

Normalized Background Tolerance Levels in ILC Tracking Detectors

- **Introduction: motivation & methodology**
- **Detector tolerance levels**
 - ① **naive detector model**
 - ① **pain-threshold estimates**
 - ⦿ **1% “generic”**
 - ⦿ **detector-specific (where available)**
- **Comparison with predicted pair-induced background levels**
- **Conclusions**

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Introduction

○ Motivation

- ① assess detector sensitivity to IR design changes (e.g. DID) on a scale ‘normalized’ to relevance
 - ⊙ **10 x a “very small” number may just be a “small” number, rather than a problem**
- ① compare the sensitivity of various detector concepts (or subdetector technologies) to background levels in a given IR configuration

○ Methodology

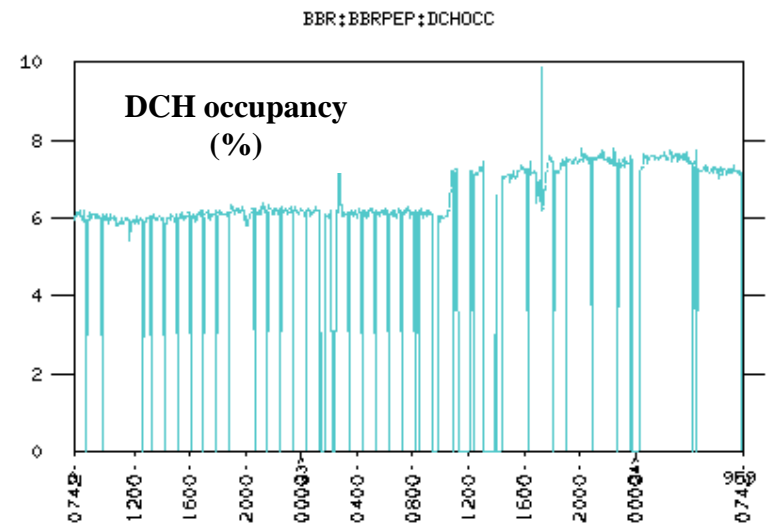
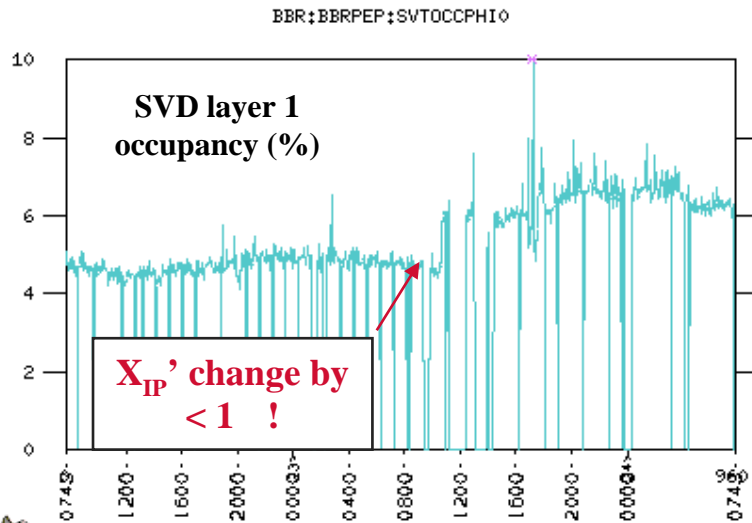
- ① define tolerance level, either
 - ⊙ in a generic fashion: 1% occupancy - allowing for a factor of ~ 10 contingency for surprises & unknown effects
 - ⊙ using estimates supplied by the Detector Concept Groups
- ① compare background levels predicted by simulation, to tolerance levels (‘pain thresholds’) in various subdetectors, in a consistent fashion
- ① so far limited to
 - ⊙ tracking detectors
 - ⊙ pair-induced backgrounds from ideal beams (no fluctuations)

Acknowledgements

- **Much of what follows draws heavily on**
 - ① **the hard work of the people who produced the plots shown today**
 - ① **Karsten's & Takashi's presentations last week: thanks!**

A naive detector-tolerance model

Subdetector	Tolerance criterion
Vertex detector and/or Silicon Tracker	Rad. damage (worst-case: CCD's) : $\int < 3\text{-}10 \times 10^9 \text{ n cm}^{-2}$ Occupancy (pattern recognition): $< 1\%$ (2-d hit density) Occupancy (pile-up): ≤ 1 hit / channel ("buffered")
Time Projection Chamber	Occupancy (pattern recognition): $< 1\%$ (3-d density) ? <i>Experts disagree on impact on reconstruction + space charge</i>



Detector-response model (*)

(*) As per R. Settles et. al., TESLA St Malo workshop. Checked with R. Settles & P. Colas @ Snowmass '05.

Subdetector	Granularity	Sensitivity window	Fract'l sensitivity
Vertex detector (Layer 1)	20 x 20 pixels = 2500 pixels/mm ²	50 s (~ 150 bunches)	Chgd trks: = 1.0 (4 pixels) : = 0.02 (4 pixels)
TPC	1.5 10 ⁶ pads x 10 ³ time buckets = 1.5 10 ⁹ voxels		Chgd trks: = 1.0 (3 p x 200 r x [5-10] tb) : = 0.02 (3 p x 200 tb) n: = 0.01 (3 p x 200 tb) : = 1.0 (6 p x 1000 tb)

“1% generic”

Background tolerance levels (*)

(*) As per R. Settles et. al., TESLA St Malo workshop
Detector-specific data from T. Maruyama + detector
response to MDI questions, Aug 05.

