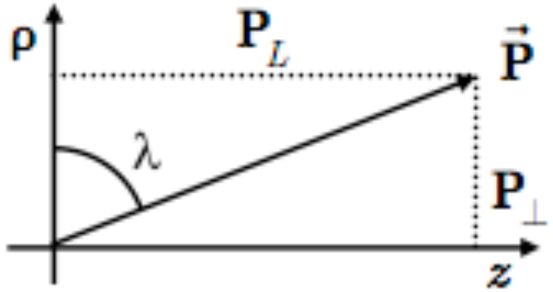
Important also to calculate the average radius of the “loopers”. Low momentum particles carry no basic information on the physics of the hard processes while they might jeopardize pattern recognition by increasing the occupancy in the innermost layers.

For p_t<300MeV
<25cm in CMS (4T) pixel only
<50cm in ATLAS (2T) pixel and Si-microstrips

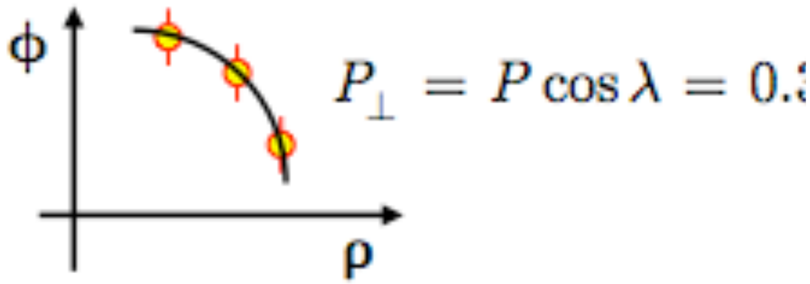
Basic concepts: momentum measurement

In hadronic colliders we want to measure mainly the transverse momentum since elementary processes happens among partons that are not at rest in tl laboratory (momentum conservation only in the transverse plane)

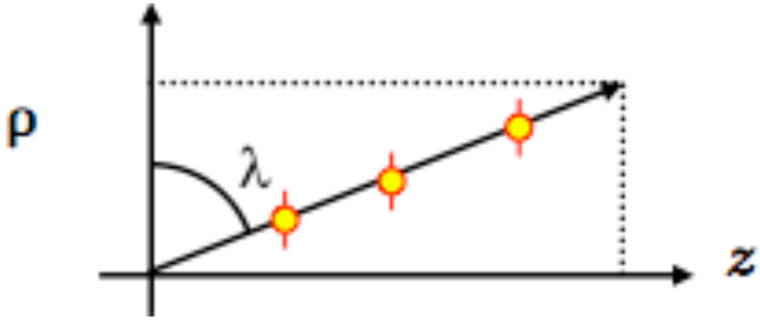
The momentum of the particle is projected along two directions



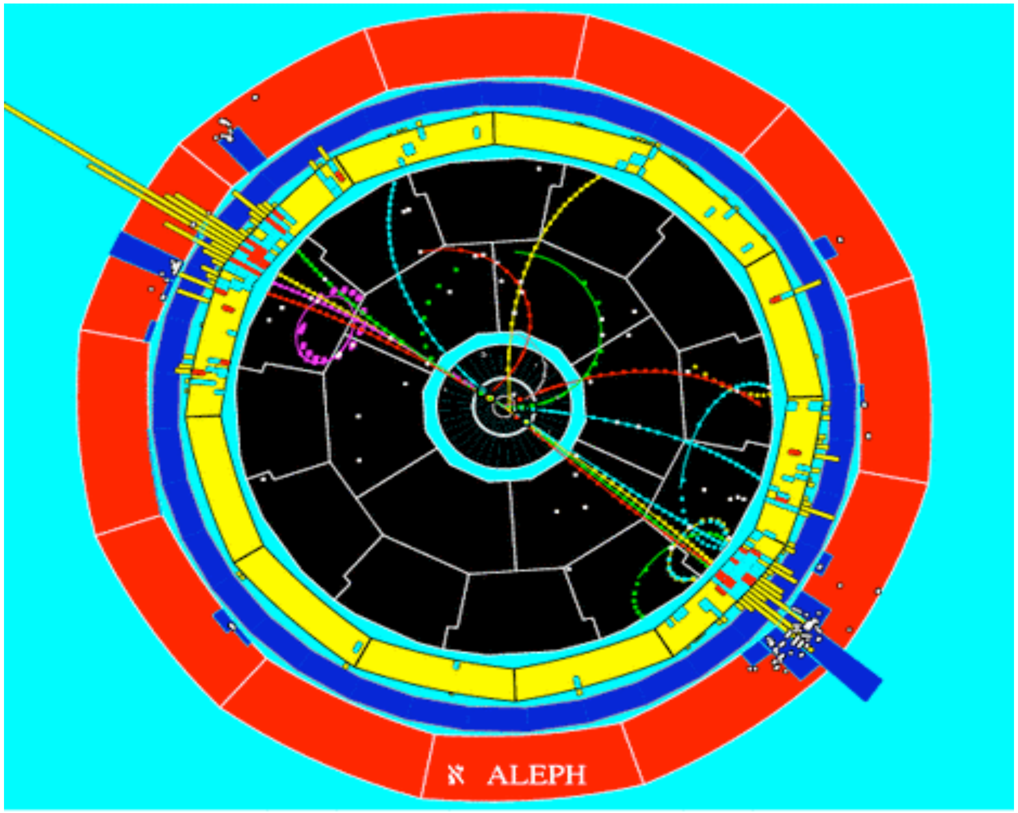
in the ρ – ϕ plane we measure the transverse momentum

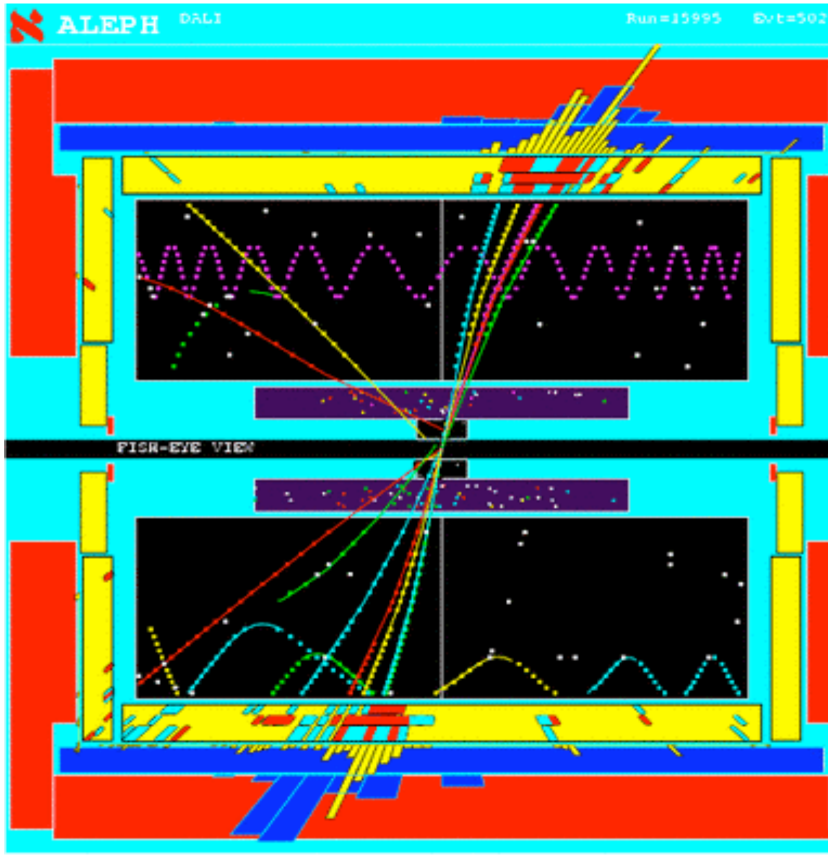


in the ρ – *z* plane we measure the dip angle λ

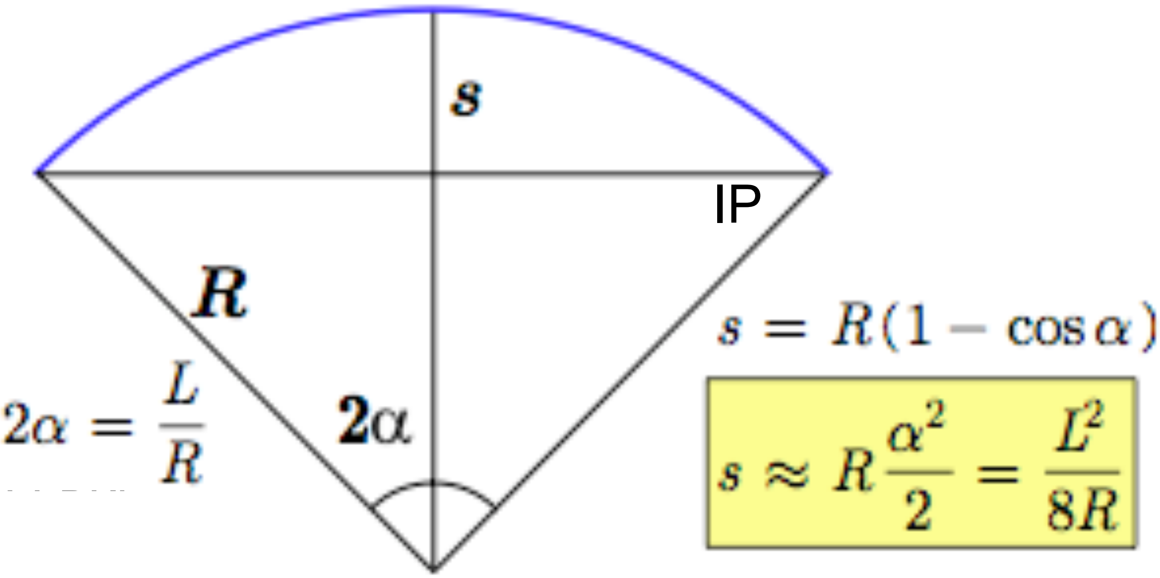


Track reconstruction in Aleph





Basic concepts: sagitta measurement



$$2\alpha = \frac{L}{R}$$

$$s = R(1 - \cos\alpha)$$

$$\boxed{s \approx R\frac{\alpha^2}{2} = \frac{L^2}{8R}}$$

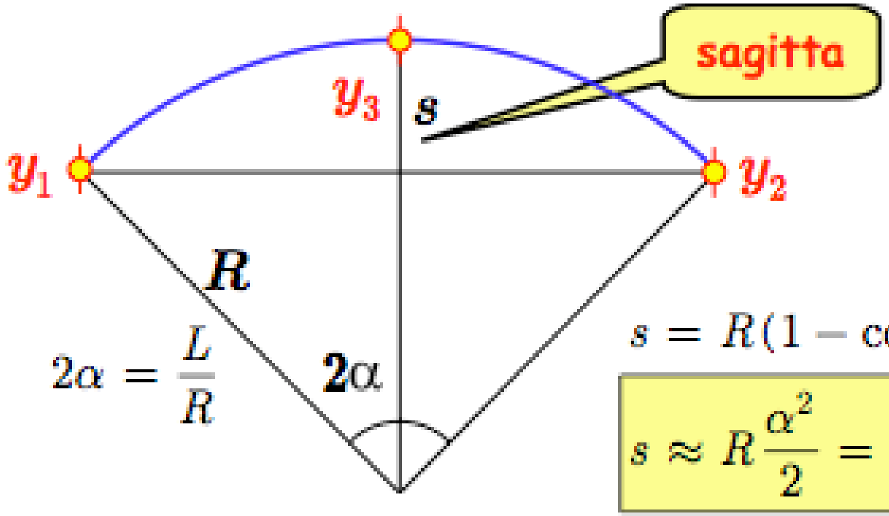
A few examples assuming a track length of 1m and magnetic fields of 2 and 4T

P_t=1 GeV	R(2T)=1,67m	R(4T)= 0,83m	s(2T)=75mm	s(4T)= 150mm
P_t=10 GeV	R(2T)=16,7m	R(4T)= 8,3m	s(2T)=7,5mm	s(4T)= 15mm
P_t=100 GeV	R(2T)=167m	R(4T)= 83m	s(2T)=0,75mm	s(4T)= 1,5mm
P_t=1 TeV	R(2T)=1670m	R(4T)= 830m	s(2T)=0,075mm	s(4T)= 0,15mm

Momentum resolution

Since the transverse momentum is proportional to the bending radius, the momen
resolution depend on the accuracy in measuring R

$$\boxed{R = \frac{p}{0.3B} \qquad \frac{\delta p}{p} = \frac{\delta R}{R}}$$



$$2\alpha = \frac{L}{R}$$

$$s = y_3 - \frac{y_1 + y_2}{2} \qquad \delta s = \sqrt{\frac{3}{2}}\delta y \sim \delta y$$

$$s = R(1 - \cos\alpha)$$

$$\boxed{s \approx R\frac{\alpha^2}{2} = \frac{L^2}{8R}}$$

$$|\delta s| = \frac{L^2}{8R}\frac{\delta R}{R} \sim \delta y \qquad \frac{L^2}{8R}\frac{\delta p}{p} = \delta y$$

$$\frac{\delta p}{p} = \frac{8R}{L^2}\delta y \qquad \frac{\delta p}{p} = \frac{8p}{0.3BL^2}\delta y$$

$$\boxed{\frac{\delta p}{p^2} = \frac{8\delta y}{0.3BL^2}}$$

The error in measuring momenta is proportional to momentum, decreases linearly
the accuracy of the measurements and is inversely proportional to the bending po
BL². A big lever arm is the most effective tools. Beam spot and last layers are cru

Momentum Resolution

Useful formulas for practical purposes

[illegible]

When N measurement points are distributed along the trajectory.

$$\boxed{\frac{\delta p}{p^2} = \frac{\sigma}{0.3BL^2}\sqrt{4C_N}}$$

$$C_N = \frac{180N^3}{(N-1)(N+1)(N+2)(N+3)}$$

For N>10 C_N= 180/N+4.

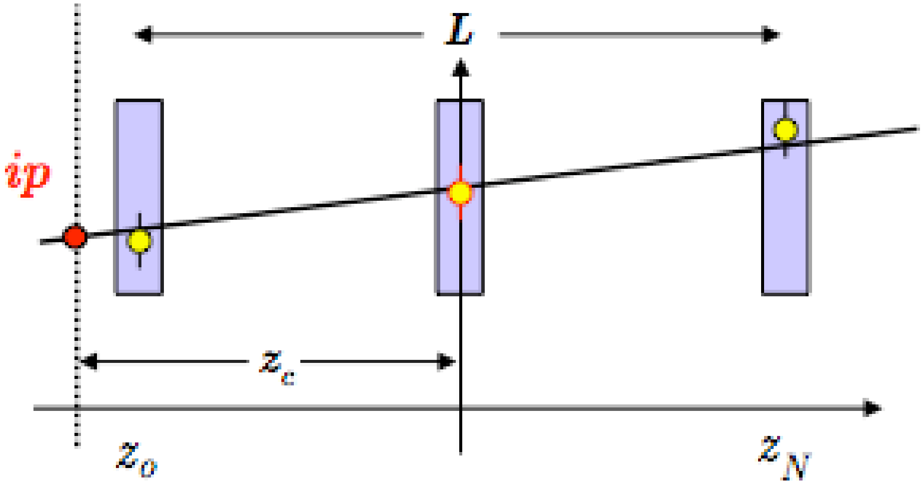
The dependance on the number of measurements is weak. Still **BL^2** dominates
Unfortunately solenoidal magnets with large B and large L are very expensive.
The cost scales with the stored energy. And also the tracking systems are not ch

Cost of a solenoidal magnet (M\$)=0.523[(E/1 MJ)]$^{0.662}$
$E= B^2V/2\mu_o$ ($V=\pi L^2 l$) where L is the radius and l is the length of the soleno

The CMS solenoid stores 2.6×10^9 Joule and costs about 100M\$

Impact parameter resolution and sign of the charge

Simple considerations lead to an error on the impact parameter dominated by th precisionof the first measuring layers, their distance from the interaction point an the precision on the meaurement of the slope given by the entire tracker



$$\sigma_{ip}^2 = \sigma_a^2 + z_c^2\sigma_b^2$$

Using typical resolution of about 1 μm at a few cm distance from the beam line 10-15 μm ip resolution are easily achievable

The maximum momentum which allows the identification of the charge depends again on BL^2.

$$p < \frac{0.3BL^2}{3\sqrt{4C_N}\sigma_y}$$

Basic parameter for LHC trackers

- Optimal momentum resolution (Higgs→4μ; better cuts on the Z mass and use of invariant mass in general to reduce the irreducible backgrounds).

- **$\Delta p_t/p_t$=0.2-0.4 p_t (TeV)**

- High efficiency in reconstruction of tracks both isolated (muon and electrons) and within high transverse energy jets. (muon trigger validation, isolation cuts for single photons (H→γ) and tracks in general).

- **ε>95% for p_t>2GeV**

Basic parameters for LHC trackers

- Good impact parameter resolution (10-20μm)
Reconstruction of different primary vertices within the same high luminosity event. Tagging capability for b and tau jets.

- Radiation resistance: 10 years of running (1.5-2.4x10^{14}n/cm^2)

- Amount of material kept under control: to minimize photon conversion and secondary interactions within the tracker itself.

- Costs within the maximum available budget: 70-80MCHF.

The approach

Silicon microstrip detectors allow a very good point resolution (10-30 micron) that coupled to lever arms around 1m in solenoidal fiel of 2-4T would allow an adequate momentum resolution, good impact parameter resolution for b-tagging and excellent measurement of the charge up to 1TeV and beyond.

Single bunch crossing resolution is feasible in silicon (collection time <10ns) with fast read-out electronics.

The real challenge is pattern recognition for track reconstruction: the high density of tracks typical of the inner regions of high luminosity hadronic colliders can be tackled with extreme segmentations both in r-phi and r-z : pixel detectors and silicon microstrip modules.

Pattern Recognition = high granularity.

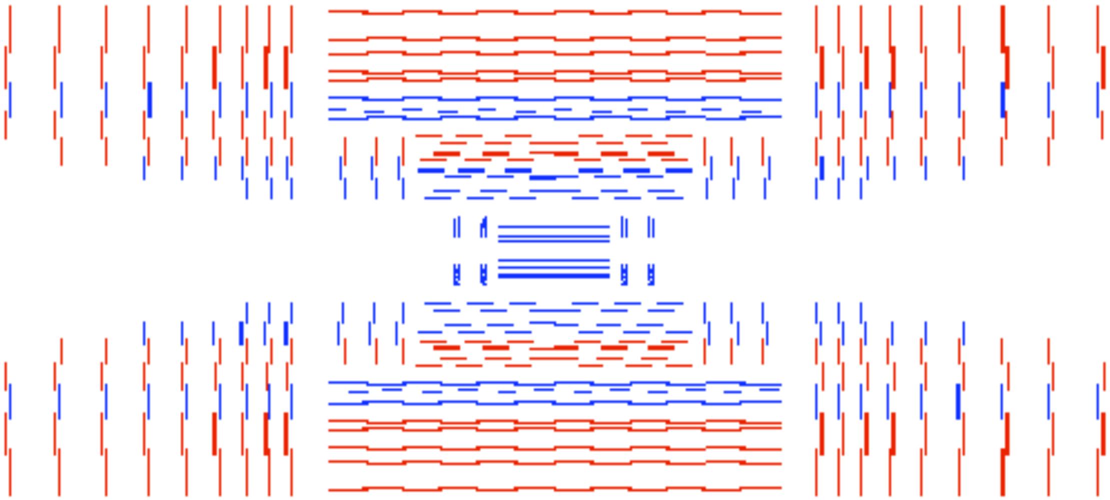
Let’s consider a large drift chamber 1m radius and 6m length. Let’s p
a wire every 3mm (impossible to do in real life, wire tension, sagitta
etc); 300k electronics channels and 300 detection planes; assume al
that we have found a gas so fast to collect all charge in 25ns.

With this chamber we can reasonably afford pattern recognition problems for events producing 30 charged tracks every 25ns (Average occupancy 300layersx30 tracks/300K channels= 3%).

