

# **Marlin et al**

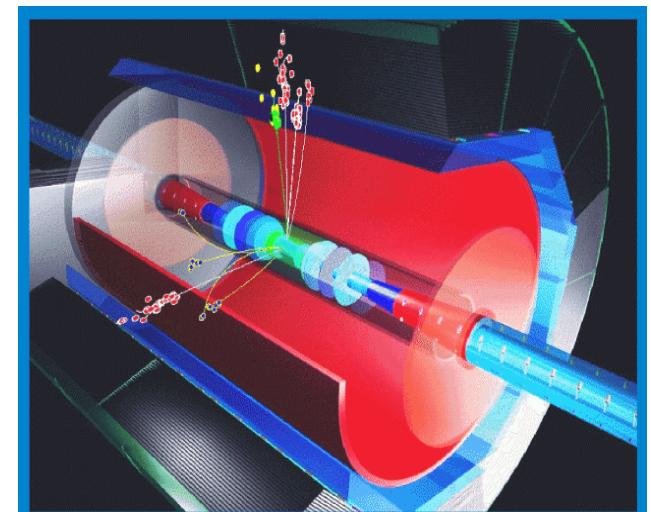
## **Introduction to ILC-LDC Simulation and Reconstruction Software**

Frank Gaede  
DESY

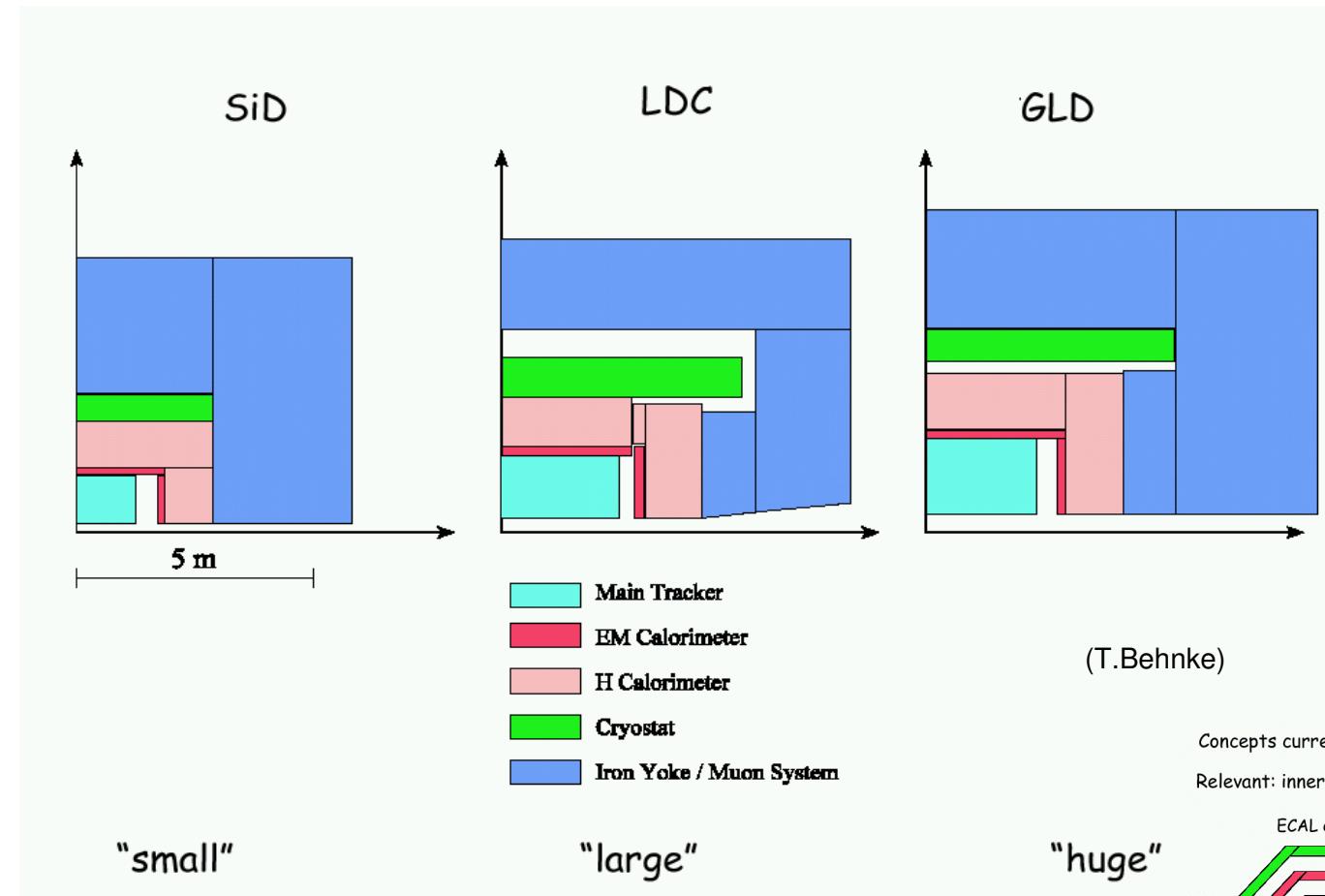
ILC Detector and Physics  
Workshop, Snowmass  
August 14-27, 2005

# Outline

- Introduction - overview international software
- Central tools for LDC study
  - **LCIO** – data model & persistency
  - **Simdet** – fast simulation
  - **Brahms** – geant3 full simulation and reconstruction
  - **Mokka** – geant4 full simulation
  - **Marlin** – C++ reconstruction framework
  - **LCCD** - conditions data toolkit
  - **GEAR** – geometry description
- Summary & Outlook



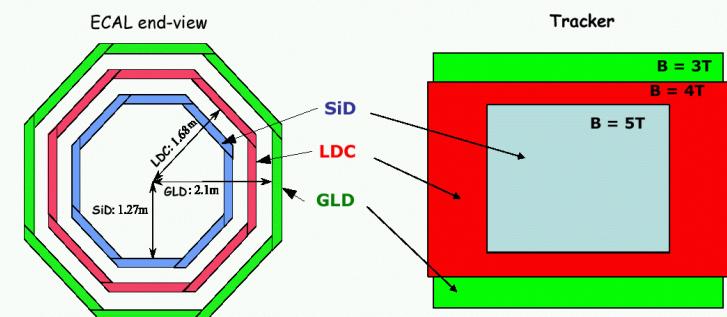
# Detector Concept Study



three **interregional**  
detector concept  
studies ongoing

Concepts currently studied differ mainly in **SIZE** and **aspect ratio**

Relevant: inner radius of ECAL: defines the overall scale



Need (common?) **Simulation and Reconstruction**  
software to study detector concepts' performance !