Limits are expressed in # particles either per sensitivity window [SW] (typically 50 μ s \approx 150 bunches in VXD/TPC), per bunch train [tr], or per bunch crossing [BX]

Subdetector	Charged hits		n (~ 1 MeV)	Model
Vtx detector (L1)	6 mm ⁻² / SW 100 mm ⁻² tr ⁻¹	300 mm ⁻² /SW	3 x 10 ⁷ mm ⁻² 10 ⁸ mm ⁻² (/y?)	1 % generic GLD
Si tracker	Pile-up: 0.2 / 1.0 mm ⁻² tr ⁻¹	Pile-up: 10/50 mm ⁻² tr ⁻¹		SiD: analog/digital
TPC (/SW)	1.5 x 10 ⁷ voxels \approx 2.5 - 5 10 ³ tracks	1.25 x 10 ⁶	2.5 x 10 ⁷ n	1 % generic

Notes

1. No generic answers – depend strongly on subdetector technology
2. Need to clarify impact of TPC occupancy on track reco efficiency & space charge
3. Only rough estimates so far. Real answer needs detailed simulations, pattern recognition studies, space charge, understanding of background distribution....
4. 1% may sound overconservative...but we need $\sim x 10$ safety factor!

Assumed Vertex-Detector Geometries

Concept	GLD	LDC	SiD
Radius (cm)	r1= 2.0	r1= 1.55	r1 = 1.40
Full length (cm)		L_z = 10.0	L_z = 12.5
Area (cm ²)	<i>Use GLD-provided normalization</i>	S = 97.4	S = 110

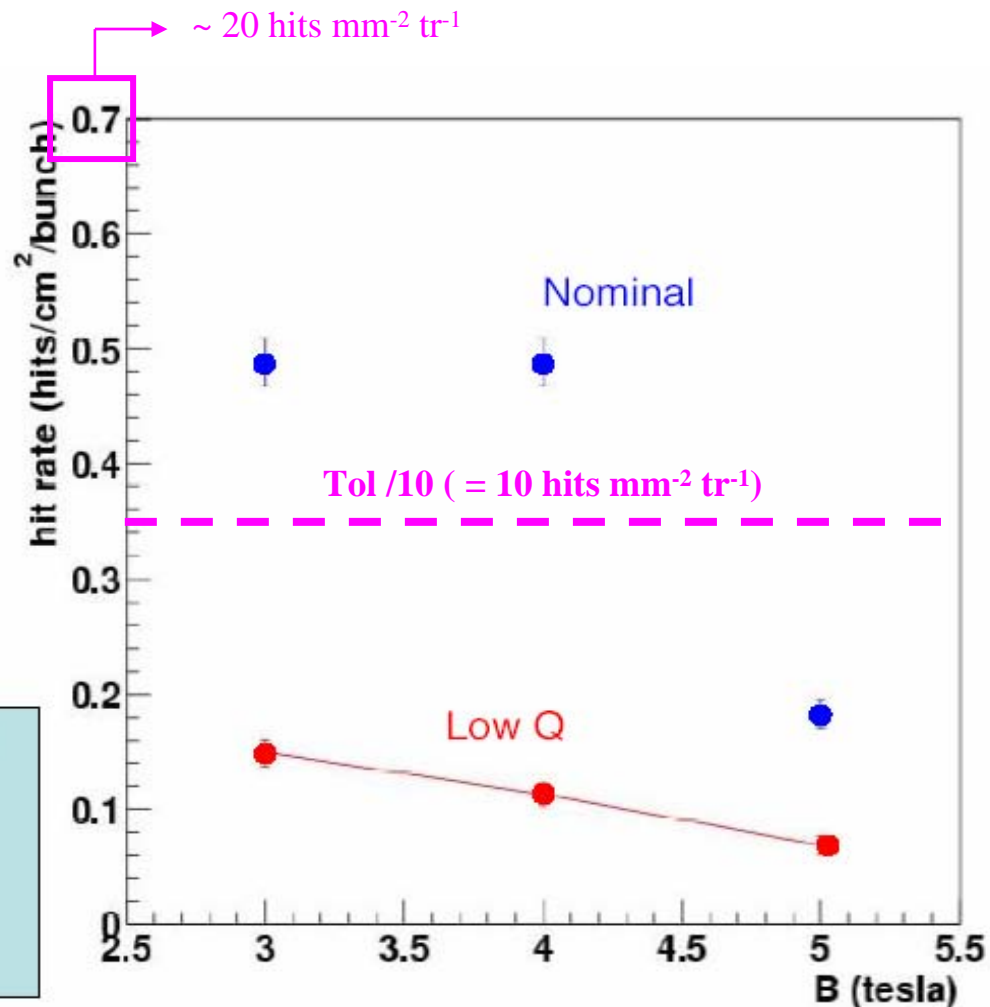
e⁺ - e⁻ Pairs

- Dominant background
- Very dependent on
 - ① Beam parameters
 - ① Solenoid field strength
 - ① Solenoid compensation (for 20 mrad)
 - ① VXD layer radius
 - ① Forward geometry