If now every 25ns you produce 1000 charged tracks you can maintai
the same reconstruction efficiency only by SEGMENTING in Z the CHAMBER (1 chamber 6mlong→ 30 chambers 20cm each one).

Is the basic idea we had for the CMS Tracker. The segmentation increases in the most congested regions: 20cm-10cm-1cm

Conceptual design of the CMS tracker



II radial region: 25cm<r<110cm :$10^{13}cm^{-2}<\Phi<10^{14}cm^{-2}$

Radiation resistance silicon microstrip detectors

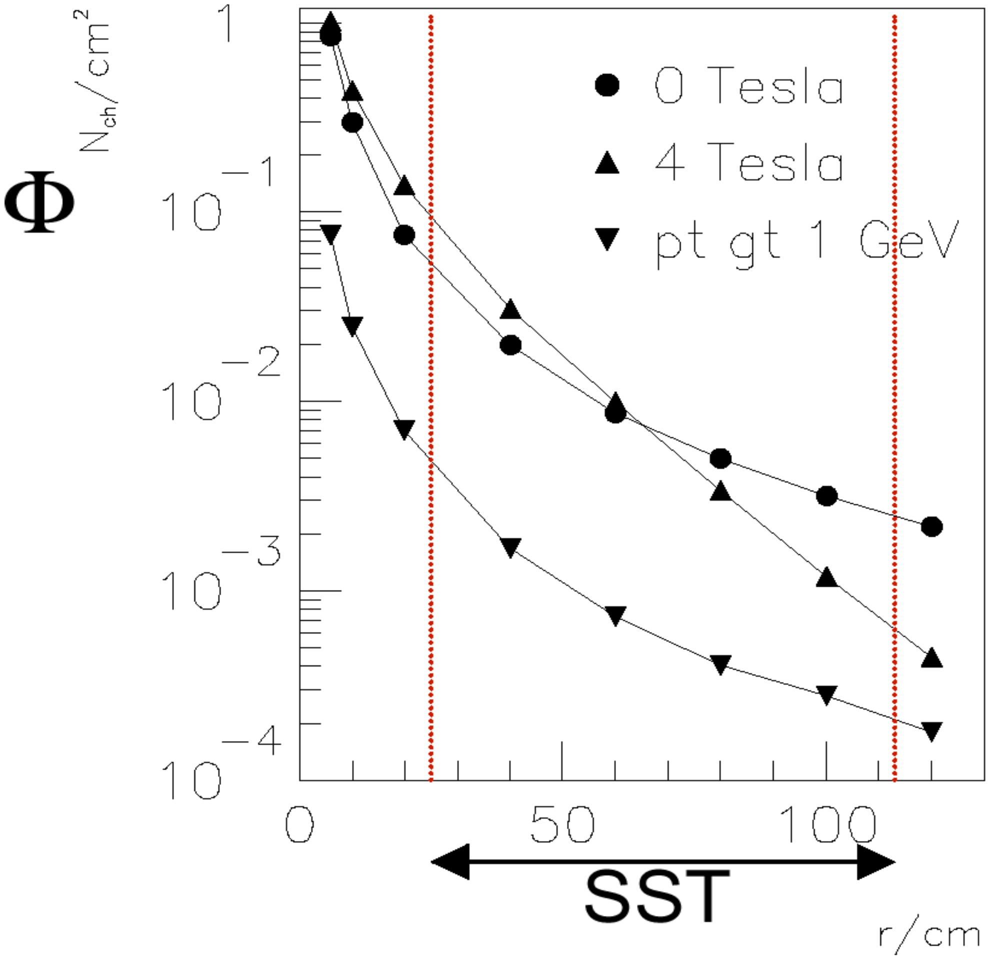
- Large scale, low cost production of rad-hard detectors (2x10^{14}n/cm

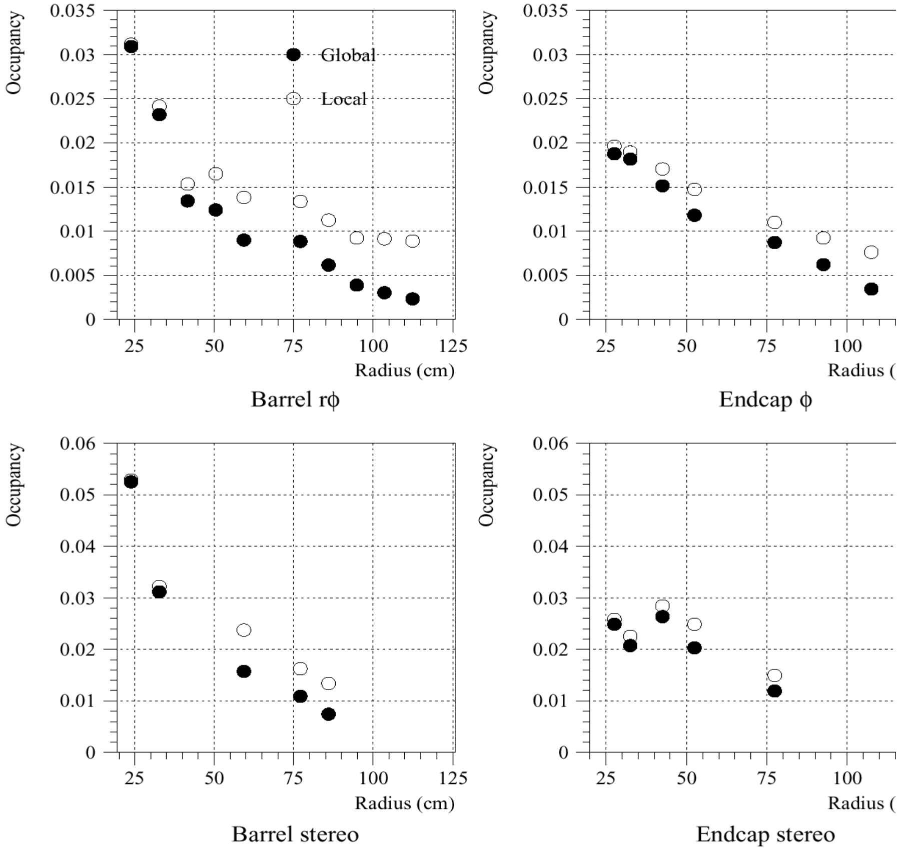
I radial region: 5cm<r<20cm :$10^{14}cm^{-2}<\Phi<10^{15}cm^{-2}$

Pixel detector in hybrid technology

- Development of a pixel detector capable to withstand 10^{15}n/cm^2

Track occupancy





Primary charged particle densities integrating 20 minimum bias events

Very good idea…. but

•The read-out channels become 30x300K=10M. The silicon is solid a
must be precisely held in place; each channel implies power and
cooling →material

•Everything must be radiation resistant and detectors available in 19
were dying after a few tens of krad.

•Cost of 25.000 detectors and 10M electronics channels.
•The cost of non rad-hard detectors was around 4000CHF/sensor; th
cost for electronics was quoted between 5 and 10CHF/channel.

•How can we organize to produce 16.000 modules (100-300 module
used in previous vertex detector)

•How can be developed a pixel detector?

Two different strategies

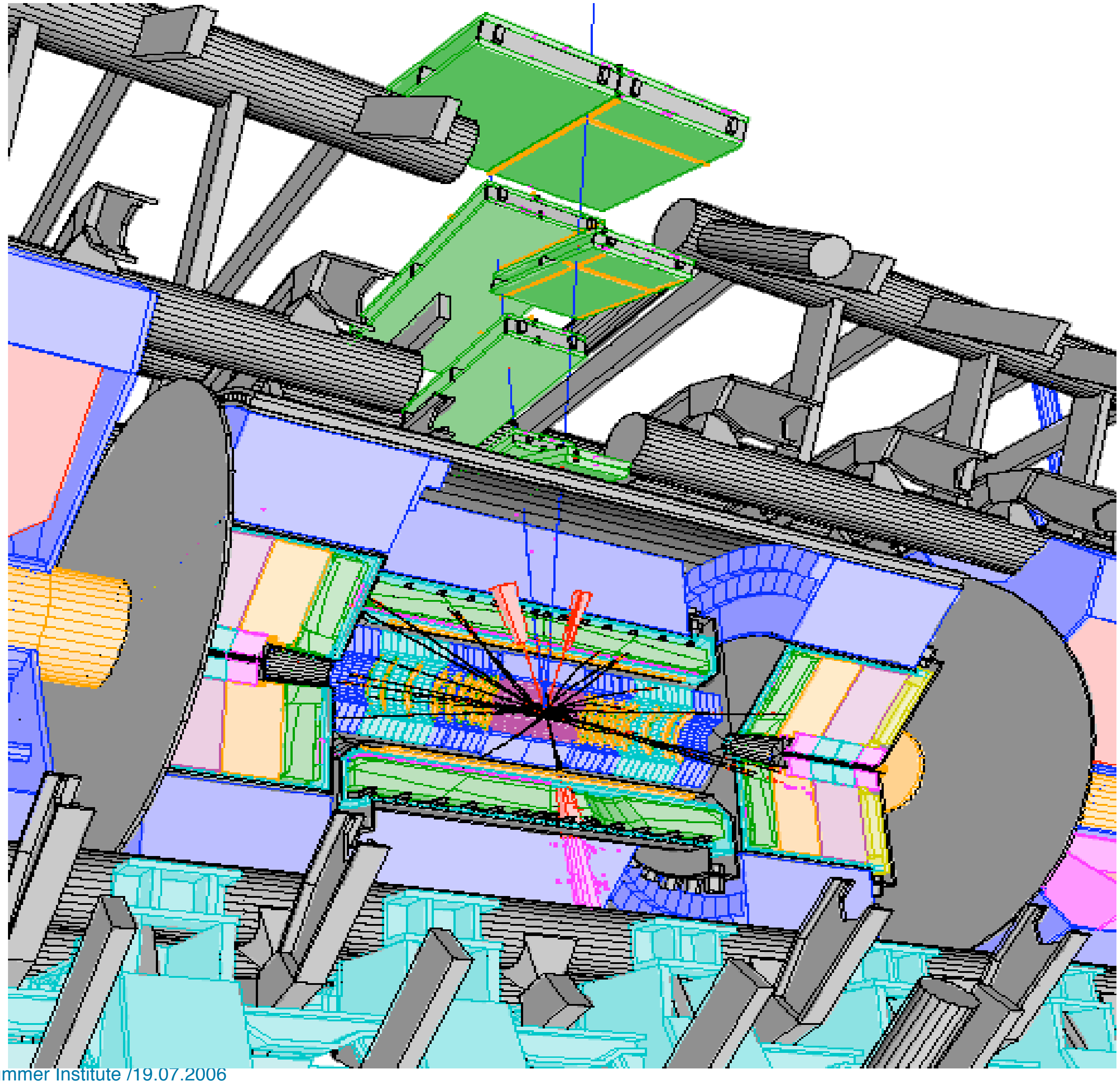
This approach has been followed very aggressively by CMS and the collaboration agreed to build the first full silicon tracker in HEP

- more challenge in terms of technology and costs
- higher performance particularly in pattern recognition

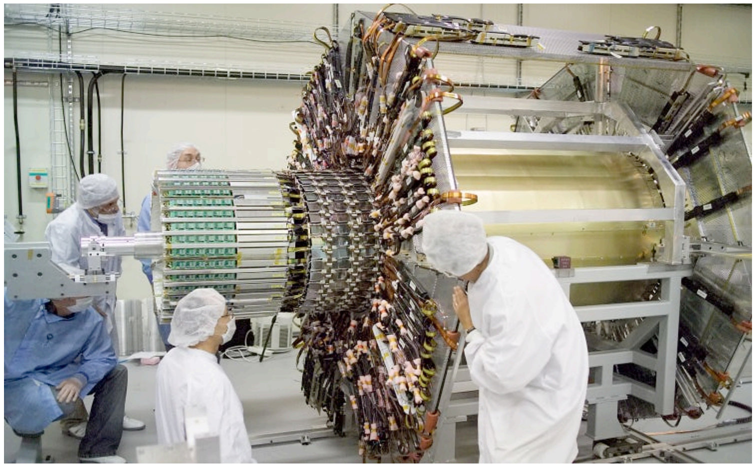
Atlas has adopted a more traditional approach based on a hybrid tracker: pixel and silicon microstrip detectors in the innermost part and a large gaseous detectors in the outer part (straw tubes).

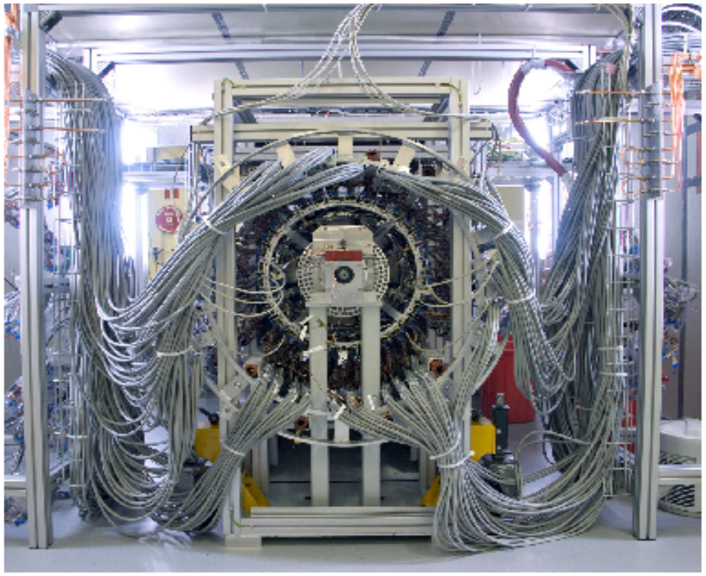
- development of new technologies limited to pixels
- higher risks in terms of performance (high occupancy foreseer in the TRT for the high luminosity run of LHC).

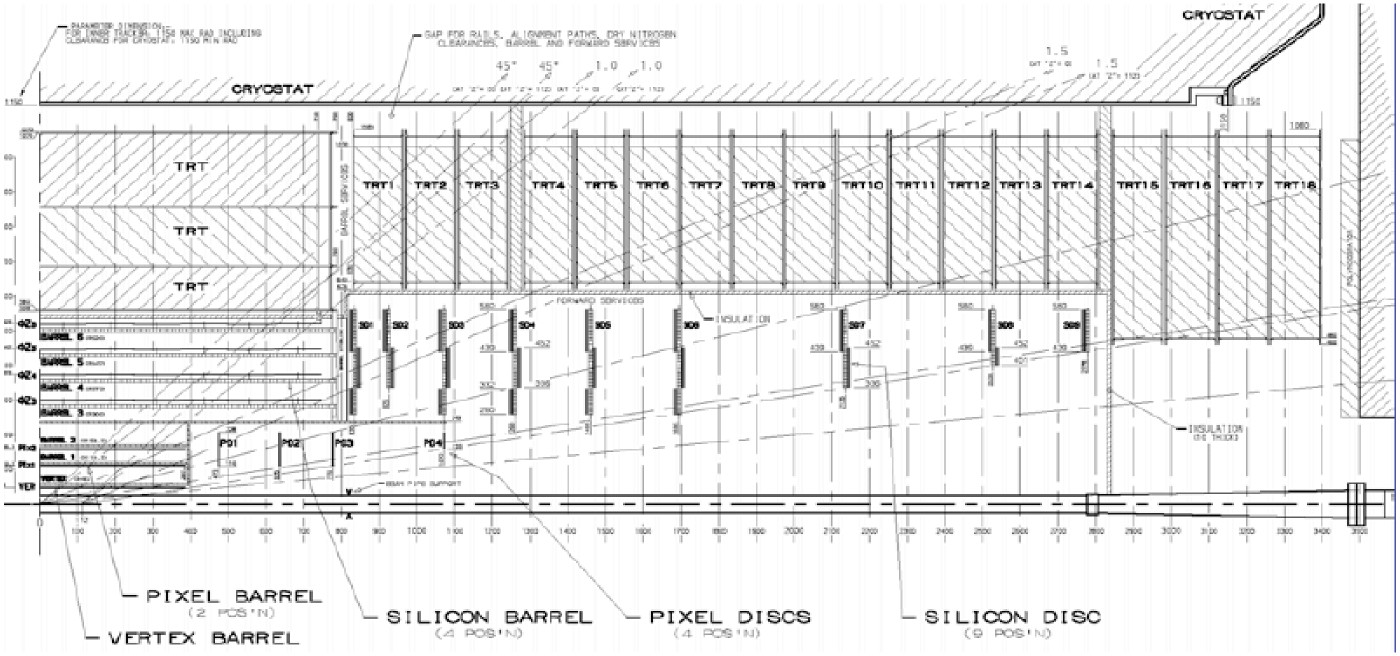
ATLAS



Atlas tracker







The ATLAS tracker

Pixel Detector

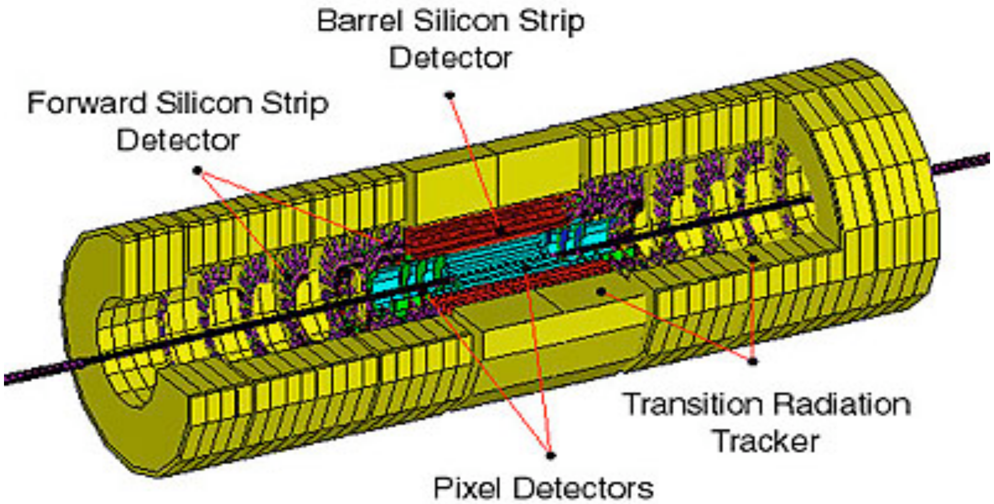
- 3 barrels, 3+3 disks: 80×10^6 pixels
- barrel radii: 4.7, 10.5, 13.5 cm
- pixel size 50×400 μm
- s_{rf}= 6-10 μm s_z = 66 μm

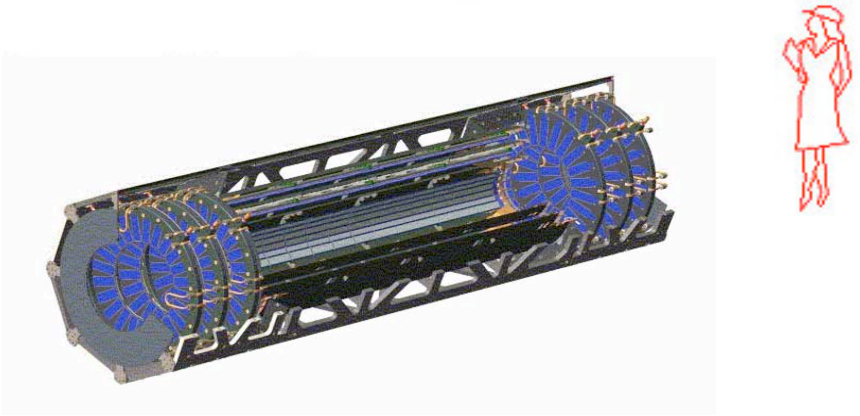
SCT

- 4 barrels, disks: 6.3×10^6 strips
- barrel radii:30, 37, 44 ,51 cm
- strip pitch 80 μm
- stereo angle ~40 mr
- s_{rf}= 16 μm s_z = 580μm