**SiD:** Silicon based concept

**GLD:** even larger detector concept

**LDC:** large detector concept

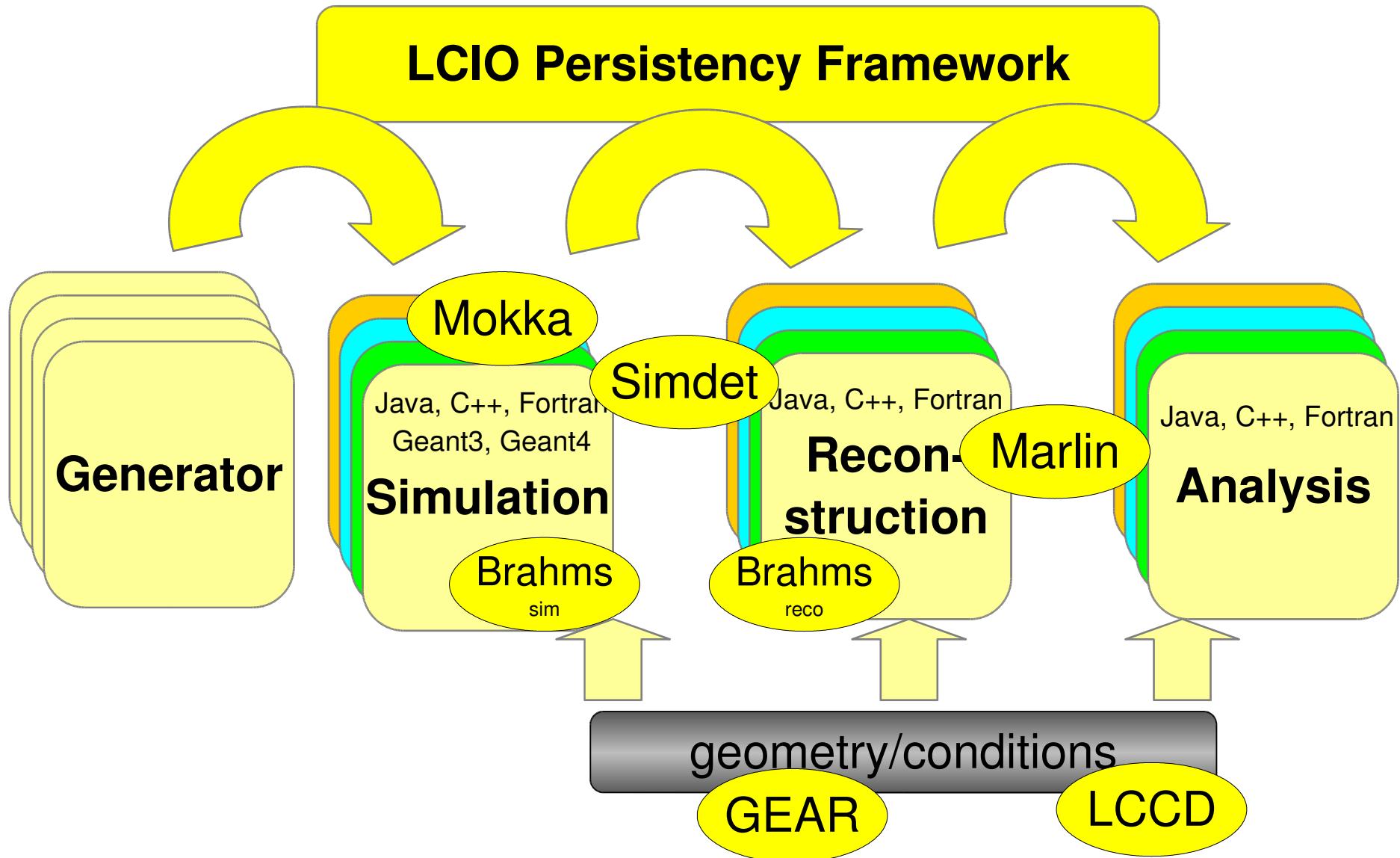
# ILC software packages

	Description	Detector	Language	IO-Format	Region
<b>Simdet</b>	fast Monte Carlo	TeslaTDR	Fortran	StdHep/LCIO	EU
<b>SGV</b>	fast Monte Carlo	simple Geometry, flexible	Fortran	None (LCIO)	EU
<b>Lelaps</b>	fast Monte Carlo	SiD, flexible	C++	SIO, LCIO	US
<b>Mokka</b>	full simulation – Geant4	TeslaTDR, LDC, flexible	C++	ASCI, LCIO	EU
<b>Brahms-Sim</b>	Geant3 – full simulation	TeslaTDR	Fortran	LCIO	EU
<b>SLIC</b>	full simulation – Geant4	SiD, flexible	C++	LCIO	US
<b>LCDG4</b>	full simulation – Geant4	SiD, flexible	C++	SIO, LCIO	US
<b>Jupiter</b>	full simulation – Geant4	JLD (GDL)	C++	Root (LCIO)	AS
<b>Brahms-Reco</b>	reconstruction framework (most complete)	TeslaTDR	Fortran	LCIO	EU
<b>Marlin</b>	reconstruction and analysis application framework	Flexible	C++	LCIO	EU
<b>hep.lcd</b>	reconstruction framework	SiD (flexible)	Java	SIO	US
<b>org.lcsim</b>	reconstruction framework (under development)	SiD (flexible)	Java	LCIO	US
<b>Jupiter-Satelite</b>	reconstruction and analysis	JLD (GDL)	C++	Root	AS
<b>LCCD</b>	Conditions Data Toolkit	All	C++	MySQL, LCIO	EU
<b>GEAR</b>	Geometry description	Flexible	C++ (Java?)	XML	EU
<b>LCIO</b>	Persistency and datamodel	All	Java, C++, Fortran	-	AS,EU,US
<b>JAS3/WIRED</b>	Analysis Tool / Event Display	All	Java	xml, stdhep, heprep, LCIO,	US,EU

# A Common Software Framework for the ILC ?

- a common software framework for the ILC that is flexible and easy to use would be highly desirable
  - (also for detector concept study!)
- **but:**
  - ILC emerged out of three regional studies
  - all groups have developed their own software as needed for the R&D
  - different languages used: C++, Java, f77
  - ...
- **aim:**
  - develop modular software and define interfaces so that packages can coexist/cooperate - (**and eventually converge !?**)
  - common basis: **LCIO**

