AutomaticBoardDetector

processMap does:
1. set the map TC Type
2. call fillMap
3. set the links in the map

Who decides what the value of WhoDecidesForTheLinks should be?
A configuration parameter?
Some hardcoded algorithm like if (IR2 and production) then MAP decides?
Decided at boot time when the Fsm is created?

Should the setters be private and BaseMapFiller a friend class?

fire does:
1. call _mapFiller->processMap(....)
2. call fireSpecific(....)
3. set the links using map() and an odfLinks object.

ConcreteMap

For example for old TSF fpgaToEngine()
the same

ConcreteConfigure

-L1Accept(ConcreteMap*)
+fire(dg:odfTransition*,fsm:odfFsm*): odfDatagram*

ConcreteMap

-For Example for old TSF fpgaToEngine()