500 GeV	Beam	# e ⁺ /e ⁻ /BX	Total energy
	Nominal (N)	98 K	197 TeV
	Low Q (Q)	38	86
	High Y (Y)	104	191
	Low P (P)	232	709
	High Lum (H)	268	944
1 TeV	Nominal	174	1042
	Low Q	73	486
	High Y	229	1356
	Low P	458	4596
	High Lum	620	7367

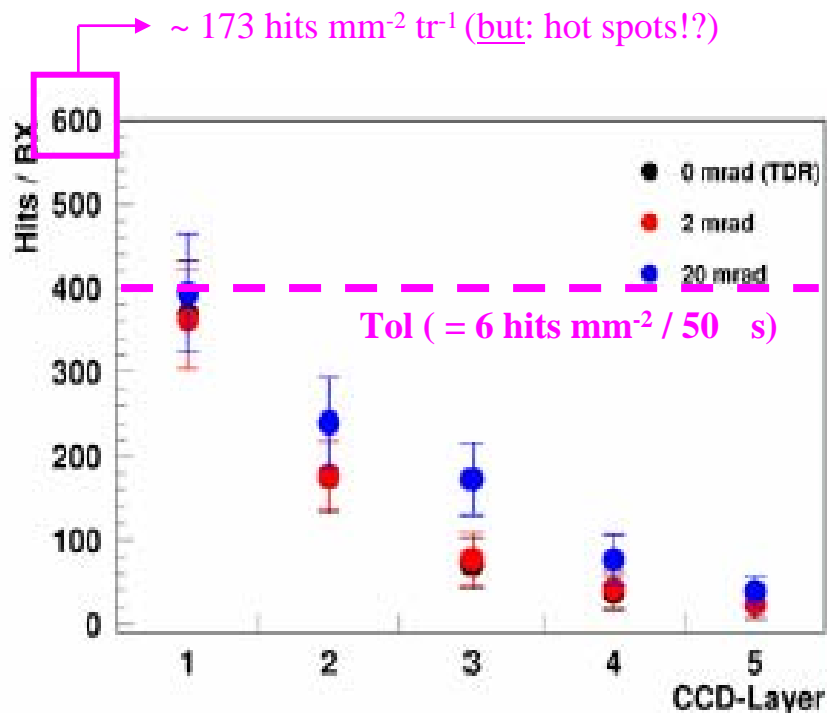
- Pair background hit rate on the 1st layer of the Vertex Detector (R=24mm)
- Simulation using CAIN and JUPITER
- Hit rate of the Low Q option is $\sim 1/3$ of the nominal option, as expected

Pair B.G. hit rate (/cm ² /bunch)		
B(tesla)	Nominal	LowQ
3	0.488	0.149
4	0.48	0.113
5	0.183	0.069



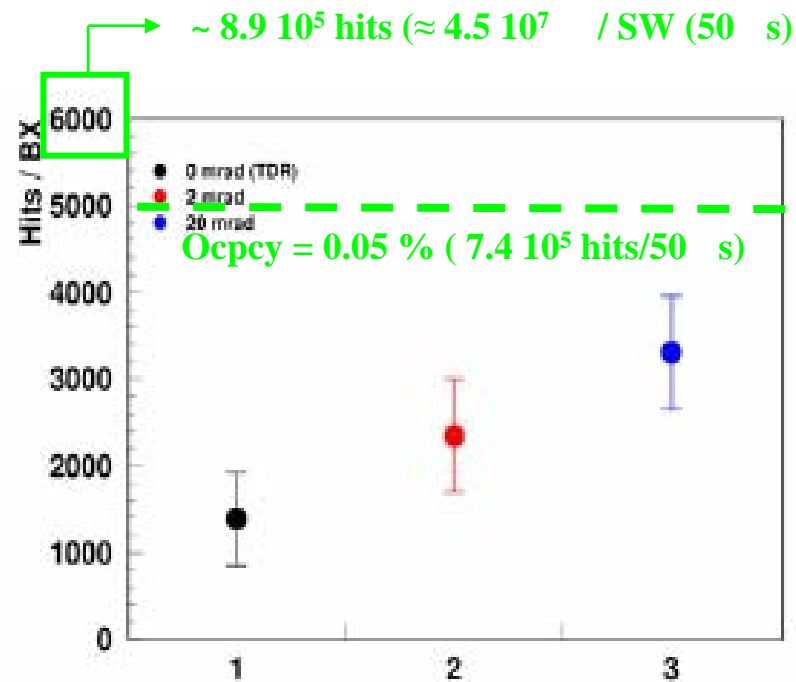
Crossing-angle dependence (LDC)

TESLA Beam parameters
VXD tolerance: 1% generic
TPC tolerance: tbd



○ VXD hits

- ① No difference between 0 mrad and 2 mrad
- ① x 1.5-2 higher background in 20 mrad

