# Bi-Hamiltonian Formulation of Generalized Toda Chains 

Pantelis A. DAMIANOU<br>Department of Mathematics and Statistic, University of Cyprus, 1678, Nicosia, Cyprus E-mail: damianou@ucy.ac.cy

In this paper we prove that the Bogoyavlensky-Toda lattices corresponding to simple, classical Lie groups are bi-Hamiltonian. We illustrate in detail the case of $B_{N}$ Toda systems.

## 1 Introduction

In this paper we establish for the first time the bi-Hamiltonian nature of the Toda lattices corresponding to classical simple Lie groups. These are systems that generalize the usual finite, non-periodic Toda lattice (which corresponds to a root system of type $A_{n}$ ). This generalization is due to Bogoyavlensky [2]. These systems were studied extensively in [10] where the solution of the system was connected intimately with the representation theory of simple Lie groups. There are also studies by Adler, van Moerbeke [1] and Olshanetsky, Perelomov [15]. We call such systems the Bogoyavlensky-Toda lattices. We make the following more general definition which involves systems with exponential interaction: Consider a Hamiltonian of the form

$$
\begin{equation*}
H=\frac{1}{2}(\boldsymbol{p}, \boldsymbol{p})+\sum_{i=1}^{m} e^{\left(\boldsymbol{v}_{i}, \boldsymbol{q}\right)} \tag{1}
\end{equation*}
$$

where $\boldsymbol{q}=\left(q_{1}, \ldots, q_{N}\right), \boldsymbol{p}=\left(p_{1}, \ldots, p_{N}\right), \boldsymbol{v}_{1}, \ldots, \boldsymbol{v}_{m}$ are vectors in $\mathbb{R}^{N}$ and $($,$) is the standard$ inner product in $\mathbb{R}^{N}$. The set of vectors $\Delta=\left\{\boldsymbol{v}_{1}, \ldots, \boldsymbol{v}_{m}\right\}$ is called the spectrum of the system. In this paper we limit our attention to the case where the spectrum is a system of simple roots for a simple Lie algebra $\mathcal{G}$. In this case $m=l=\operatorname{rank} \mathcal{G}$. It is worth mentioning that the case where $m, N$ are arbitrary is an open and unexplored area of research. The main exception is the work of Kozlov and Treshchev [11] where a classification of system (1) is performed under the assumption that the system possesses $N$ polynomial (in the momenta) integrals. Such systems are called Birkhoff integrable.
Example. The usual Toda lattice corresponds to a Lie algebra of type $A_{N-1}$. In other words, $l=N-1$ and we choose $\Delta$ to be the set:

$$
\boldsymbol{v}_{1}=(1,-1,0, \ldots, 0), \quad \ldots \ldots \ldots, \quad \boldsymbol{v}_{N-1}=(0,0, \ldots, 0,1,-1) .
$$

The Hamiltonian becomes:

$$
\begin{equation*}
H\left(q_{1}, \ldots, q_{N}, p_{1}, \ldots, p_{N}\right)=\sum_{i=1}^{N} \frac{1}{2} p_{i}^{2}+\sum_{i=1}^{N-1} e^{q_{i}-q_{i+1}} \tag{2}
\end{equation*}
$$

which is the well-known classical Toda lattice.
The results of this paper were announced in [5] where it was pointed out that the higher Toda flows of the $B_{N}, C_{N}$ and $D_{N}$ systems are bi-Hamiltonian, but there was no similar result for the initial flow. Usually, it is more convenient to work instead in the space of the natural ( $q, p$ ) variables, with the Flaschka variables $(a, b)$. We end-up with a new set of polynomial equations
in the variables $(a, b)$. One can write the equations in Lax pair form. The Lax pair $(L(t), B(t))$ in $\mathcal{G}$ can be described in terms of the root system. The symplectic bracket is transformed in $(a, b)$ coordinates into a Lie-Poisson bracket denoted by $\pi_{1}$. The construction of the bi-Hamiltonian pair may be summarized as follows: Define a recursion operator $\mathcal{R}$ in $(a, b)$ space by finding a second bracket, $\pi_{3}$, and inverting the initial Poisson bracket $\pi_{1}$. Define the negative recursion operator $\mathcal{N}$ by inverting the second Poisson bracket $\pi_{3}$. This recursion operator is the inverse of the operator $\mathcal{R}$. Finally, define a new rational bracket $\pi_{-1}$ by $\pi_{-1}=\mathcal{N} \pi_{1}=\pi_{1} \pi_{3}^{-1} \pi_{1}$. We obtain a bi-Hamiltonian formulation of the system:

$$
\pi_{1} \nabla H_{2}=\pi_{-1} \nabla H_{4}
$$

where $H_{i}=\frac{1}{i} \operatorname{tr} L^{i}$. The brackets $\pi_{1}$ and $\pi_{-1}$ are compatible and Poisson. In this paper we treat in detail the $B_{N}$ case. For complete results and full proofs for all classical simple Lie groups, see [6]. We begin with a review of the classical Toda lattice.

## $2 \quad \boldsymbol{A}_{N}$ Toda lattice

Equation (2) is the classical, finite, nonperiodic Toda lattice. This system was investigated in $[7-9,13,14]$ and in numerous of other papers that are impossible to list here. To determine the constants of motion, one uses Flaschka's transformation:

$$
a_{i}=\frac{1}{2} e^{\frac{1}{2}\left(q_{i}-q_{i+1}\right)}, \quad b_{i}=-\frac{1}{2} p_{i} .
$$

Then Hamilton's equations become

$$
\begin{aligned}
& \dot{a}_{i}=a_{i}\left(b_{i+1}-b_{i}\right), \\
& \dot{b}_{i}=2\left(a_{i}^{2}-a_{i-1}^{2}\right) .
\end{aligned}
$$

These equations can be written as a Lax pair $\dot{L}=[B, L]$, where $L$ is the Jacobi matrix

$$
L=\left(\begin{array}{cccccc}
b_{1} & a_{1} & 0 & \cdots & \cdots & 0 \\
a_{1} & b_{2} & a_{2} & \cdots & & \vdots \\
0 & a_{2} & b_{3} & \ddots & & \\
\vdots & & \ddots & \ddots & & \vdots \\
\vdots & & & \ddots & \ddots & a_{N-1} \\
0 & \cdots & & \cdots & a_{N-1} & b_{N}
\end{array}\right)
$$

and $B$ is the skew-symmetric part of $L$ (In the decomposition, lower Borel plus skew-symmetric). This is an example of an isospectral deformation; the entries of $L$ vary over time but the eigenvalues remain constant. It follows that the functions $H_{i}=\frac{1}{i} \operatorname{tr} L^{i}$ are constants of motion.

Consider $\mathbb{R}^{2 N}$ with coordinates $\left(q_{1}, \ldots, q_{N}, p_{1}, \ldots, p_{N}\right)$, the standard symplectic bracket

$$
\{f, g\}_{s}=\sum_{i=1}^{N}\left(\frac{\partial f}{\partial q_{i}} \frac{\partial g}{\partial p_{i}}-\frac{\partial f}{\partial p_{i}} \frac{\partial g}{\partial q_{i}}\right)
$$

and the mapping $F: \mathbb{R}^{2 N} \rightarrow \mathbb{R}^{2 N-1}$ defined by

$$
F:\left(q_{1}, \ldots, q_{N}, p_{1}, \ldots, p_{N}\right) \rightarrow\left(a_{1}, \ldots, a_{N-1}, b_{1}, \ldots, b_{N}\right)
$$

There exists a bracket on $\mathbb{R}^{2 N-1}$, which satisfies

$$
\{f, g\} \circ F=\{f \circ F, g \circ F\}_{s}
$$

This bracket (up to a constant multiple) is given by

$$
\begin{equation*}
\left\{a_{i}, b_{i}\right\}=-a_{i}, \quad\left\{a_{i}, b_{i+1}\right\}=a_{i} \tag{3}
\end{equation*}
$$

all other brackets are zero. $H_{1}=b_{1}+b_{2}+\cdots+b_{N}$ is the only Casimir. The Hamiltonian in this bracket is $H_{2}=\frac{1}{2} \operatorname{tr} L^{2}$. The Lie algebraic interpretation of this bracket can be found in [10]. We denote this bracket by $\pi_{1}$. The invariants $H_{i}$ are in involution with respect to this Lie Poisson bracket $\pi_{1}$.