TRT

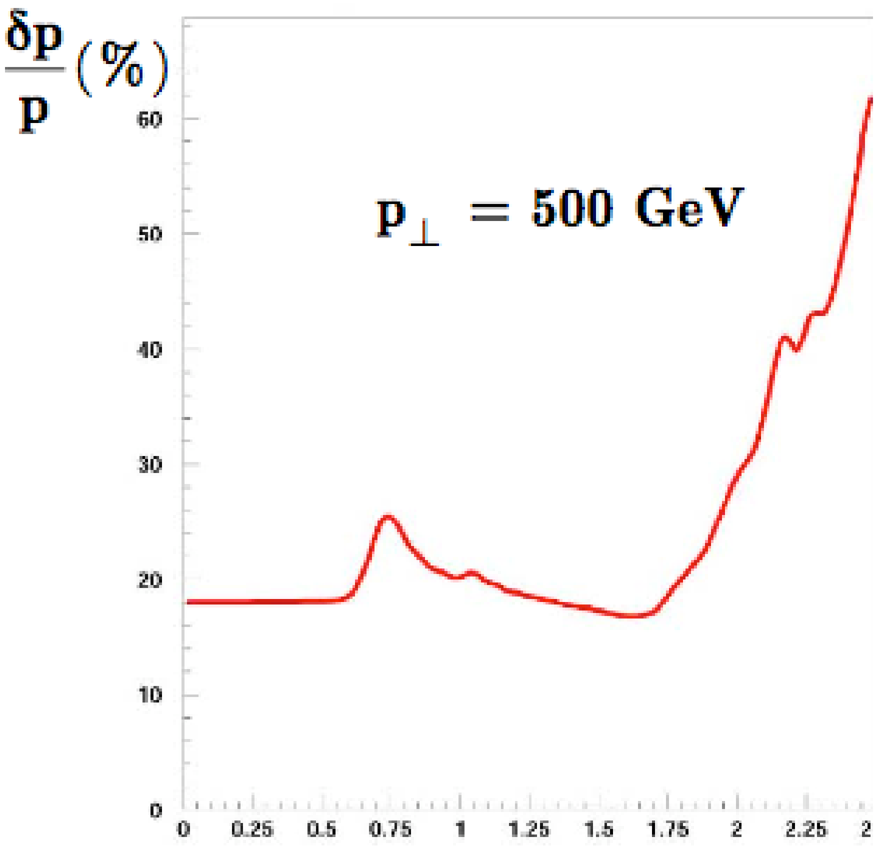
- barrel: 55 cm < R < 105 cm
- 36 layers of straw tubes
- s_{rf}= 170 μm
- 400.000 channels





Momentum resolution of ATLAS

We can now give a rough estimate of the momentum resolution of the ATLAS tracking systems



TRT: 36 point with σ = 170 μm from 55 cm to 105 cm: as a single point with σ = 28 μm at R_{max} = 80 cm

R_{min} = 4.7 cm, L = 75 cm

N+1= 3 + 4 + 1 = 8

σ = 12, 16, 28 ~ 20 μm

$$C_N \approx 12 \qquad \sqrt{4C_N} \approx 7$$

$$\boxed{\frac{\delta p}{p^2} \sim 4 \times 10^{-4}\ GeV^{-1}}$$

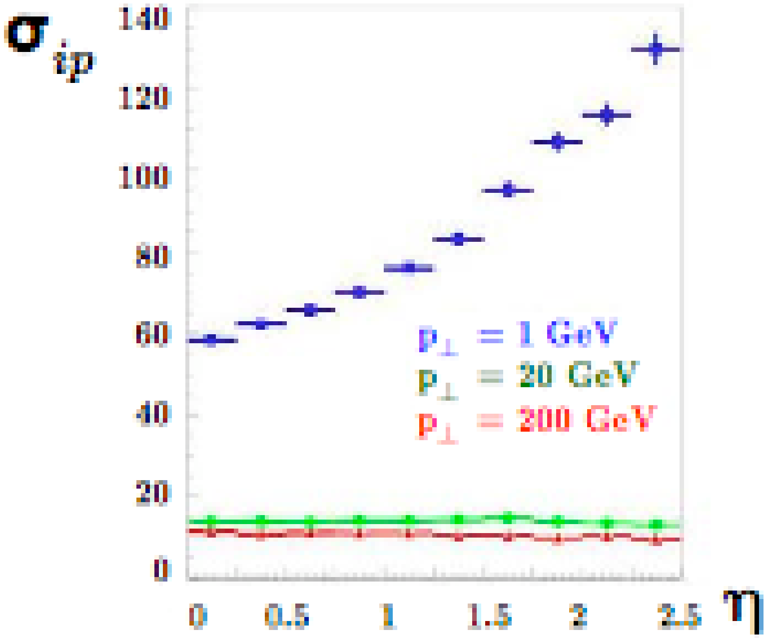
At 500 GeV $$\frac{\delta p}{p} = 20 \times 10^{-2}$$

Impact parameter resolution Atlas

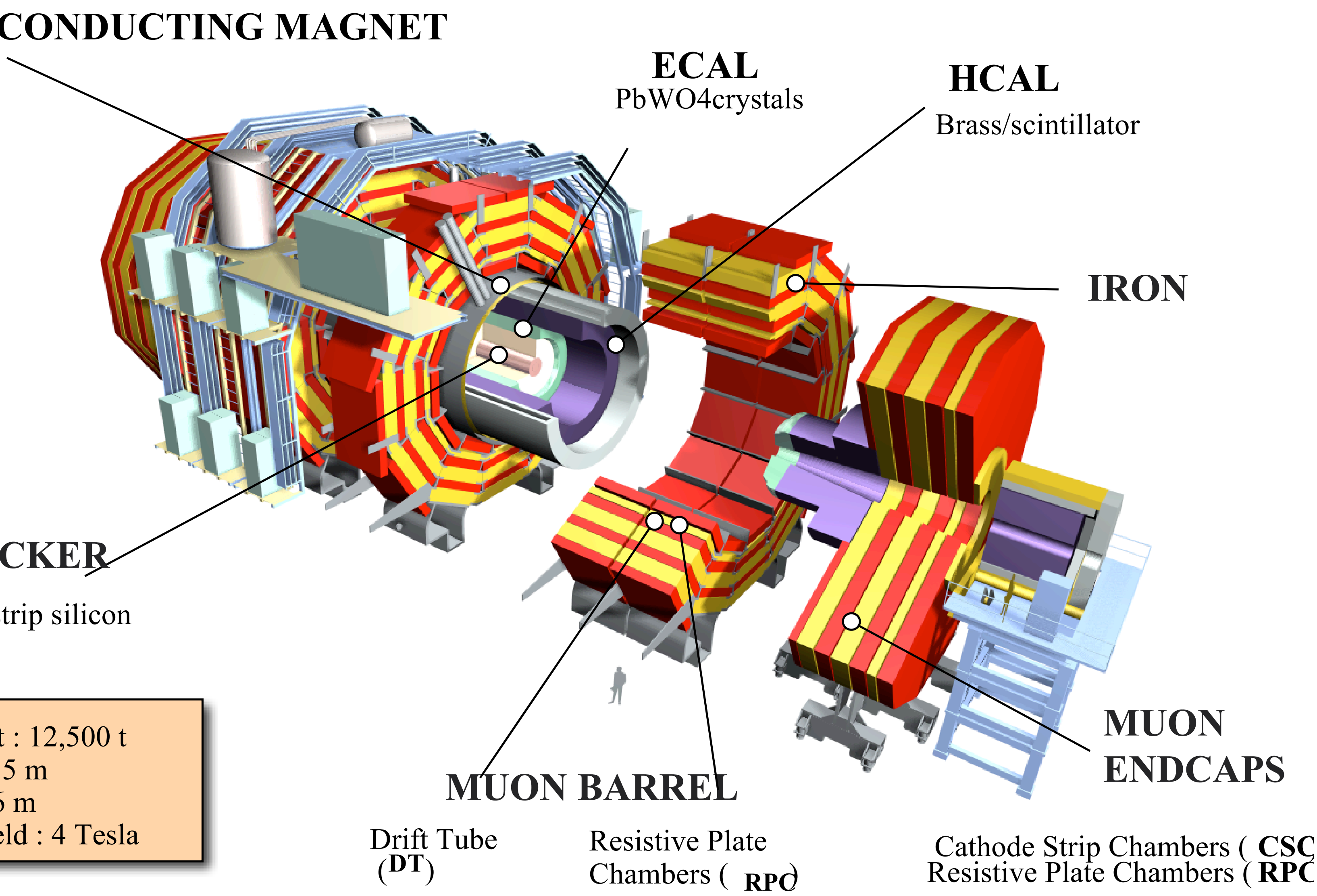
For the ATLAS detector **montecarlo studies** have shown that the resolutions can be parametrised as

$$\sigma_{ip} = 11 \oplus \frac{73}{p_\perp \sqrt{\sin\theta}} \qquad [\mu m]$$

$$\frac{\delta p_\perp}{p_\perp^2} = 0.00036 \oplus \frac{0.013}{p_\perp \sqrt{\sin\theta}} \qquad [GeV^{-1}]$$



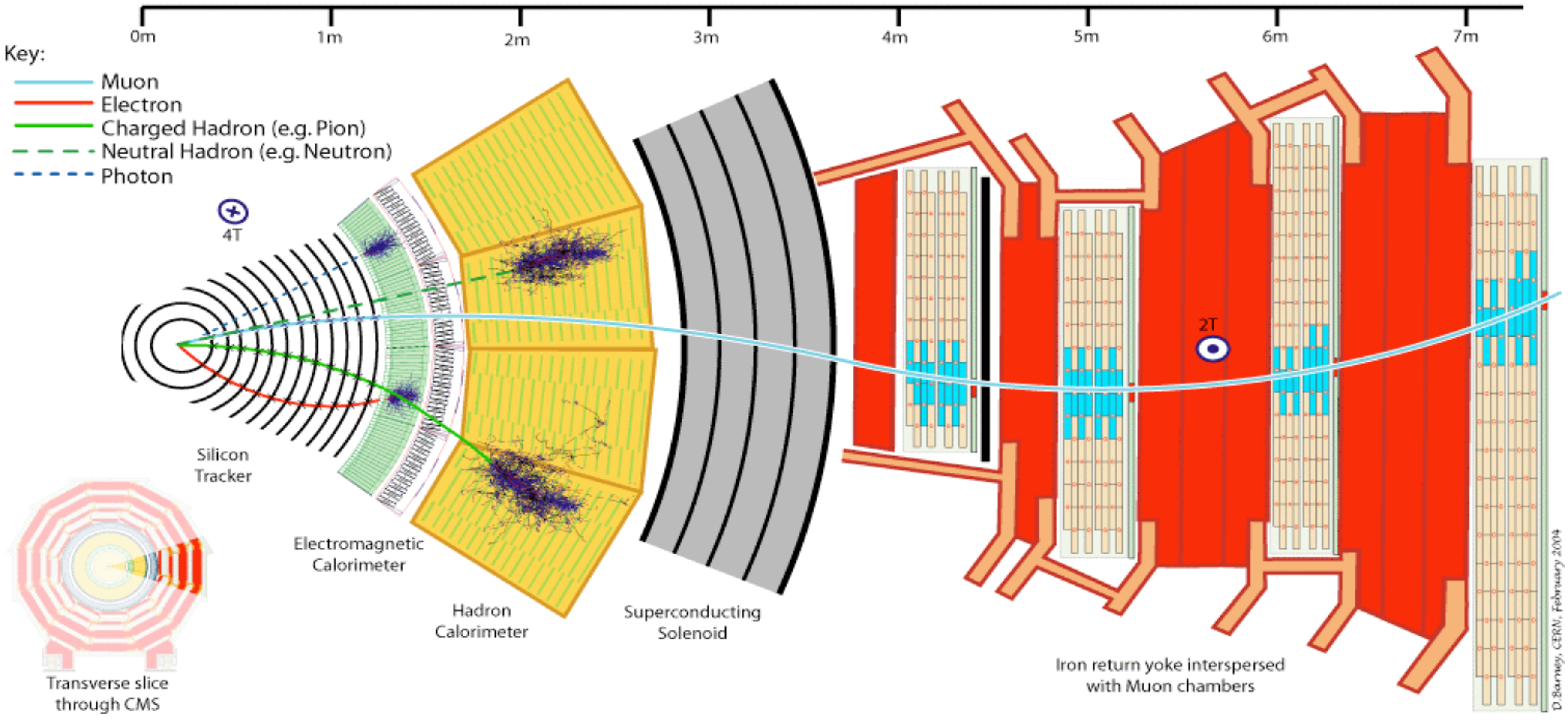
The CMS detector



Total weight : 12,500 t
Diameter : 15 m
Length: 21.6 m
Magnetic field : 4 Tesla

Tracking in CMS

>13 precision measuring points per track + 4T solenoidal field



The CMS Full Silicon Tracker

Pixel Detector

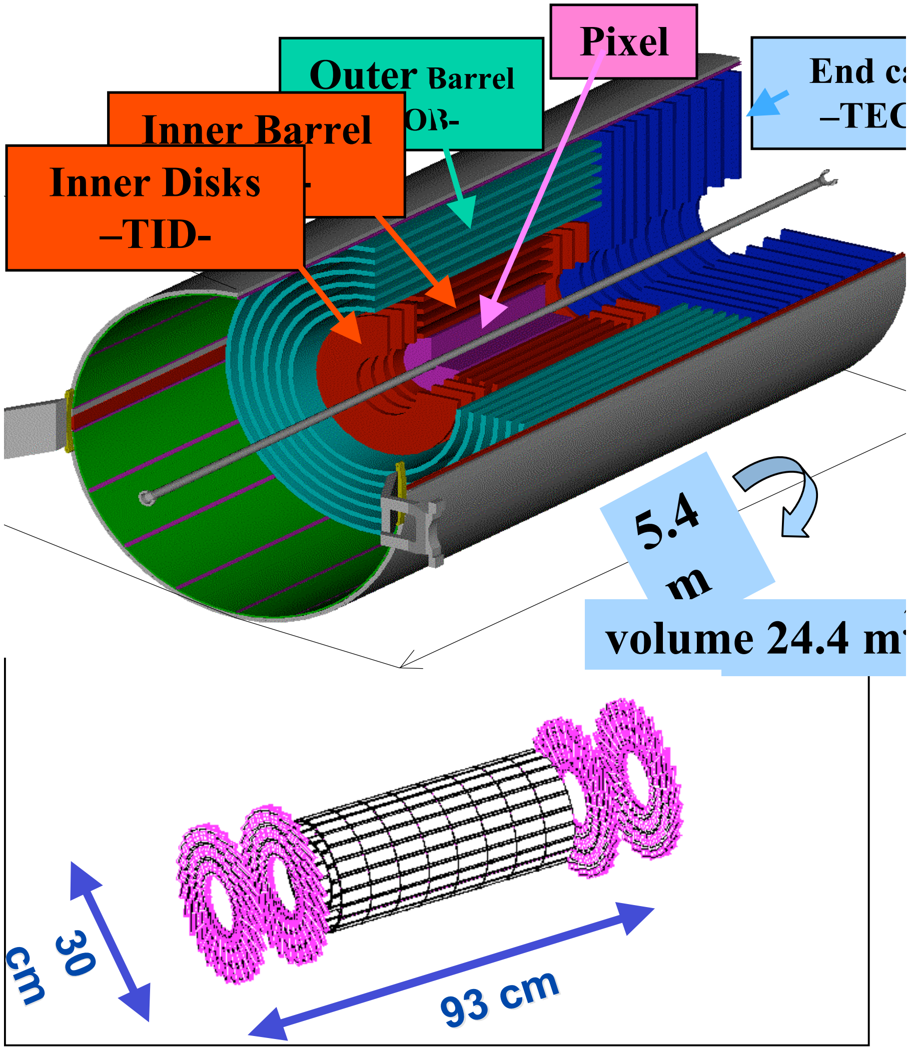
- 2 barrels, 2 disks: 40×10^6 pixels
- barrel radii: 4.1, ~10. cm
- pixel size 100×150 μm
- $\sigma_{r\phi}$= 10 μm σ_z = 10 μm

Internal Silicon Strip Tracker

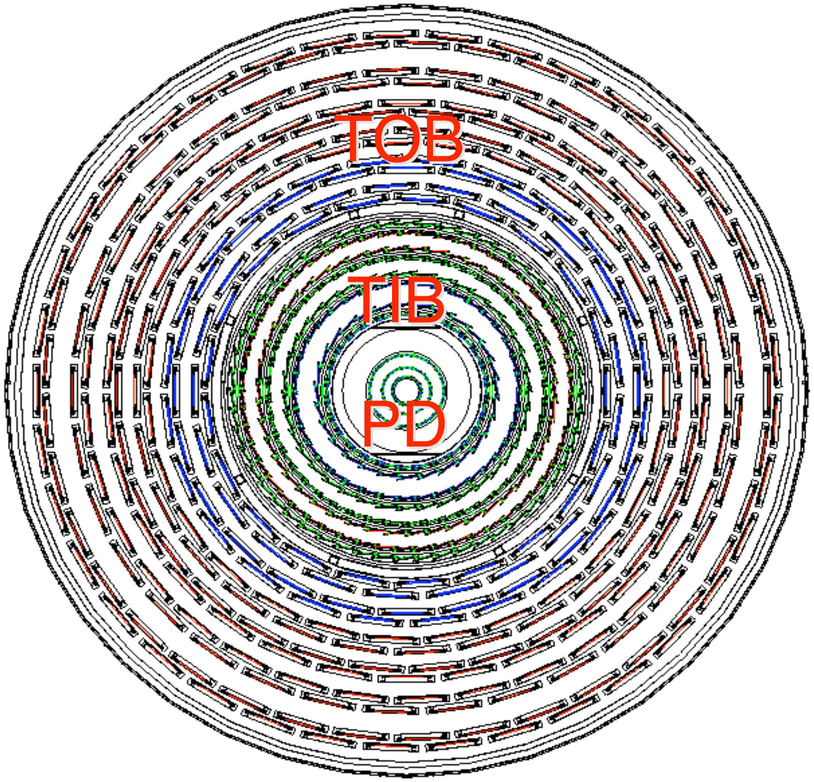
- 4 barrels, many disks: 2×10^6 strips
- barrel radii:
- strip pitch 80,120 μm
- $\sigma_{r\phi}$= 20 μm σ_z = 20 μm

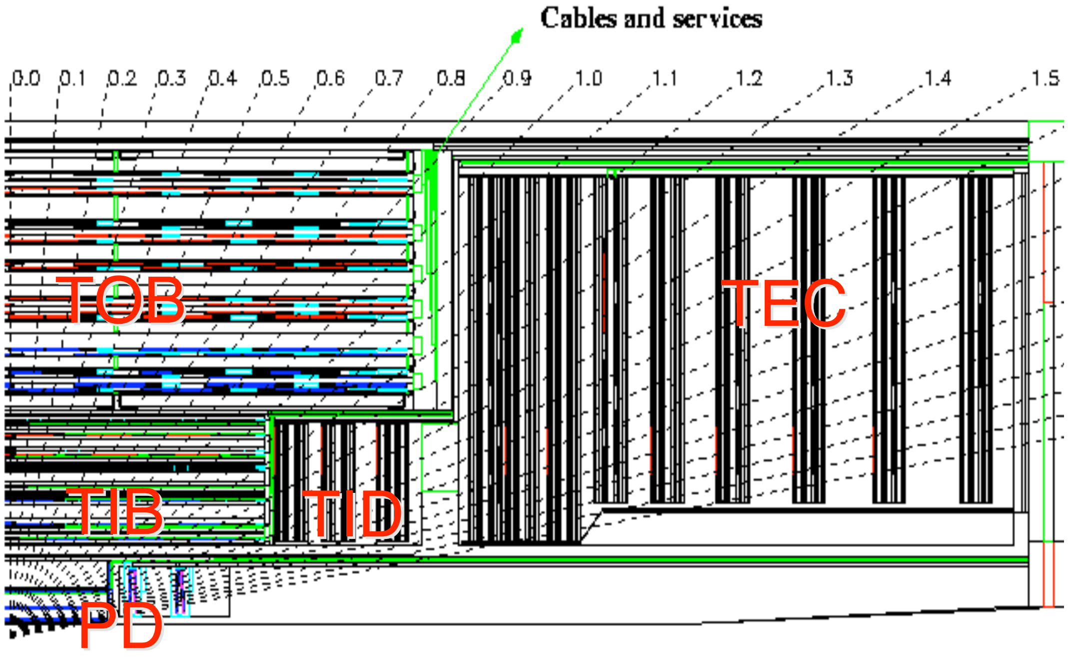
External Silicon Strip Tracker

- 6 barrels, many disks: 8×10^6 strips
- barrel radii: max 110 cm
- strip pitch 80, 120 μm
- $\sigma_{r\phi}$= 30 μm σ_z = 30 μm