# Overview of LDC software tools

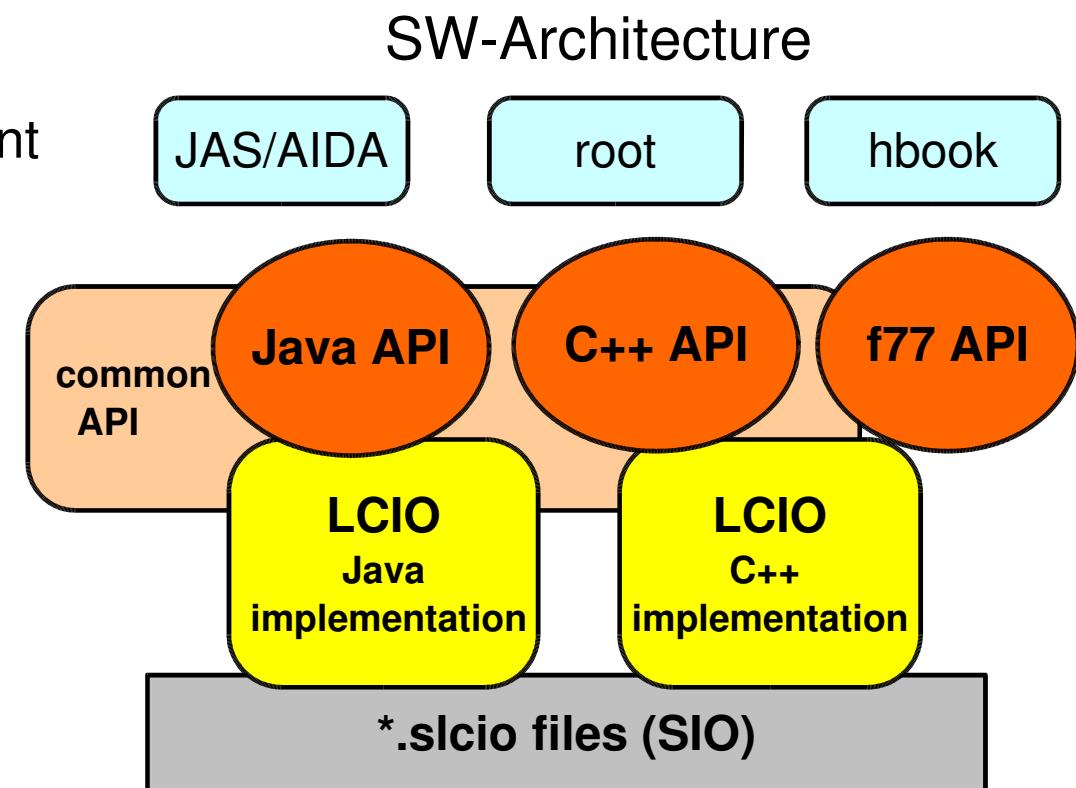


# LCIO overview

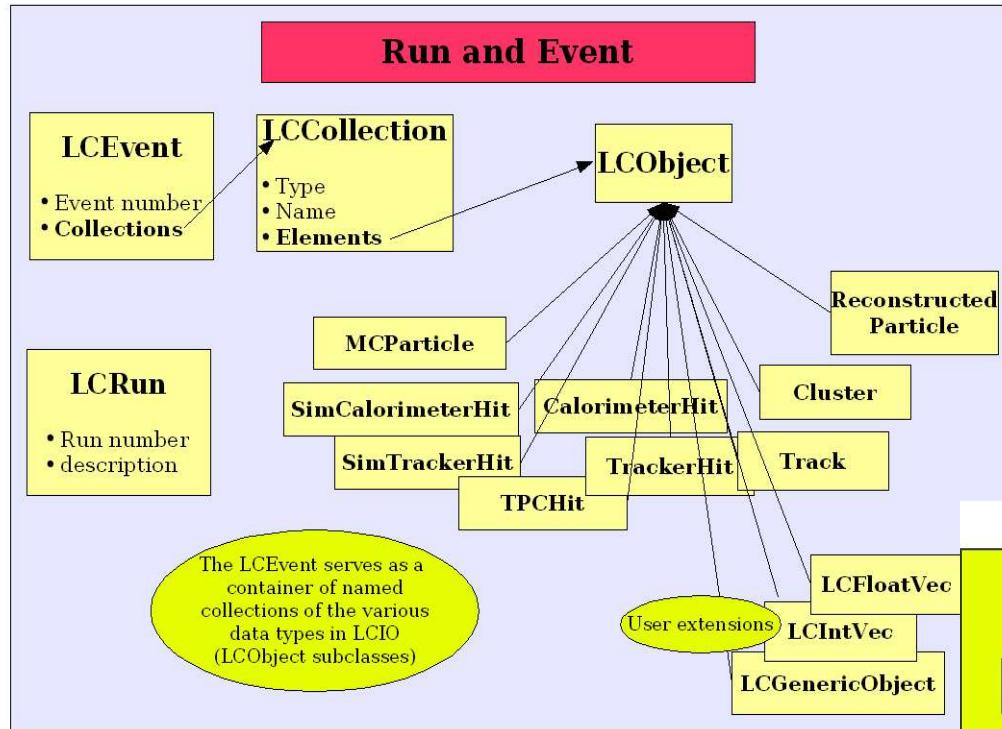
- DESY and SLAC joined project:
  - provide common basis for ILC software
- Features:
  - Java, C++ and f77 (!) API
  - extensible data model for current and future simulation and testbeam studies
  - user code separated from concrete data format
  - no dependency on other frameworks

**simple & lightweight**

now de facto standard  
for ILC software

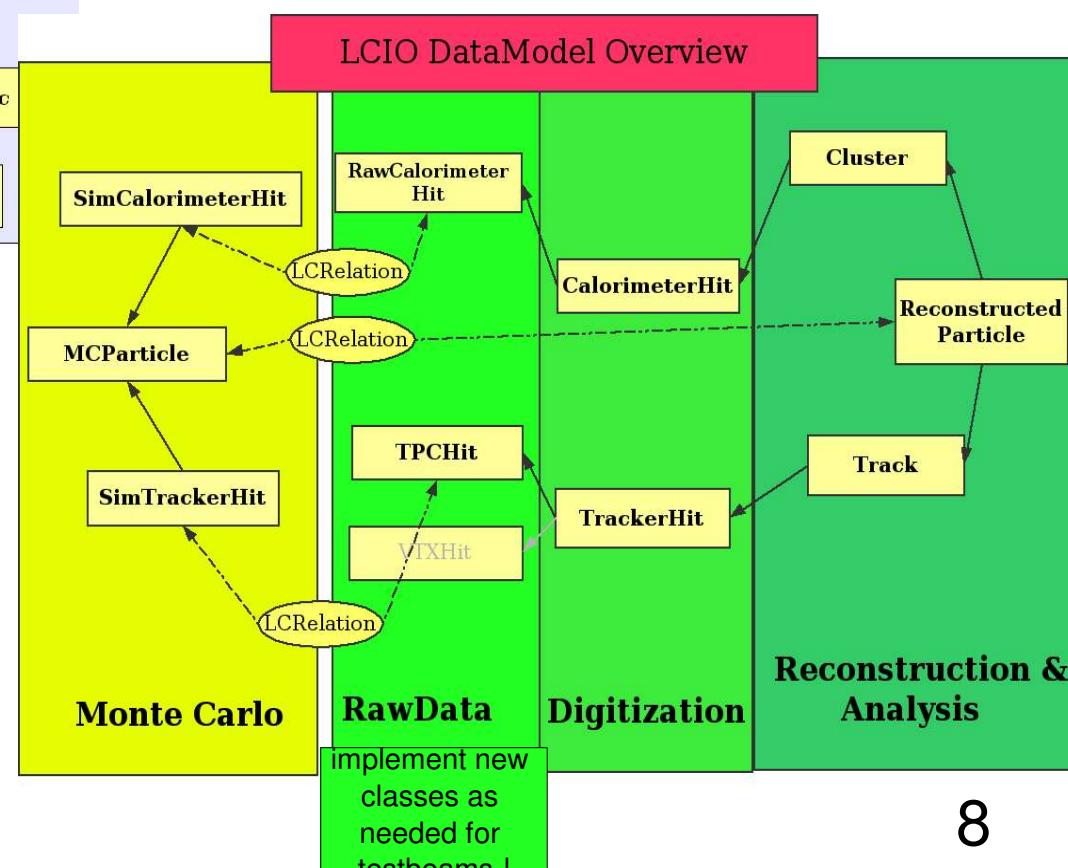


# LCIO data model



hierarchy of data objects in the event

event serves as container of untyped collections



# LCIO status [v01-05]

- changed return values of E, P, m to double for MCParticle and ReconstructedParticle
  - stored are still floats
  - requires some trivial changes (float->double) in code where indicated by the compiler !
- new template UTIL::LCTypedVector<T> for creating std::vector<LCObjectType> from LCCollections
  - allows to use iterators and STL algorithms, e.g. std::for\_each()
- added first implementations of generic tracker raw data classes (TPC, VTX, SiliconStrip,...)
  - TrackerRawData, TrackerData, TrackerPulse
- files are downward compatible with LCIO 1.4
- bug fixes
- see \$LCIO/doc/versions.readme for more

# LCIO on the web

[Overview \(LCIO API Documentation, Version v01-03\) - Mozilla Firefox](http://lcio.desy.de/v01-03/doc/api/index.html)

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http://lcio.desy.de/v01-03/doc/api/index.html

**LCIO API Version v01-03**

All Classes

Packages  
hep.lcio.data  
hep.lcio.event

All Classes

AnalysisJob  
CalorimeterHit  
Cluster  
DataNotAvailableException  
EventException  
ICalorimeterHit  
ICluster  
ILCCollection  
ILCEvent  
ILCFactory  
ILCFloatVec  
ILCIntVec  
ILCParameters  
ILCRelation  
ILCRunHeader  
ILCStrVec  
IMCParticle  
IParticleID

LCIO  
Version v01-03

LCIO - a persistency framework for linear collider simulation studies.

See:

Description

**Packages**

<a href="#">hep.lcio.data</a>	The package hep.lcio.data has been removed - interfaces are now all defined in hep.lcio.event.
<a href="#">hep.lcio.event</a>	Primary user interface for LCIO.
<a href="#">hep.lcio.example</a>	Simple usage examples.
<a href="#">hep.lcio.exceptions</a>	Exceptions thrown by LCIO.
<a href="#">hep.lcio.implementation.event</a>	Default IO implementation.
<a href="#">hep.lcio.implementation.io</a>	SIO specific LCIO implementation.
<a href="#">hep.lcio.io</a>	Interfaces for IO library.
<a href="#">hep.lcio.test</a>	
<a href="#">hep.lcio.util</a>	Utilities for use with LCIO.

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http://lcio.desy.de/v01-03/doc/

simulation/geant4 LCIO Linux DESY IT Group LEO English/German ...

