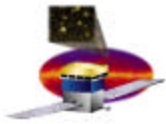


# Command Control And Configuration

**16 August 2001**

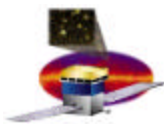
**Stanford Linear Accelerator Center  
Stanford CA**



# Command Reception

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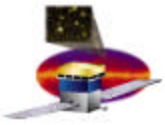
- The LAT receives commands on a MIL-STD-1553 bus
- Flight software is responsible for
  - Removing any jacketing protocol
  - Performing validity checks on the raw packets
    - CRC or parity (TBD)
  - Classifying the command by type (next slide)



# Command Types

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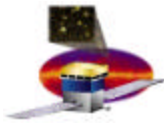
- **Commands Belong To One Of Two Types**
  - **Real Time Commands**
    - Validated commands of this type execute immediately
    - Flight software keeps statistics of:
      - Commands received
      - Commands accepted
      - Commands executed locally
      - Commands forwarded for execution on another processor
  - **Block Commands Comprising:**
    - Executable code uploads
    - Table/parameter uploads
    - Command list uploads
- **Command Type Is Distinguished By 1553 Subaddress**



# Block Commands

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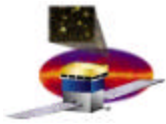
- **Typically Spread Over Multiple Packets**
  - Packets must include a packet protocol
  - Appears naturally in the CCSDS protocol
- **Packet Size**
  - **Packet Size Is A Compromise Between**
    - Large packet transmission efficiency
    - Large packet error recovery (retransmission) inefficiency
  - Packets are likely to be in the range 1-2 kByte
- **Interleaving Block Commands**
  - All block transmissions are not created equal
    - More important to upload a command list than a piece of code
  - FSW will accept multiple block transmissions interleaved
    - Protocol must contain sufficient information to distinguish different blocks



# Command Lists

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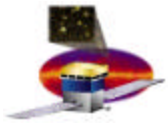
- **Command List Is Example Of A Block Command**
- **Command Lists Determine Time Ordered LAT Activity**
  - **Each command is time tagged to a precision of one second**
  - **Command execution is scheduled with an accuracy of 10 msec**
  - **Flight software will store up to (TBD) such commands**
    - **Not yet determined, but commensurate with storing up to 48 hours of commands so that a missed uplink does not interrupt LAT operations**



# Control

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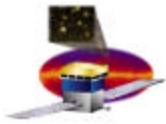
- **The Spacecraft Interface Unit (SIU) provides LAT control**
- **SIU Receives And Implements Commands From**
  - **Real time commands**
  - **Command lists**
- **SIU Controls Power Distribution (Except It's Own Power)**
  - **By command protocol to the power distribution box, to control and monitor power to TEMs, AEM, GLT, EPU**
  - **By command protocol to TEMs and AEM to control and monitor power to the front end electronics**
- **SIU Controls LAT Configuration**
  - **By command protocol to TEMs, AEM, GLT and front end electronics**
  - **By CPU to CPU communications with EPU**



# Configuration

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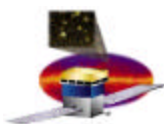
- **A Configuration Completely Describes The State Of The LAT**
- **Configurations Have Many Uses**
  - **To meet scientific objectives**
    - Change LAT properties during a transient
  - **To protect LAT health**
    - Shut down ACD HV while transiting the SAA
  - **To circumvent component failure**
    - Take a noisy tracker strip out of the trigger
  - **To control redundancy paths**
    - Use global trigger box B instead of global trigger box A



# Configuration Management

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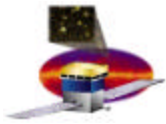
- **Configurations Are Managed By The SIU**
- **The SIU Must Communicate Configurations Across Three Interfaces**
  - **To and from the ground**
    - Uplink new configurations (source from 1553)
    - Downlink configurations used (sink to SSR)
  - **To and from non volatile storage (EEPROM)**
    - Save static configurations arriving from the ground
    - Use static configurations to set up the LAT
  - **To and from the DAQ (using DAQ serial protocol)**
    - Set up requested configurations in hardware
    - Read back the current hardware configuration