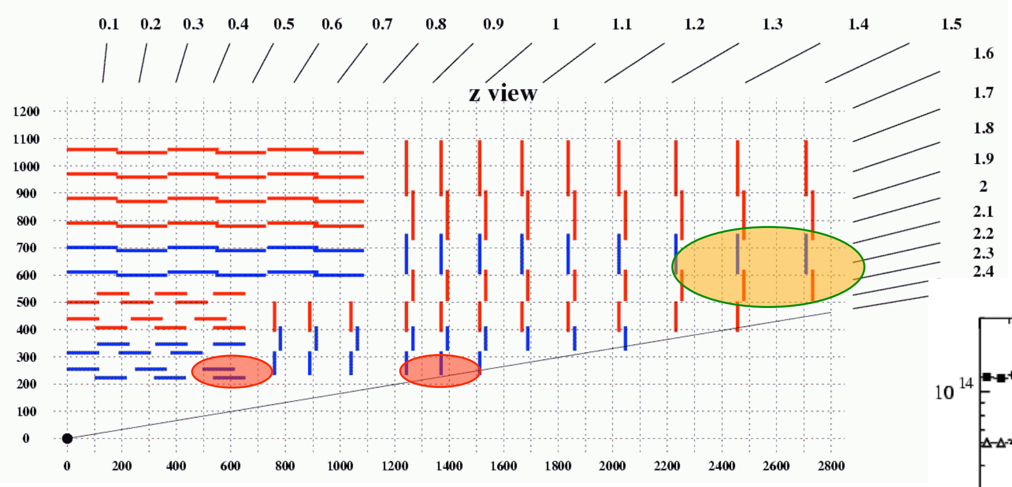
The CMS Full Silicon Tracker



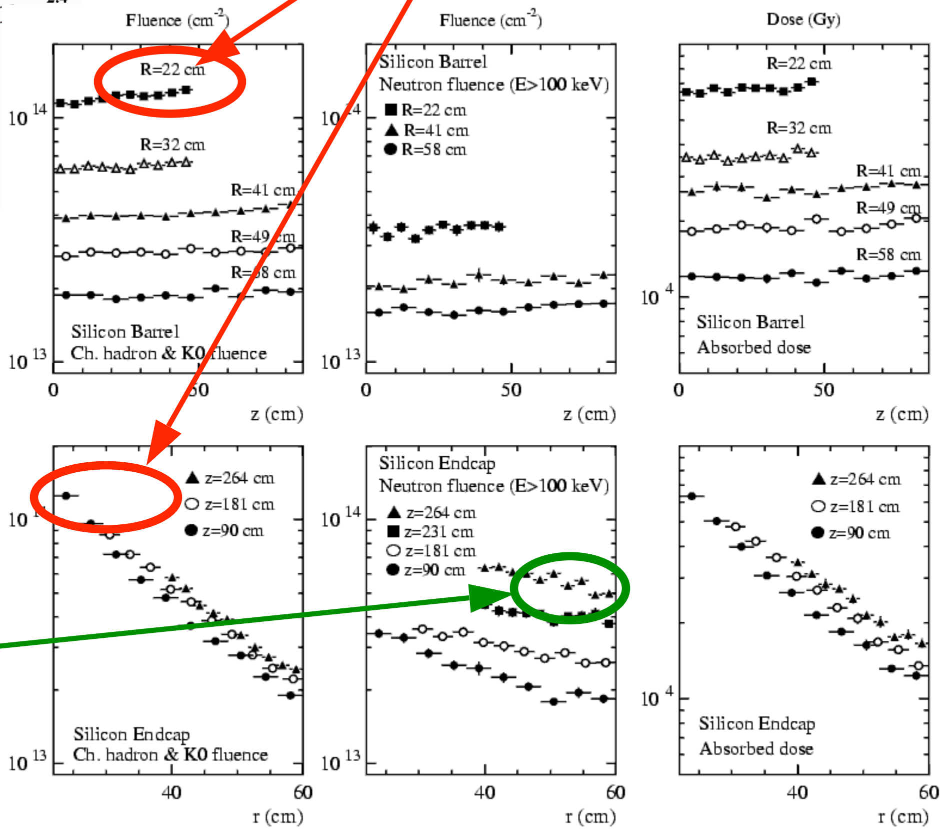


- 207m^2 of microstrip silicon detectors 15.232 modules
- 6136 thin sensors, 320μm (HPK) and19292, thick sensors 500μm (HPK + STM) all produced on 6” wafers.
- 60M channels pixel detector.

Radiation levels foreseen for the CMS tracker



~1.5x10^{14}cm^{-2}

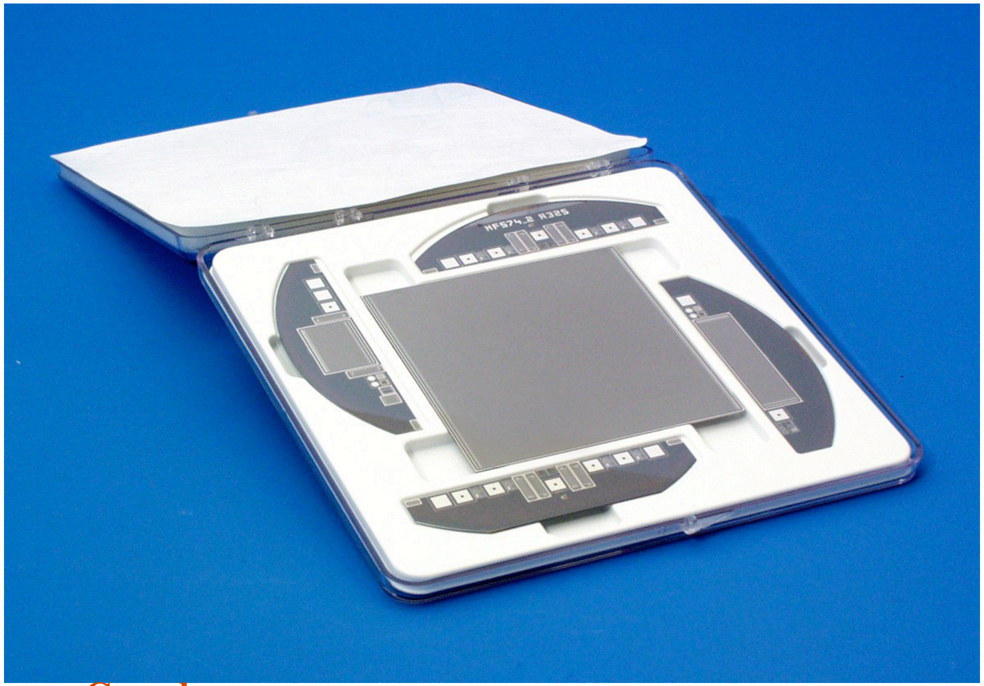


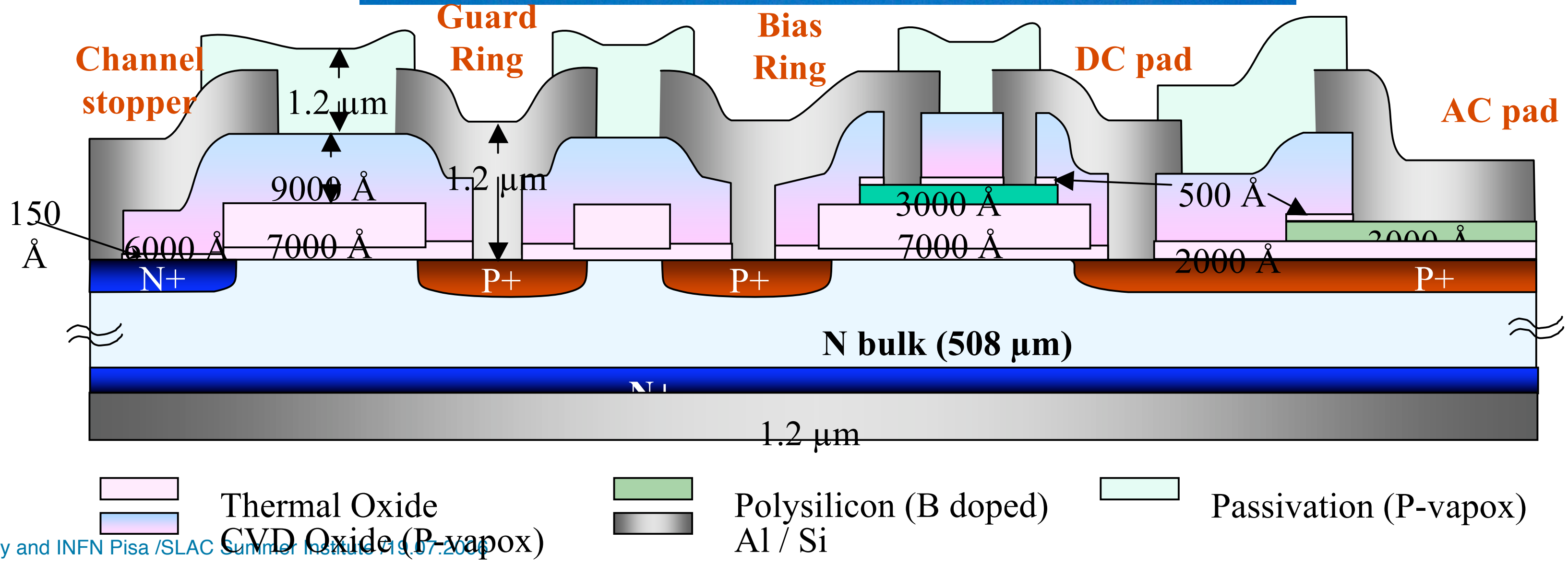
~0.5x10^{14} n/cm^{-2}

Sensors: radiation resistant technology

- Single-sided detectors p+ on n.
- Double-sided layers produced coupling two detectors back-to-back.
- AC coupling (no effect due to the increase of the leakage current)
- Polysilicon bias resistor integrated in the sensor (highly stable)
- High breakdown >500V (technology+careful design of the edge regions: asymmetric guard ring , n+ implant at the edge, distance between the active area and the edges d= 2* thickness + 150μm; 15 metal overhang per side; rounded edges).
- The width of the p+ implant is 0.15-0.20 of the readout pitch (minima capacity).
- Crystal orientation <100> no sensitivity of the capacitance to irradiat
- Increasing resistivity from inside to outside 2-4KΩcm.
- Increasing thickness 320-500μm for modules length 12 to 18 cm.
- Low costs (6” wafers and high throughput production lines).

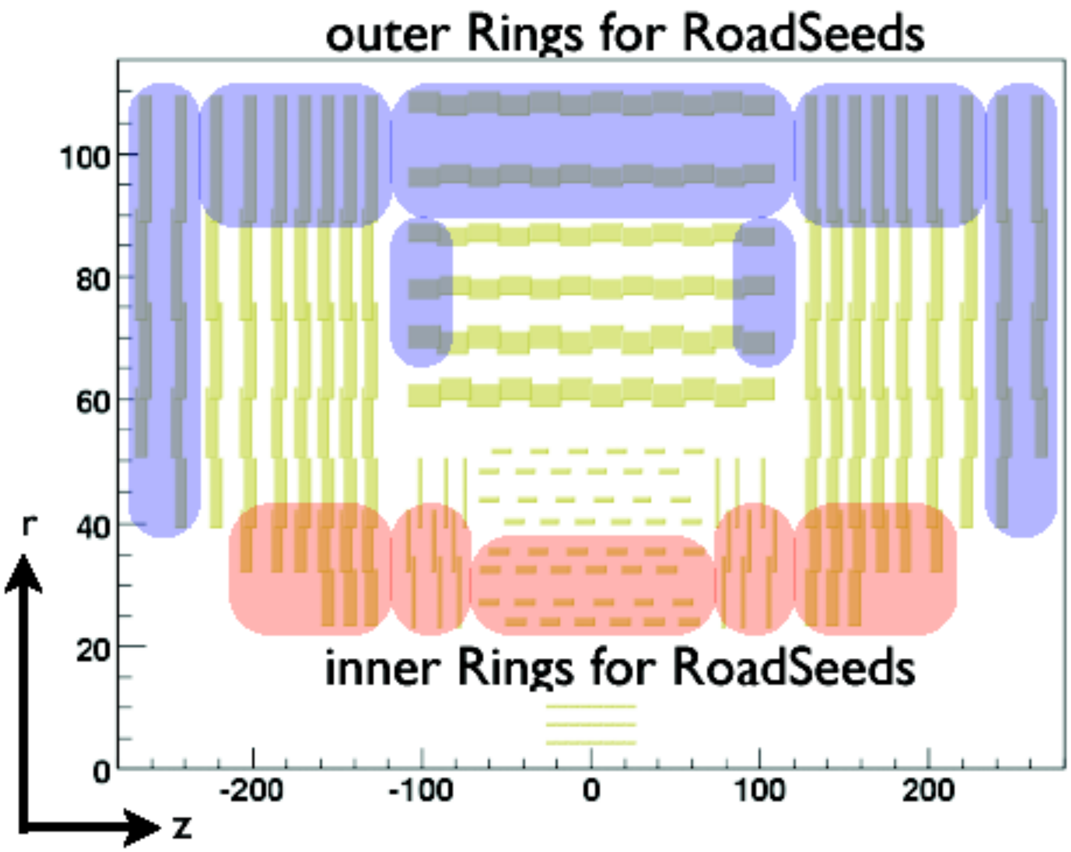
A CMS detector on 6” wafer





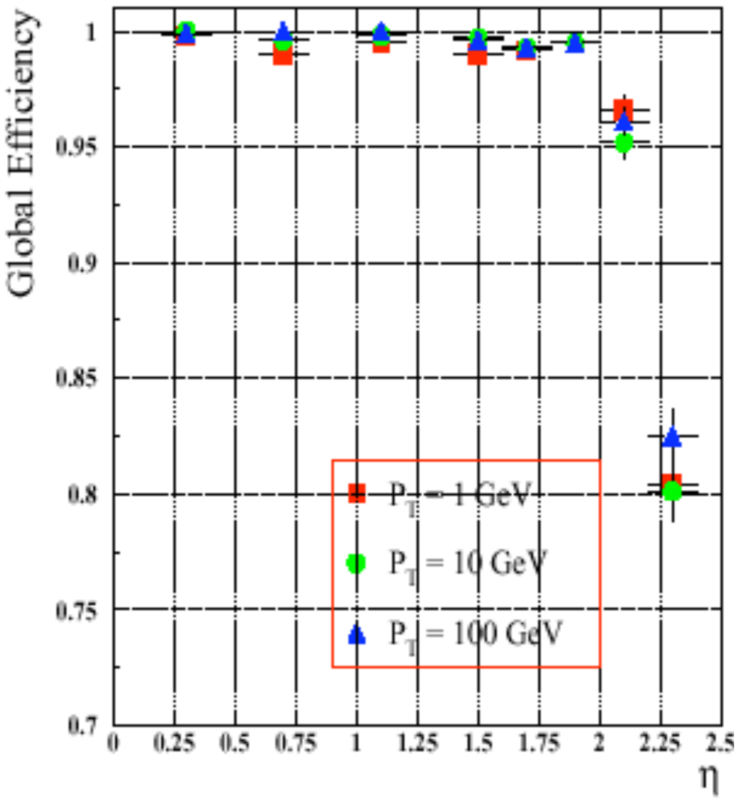
Track reconstruction

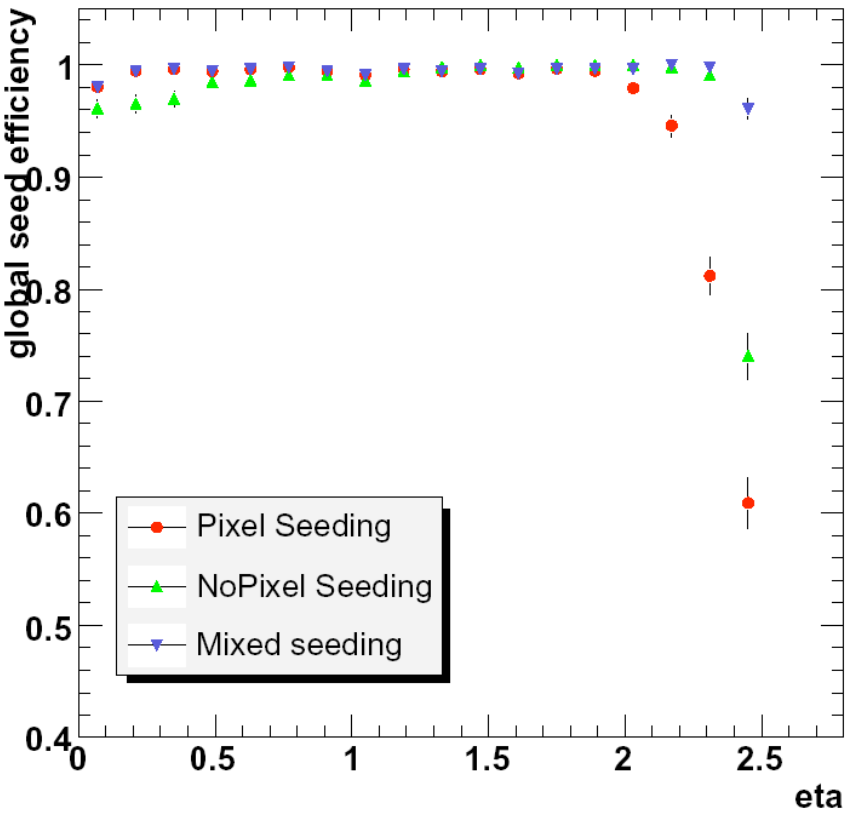
1. Kalman Filter
   - Pixel seeds
   - Cosmic seed (no-pixel seed, but non-pointing geometry)
   - Pixel only
2. Road Search
   - w/ or w/o pixels



Tracking performance: isolated tracks

- Tracking efficiency (Kalman filter) for isolated muons
- > 99% for η<2.4

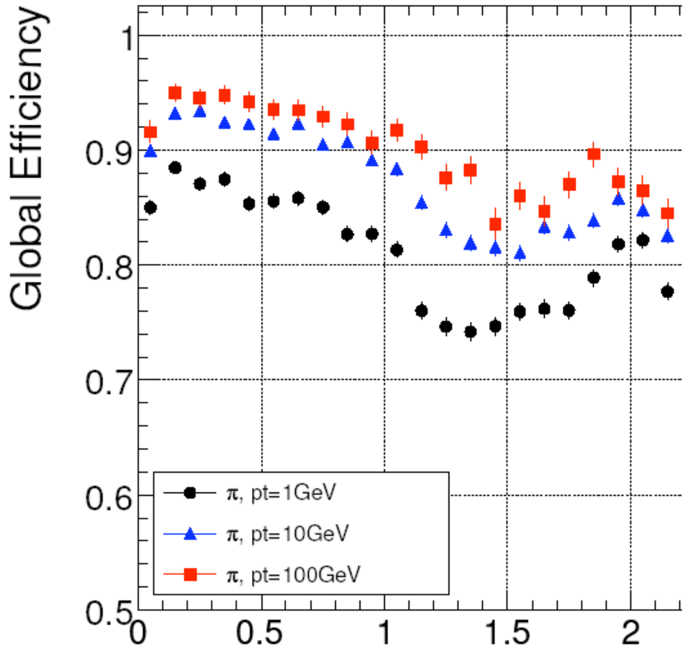




Track reconstruction in high pt jets

Track finding efficiency in 200 GeV E_T Jets; $p_T > 0.9$ GeV

		$|\eta| < 0.7$	$1.2 < |\eta| < 1.6$
≥ 6 hits	(eff.)	93.7 ± 0.6	91.6 ± 0.6
	(ghosts)	0.26 ± 0.09	0.10 ± 0.07
≥ 8 hits	(eff.)	88.3 ± 0.9	86.8 ± 0.8
	(ghosts)	0.10 ± 0.07	0.10 ± 0.07