The quadratic Toda bracket appears in conjunction with isospectral deformations of Jacobi matrices. First, let $\lambda$ be an eigenvalue of $L$ with normalized eigenvector $v$. Standard perturbation theory shows that

$$
\nabla \lambda=\left(2 v_{1} v_{2}, \ldots, 2 v_{N-1} v_{N}, v_{1}^{2}, \ldots, v_{N}^{2}\right)^{T}:=U^{\lambda}
$$

where $\nabla \lambda$ denotes $\left(\frac{\partial \lambda}{\partial a_{1}}, \ldots, \frac{\partial \lambda}{\partial b_{N}}\right)$. Some manipulations show that $U^{\lambda}$ satisfies

$$
\pi_{2} U^{\lambda}=\lambda \pi_{1} U^{\lambda}
$$

where $\pi_{1}$ and $\pi_{2}$ are skew-symmetric matrices. It turns out that $\pi_{1}$ is the matrix of coefficients of the Poisson tensor (3), and $\pi_{2}$, whose coefficients are quadratic functions of the $a$ 's and $b$ 's, that can be used to define a new Poisson tensor. It is a Poisson bracket in which the Hamiltonian vector field generated by $H_{1}$ is the same as the Hamiltonian vector field generated by $H_{2}$ with respect to the $\pi_{1}$ bracket. The defining relations are:

$$
\left\{a_{i}, a_{i+1}\right\}=\frac{1}{2} a_{i} a_{i+1}, \quad\left\{a_{i}, b_{i}\right\}=-a_{i} b_{i}, \quad\left\{a_{i}, b_{i+1}\right\}=a_{i} b_{i+1}, \quad\left\{b_{i}, b_{i+1}\right\}=2 a_{i}^{2},
$$

all other brackets are zero. This bracket, due to Adler, has det $L$ as Casimir and $H_{1}=\operatorname{tr} L$ is the Hamiltonian. The eigenvalues of $L$ (and therefore the $H_{i}$ as well) are still in involution. Furthermore, $\pi_{2}$ is compatible with $\pi_{1}$. We also have

$$
\begin{equation*}
\pi_{2} \nabla H_{l}=\pi_{1} \nabla H_{l+1}, \quad l=1,2, \ldots \tag{4}
\end{equation*}
$$

These relations are similar to the Lenard relations for the KdV equation; they are generally called the Lenard relations. Taking $l=1$ in (4), we conclude that the Toda lattice is bi-Hamiltonian. In fact, using results from [5], we can prove that the Toda lattice is multi-Hamiltonian:

$$
\pi_{2} \nabla H_{1}=\pi_{1} \nabla H_{2}=\pi_{0} \nabla H_{3}=\pi_{-1} \nabla H_{4}=\cdots
$$

The notion of bi-Hamiltonian system is due to Magri [12].
The sequence of Poisson tensors can be extended to form an infinite hierarchy. In order to produce the hierarchy of Poisson tensors one uses master symmetries. The first two Poisson brackets are precisely the linear and quadratic brackets we mentioned above. If a system is biHamiltonian and one of the brackets is symplectic, one can find a recursion operator by inverting the symplectic tensor. The recursion operator is then applied to the initial symplectic bracket to produce an infinite sequence. However, in the case of Toda lattice (in Flaschka variables $(a, b))$ both operators are non-invertible and therefore this method fails. Recursion operators were introduced by Olver [16].

In the case of Toda equations, the master symmetries map invariant functions to other invariant functions. Hamiltonian vector fields are also preserved. New Poisson brackets are generated by using Lie derivatives in the direction of these vector fields and they satisfy interesting deformation relations. We quote the results from refs. [3, 4].

Theorem 1. There exists a sequence of vector fields $X_{i}$, for $i \geq-1$, and a sequence of contravariant 2-tensors $\pi_{j}, j \geq 1$, satisfying:
i) $\pi_{j}$ are all Poisson;
ii) the functions $H_{i}, i \geq 1$, are in involution with respect to all of the $\pi_{j}$;
iii) $X_{i}\left(H_{j}\right)=(i+j) H_{i+j}, i \geq-1, j \geq 1$;
iv) $L_{X_{i}} \pi_{j}=(j-i-2) \pi_{i+j}, i \geq-1, j \geq 1$;
v) $\left[X_{i}, X_{j}\right]=(j-i) X_{i+j}, i \geq 0, j \geq 0$;
vi) $\pi_{j} \nabla H_{i}=\pi_{j-1} \nabla H_{i+1}$, where $\pi_{j}$ denotes the Poisson matrix of the tensor $\pi_{j}$.

