## Latest analysis with the new Ivan's constants:

## New epsilons from the variable lambda MC simulation:


// However, to do the cross-talk \& charge sharing right, we need individual corrections for each pad.
// The following offsets were determined after Jose's calibration to determine TOP_measured, and
// using TOP_expected from Ivan's MC with a variable lambda analysis, and requiring dTOP $=0$. This determines timing
// epsilon offsets. In the rest of the analysis, I assume that these epsilons are due to the calibration errors
// and assign them to TOP_measured. This is very important !!!!!
// The 2-nd tweak (in brackets) made it more precise (probably due to a change in the cross-talk alghoritm); the 3-rd tweak is from 3.20.2006, // when Ivan improved numbers after many changes in his program, including tweaking the geometry of mirror,etc.
$/ / * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * * *$
// Example of slot 2:

> time_offset_slot2_phillips_peak_1[7] $=-0.3864+(-0.061)-0.056 ;$
> time_offset_slot2_phillips_peak_1[8] $=-0.3894+(-0.009)-0.057 ;$
> time_offset_slot2_phillips_peak_1[9] $=-0.4975+(-0.0559)-0.040 ;$
> time_offset_slot2_phillips_peak_1[10] $=-0.3476+(-0.081)-0.032 ;$
> time_offset_slot2_phillips_peak_1[23] $=-0.4696+(-0.0992)-0.041 ;$
> time_offset_slot2_phillips_peak_1[24] $=-0.3291+(-0.051)-0.052 ;$
> time_offset_slot2_phillips_peak_1[25] $=-0.5517+(-0.0739)-0.048 ;$
> time_offset_slot2_phillips_peak_1[26] $=-0.494+(-0.074)-0.050 ;$
> time_offset_slot2_phillips_peak_1[40] $=-0.323+(-0.061)-0.054 ;$
> time_offset_slot2_phillips_peak_1[41] $=-0.402+(-0.0765)-0.058 ;$
> time_offset_slot2_phillips_peak_1[55] $=-0.2467+(-0.0961)-0.047 ;$
> time_offset_slot2_phillips_peak_1[57] $=-0.2295+(-0.121)-0.059 ;$
> time_offset_slot2_phillips_peak_1[58] $=-0.2272+(-0.0847)-0.074 ;$
time_offset_slot2_phillips_peak_2[7] = -0.9717+(-0.091)-0.052;
time_offset_slot2_phillips_peak_2[8] $=-0.0607+(-0.0439)-0.016$;
time_offset_slot2_phillips_peak_2[9] = $-1.389+(-0.0588)+0.059$;
time_offset_slot2_phillips_peak_2[10] $=-0.3546+(-0.04295)-0.029$;
time_offset_slot2_phillips_peak_2[23] = -1.083+(-0.0208)+0.035;
time_offset_slot2_phillips_peak_2[24] $=0.0638+(-0.0427)-0.008$;
time_offset_slot2_phillips_peak_2[25] = -1.389+(0.0179)+0.018;
time_offset_slot2_phillips_peak_2[26] $=-0.3525+(-0.0477)+0.064$;
time_offset_slot2_phillips_peak_2[40] $=0.29+(-0.1676)-0.083$;
time_offset_slot2_phillips_peak_2[41] $=-1.04+(-0.0147)-0.025$;
time_offset_slot2_phillips_peak_2[55] $=-0.579+(0.0392)-0.121$;
time_offset_slot2_phillips_peak_2[57] $=-0.8223+(0.0108)-0.015$;
time_offset_slot2_phillips_peak_2[58] $=-0.1027+(-0.005)-0.063$;
Examples of (TOP_measured-TOP_expected) after the latest tweak (position 1, run 12b):

Slot 2:


## chanart








Bentorater



Slot 4:






Slot 5:










Encrowna



```
// Additional global slot offsets (!?!?); found necessary to add this after the previous step was finished.
// Not completely clear why I need it. Perhaps, individual fits were not precise enough.
//
    for (Int_t i=1; i<65;i++)
{
    time_offset_slot2_phillips_peak_1[i] = time_offset_slot2_phillips_peak_1[i]-0.112;
    time_offset_slot3_phillips_peak_1[i] = time_offset_slot3_phillips_peak_1[i]-0.043;
    time_offset_slot4_phillips_peak_1[i] = time_offset_slot4_phillips_peak_1[i]-0.042;
    time_offset_slot5_phillips_peak_1[i] = time_offset_slot5_phillips_peak_1[i]-0.007;
    time_offset_slot6_phillips_peak_1[i] = time_offset_slot6_phillips_peak_1[i]-0.130;
    time_offset_slot2_phillips_peak_2[i] = time_offset_slot2_phillips_peak_2[i]-0.164;
    time_offset_slot3_phillips_peak_2[i] = time_offset_slot3_phillips_peak_2[i]-0.112;
    time_offset_slot4_phillips_peak_2[i] = time_offset_slot4_phillips_peak_2[i]-0.029;
    time_offset_slot5_phillips_peak_2[i] = time_offset_slot5_phillips_peak_2[i]-0.124;
    time_offset_slot6_phillips_peak_2[i] = time_offset_slot6_phillips_peak_2[i]-0.441;
}
```

Result of the variable lambda analysis after all corrections done (position 1, run 12b):


## Slot 3, all pads, 1-st peak



Slot 3, all pads, 2-nd peak



## Slot 6, all pads, 2-nd peak



Slot 4, all pads, 1 -st peak




## Chromatic correction using a theoretical correlation between $d \Theta_{\mathrm{C}}$ and dTOP/Lpath, based on my spreadsheet:

## Expected chromatic correction



# Apply the spreadsheet correction to data (position 1, run 12b): 



- Apply the correction to the 2-nd peak only.
- The corrected resolution is better.