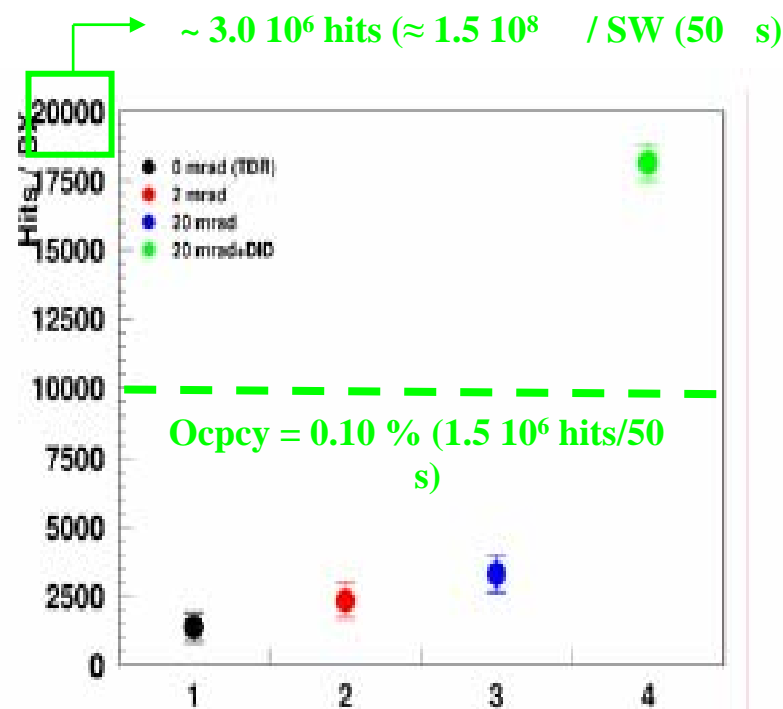
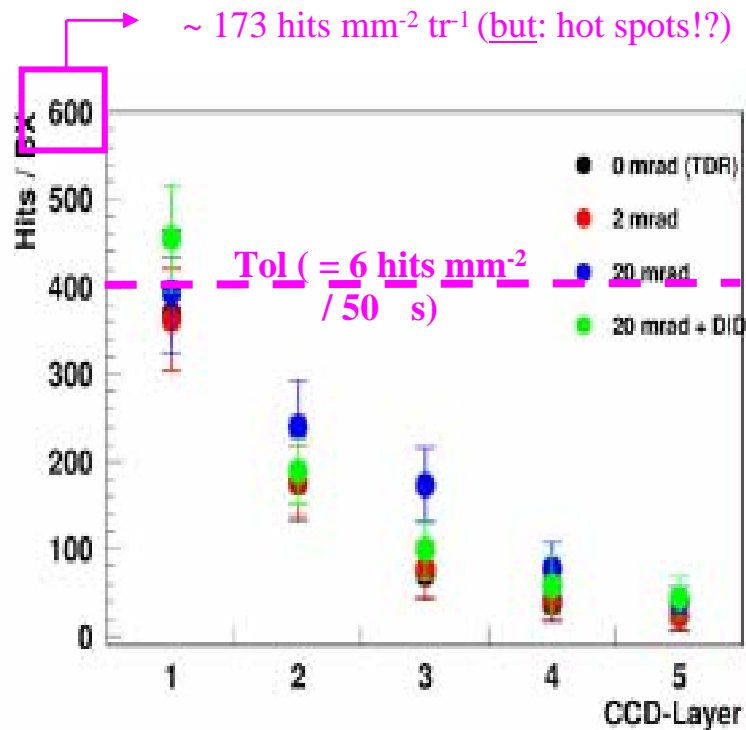


○ TPC hits: converted only (no *n*'s) from elm effects (pairs)

- ① Twice as much in 2 mrad than in 0 mrad
- ① Twice as much in 20 mrad than in 2 mrad
- ① *neutrons*: under study (gas, ECAL...)

DID effect on VXD & TPC hits (LDC)

TESLA Beam parameters
VXD tolerance: 1% generic
TPC tolerance: tbd



○ VXD hits

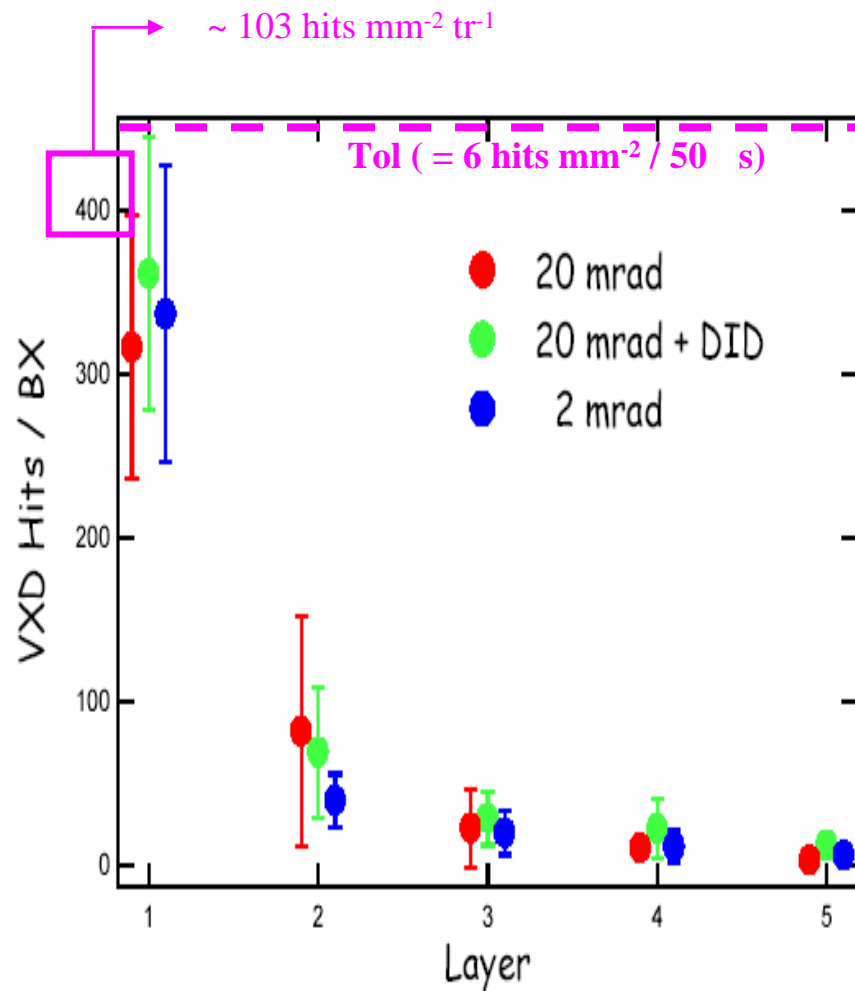
- ① DID field reduces VXD hits to 2 mrad level in all but layer 1