Remark 1. Theorem 1 was extended for all integer values of the index in [5].
Remark 2. To define the vector fields $X_{n}$ one considers expressions of the form

$$
\dot{L}=[B, L]+L^{n+1} .
$$

This equation is similar to a Lax equation, but in this case the eigenvalues satisfy $\dot{\lambda}=\lambda^{n+1}$ instead of $\dot{\lambda}=0$.

## $3 \quad B_{N}$ Toda systems

In this section, we show that higher polynomial brackets exist also in the case of $B_{n}$ Toda systems. We will prove that these systems possess a recursion operator and we will construct an infinite sequence of compatible Poisson brackets in which the constants of motion are in involution. Finally, we show that these systems are bi-Hamiltonian. The Hamiltonian for $B_{n}$ is

$$
H=\frac{1}{2} \sum_{1}^{n} p_{j}^{2}+e^{q_{1}-q_{2}}+\cdots+e^{q_{n-1}-q_{n}}+e^{q_{n}} .
$$

We make a Flaschka-type transformation

$$
a_{i}=\frac{1}{2} e^{\frac{1}{2}\left(q_{i}-q_{i+1}\right)}, \quad a_{n}=\frac{1}{2} e^{\frac{1}{2} q_{n}}, \quad b_{i}=-\frac{1}{2} p_{i} .
$$

Then

$$
\dot{a}_{i}=a_{i}\left(b_{i+1}-b_{i}\right), \quad \dot{b}_{i}=2\left(a_{i}^{2}-a_{i-1}^{2}\right), \quad i=1, \ldots, n,
$$

with the convention that $a_{0}=b_{n+1}=0$.
These equations can be written as a Lax pair $\dot{L}=[B, L]$, where $L$ is the symmetric matrix

$$
L=\left(\begin{array}{cccccccc}
b_{1} & a_{1} & & & & & & \\
a_{1} & \ddots & \ddots & & & & & \\
& \ddots & \ddots & a_{n-1} & & & & \\
& & a_{n-1} & b_{n} & a_{n} & & & \\
& & & a_{n} & 0 & -a_{n} & & \\
& & & & -a_{n} & -b_{n} & \ddots & \\
& & & & & \ddots & \ddots & -a_{1} \\
& & & & & & -a_{1} & -b_{1}
\end{array}\right)
$$

and $B$ is the skew-symmetric part of $L$ (In the decomposition, lower Borel plus skew-symmetric). We note that the determinant of $L$ is zero.

In the new variables $a_{i}, b_{i}$, the canonical bracket on $\mathbb{R}^{2 N}$ is transformed into a bracket $\pi_{1}$ which is given by

$$
\left\{a_{i}, b_{i}\right\}=-a_{i}, \quad\left\{a_{i}, b_{i+1}\right\}=a_{i}
$$

It is easy to show by induction that

$$
\operatorname{det} \pi_{1}=a_{1}^{2} a_{2}^{2} \cdots a_{n}^{2}
$$

The invariant polynomials for $B_{n}$, which we denote by

$$
H_{2}, \quad H_{4}, \ldots, \quad H_{2 n}
$$

are defined by $H_{2 i}=\frac{1}{2 i} \operatorname{Tr} L^{2 i}$.
We look for a bracket $\pi_{3}$ which satisfies

$$
\pi_{3} \nabla H_{2}=\pi_{1} \nabla H_{4} .
$$

We define the following homogeneous cubic bracket $\pi_{3}$ :

$$
\begin{aligned}
& \left\{a_{i}, a_{i+1}\right\}=a_{i} a_{i+1} b_{i+1}, \quad\left\{a_{i}, b_{i}\right\}=-a_{i} b_{i}^{2}-a_{i}^{3}, \quad\left\{a_{n}, b_{n}\right\}=-a_{n} b_{n}^{2}-2 a_{n}^{3}, \\
& \left\{a_{i}, b_{i+2}\right\}=a_{i} a_{i+1}^{2}, \quad\left\{a_{i}, b_{i+1}\right\}=a_{i} b_{i+1}^{2}+a_{i}^{3}, \\
& \left\{b_{i}, b_{i+1}\right\}=2 a_{i}^{2}\left(b_{i}+b_{i+1}\right), \quad\left\{a_{i}, b_{i-1}\right\}=-a_{i-1}^{2} a_{i}, \\
&
\end{aligned}
$$