The empirical correction from data (peak 2 only):





## Apply the empirical correction to data:



- Apply the same correction to both peaks.
- The correction works only for the 2-nd peak, as one wopuld expect.


## Latest analysis as a function of position:

- Fit the projections with a single Gaussian fctn.

1a) Correlation between Cherenkov angle from pixels and TOP - peak 1:

## Position 1:




Position 3:


Position 5:




1b) Correlation between Cherenkov angle from pixels and TOP - peak 2:

Position 1:


Position 3:



Position 5:




2a) Peak 1 using pixels (uncorrected \& corrected with TOP/Lpath):

- The uncorrected spectra fitted with a single Gaussian fctn.


## Position 1:



Position 3:



Cherenkov angle (pixels), chrom atic corr, from TOP/Lpath
Project to $X$


## Position 5:




2b) Peak 2 using pixels (uncorrected \& corrected with TOP/Lpath):

- The uncorrected spectra fitted with a single Gaussian fctn.


## Position 1:

Prosectiox



Position 3:



## Position 5:




- When two Gaussians are involved, quote a weighted average of two sigmas

3a) Peak 1 using TOP (uncorrected \& corrected with pixels):

- The uncorrected spectra fitted with a single Gaussian fctn.


## Position 1:




Position 3:


Cherenkov angle (TOP/LPath), chromatic corr. trom pixelis


Position 5:



3b) Peak 2 using TOP (uncorrected \& corrected with pixels):

- The uncorrected spectra fitted with a single Gaussian fctn.


## Position 1:

Project to $Y$


## Position 3:



## Position 5:

Propectior





- When two Gaussians are involved, quote a weighted average of two sigmas


Comparison with Jose:


Suggestion for the SNIC conference:
Cherenkov angle resolution $=\mathbf{f}(\mathbf{L}$ _path $)$


| Direct |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Position along the bar | Run | Ave. photon <br> L_path <br> [m] | $\left\|\begin{array}{l} \text { Error } \\ {[\mathrm{m}]} \end{array}\right\|$ | Ch. ang. resol. pixels - simply project <br> [mrad] | Ch. ang. resol. TOP/L_path - simply project [mrad] | Ch. ang. resol. pixels - correct with TOP/L_path [mrad] | Ch. ang. resol. TOP/L_path - correct with pixels [mraD] |
|  | 12b | 0.85 | 0.04 | 14.42059337 | 13.21989529 | 14.59336824 | 11.77159423 |
| 2 |  |  |  |  |  |  |  |
| 3 | 13 | 2.3 | 0.1 | 15.45375218 | 8.422338569 | 13.17321125 | 7.133237638 |
| 4 |  |  |  |  |  |  |  |
| 5 | 14 | 3.77 | 0.17 | 14.62303665 | 5.980802792 | 13.14705281 | 6.359511344 |
| 6 |  |  |  |  |  |  |  |


| Backward |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Position along the bar | Run | Ave. photon L_path in bar [m] | $\left\|\begin{array}{l} \text { Error } \\ {[\mathrm{m}]} \end{array}\right\|$ | Ch. ang. resol. pixels - simply project [mrad] | Ch. ang. resol. TOP/L_path - simply project [mrad] | Ch. ang. resol. pixels - correct with TOP/L_path [mrad] | Ch. ang. resol. TOP/L_path - correct with pixels [mrad] |  |  |  |
|  | 12b | 9.7 | 0.46 | 14.31588133 | 7.02617801 | 11.85992646 | 5.92495637 |  |  |  |
| 2 |  |  |  |  |  |  |  |  |  |  |
| 3 | 13 | 8.2 | 0.38 | 14.41710297 | 6.989528796 | 12.07394315 | 5.497109264 |  |  |  |
| 4 |  |  |  |  |  |  |  |  |  |  |
| 5 | 14 | 6.78 | 0.31 | 15.08376963 | 6.656195462 | 12.54827221 | 5.759162304 |  |  |  |
| 6 |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  | Both |  |  |  | nitez |  |
|  |  | $\begin{aligned} & \text { Ave. photon } \\ & \text { L_path } \\ & {[\mathrm{m}]} \end{aligned}$ | $\left\|\begin{array}{l} \text { Error } \\ {[\mathrm{m}]} \end{array}\right\|$ | Ch. ang. resol. pixels - simply project [mrad] | Ch. ang. resol. TOP/L_path - simply project [mrad] | Ch. ang. resol. pixels - correct with TOP/L_path [mrad] | Ch. ang. resol. TOP/L_path - correct with pixels [mraD] | Ch. ang. resol pixels - simply project [mrad] | Ch. ang. resol. TOP/L_path - simply project [mrad] | Ch. ang. resol. pixels - correct with TOP/L_path [mrad] |
|  |  | 0.85 | 0.04 | 14.42059337 | 13.21989529 | 14.59336824 | 11.77159423 | 12.42 | 8.535 | 14.56 |
|  |  | 2.3 | 0.1 | 15.45375218 | 8.422338569 | 13.17321125 | 7.133237638 | 12.81 | 7.137 | 12.1 |
|  |  | 3.77 | 0.17 | 14.62303665 | 5.980802792 | 13.14705281 | 6.359511344 | 13.69 | 7.068 | 11.64 |
|  |  | 6.78 | 0.31 | 14.31588133 | 7.02617801 | 11.85992646 | 5.92495637 | 15.41 | 5.828 | 11.52 |
|  |  | 8.2 | 0.38 | 14.41710297 | 6.989528796 | 12.07394315 | 5.497109264 | 15.41 | 5.656 | 11.35 |
|  |  | 9.7 | 0.46 | 15.08376963 | 6.656195462 | 12.54827221 | 5.759162304 | 15.88 | 5.572 | 11.46 |