○ TPC hits: converted only (no *n*'s) from elm effects (pairs)

- ① Significantly more TPC hits - but still a factor of 5 below the 1% occupancy tolerance

Crossing-angle dependence (SiD)

ILC 500 nominal parameters
VXD tolerance: 1% generic

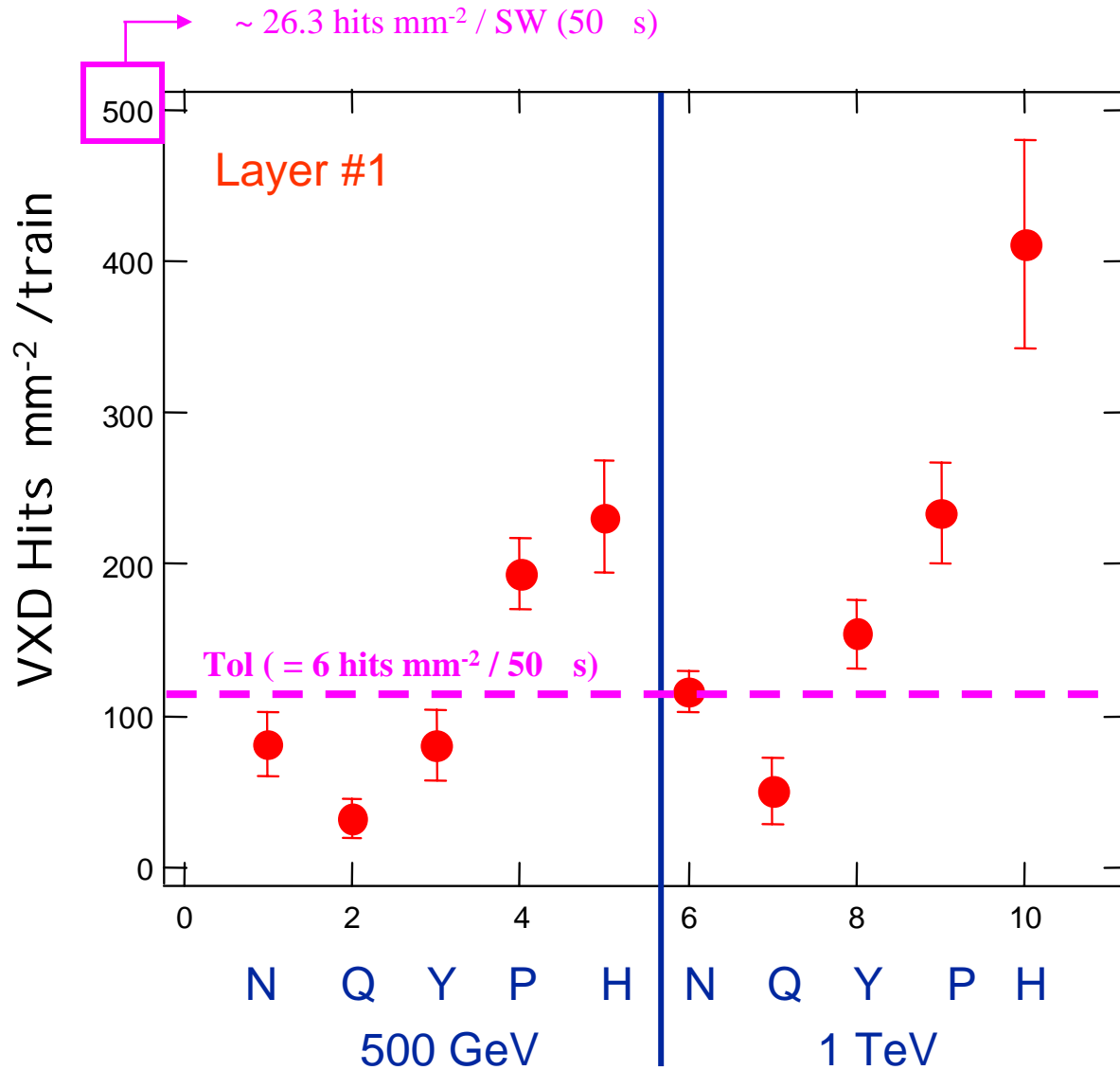


- Average and RMS from 20 BXs.
- 20 mrad and 20 mrad + DID will have more VXD hits than 2 mrad.
- But bunch-to-bunch fluctuation is larger than the crossing angle difference.