We summarize the properties of this new bracket in the following:
Theorem 2. The bracket $\pi_{3}$ satisfies the following:

1. $\pi_{3}$ is Poisson;
2. $\pi_{3}$ is compatible with $\pi_{1}$;
3. $H_{2 i}$ are in involution.

Define $\mathcal{R}=\pi_{3} \pi_{1}^{-1}$. Then $\mathcal{R}$ is a recursion operator. We obtain a hierarchy

$$
\pi_{1}, \pi_{3}, \pi_{5}, \ldots
$$

consisting of compatible Poisson brackets of odd degree in which the constants of motion are in involution.
4. $\pi_{j+2} \operatorname{grad} H_{2 i}=\pi_{j} \operatorname{grad} H_{2 i+2} \forall i, j$.

The proof of this result is in [4].
Following the procedure outlined in the introduction we obtain a bi-Hamiltonian formulation of the system. In other words, we define $\pi_{-1}=\mathcal{N} \pi_{1}=\pi_{1} \pi_{3}^{-1} \pi_{1}$ and use it to obtain the desired formulation. We illustrate with the $B_{2}$ Toda system. In this case $\operatorname{det} \pi_{1}=a_{1}^{2} a_{2}^{2}$ and $\operatorname{det} \pi_{3}=a_{1}^{2} a_{2}^{2} \Delta^{2}=\operatorname{det} \pi_{1} \Delta^{2}$, where

$$
\Delta=a_{1}^{4}+2 a_{2}^{2} a_{1}^{2}+2 a_{2}^{2} b_{1}^{2}+b_{1}^{2} b_{2}^{2}-2 a_{1}^{2} b_{1} b_{2}
$$

The explicit formula for $\pi_{-1}$ is

$$
\pi_{-1}=\frac{1}{\Delta} A
$$

where

$$
A=\left(\begin{array}{cccc}
0 & -a_{1} a_{2} b_{2} & -a_{1}\left(b_{2}^{2}+a_{1}^{2}+2 a_{2}^{2}\right) & a_{1}\left(b_{1}^{2}+a_{1}^{2}+2 a_{2}^{2}\right) \\
a_{1} a_{2} b_{2} & 0 & a_{1}^{2} a_{2} & -a_{2}\left(b_{1}^{2}+2 a_{1}^{2}\right) \\
a_{1}\left(b_{2}^{2}+a_{1}^{2}+2 a_{2}^{2}\right) & -a_{1}^{2} a_{2} & 0 & -2 a_{1}^{2}\left(b_{1}+b_{2}\right) \\
-a_{1}\left(b_{1}^{2}+a_{1}^{2}+2 a_{2}^{2}\right) & a_{2}\left(b_{1}^{2}+2 a_{1}^{2}\right) & 2 a_{1}^{2}\left(b_{1}+b_{2}\right) & 0
\end{array}\right) .
$$

This bracket is Poisson by construction. It is also compatible with $\pi_{1}$. We note that $\Delta=\sqrt{\operatorname{det} \mathcal{R}}$ and it is also equal to the product of the non-zero eigenvalues of $L$. Using the rational bracket $\pi_{-1}$ we establish the bi-Hamiltonian nature of the system, i.e.

$$
\pi_{1} \nabla H_{2}=\pi_{-1} \nabla H_{4} .
$$

In fact the system is multi-Hamiltonian:

$$
\pi_{1} \nabla H_{2}=\pi_{-1} \nabla H_{4}=\pi_{-3} \nabla H_{6}=\cdots,
$$

where

$$
\pi_{-(2 i-1)}=\mathcal{N}^{i} \pi_{1} .
$$

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