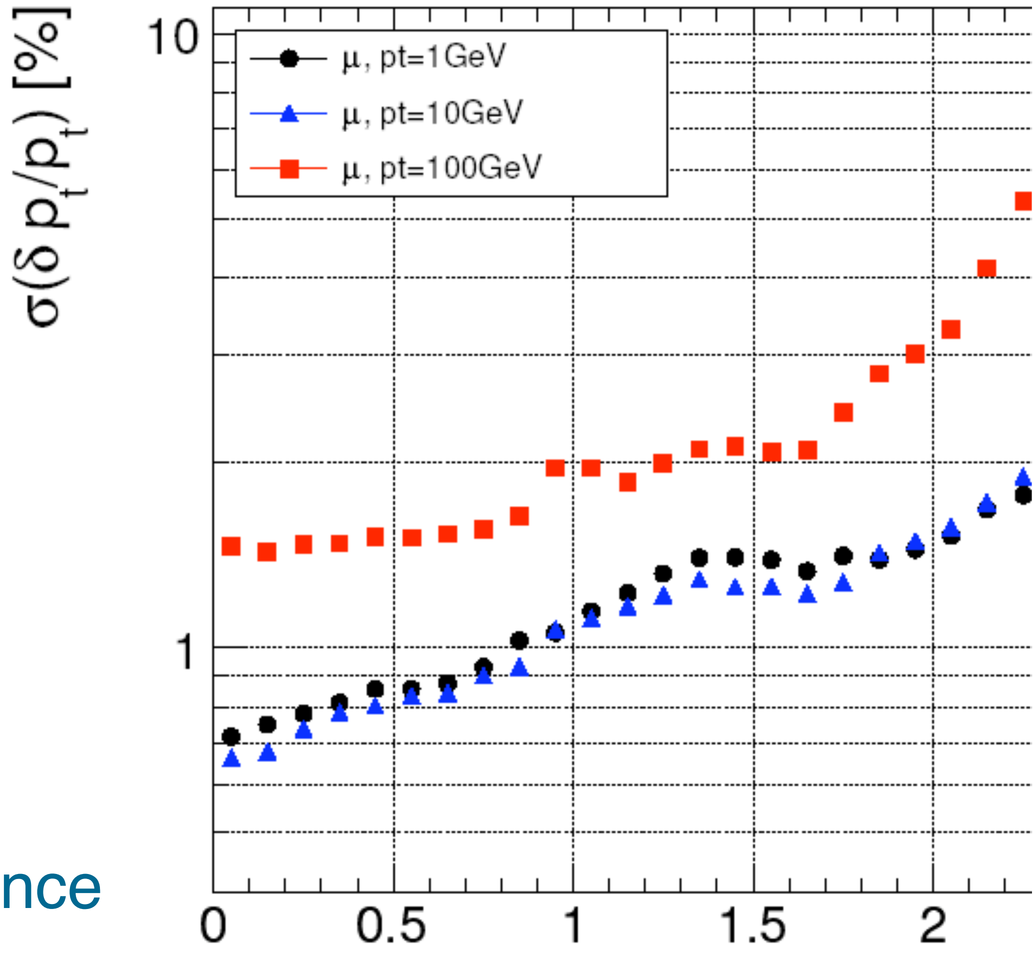


Reconstruction efficiency for low momentum pions

Momentum resolution

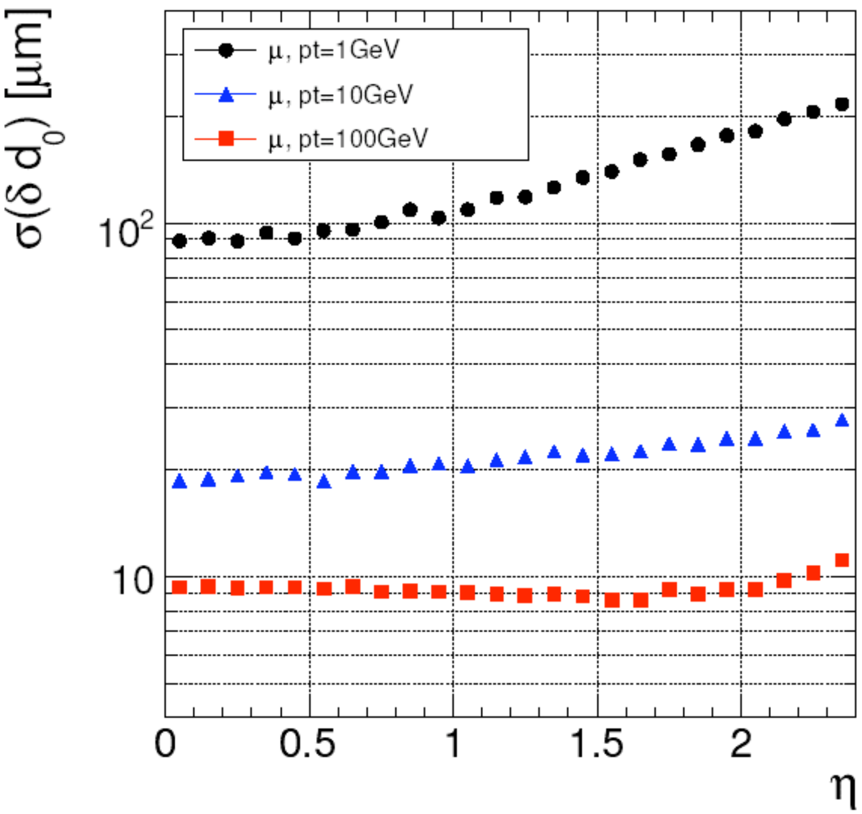
$\Delta p_t/p_t = 0.15\ p_t$ (TeV)
for high pt tracks

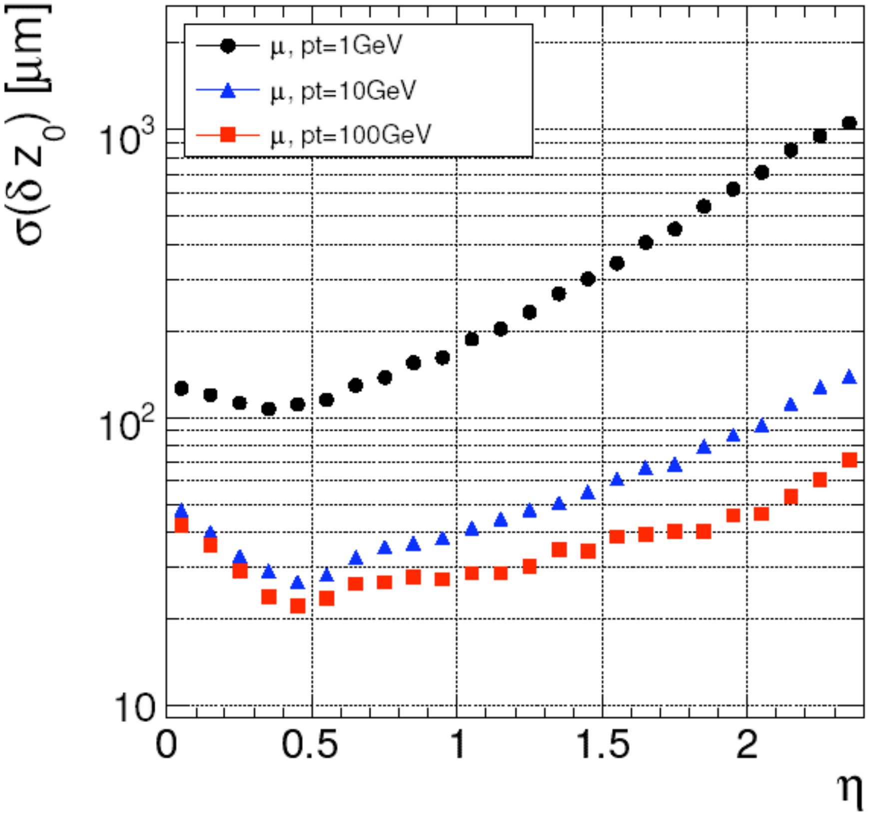
$\Delta p_t/p_t = 1.5\%$ for $p_t = 100$GeV
$\Delta p_t/p_t = 7.5\%$ for $p_t = 500$GeV



Spectacular invariant mass distributions.
Precision measurements
and positive effects on significance
of elusive channels

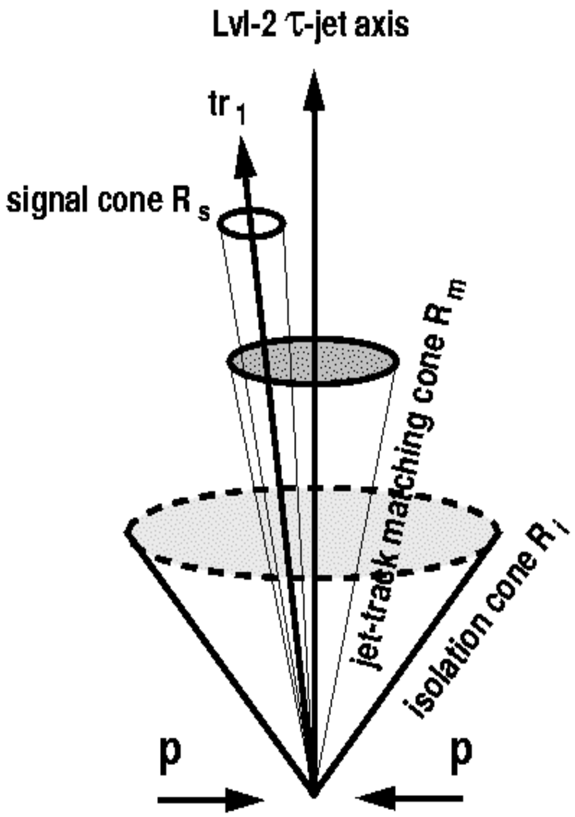
Impact parameter resolution

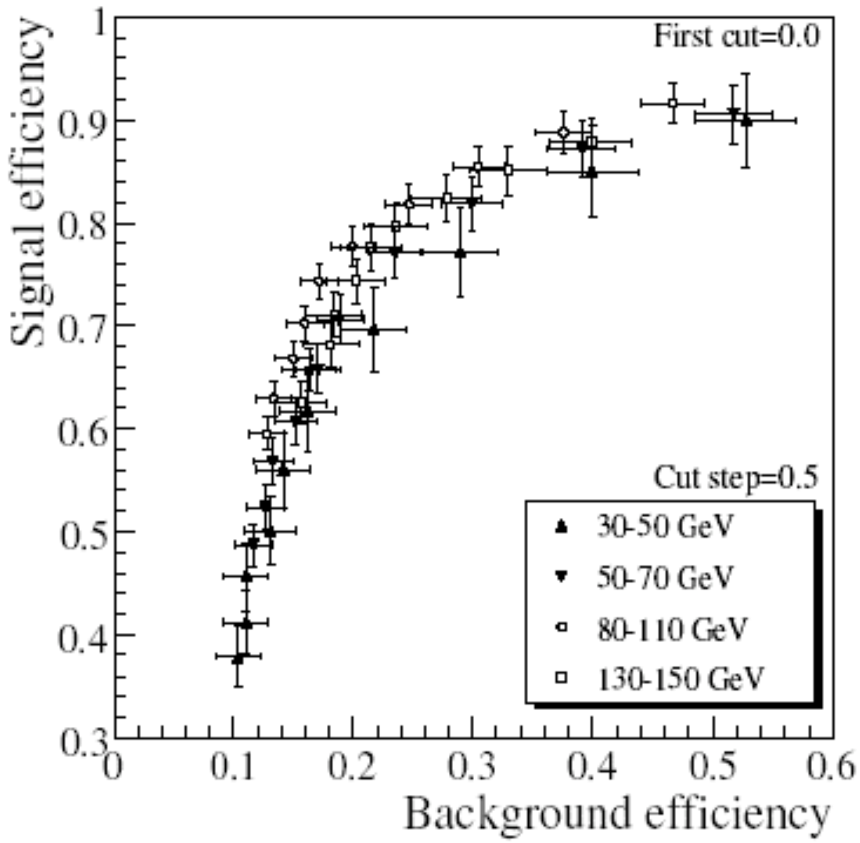




Excellent results both in the transverse plane (10-20μm) and the r-z plane (20-40μm) (several tagging techniques available)

Tau Tagging efficiency





Several tagging techniques that exploit the isolation of the decay products:

mass tag, secondary vertex, impact parameter

Developed for HLT, have been refined for offline.

Vertexing

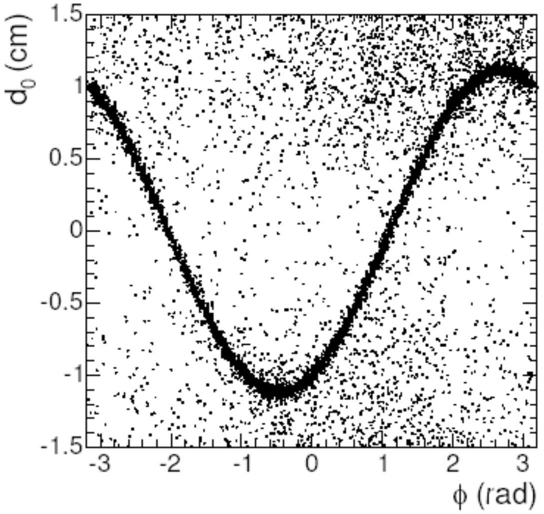
Online pixel primary vertex finding

Offline Vertex reconstruction: efficiency to find primary vertex in High luminosity run >95%

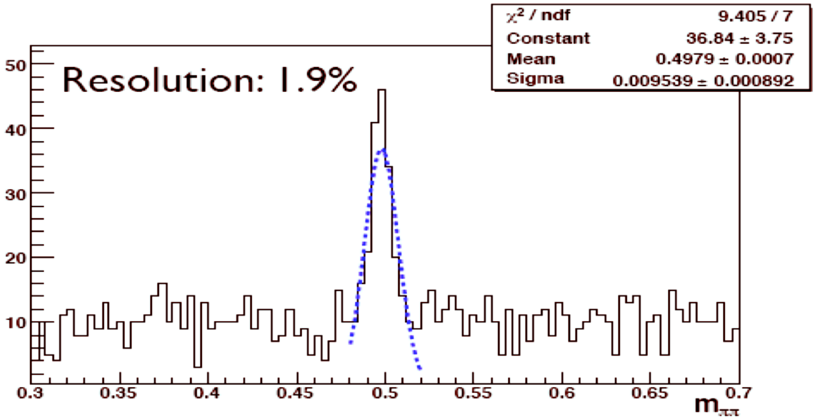
Recent developments

- V^0 and Λ^0 reconstruction
- Tertiary vertex finder for B-jets

Beam spot with ~ 1000 MB events



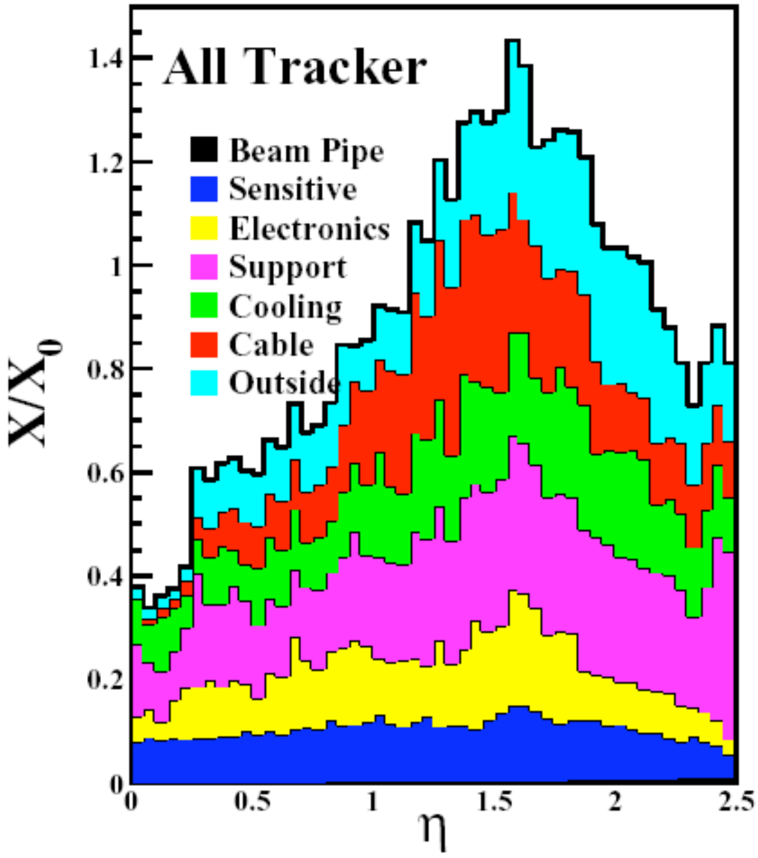
Offline P.V. resolution	σ_x (μm)	σ_z (μm)
$H(150GeV/c^2) \rightarrow ZZ \rightarrow 4e$	17	21
$H(115GeV/c^2) \rightarrow \gamma\gamma$, g fusion	25	32
$H(115GeV/c^2) \rightarrow \gamma\gamma$, VB fusion	20	31
$B_s^0 \rightarrow J/\psi\ \phi$, primary vertex	44	65
b-jets; $30 < E_T < 50GeV$	24	31
$t\bar{t}$	13	18
Drell-Yan 2μ	13	25
$t\bar{t}H$	10	14

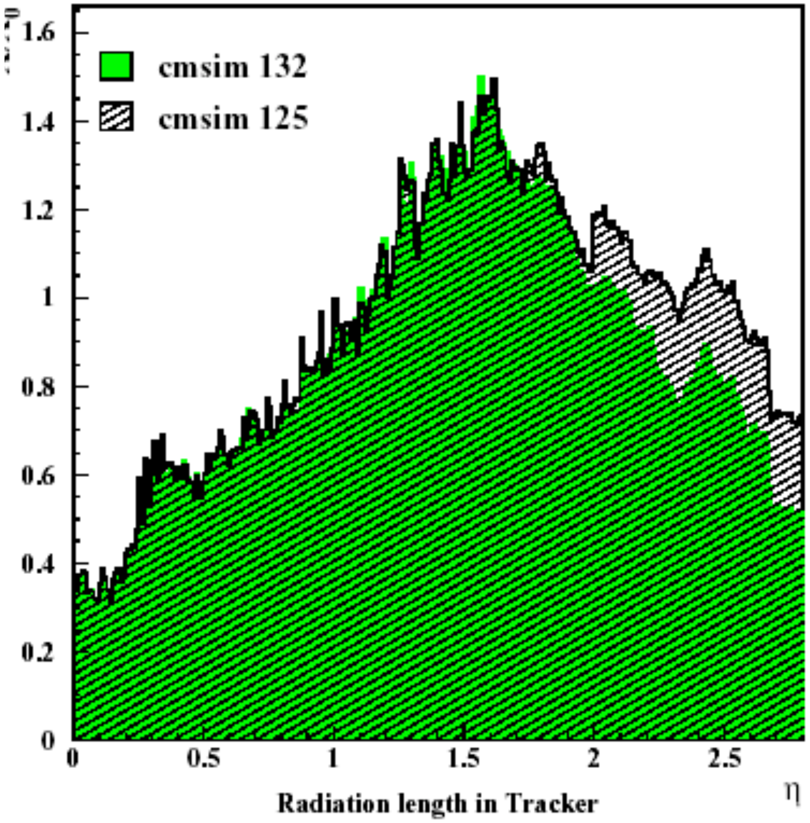


M(π+π–)