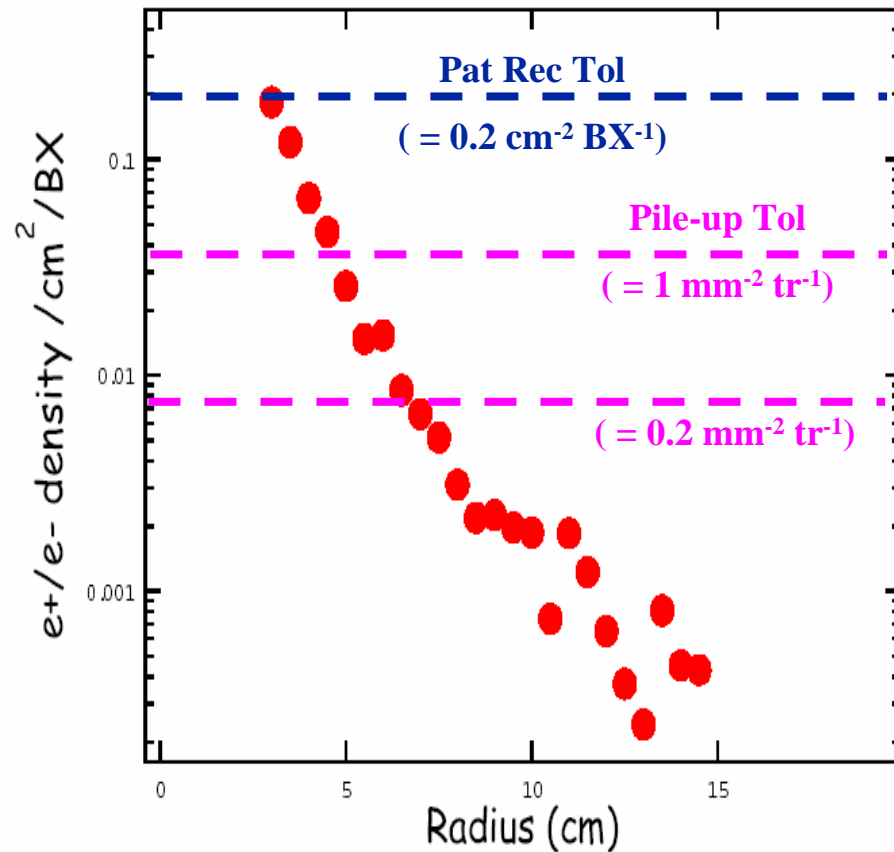
VXD hit density (SiD)

VXD tolerance: 1% generic

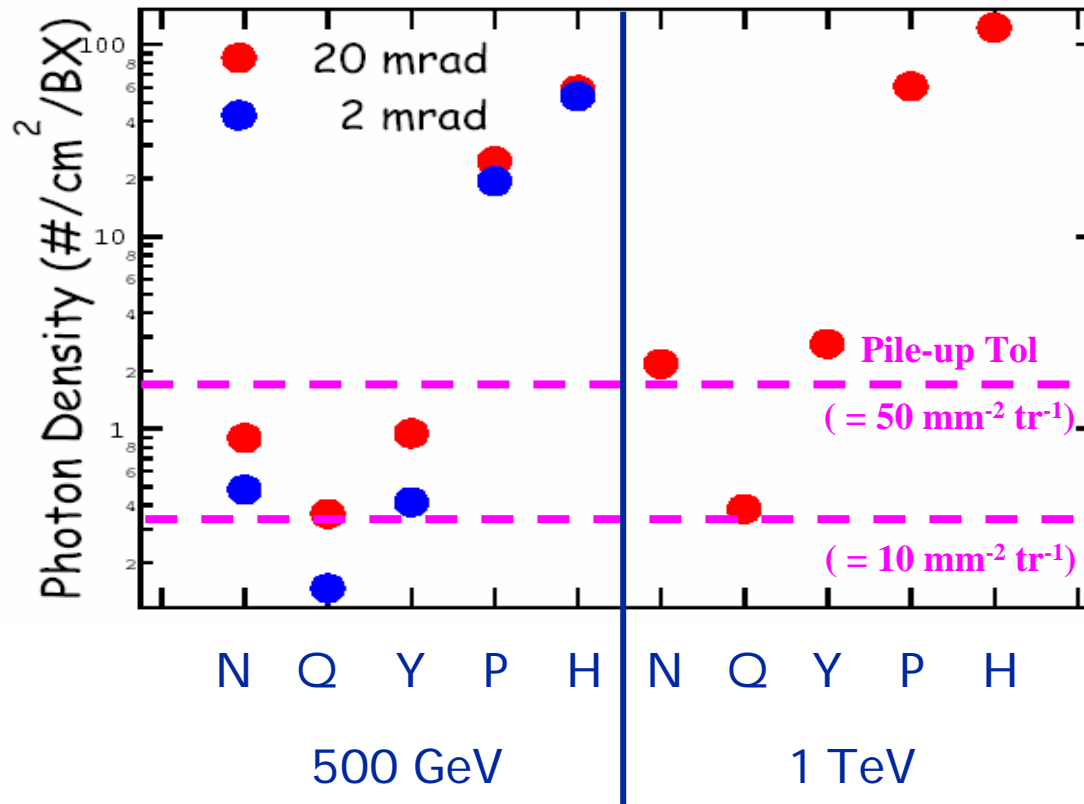
Pair background \sim Xing-angle independent (at least in set N)



Forward Tracker Layer #1 hits



- Steep radial dependence
- Innermost region is at the tolerance level for pattern recognition ($0.2 \text{ cm}^{-2} / \text{BX}$).