## Configuration Arithmetic (1)

- A Configuration Is A Large Volume Of Information

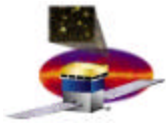
| Subsystem          | Element   | Bytes/<br>Element | # Elements                                     | Total<br>(bytes) |
|--------------------|-----------|-------------------|--|------------------|
| ACD                | GAFE      | 4                 | 6 (boards) * 2 (redundancy)<br>* 18 (channels) | 864              |
|                    | GARC      | 14                | 6 (boards) * 2 (redundancy)                    | 168              |
| CAL                | GCFE      | 5                 | 16 (towers) * 192 (logs ends)                  | 15360            |
|                    | GCRC      | 8                 | 16 (towers) * 16 (GTRC/tower)                  | 2048             |
| TKR                | GTFE      | 26                | 16 (towers) * 36 (layers)<br>* 24 (GTFE/layer) | 359424           |
|                    | GTRC      | 2                 | 16 (towers) * 36 (layers)                      | 1152             |
| TEM                | Registers | 2                 | 16 (towers) * 44 (registers)                   | 1408             |
| AEM                | Registers | 2                 | 1 * 20 (registers)                             | 40               |
| GLT                | Registers | 2                 | 8 (triggers) * 6 (registers)                   | 96               |
|                    |           |                   |  |                  |
| <b>Grand Total</b> |           |                   |  | <b>380560</b>    |



## Configuration Arithmetic (2)

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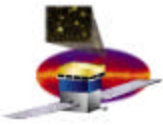
- **Simple, Absolute Configuration Descriptions Are Not Viable**
  - Require large amounts of memory
  - Difficult to upload/download
- **More Compact Notation Needed**
  - **Variation from standard**
    - Assume standard configuration is to enable all strips into the trigger, then only need to keep a list of those strips which should be removed from the trigger
    - Very compact
    - Somewhat ad hoc
  - **Result of command set**
    - Define configuration as position reached as a result of executing a list of commands
    - Comparable to the method that must actually be used to establish the configuration
    - Not quite as compact (but not so bad if meta-commands and broadcasts can be used)



# Operational Uses Of Configurations

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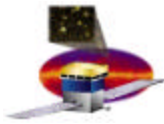
- **Can Be Divided Into Two Major Categories**
  - **Diagnostic/Calibration Running**
    - Diagnostic configurations difficult to predict
    - Calibration frequently rotates through a list of configurations
    - Neither is a good candidate for static configurations (however compact)
    - Both require programmatic interface to configuration utilities
  - **Physics Running**
    - Physics running requires stable configuration for the duration of an observation/run
    - Good candidate for (compact) static configurations
    - Configurations can be made and tested before launch...
      - ... but don't expect them to remain static over the course of the mission



# Spontaneous Loss Of Configuration

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- **Configuration During Physics Running Should Remain Constant**
  - Load configuration at start of run
  - Read back configuration to confirm it
  - Record configuration for each run
  - Read back the configuration at end run to confirm no change
- **But This Is Not A Perfect World**
  - A tracker strip might go noisy during a run
  - An event processing unit may take an SEU exception
- **SIU Reaction To Loss Of Configuration (In Priority Order)**
  - **Protect the LAT**
    - If a current is far outside tolerance, switch component off
  - **Protect the physics data**
    - Bring run to a controlled halt
  - **Try to continue the mission plan**
    - SIU may be able to reboot an EPU that took an exception



## Autonomous Update Of Configurations

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- **Uplink And Downlink Bandwidth Is A Precious Commodity**
  - Prefer to use it for physics data, not calibration/diagnosis
- **Some Calibration/Diagnosis Better Done In Situ. Example:**
  - Enable all TKR strips into data
  - Trigger LAT ~100k times
  - Build and save map of dead and noisy strips
  - Use maps as part of physics acquisition configuration
- **Advantages**
  - Little or no impact on downlink bandwidth (report results of diagnostic, not each event that went into it)
  - Little or no impact on uplink bandwidth (no need to uplink the results of a ground analysis)
  - Little or no impact on observation time (~100k events can be captured in ~10 seconds)