## Documentation for LCIO v01-03

- [Users manual](#) ( also available as [pdf](#) and [ps](#)) **Read before you get started**
- [Java API documentation](#)
- [C++ API documentation](#)
- (printable version of the C++ API reference: [lciorefman.ps](#))
- XML data format description: [lcio.xml](#)

Last modified: Thu Sep 23 14:51:51 2004

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http://lcio.desy.de/v01-03/doc/manual\_html/manual.html

## Building the library

A few variables have to be set depending on your development environment, e.g.

- Linux (and bash):

```
export LCIO=/lcio/v01-03
export PATH=$LCIO/tools:$LCIO/bin:$PATH
export JDK_HOME=/usr/lib/j2sdk
-- modify as appropriate
```
- Windows/Cygwin - DOS shell:

```
set PATH=c:/cygwin/bin;%PATH%
set LCIO=c:/lcio/devel/v01-03
set JDK_HOME=c:/j2sdk1.4.1_01
-- modify as appropriate
set PATH=%LCIO%tools;%LCIO%bin;%PATH%
```

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http://lcio.desy.de/v01-03/doc/doxygen/

Main Page Namespace List Class Hierarchy Compound List File List Namespace Members Compound Members Related Pages

## IMPL::ReconstructedParticleImpl class Reference

Implementation of ReconstructedParticle [More...](#)

```
#include <ReconstructedParticleImpl.h>
```

Inheritance diagram for IMPL::ReconstructedParticleImpl:

```

    EVENT::LCOObject
    +--> EVENT::ReconstructedParticle
    +--> IMPL::AccessChecked
    +--> ReconstructedParticleImpl
    +--> ReconstructedParticleImpl

```

```

EVENT::LCOObject
+--> EVENT::ReconstructedParticle
+--> IMPL::AccessChecked
+--> ReconstructedParticleImpl
+--> ReconstructedParticleImpl

```

**ReconstructedParticleImpl()**  
Default constructor, initializes values to 0.

**virtual ~ReconstructedParticleImpl()**

LCIO-1PS - Overview

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LCIO-1PS - Overview Class Reference

Implementation of [Class](#)  
Inherits from [LCOObject](#)  
Inherited by [DPL::ClusterImpl](#)

**Public Member Functions**

- [ClusterImpl \(\)](#)  
Initial construction, initializes values to 0.
- [virtual ~ClusterImpl \(\)](#)
- [void setClusterSize \(int size\)](#)  
Sets the size of the cluster.
- [void setClusterType \(int type\)](#)  
Forced hard update of the type of cluster.
- [virtual float getPhi \(float\) const](#)  
Return phi.
- [virtual float getTheta \(float\) const](#)  
Return theta.
- [virtual float getLambda \(float\) const](#)  
Return lambda.
- [virtual float getChi2 \(float\) const](#)  
Return chi2.
- [virtual float getNDF \(float\) const](#)  
Return the number of degrees of freedom.
- [virtual float getNDF \(float\) const](#)  
Get the number of degrees of freedom.
- [void float getPhi \(float\) const](#)  
Return creation of cluster of position. Theta.
- [virtual float getTheta \(float\) const](#)  
Return creation of cluster of position. Phi.
- [virtual float getLambda \(float\) const](#)  
Get the number of degrees of freedom (Polarization).

**Protected Member Functions**

- [void setPhi \(float phi\)](#)
- [void setTheta \(float theta\)](#)
- [void setLambda \(float lambda\)](#)
- [void setNDF \(float ndf\)](#)
- [void setPhiError \(float phiError\)](#)
- [void setThetaError \(float thetaError\)](#)
- [void setLambdaError \(float lambdaError\)](#)
- [void addPhi \(float phi\)](#)
- [void addTheta \(float theta\)](#)
- [void addLambda \(float lambda\)](#)
- [void addNDF \(float ndf\)](#)
- [void addPhiError \(float phiError\)](#)
- [void addThetaError \(float thetaError\)](#)
- [void addLambdaError \(float lambdaError\)](#)
- [void addPhi \(float phi\) const](#)
- [void addTheta \(float theta\) const](#)
- [void addLambda \(float lambda\) const](#)
- [void addNDF \(float ndf\) const](#)
- [void addPhiError \(float phiError\) const](#)
- [void addThetaError \(float thetaError\) const](#)
- [void addLambdaError \(float lambdaError\) const](#)

**Protected Attributes**

- [float m\\_phi](#) = 0.0
- [float m\\_theta](#) = 0.0
- [float m\\_lambda](#) = 0.0
- [float m\\_ndf](#) = 0.0
- [float m\\_phiError](#) = 0.0
- [float m\\_thetaError](#) = 0.0
- [float m\\_lambdaError](#) = 0.0

home: <http://lcio.desy.de>

forum: <http://forum.linearcollider.org>

bugs: <http://bugs.freehep.org>

# LCIO Future Plans

- current data model fairly complete
  - check usability of data model, e.g. track parameters
    - ongoing through development of reconstruction code !
  - need to define conventions on how to use LCIO
    - collection names, object types, collections to be present in event
- need to make LCIO more convenient (and efficient)
  - decoding of MCParticle information (parent/daughter, ...)
  - inverse relations ( get all tracks for one MCParticle )
  - attach user information to LCOBJects
  - would like to make C++ version more C++ like, e.g.  
allow to use STL algorithms (templates in general)
- -> had first LCIO meeting here at snowmass ...

# Simulation tools: Simdet, Brahms

## • **SIMDET**

- parameterized fast Monte Carlo (f77)
- tracks + cov. matrix and clusters
- hard coded geometry: TESLA TDR Detector

writes LCIO

## • **Brahms**

- geant3 full simulation (f77)
- hard coded geometry: TESLA TDR Detector
- full standalone reconstruction part (pflow)
- tracking based on LEP reconstruction code

reads + writes LCIO

for download (cvs web interface )  
and more information:  
[http://www-zeuthen.desy.de/linear\\_collider](http://www-zeuthen.desy.de/linear_collider)

# Simulation tools: Mokka

- geant4 based full detector simulation for the ILC
- developed at LLR-Ecole Polytechnique (P. Mora de Freitas, G. Musat)
- <http://polywww.in2p3.fr/geant4/tesla/www/mokka/mokka.html>
- some features:
  - steering files for configuration
  - all geant4 physics lists available
  - **writes LCIO**
  - reads StdHep / ASCII HepEvt
- Geometry
  - MySQL databases
    - geometry parameters
    - one database per subdetector
  - C++ Geometry Drivers
    - one for each subdetector type (e.g. TPC, HCAL)
    - define material and sensitive detector
  - abstract geometry layer: CGA

new features: (v05-01)