- Twice as many photons in 20 mrad than in 2 mrad
- More than the detector tolerance level for “Low Power” and “High Lum” options

Open issues

- **Tolerable TPC occupancy = ? (track reconstruction / space charge)**
- **Neutrons**
 - ① background impact very sensitive to actual spectrum (e.g. TPC gas, plastic in calorimeter,...). Should be studied in calorimeter also!
 - ① present simulations often statistics limited
 - ① neutrons worse @ 1 TeV c.m. by ~ 1 order of magnitude?
 - ① can extraction-line losses contribute significantly?
- **Synchrotron radiation**
 - ① can we design a “bounce-proof” SR masking layout?
 - ① back-scattering from apertures!
 - ① edge- & tip-scattering off masks!
- **Single-beam backgrounds: electromagnetic shower debris**
 - ① halo scraping in or near final doublet (coupled to SR/collimation depth)
 - ① beam-gas
- **Backgrounds in forward detectors?**
- **Hot spots & asymmetries (for all of the above): 1 o.o.m? Impact?**

Summary

- Proposed a **'standardized'** way to **compare**
 - ① background levels in a given detector, across IR designs
 - ① IR designs across detector concepts
- A **'1 % occupancy limit'** (per train or per SW), implying a **'x 10' safety factor** are probably adequate, at this stage & in most cases, for the vertex detector & Si tracker
- **Comparison** of predicted pair-background levels to (conservative!) detector tolerance levels (aver'gd over X-angle):
 - ① vertex detectors:
 - ⊙ LCD, SiD: layer 1 @ ~ occupancy tolerance (~ 1%)
 - ⊙ GLD: layer 1 @ 1 order of magnitude below tolerance
 - ⊙ all: high L/ low P parm sets significantly higher occ'pcy
 - ① Si tracker (SiD): Pat Rec OK, pile-up x 5-10 > tolerance (buffering)
 - ① TPC:
 - ⊙ predicted occupancy from e^+e^- pairs is at the level of 0.02% to 0.20% (DID)
 - ⊙ however, impact of such occupancies on (i) track reconstruction efficiency and (ii) space charge, remain to be understood
- Several important **open** issues: let's go beyond pairs & trackers!

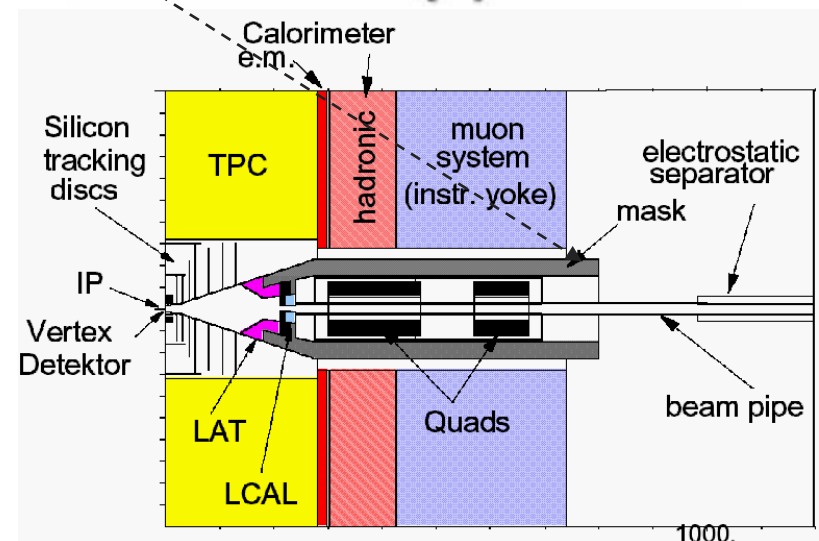
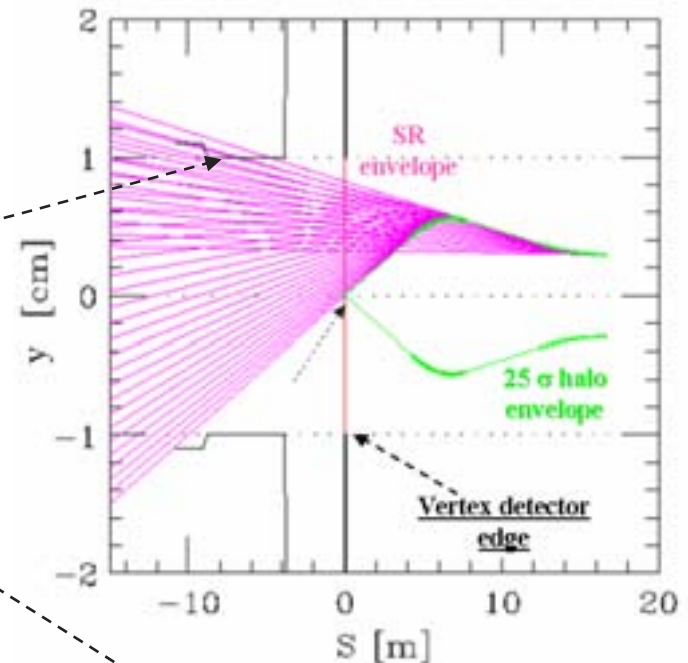
Spares