Big worries: material budget

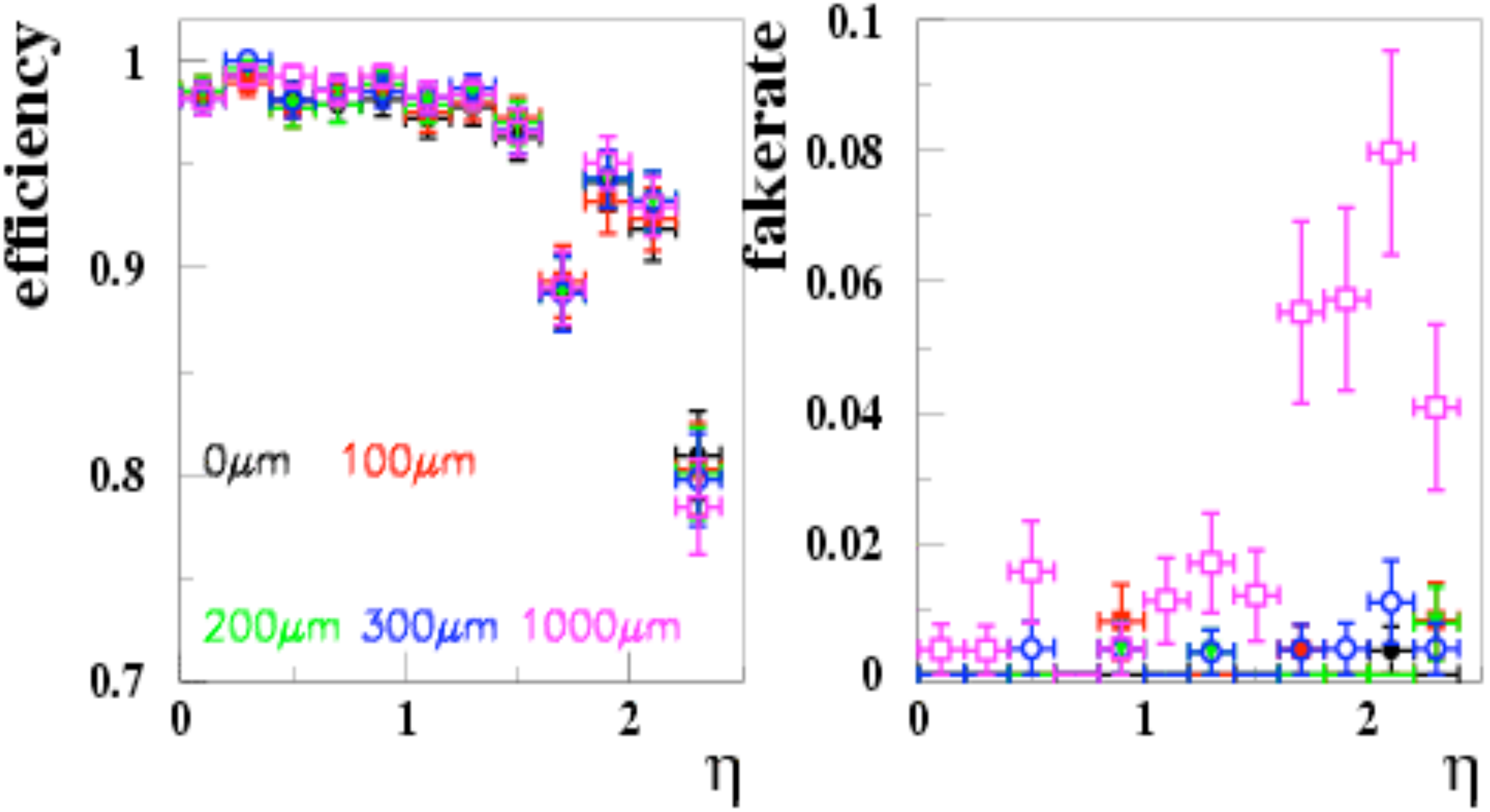
During construction all components are measured and weighted to update the description of the material budget. Detailed simulations are continuously improved. Incredible care is put in choosing low mass materials everywhere….. but ….





Big worry: the alignment

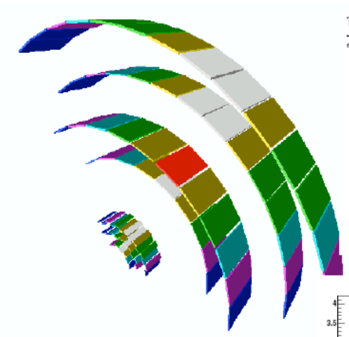
Pattern recognition algorithms work still very well with initial misalignments up to 1mm and 1 mrad for events W->$\mu\nu$ a $2*10^{33}$



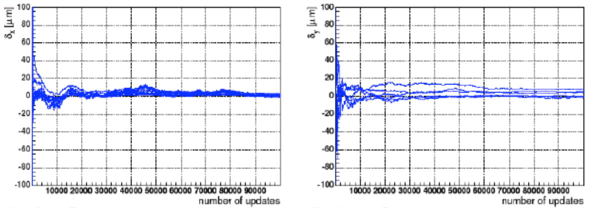
Alignment tools

Three different algorithms in CMS

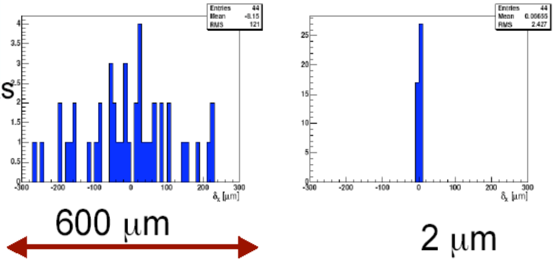
- HIP
  - Iterative method – no correlations between sensors considered
- Kalman Filter
  - Full correlation among sensors
- Millipede II
  - Residual minimization – evolution of Millipede (CDF H1)

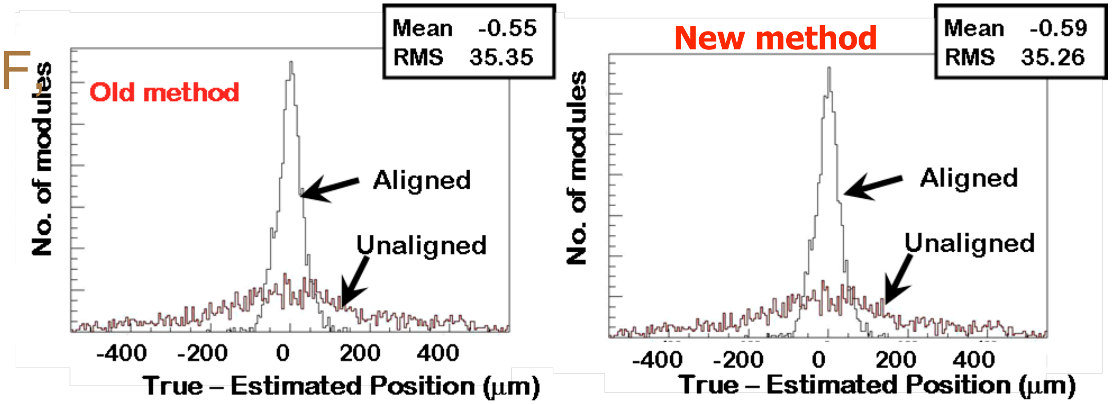


After 100K single muon tracks



Left: Convergence in x in μm, Right: Convergence in y in μm

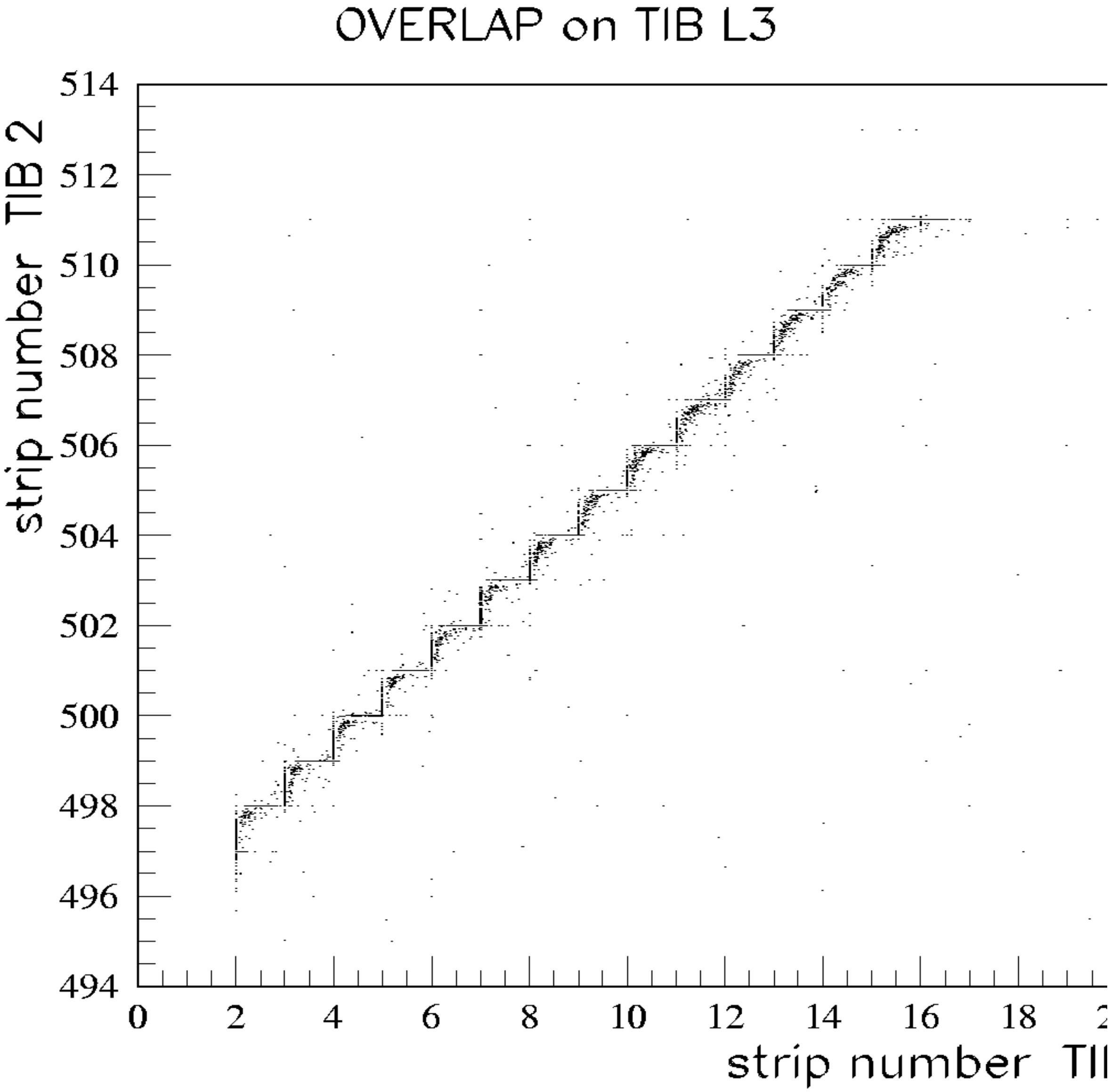




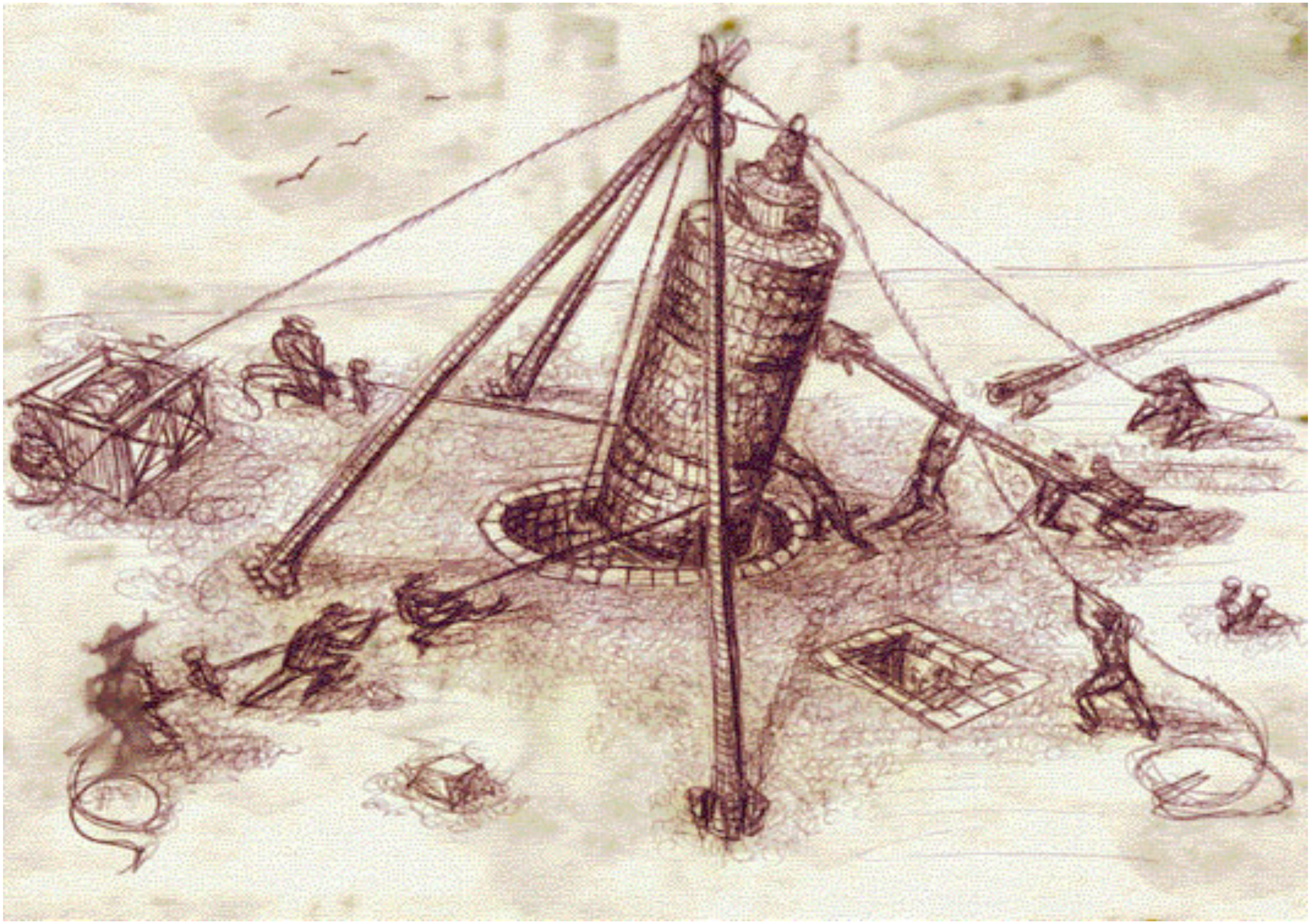
TIB overlap (alignment)

Correlation between adiacent detectors

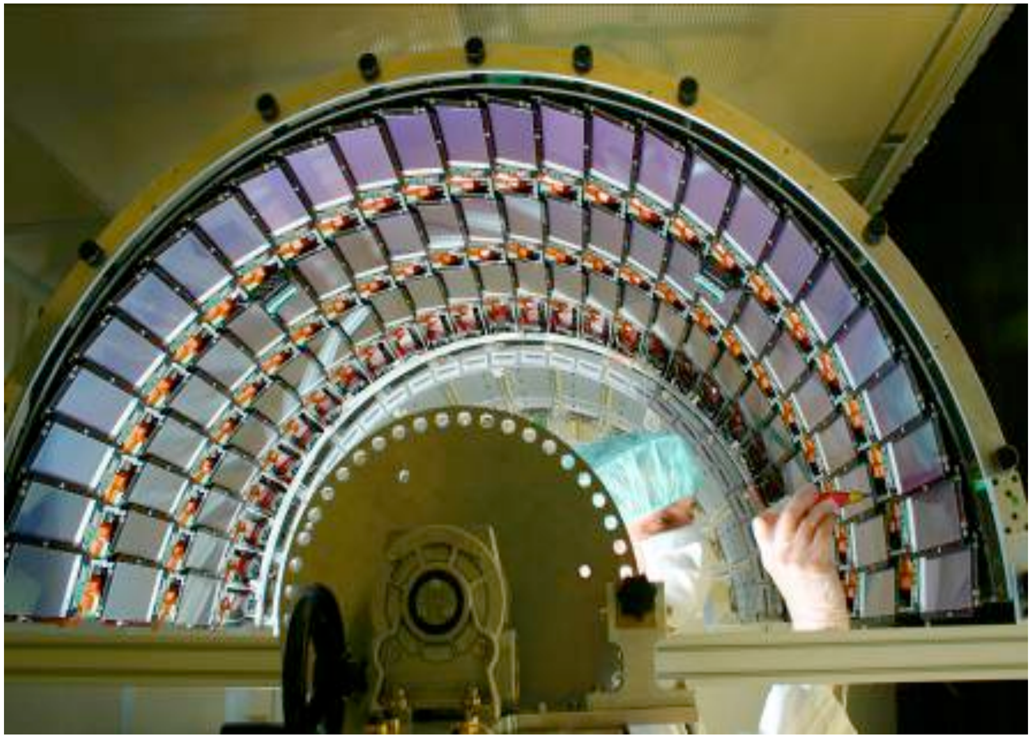
~15-20 channels in the overlap~2mm

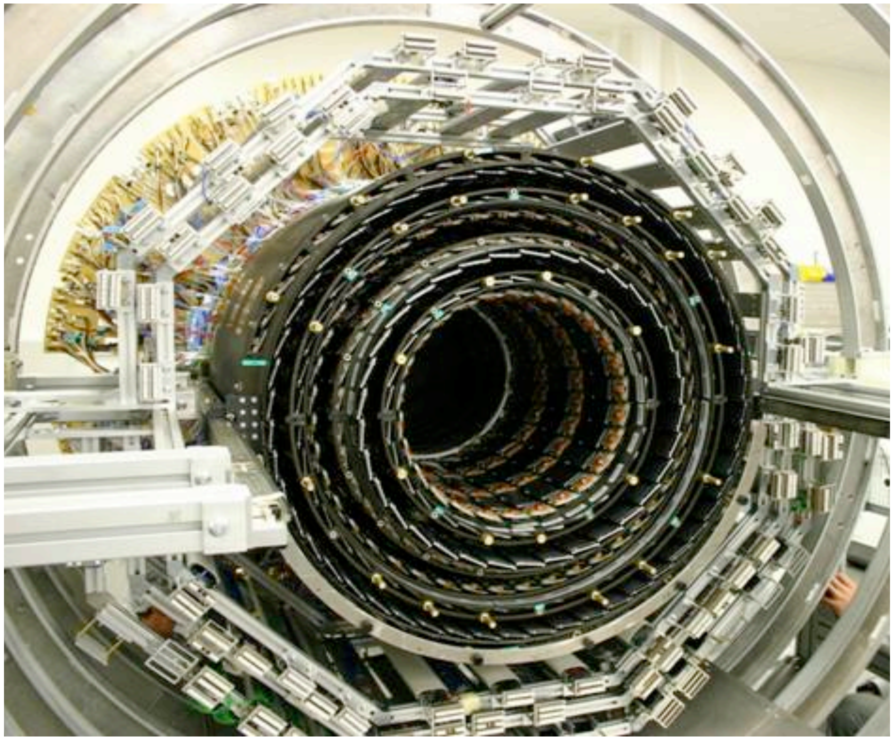


Where we are now

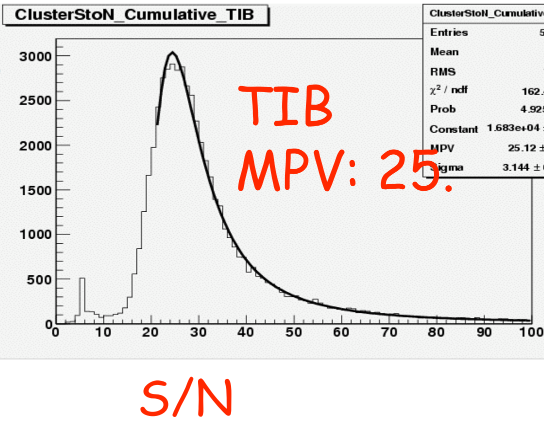


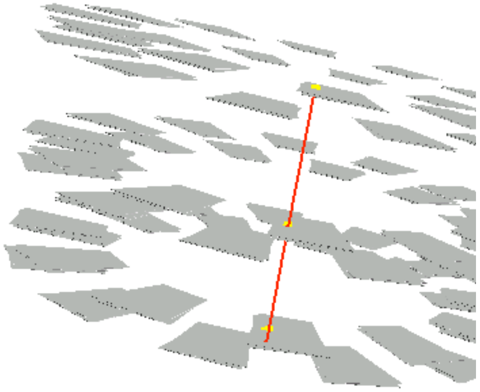
TIB/TID (Italy): 90% completed





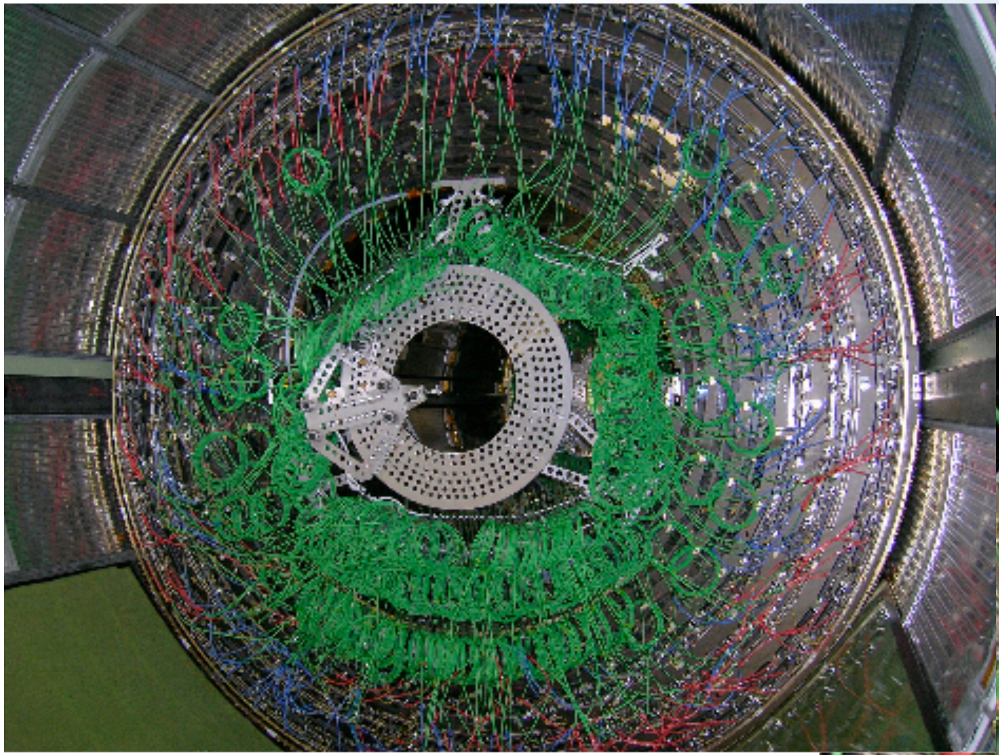
Excellent quality: bad channels <0.1%
Pre-commissioning in cold already done.
Cosmic ray test: pre-alignment constants and excellent S/N ratio.