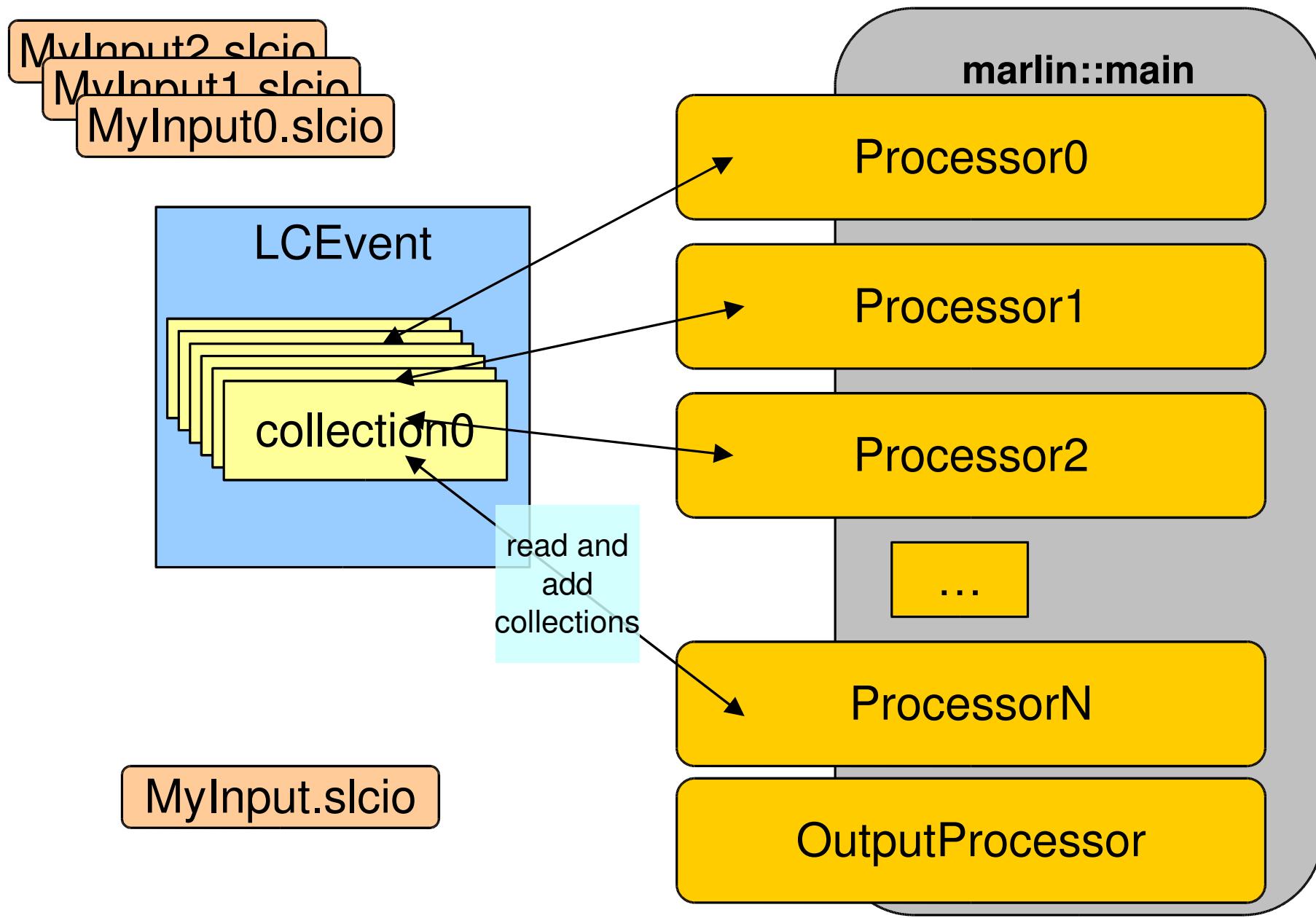
- **SID detector model**
- **scalable detector models**  
-> detector optimization !!

# Marlin - Introduction

**M**odular **A**nalysis & **R**econstruction for the **L** **I** **N**ear Collider

- modular C++ application framework for the analysis and reconstruction of LCIO data
  - uses LCIO as transient data model
  - similar to US org.lcsim Java framework
- 
- **Application framework:**
    - set of classes that provide the core functionality needed in problem domain and provide hooks (callbacks) for specific user code
    - provides main program
    - note: most current experiments that use OO (C++) have application frameworks

# Marlin – schematic overview



# Marlin Processor

- provides main **user callbacks**
- has **own set of input parameters**
  - int, float, string (single and arrays)
  - parameter description
- naturally modularizes the application
- **order of processors is defined via steering file:**
  - easy to exchange one or several modules w/o recompiling
  - can run the same processor with different parameter set in one job
- **processor task can be as simple as creating one histogram or as complex as track finding and fitting in the central tracker**

```
marlin::Processor  
init()  
processRunHeader(LCRunHeader* run)  
processEvent( LCEvent* evt)  
check( LCEvent* evt)  
end()
```

```
UserProcessor  
processEvent( LCEvent* evt){  
    // your code goes here...  
}
```



# Marlin features

- core processors

- **AIDAProcessor**

- for easy creation of histograms, clouds, ntuples

- **OutputProcessor**

- writes current event or subset thereof

- **MyProcessor**

- simple example – serves as template for user code

- **ConditionsProcessor**

New

- read conditions transparently with LCCD

- **DataSourceProcessor**

New

- read non LCIO input, e.g. StdHepReader

- **SimpleFastMCPProcessor**

New

- fast smearing Monte Carlo
    - needs testing

- fully configurable through steering files:

- program flow
    - input parameters
    - processor based and global

- self-documenting:

- MyApplication -l will print all available processors with their parameters and example/default values

# Marlin - new features I

- v00-09 (details in \$MARLIN/doc/release.notes)
- new optional XML steering files
  - based on TinyXml (open source) – included in Marlin
  - same basic structure as old ASCII steering files
  - additional features:
    - allows conditional execution of `processEvent()` method based on boolean flags set by processors
    - allows grouping of processors with shared parameters
  - 'Marlin -x > steer.xml' creates example steering file with all available processors
- XML can be used in Marlin for other input files

# Marlin – example XML steering

```

- <marlin>
  - <execute>
    <processor name="MyAIDAProcessor"/>
    <processor name="MyEventSelection"/>
  - <if condition="MyEventSelection">
    <group name="Tracking"/>
    <processor name="MyClustering"/>
    <processor name="MyPFlow"/>
    <processor name="MyLCIOOutputProcessor"/>
  </if>
</execute>
- <global>
  <parameter name="LCIOInputFiles"> simjob.slcio </parameter>
  <parameter name="MaxRecordNumber" value="5001"/>
  <parameter name="SupressCheck" value="false"/>
</global>
- <processor name="MyLCIOOutputProcessor" type="LCIOOutputProcessor">
  <parameter name="LCIOOutputFile" type="string">outputfile.slcio </parameter>
  <parameter name="LCIOWriteMode" type="string">WRITE_NEW</parameter>
</processor>
- <group name="Tracking">
  <parameter name="NTPCLayers" value="200"/>
  <processor name="MyTrackfinder" type="Trackfinder"/>
  - <processor name="MyTrackfitter" type="Trackfitter">
    <parameter name="Algorithm" value="DAF"/>
  </processor>
</group>
<!-- ... -->
</marlin>
```

- ActiveProcessors replaced by <execute>...</execute> section
- Reconstruct only events that pass the event selection

- Parameters defined as content of <parameter/> tag or as its value attribute

- Processors can be enclosed by <group/> tag
- Parameters in <group/> joined by all processors

# Marlin - new features II

- Exceptions (subclasses of `Icio::Exception`):
  - uncaught Exceptions terminate program with error message (given in constructor)
  - **ParseException**
    - thrown if steering has wrong syntax
  - **SkipEventException**
    - can be thrown by any processor
    - skips `processEvent()` for all subsequent processors
    - printout at end of program (#evts skipped by processor)
  - **StopProcessingException**
    - can be thrown by any Processor
    - ends program gracefully by calling all `end()` methods
  - **others ?**

# Marlin - new features III

- improved Makefiles
  - make it easier to build against an installed version of Marlin:
    - INCLUDE += `\$(MARLIN)/bin/marlin\_includes.sh`
    - LIBS += `\$(MARLIN)/bin/marlin\_libs.sh`
    - ensures same optional dependencies are used (LCCD, CLHEP, CondDBMySQL,...)
  - USERINCLUDES, USERLIBS to define additional dependencies
- global GNUmakefile:
  - allows to build marlin with several packages of processors
  - links all packages in \$MARLIN/packages directory
  - packages need to follow \$MARLIN/examples/mymarlin structure
- see workshop DVD

# MarlinReco

- **Marlin serves as a framework for the distributed development of a full suite of reconstruction algorithms !**
  - > your input is welcome !
- **(almost) complete set of standard reconstruction in Marlin available: MarlinReco (see talk by S. Aplin)**
  - first version available on DVD “ILC software for LDC”
- uses first implementation of GEAR geometry description
  - Marlin v00-09-01

# Marlin on the web



**Releases**

v00-08 has been released and is available for [download](#). Marlin can now optionally be linked against [LCCD](#) to provide easy access to conditions data. Documentation has been improved.

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**Download**

All tagged versions and the current HEAD of the repository can be downloaded from the [code repository](#).