More on open issues & 'sanity checks' (I)

○ Synchrotron radiation

① Concerns

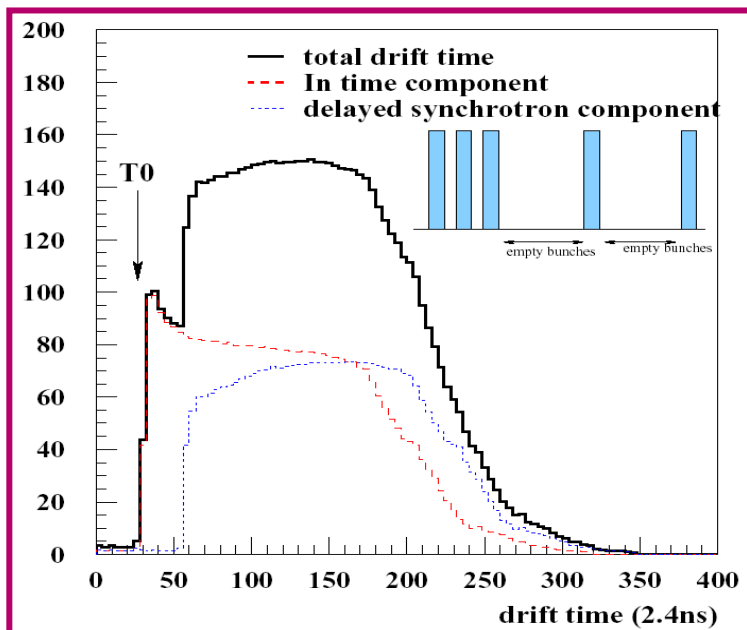
- ② backscattering from downstream aperture limitations
- ② edge- & tip- scattering from upstream SR masks
- ② impact of a partially-shared beam line on SR masking (2mr)?
 - compatibility of stay-clear apertures (spent beam, pairs, beamstrahlung) with effective masking of incoming SR
- ② any hidden alligators?
 - consistency checks between independent calculations important (e.g. TESLA TDR vs. A. Drozhdin's results)



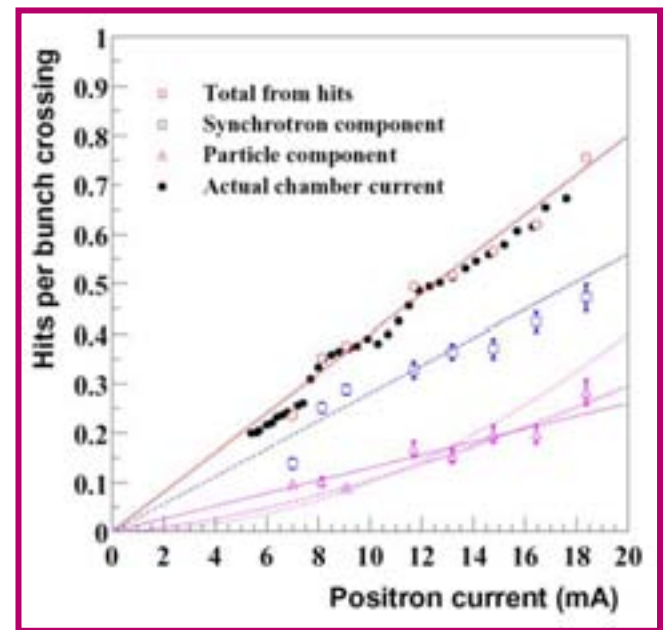
○ Synchrotron radiation *(continued)*

① Lessons from existing detectors

- BaBar design: SR background dominated by tip-scattering
- BELLE: ‘fried’ their first VDET by a combination of
 - improperly masked incoming-beam SR (very soft X-rays from XYCORs)
 - hard SR backscattered from the first beam-pipe wall on outgoing side
- Zeus + H1: SR – much of it backscattered – absorbs a large fraction of their ‘background budget’



Zeus
CTD



More on open issues & 'sanity checks' (II)

○ Muons

- ① Secondary e^\pm energy cutoff (> 50 GeV in A. Drozhdin's code in 2002) may be (have been ?) too high to realistically model 'harmful' production
- ① tunnel modelling (wrt transport): a huge job by itself....

○ Electromagnetic debris: production & transport

- ① Is the showering in 'thin' machine elements (vacuum pipe, magnets) modelled with enough realism to be sure we are not overlooking potential problems?
- ① High energy e^\pm losses 'near' the IP:
 - ⦿ what is reasonable tolerance level (TWM: 'a few ten per train'?)
 - ⦿ how near is 'near' ?

How far upstream of the IP do electromagnetic debris matter ?

Can showers produced by full-energy e^\pm 10-20 m from the IP on the incoming beam side cause substantial backgrounds, in view of ?