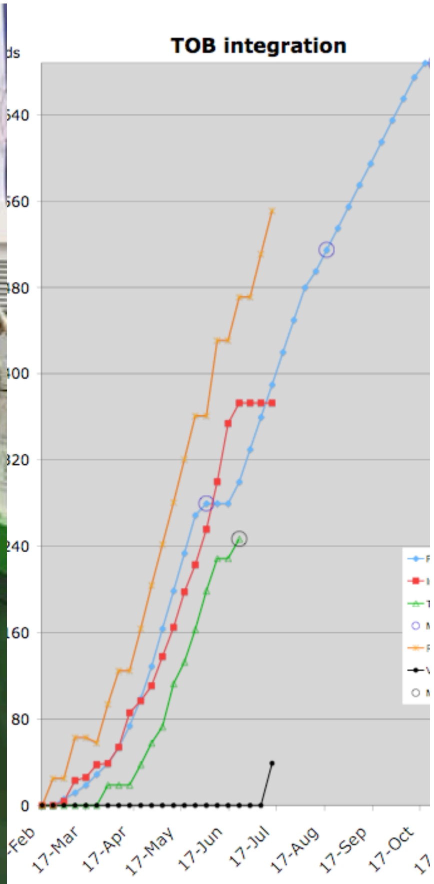


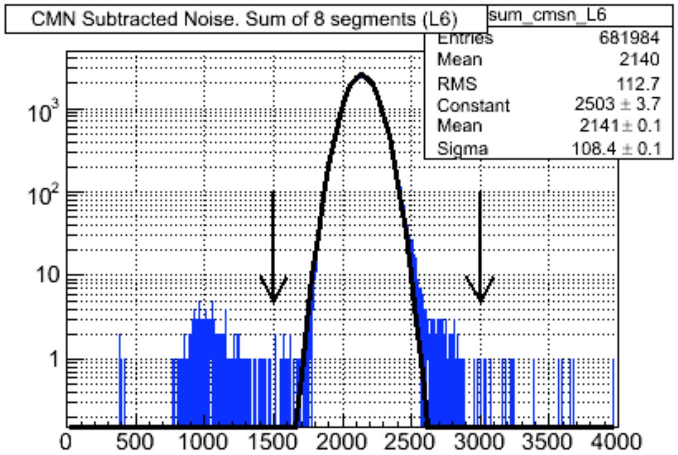


TOB (USA&CERN) = 50% completed

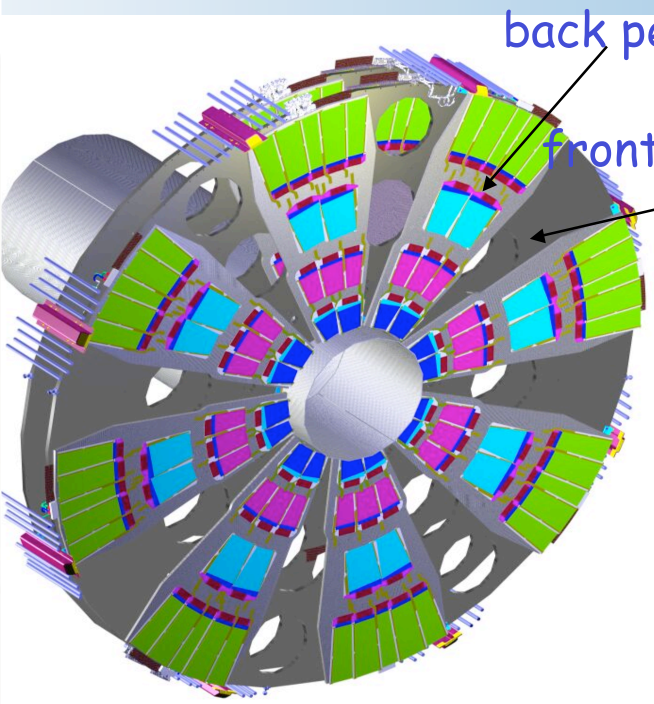
Excellent quality so far: dead or noisy strips<0.1%.

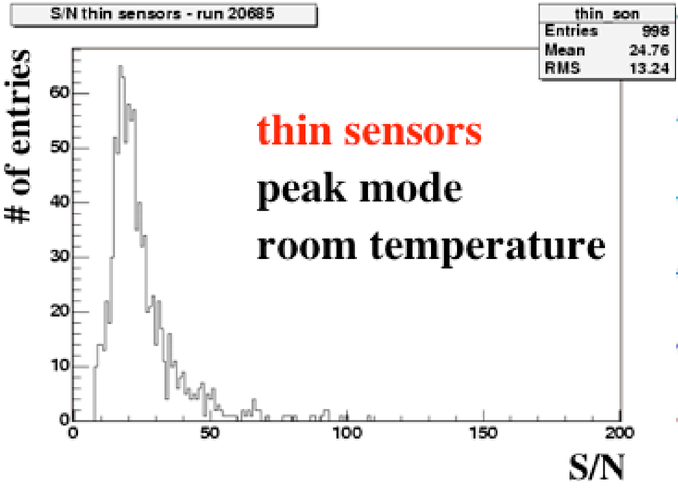






TEC (Aachen&Lyon): 40% completed

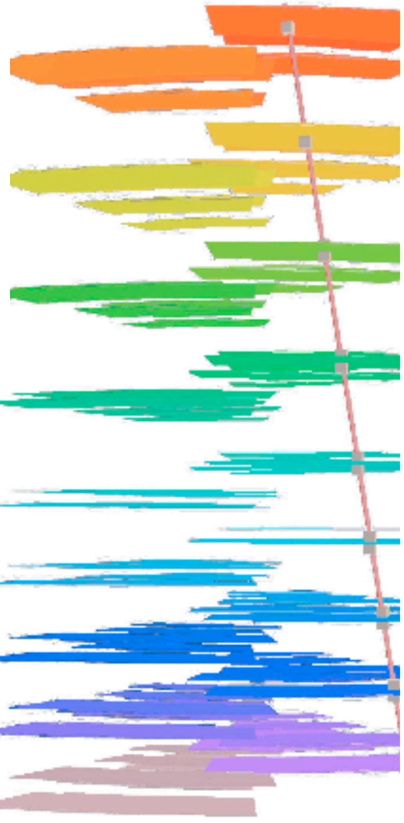




thin sensors

peak mode

room temperature



Very good quality (bad channels<0.3%). Very nice cosmic ray data S/N>25 for thin sensors in peak mode. Pre-alignment constants.

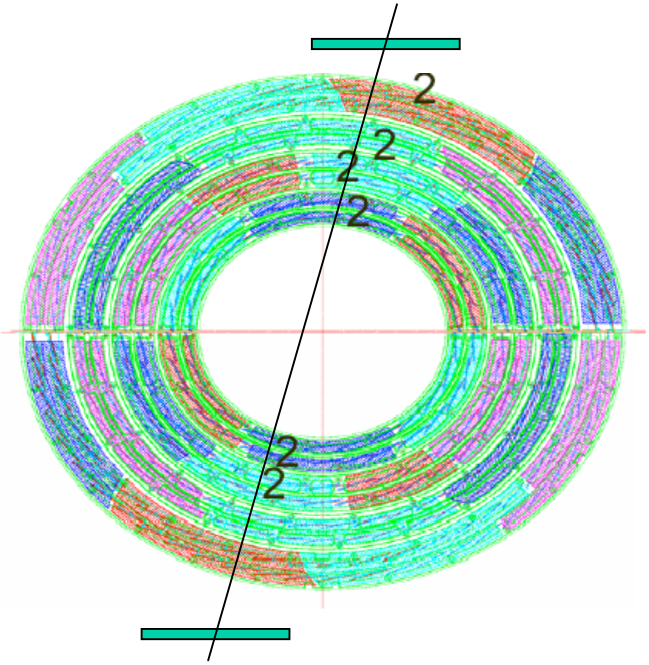
First ideas for the pilot run 900GeV (11/07)

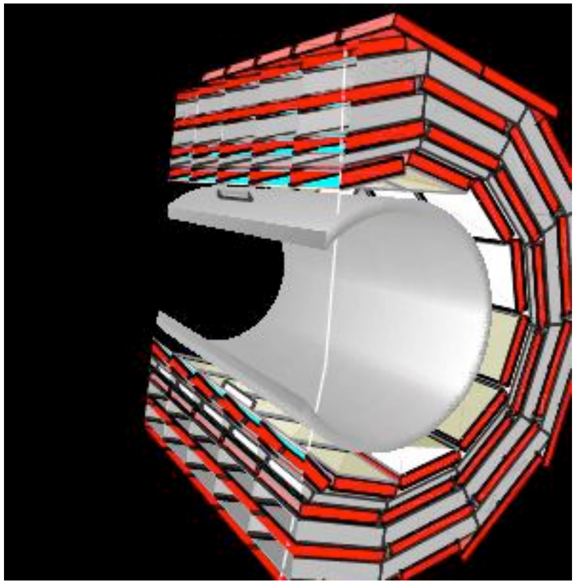
Pre-align with cosmics

Test 25% at the Tracker Integration Facilities (no B)

Cosmic run (in cold and with B)

Rate for muons> 10GeV reaching the tracker : 60Hz



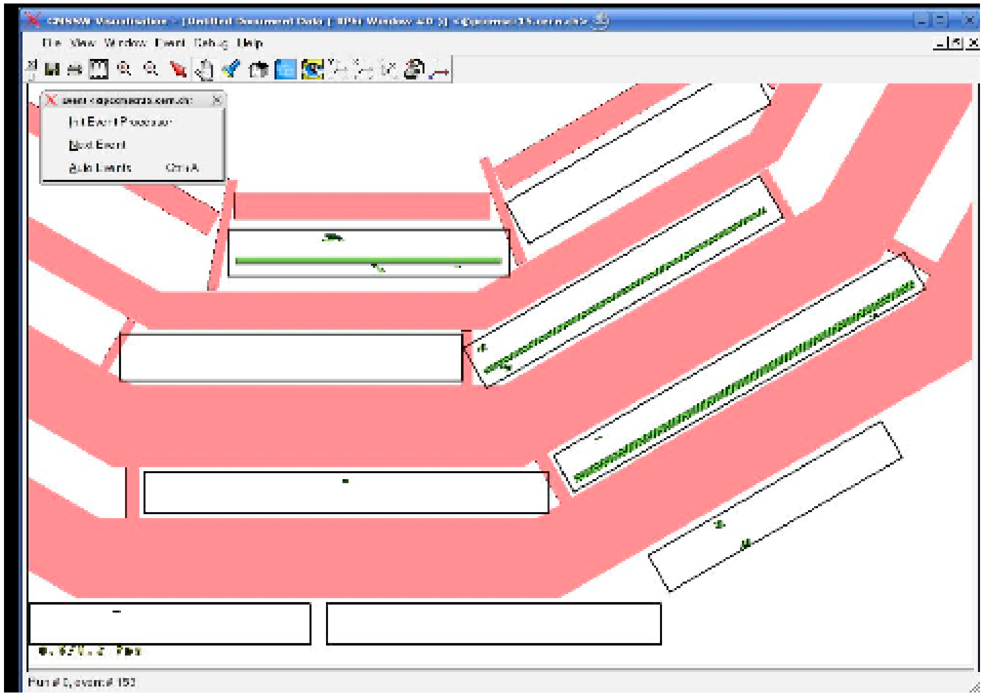


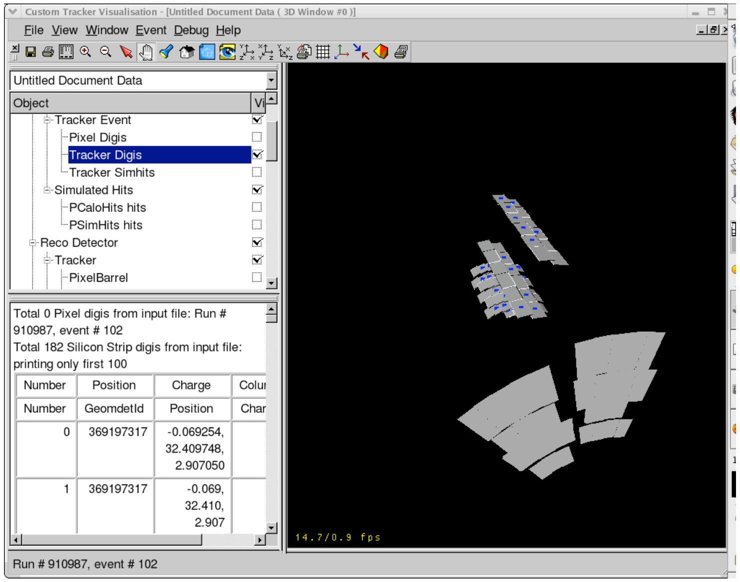
The goal is to reach a pre-aligned tracker (better than 100μm) prior to collisions. Using minimum bias events from the first collisions (700k tracks>2GeV) it seems possible to align in the range of ~20μm.

MTCC

A complete wedge of CMS (Muon Detectors, HCAL, ECAL and Tracker) is currently taking data at P5.

4 days ago first successful run: 0.5 M muon events collected in 1 night.





Total 0 Pixel digis from input file: Run # 910987, event # 102
Total 182 Silicon Strip digis from input file: printing only first 100

Number	Position	Charge	Colu
Number	GeomdetId	Position	Char
0	369197317	-0.069254, 32.409748, 2.907050	
1	369197317	-0.069, 32.410, 2.907	

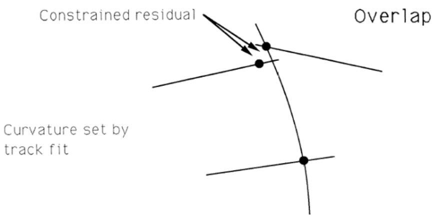
Run # 910987, event # 102

Study of the material budget (Pilot Run)

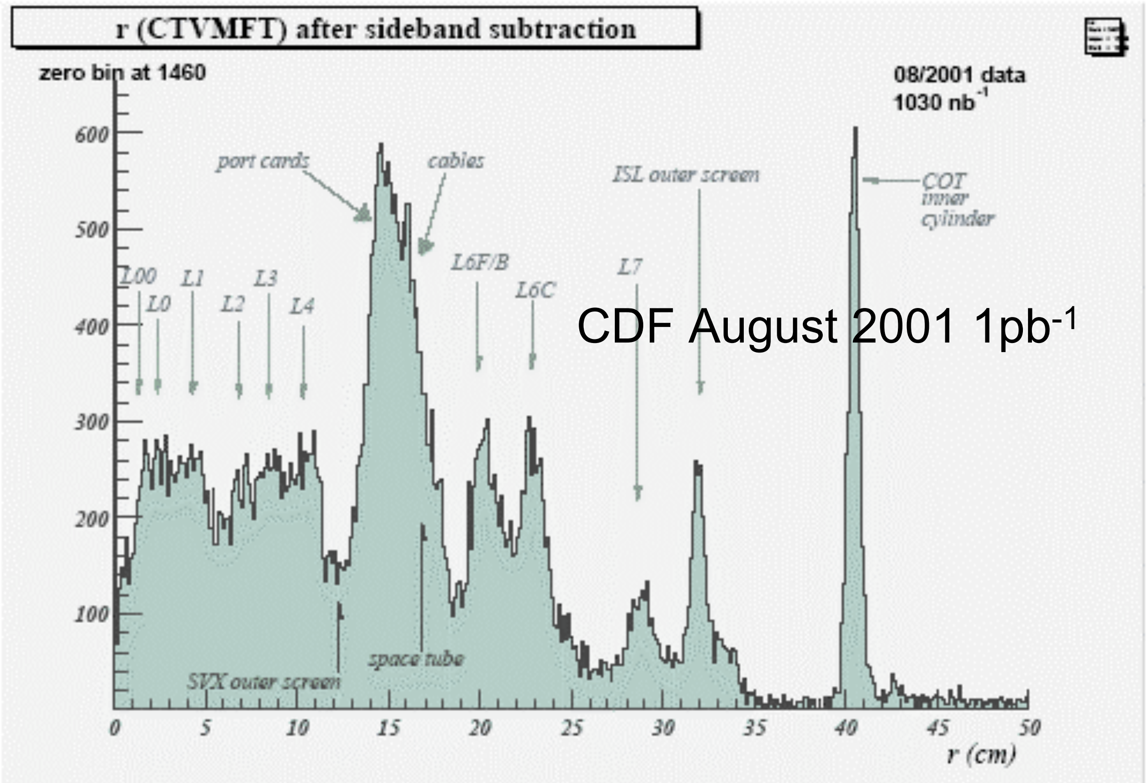
Align detector better than ~ 20 μm ($80/\sqrt{12}$)

Use overlaps to determine the hit resolution

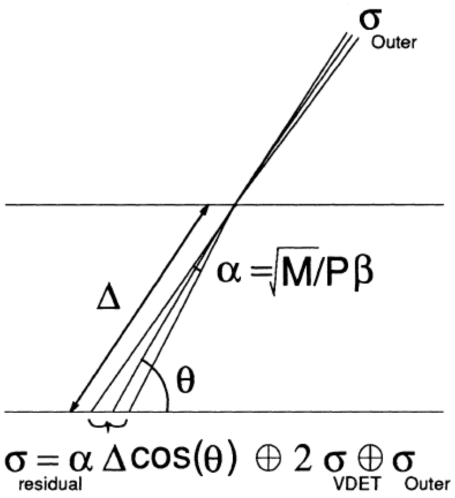
Use residuals wrt 1/p to measure material budget



$$\sigma_{res} = 2 \otimes \sigma_{vdet} \oplus \sigma_{outer} \oplus \sigma_{MS}$$