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**Documentation**

[Current API documentation](#).

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**Talks**

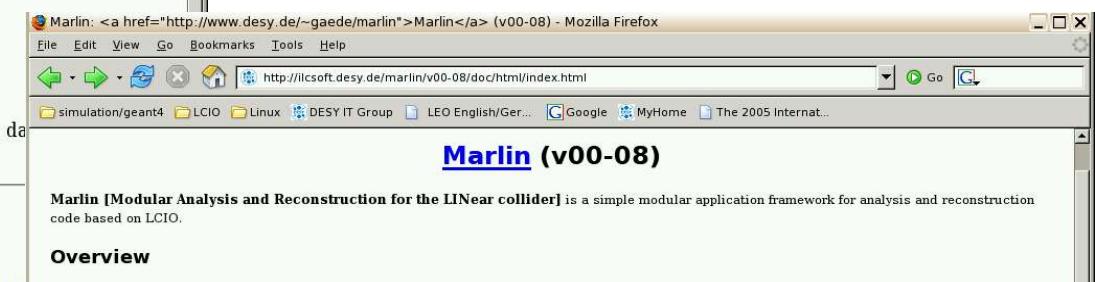
LCIO & Marlin ([pdf](#)) - talk given at the DESY Simulation WS 2004.

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Last modified: Fri Mar 11 16:01:59 2005  
by [Frank.Gaede@desy.de](mailto:Frank.Gaede@desy.de)

Done

<http://ilcsoft.desy.de/marlin>



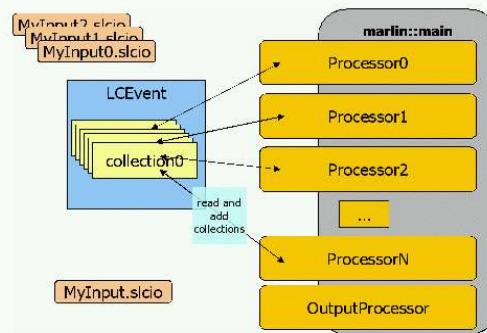
## Marlin (v00-08)

Marlin [Modular Analysis and Reconstruction for the LINear collider] is a simple modular application framework for analysis and reconstruction code based on LCIO.

### Overview

The main purpose of Marlin is to facilitate the modular development of reconstruction and analysis code based on LCIO. As a lot of different groups are involved it should be simple and straight forward to have distributed development of modules and combine existing modules as needed in a larger application.

The base class for a Marlin module is called **marlin::Processor**. It defines a set of callbacks that the user can implement in their subclasses. A steering file mechanism allows to activate the needed processors. These are then called for every event using the LCEvent as container for input and output data in terms of LC\_collections:



**Installation**

The installation of Marlin is described in the [README](#).

**Running Marlin**

After having installed Marlin you have to write your own marlin::Processor(s) subclass that performs the computation. This is fairly straight forward and Marlin provides an example in [/examples/mymarlin](#) that can serve as a template for your own projects.

Note: there is no need to write a main program as this is provided by Marlin. Existing Processors are automatically registered with Marlin provided one instance exists in the library as described in the [README](#).

**Steering files**

Done

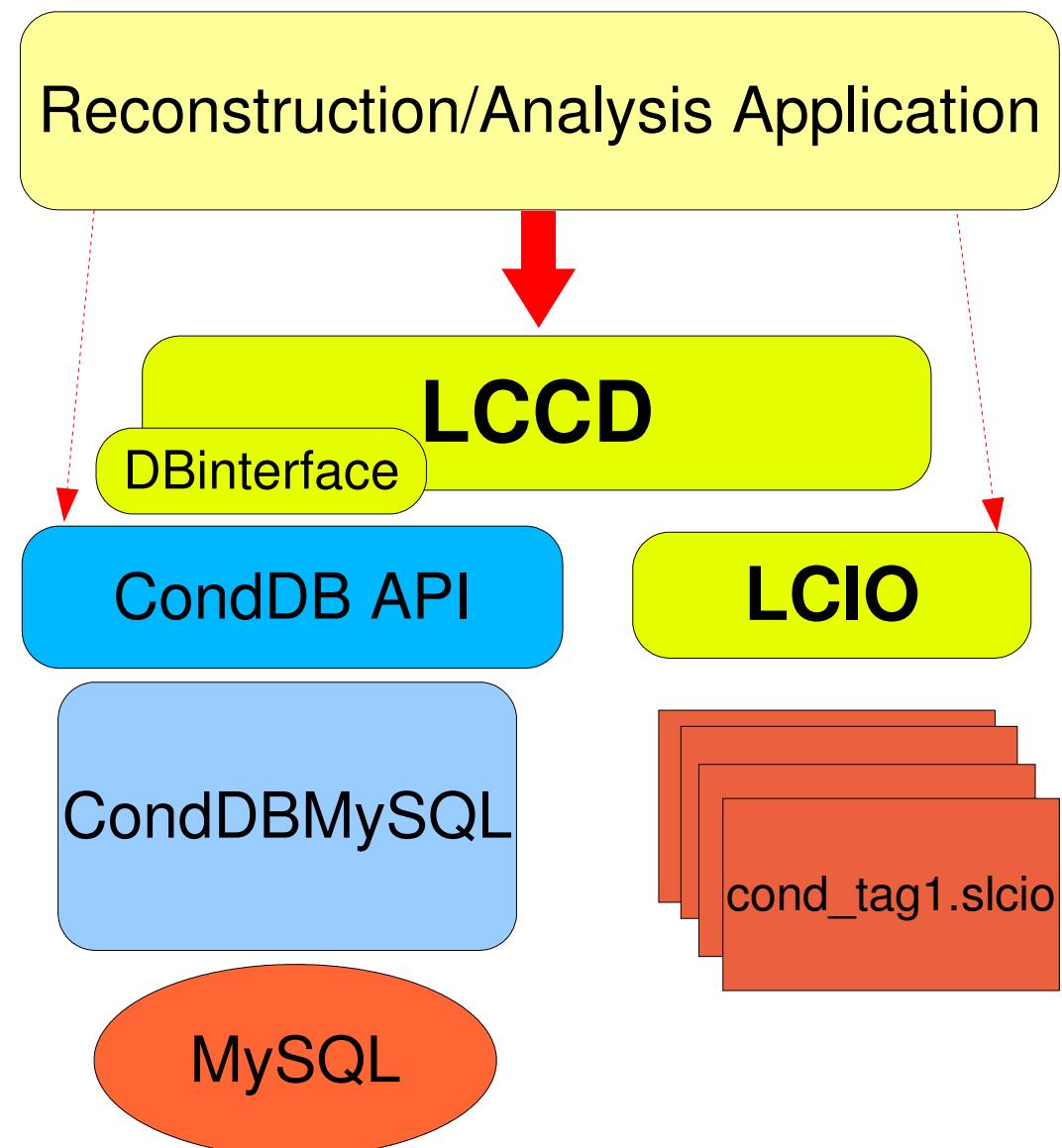
# LCCD

**L**inear **C**ollider **C**onditions **D**ata Toolkit

- handles access to conditions data transparently from
  - conditions database (CondDBMySQL (by Lisbon Atlas group))
  - LCIO files
- **Conditions Data:**
  - all data that is needed for analysis/reconstruction besides the actual event data
  - typically has lifetime/validity range longer than one event
    - can change on various timescales, e.g. seconds to years
  - need for versioning (tagging) (changing calibration constants)
  - also 'static' geometry description (channel mapping, positions,...)

# LCCD features

- **Reading conditions data**
  - from conditions database
    - for given tag
  - from simple LCIO file
    - (one set of constants)
  - from LCIO data stream
    - e.g. slow control data
  - from dedicated LCIO-DB file
    - has all constants for given tag
- **Writing conditions data**
  - as LCGenericObject collection
  - in folder (directory) structure
  - tagging
- **Browsing the conditions database**
  - through creation of LCIO files
    - vertically (all versions for timestamp)
    - horizontally (all versions for tag)



# LCCD on the web

**LCCD homepage - Mozilla Firefox**

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http://ilcsoft.desy.de/lccd/

simulation/geant4 LCIO Linux DESY IT Group LEO English/Ger... Google MyHome

**Linear Collider Conditions Data Toolkit**

LCCD is a toolkit that enables users to transparently read conditions data from LCIO files or a conditions database. See the API documentation for more.

LCCD is still under development - so please test before you use it for production.

**Releases**

v00-02 has been released and is available for [download](#) ( requires [LCIO v01-04](#)).

**Download**

All tagged versions and the current HEAD of the repository can be downloaded from [here](#).

**Documentation**

[Current \(v00-02\) API documentation](#).

**Talks**

[LCCD Proposal \(pdf\)](#) - talk given in the software meeting @ Desy.

Last modified: Fri Mar 11 15:58:08 2005  
by [Frank.Gaede@desy.de](mailto:Frank.Gaede@desy.de)

Done

**http://ilcsoft.desy.de/lccd**

**LCCD: lccd::IConditionsHandler class Reference - Mozilla Firefox**

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http://ilcsoft.desy.de/lccd/v00-02/doc/html/classlccd\_1\_1ConditionsHandler.html

simulation/geant4 LCIO Linux DESY IT Group LEO English/Ger... Google MyHome

**Iccd::IConditionsHandler Class Reference**

Abstract handler for conditions data. [More...](#)

```
#include <IConditionsHandler.hh>
```

Inheritance diagram for lccd::IConditionsHandler:

```

graph TD
    IConditionsHandler[IConditionsHandler] --> IConditionsHandlerBase[IConditionsHandlerBase]
    IConditionsHandlerBase --> IDataFileHandler[IDataFileHandler]
    IConditionsHandlerBase --> ICondHandler[ICondHandler]
    IConditionsHandlerBase --> IDBFileHandler[IDBFileHandler]
    IConditionsHandlerBase --> ISimpleFileHandler[ISimpleFileHandler]

```

[List of all members](#).

**Public Member Functions**

- `virtual void updateEvent (lcio::LCEvent *evt)=0`  
Retrieves the new conditions data if required by evt->getTimestamp() and adds a collection to event with its name.
- `virtual void update (LCCDTimeStamp timestamp)=0`  
Retrieves the new conditions data if required by timestamp.
- `virtual lcio::LCCollection * currentCollection ()=0`  
Returns the current collection of conditions data.
- `virtual void registerChangeListener (IConditionsChangeListener *cl)=0`  
Every **IConditionsChangeListener** will be notified if the conditions data of this instance has changed.
- `virtual void removeChangeListener (IConditionsChangeListener *cl)=0`  
Remove the specified listener from list of registered listeners ;

virtual const std::string& Done

# GEAR Overview

**GE**ometry **A**PI for **R**econstruction

## • Motivation:

- need well defined geometry definition that
  - is flexible w.r.t different detector concepts
- has high level information needed for reconstruction  
(different from detailed local description for simulation !)
- supports 'plug & play' philosophy of processors implementing different algorithms
- provides access to material properties (radiation/interaction lengths)

## • Idea:

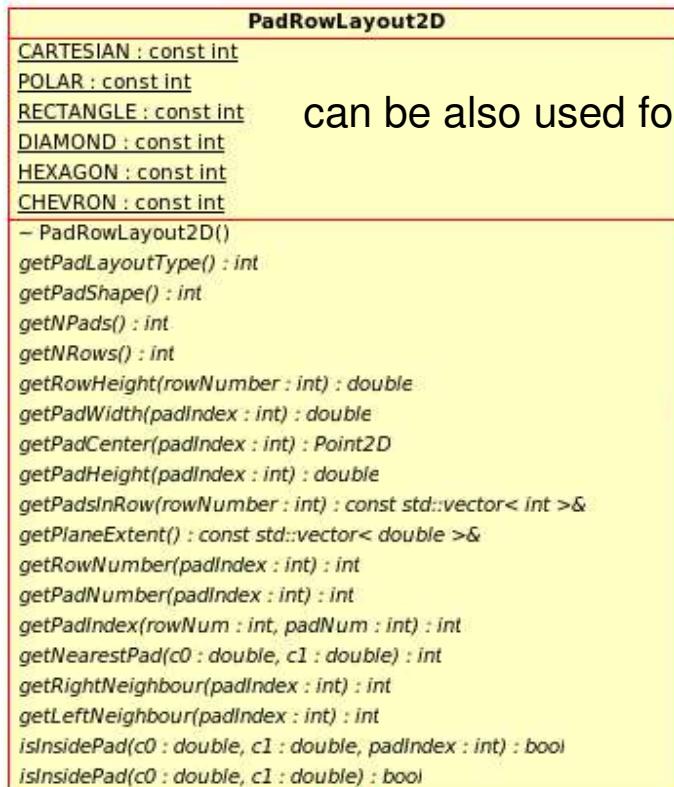
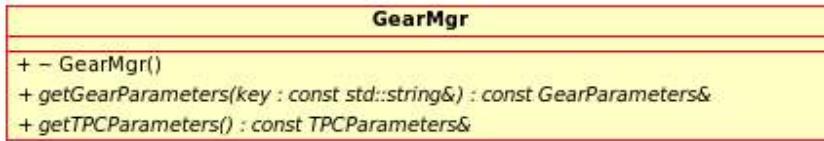
- define abstract interface (a la LCIO C++ and Java ?)
- concrete implementation based on XML files and CGA

# GEAR – Two class types

- Subdetector description
  - high level description of detector shape and readout geometry – one class for every subdetector type, e.g.
    - TPC, Ecal, Hcal (MainCalorimeter), FTD, VTX, SIT, ...
    - defines required attributes - as detailed as necessary but as abstract as possible
    - allows to add additional named attributes
  - use XML files
- Material properties
  - point properties (density, material, radlen,...)
  - distance properties integrated along (straight!?) path
  - use Mokka-CGA interface to geant4 geometry

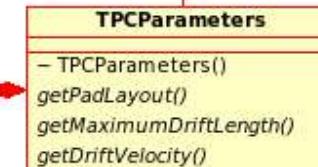
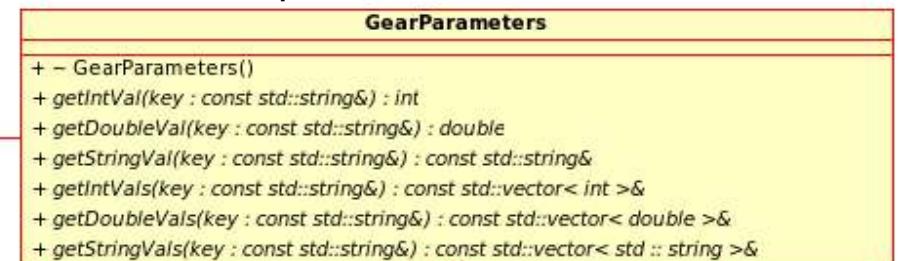
# GEAR – TPC description

holds all subdetector classes



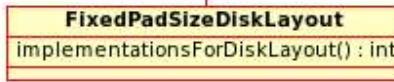
can be also used for FTD, CaloEndcap,...