CDF August 2001 1pb^{-1}



J/psi tool for material and B (Pilot run)

Need to define a new J/Psi trigger

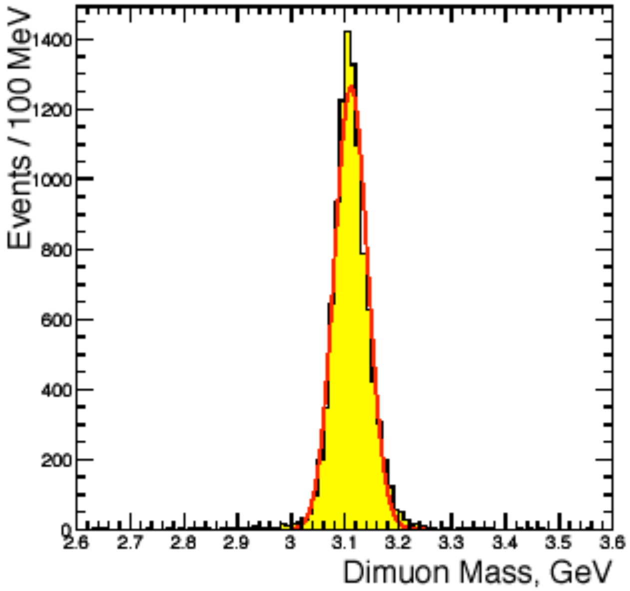
L1

- 2 muons with p_T>3 GeV

L2

- Primary vertex reconstruction (in z)
  - Currently done using pixel
  - No experience w/o pixels so far
  - In each region identified by the two muons reconstruct tracks with up to 5 hits

Need to be re-evaluated taking into account the new running conditions

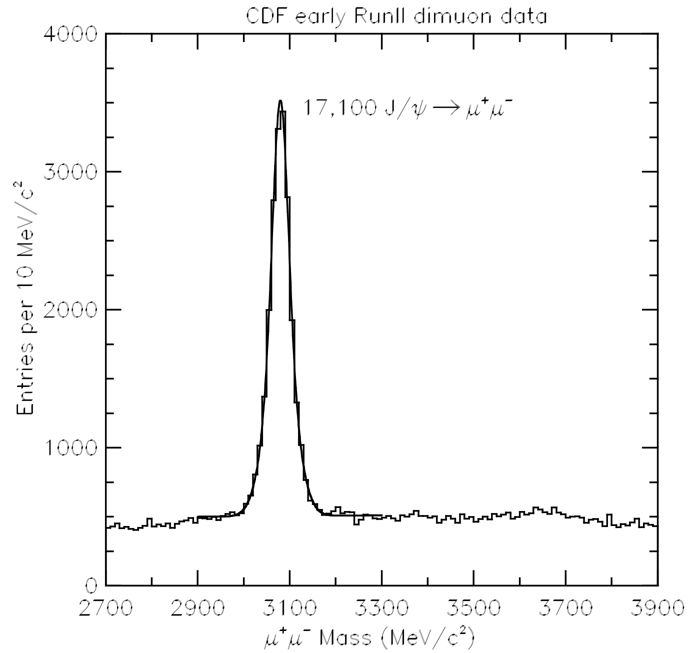


J/ψ mass residuals
Mean = 3.112 GeV
σ = 31 MeV

J/psi tool for material and B (Pilot run)

CDF Very early J/ψ data (few pb^{-1})

- **Established basic momentum scale for tracking**
- **Used to measure muon chamber efficiencies**
- **Used to measure vertex resolution of SVX**
- **Used to measure energy scale of hadron calorimeter**

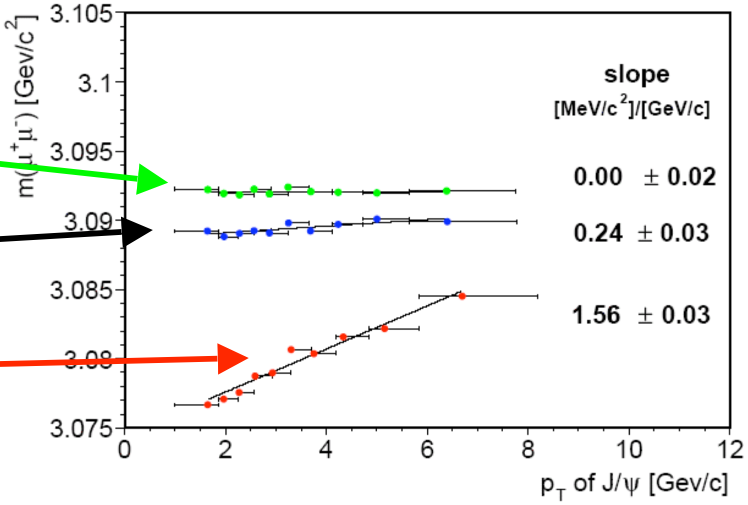


Similar tools using the mass of reconstructed J/psi, Upsilon and Z's can be used to study the Magnetic Field effects (physics run)

Additional 0.455 g/cm^2

Corrected for nominal material in simulation

No corrections



New ideas for the future: SLHC

Basic assumptions

•Luminosity 10^{35}cm^{-2} s^{-1}
•Bunch spacing 12.5ns (10ns)

•Program of new physics with an integrated luminosity of 2500fb^{-1}
•Start-up around 2015

•Need of maintaining B-tagging capability
•Momentum resolution
•Pattern recognition

•Fast (10ns) and low power (1-2mW/ch) electronics assumed to b
available

New ideas for the future: SLHC

The CMS concept can be maintained for S-LHC

- Radial region: 50-60cm<r<110cm ;

$1x10^{14}cm^{-2} < \Phi < 2.5x10^{14}cm^{-2}$

No basic new development. Optimization of existing technologies.

- Radial region: 20cm<r<50-60cm;

$2.5x10^{14}cm^{-2} < \Phi < 8x10^{14}cm^{-2}$

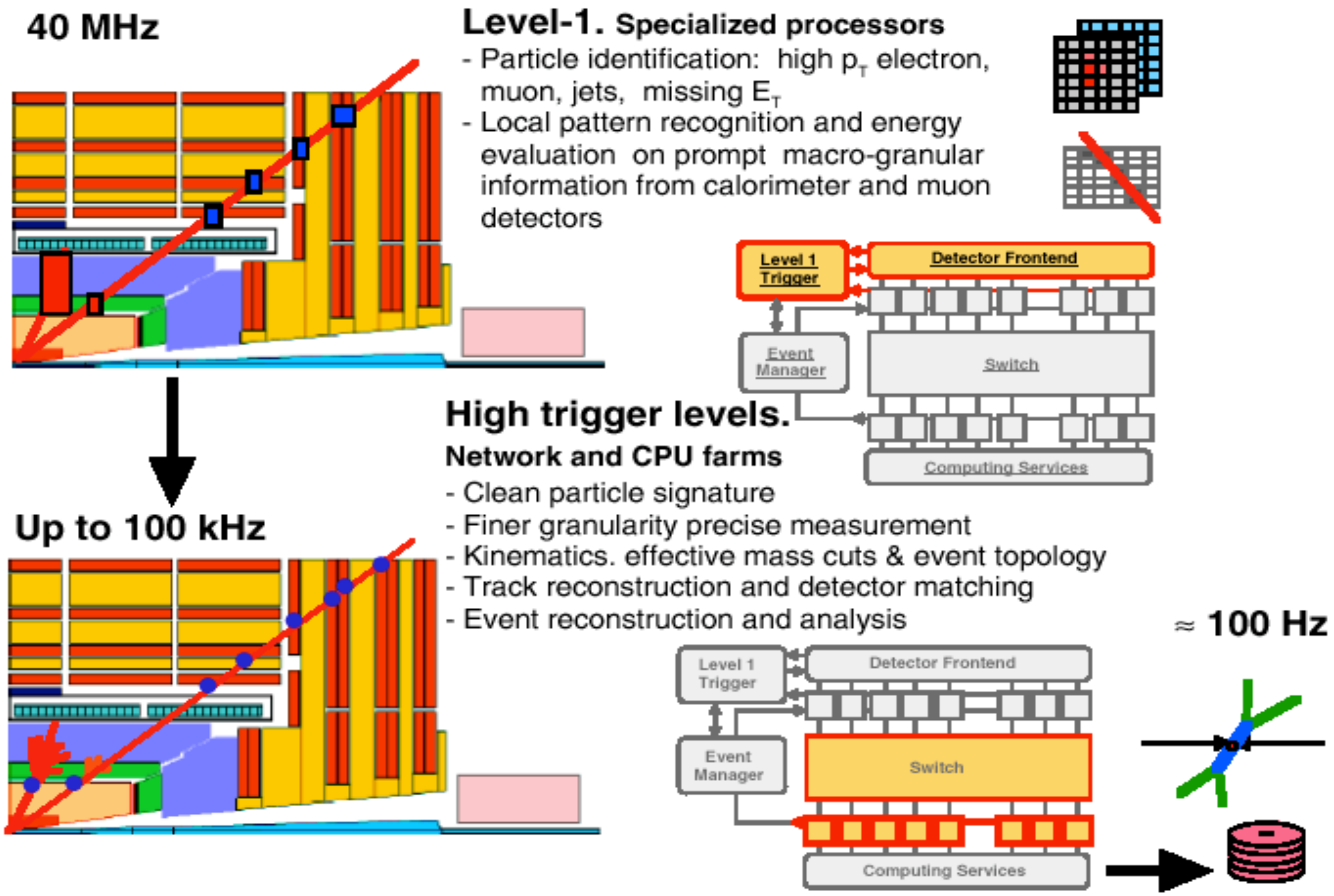
Extension of the actual pixel technology, low cost and triggering capability

- Radial region: 5cm<r<20cm :

$10^{15}cm^{-2} < \Phi < 10^{16}cm^{-2}$

New ideas, new materials.

New ideas for the future: tracking@L1



Level-1. Specialized processors
- Particle identification: high p_T electron, muon, jets, missing E_T
- Local pattern recognition and energy evaluation on prompt macro-granular information from calorimeter and muon detectors

High trigger levels.
Network and CPU farms
- Clean particle signature
- Finer granularity precise measurement
- Kinematics. effective mass cuts & event topology
- Track reconstruction and detector matching
- Event reconstruction and analysis

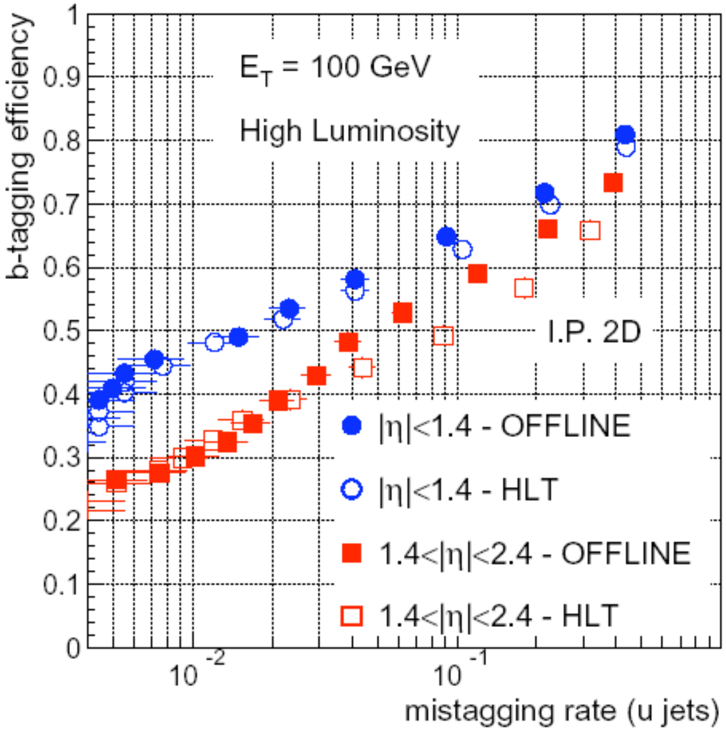
@L1 very high thresholds are needed: 250GeV for single jet, 110GeV for three jets; pt>20GeV/c for muons and E>34 GeV for electrons

What we have learnt from the HLT

Regional tracking: look for tracks only in a cone around a jet with a rough estimate of the primary vertex.

Conditional tracking: stop as soon as you have reconstructed a track with 5 hits

b-tagging vs mistagging rate at high luminosity



Impact parameter resolution and momentum resolution when stopping the track reconstruction after Nhits

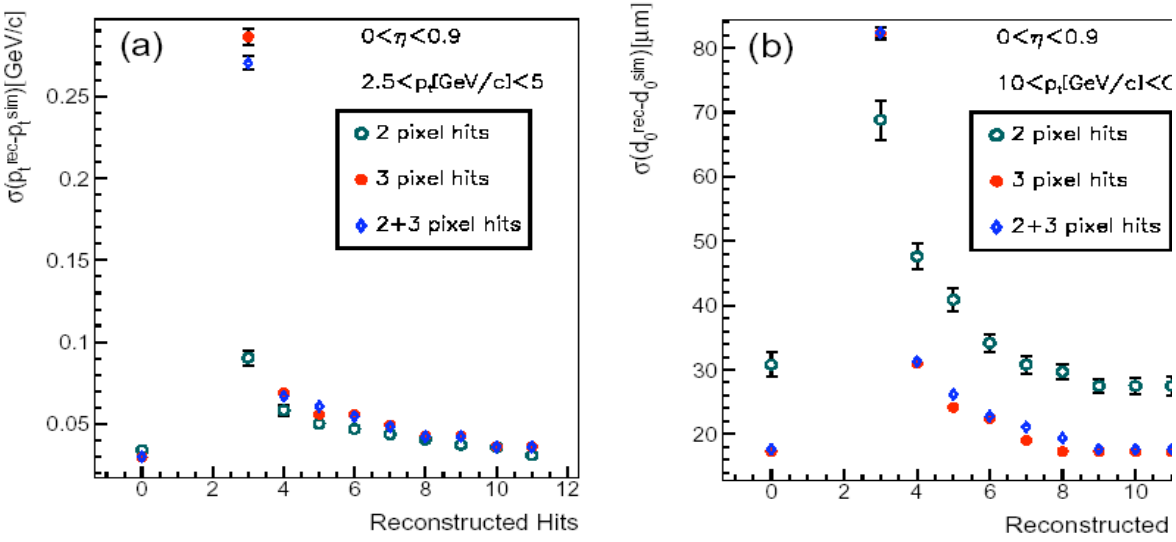
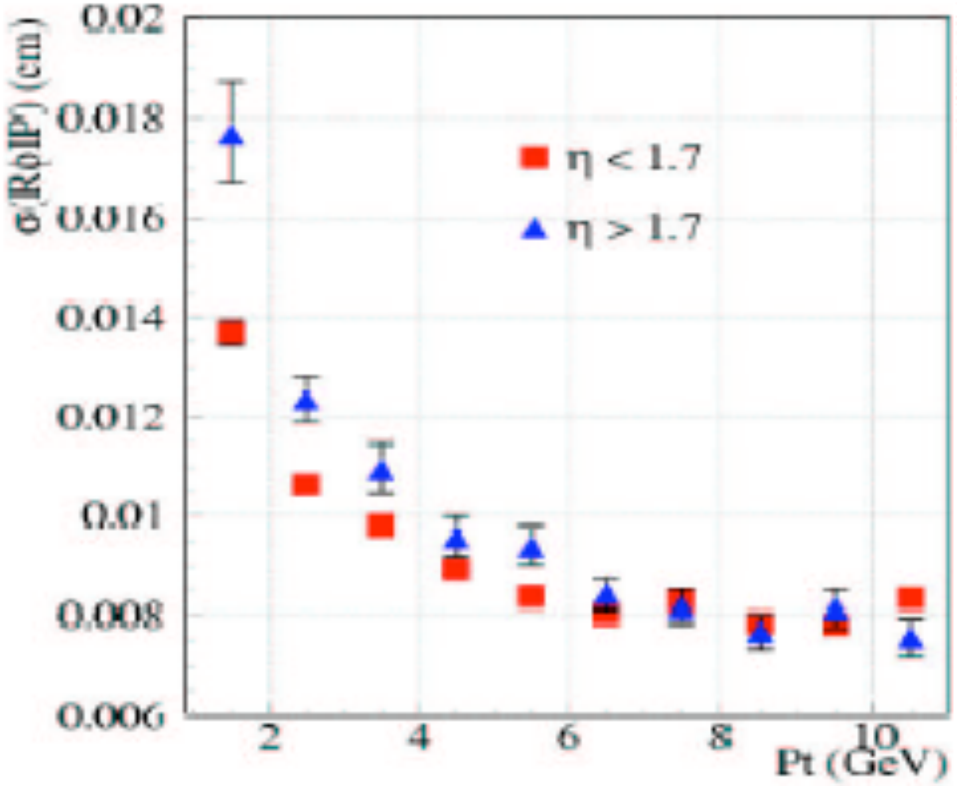
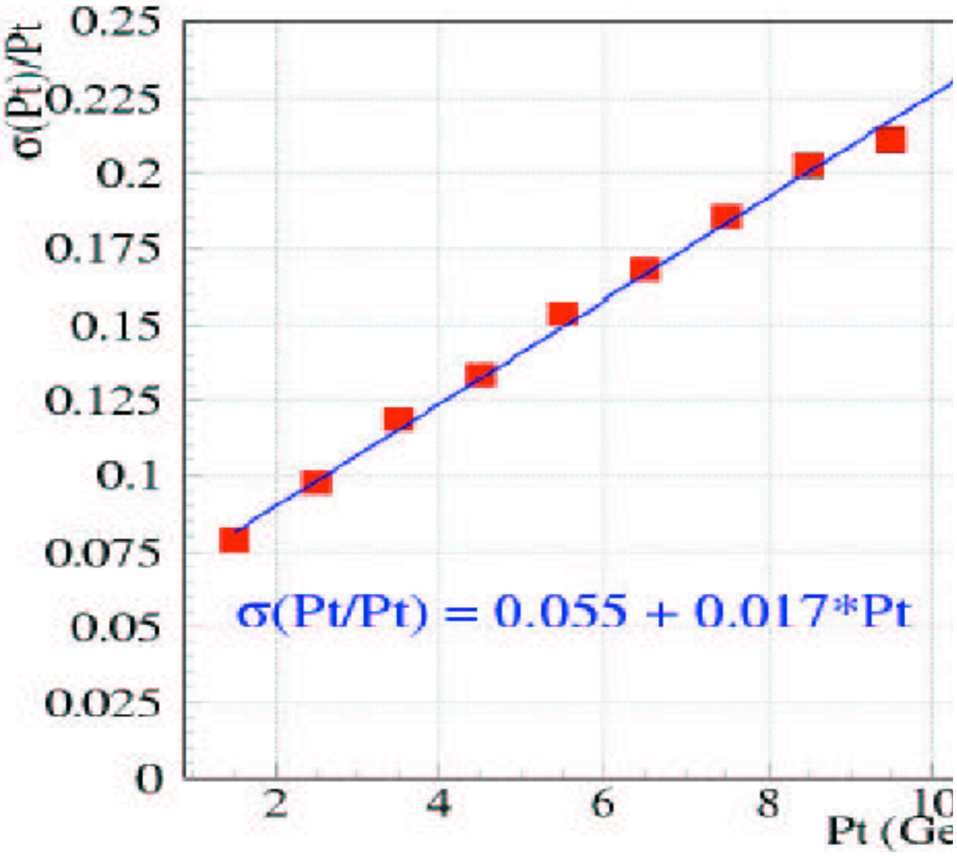


Figure 14-41 The resolution on a) P_T and b) impact parameter for partial track reconstruction, comp full track reconstruction, as a function of the number of smoothing steps in different P_T and for t region. The leftmost point at "0" reconstructed hits shows the full tracker performance.

Time needed so far 0.3-1 s

What can be achieved with 3 pixel points only





σ(high Pt) ~ 80 μm

With a dedicated read-out for the pixel detector (SUPER-LHC upgra
we plan to include the tracker in L1 trigger (a lot of physics potential
the new technique; improved S/N ratio in many difficult channels)

Conclusion

Join us!
We'll have a lot of fun !