named parameters for additional attributes



TPC specific parameters

based on discussion with  
TPC experts at LCWS 2005



implementation for disk with pad rings

# GEAR – XML file example

```

- <gear>
  - <!--
    Example XML file for GEAR describing the LDC detector
  -->
- <detectors>
  - <detector id="0" name="TPCTest" geartype="TPCParameters" type="UNKNOWN" insideTrackingVolume="yes">
    <maxDriftLength value="2500."/>
    <driftVelocity value=""/>
    <readoutFrequency value="10"/>
    <PadRowLayout2D type="FixedPadSizeDiskLayout" rMin="386.0" rMax="1626.0" padHeight="6.2" padWidth="2.2"
      maxRow="200" padGap="0.0"/>
    <parameter name="tpcRPhiResMax" type="double"> 0.16 </parameter>
    <parameter name="tpcZRes" type="double"> 1.0 </parameter>
    <parameter name="tpcPixRP" type="double"> 1.0 </parameter>
    <parameter name="tpcPixZ" type="double"> 1.4 </parameter>
    <parameter name="tpcIonPotential" type="double"> 0.0000003 </parameter>
  </detector>
  - <detector name="EcalBarrel" geartype="CalorimeterParameters">
    <layout type="Barrel" symmetry="8" phi0="0.0"/>
    <dimensions inner_r="1698.85" outer_z="2750.0"/>
    <layer repeat="30" thickness="3.9" absorberThickness="2.5"/>
    <layer repeat="10" thickness="6.7" absorberThickness="5.3"/>
  </detector>
  - <detector name="EcalEndcap" geartype="CalorimeterParameters">
    <layout type="Endcap" symmetry="2" phi0="0.0"/>
    <dimensions inner_r="320.0" outer_r="1882.85" inner_z="2820.0"/>
    <layer repeat="30" thickness="3.9" absorberThickness="2.5"/>
    <layer repeat="10" thickness="6.7" absorberThickness="5.3"/>
  </detector>
</detectors>
</gear>
```

additional user defined parameters

compatible with US – compact format

complete file for LDC as used in MarlinReco !

# GEAR – material properties

## GearDistanceProperties

```
- GearDistanceProperties()  
getMaterialNames(p0 : const Point3D&, p1 : const Point3D&) : const std::vector< std::string >&  
getMaterialThicknesses(p0 : const Point3D&, p1 : const Point3D&) : const std::vector< double >&  
getNRadlen(p0 : const Point3D&, p1 : const Point3D&) : double  
getNIntlen(p0 : const Point3D&, p1 : const Point3D&) : double  
getBdL(pos : const Point3D&) : double  
getEdL(pos : const Point3D&) : double
```

integrated along path:  
• straight line or  
• true path in B-Field ?

## GearPointProperties

```
- GearPointProperties()  
getCellID(pos : const Point3D&) : int  
getMaterialName(pos : const Point3D&) : const std::string&  
getDensity(pos : const Point3D&) : double  
getTemperature(pos : const Point3D&) : double  
getPressure(pos : const Point3D&) : double  
getRadlen(pos : const Point3D&) : double  
getIntlen(pos : const Point3D&) : double  
getLocalPosition(pos : const Point3D&) : Point3D  
getB(pos : const Point3D&) : double  
getE(pos : const Point3D&) : double  
getListLogicalVolumes(pos : const Point3D&) : std::vector< std::string >  
getListPhysicalVolumes(pos : const Point3D&) : std::vector< std::string >  
getRegion(pos : const Point3D&) : std::string  
isTracker(pos : const Point3D&) : bool  
isCalorimeter(pos : const Point3D&) : bool
```

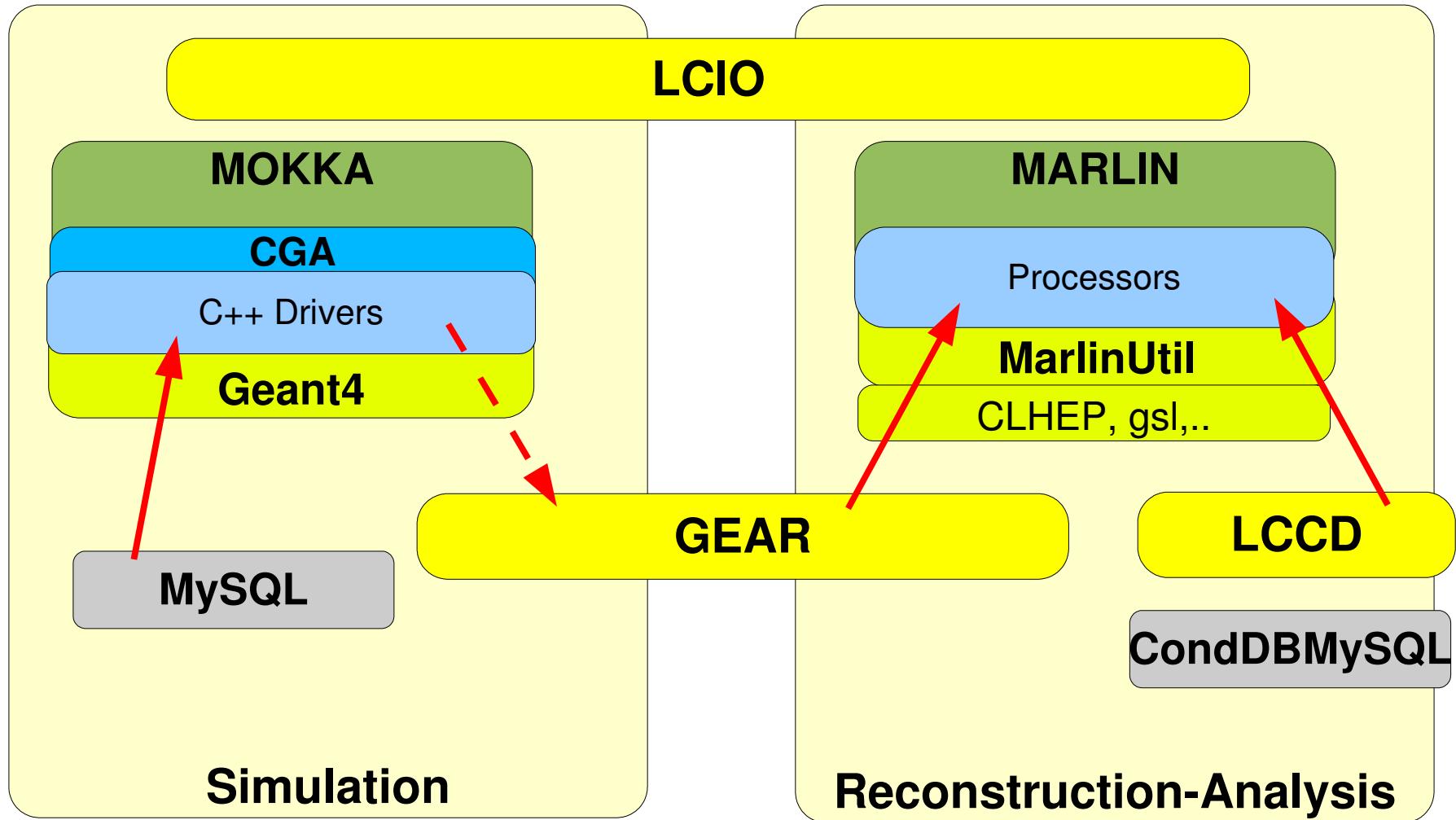
properties at point from geant4 (CGA)

based on discussions at  
Argonne Simulation  
Meeting 2004

# GEAR status and outlook

- first mini implementation with XML files for current MarlinReco: TPC, Ecal, Hcal
  - XML format 'compatible' with US compact description
  - integrated in Marlin v00-09-01 (see DVD)
  - soon to be released !
- **Plans:**
  - have discussions at snowmass with other subdetector groups about abstract interface needed: **started with VTX group !**
  - see if other groups are interested in collaborating !?
  - provide implementation of material properties based on CGA/Mokka
  - investigate option of creating GEAR XML files in Mokka geometry drivers

# LDC simulation framework



# Summary & Outlook

- a fairly complete OO-software framework exists for the LDC study based on **Mokka, Marlin, LCIO, LCCD and GEAR**
  - ready to start using it for detector concept study !
- current version of this software can be found on the DVD “ILC software for LDC ”
- has been used to produce LDC events on “International ILC Event DVD” on the DESY – computing **Grid** !
  - LCIO files for SID, LDC, GLC of Zpole, Zh and ttbar events
  - also at <http://www-flc.desy.de/snowmassdatadvd>

## To Do:

- investigate interoperability with other frameworks (ongoing !)
  - apply software to other concepts (ongoing !)
  - exchange ideas and collaborate
  - improve software ...

all software available at portal:  
<http://www-flc.desy.de/ilcsoft>