

**ALARM DELAY EXPLANATION (references to "2 out of 4" alarm delay)**  
 Input of the alarm delay circuit is normally low (<math>V\_{in}</math> typically 0.5V or less). When it goes high (<math>V\_{in}</math> typically 3.4V or more), C2 starts charging with RC=4.4s. Thanks to the positive feedback resistor R18, there is a hysteresis on the "1" input of the comparator; its output (U2-2) goes from HIGH (typ. +4.95V) to LOW (typ. -0.1V) when C2 charges to 2.09V; transition from LOW back to HIGH will not then occur until the capacitor discharges to 1.49V. This leads to the following timing:

Minimum time before U2-2 goes LOW when U8-10 goes HIGH: approximately 3.3 sec (C2 charges from 0.2V to 2.1V,  $V_{in} = 3.8V$ )  
 Minimum time U2-2 stays LOW when U8-10 goes back to normal (LOW) state: approx. 1.7 sec (C2 discharges from 2.1V to 1.5V,  $V_{in} = 0.2V$ )  
 Maximum time U2-2 stays LOW when U8-10 goes back to normal (LOW) state: approx. 4.5 sec (C2 discharges from 3.8V to 1.5V,  $V_{in} = 0.2V$ )

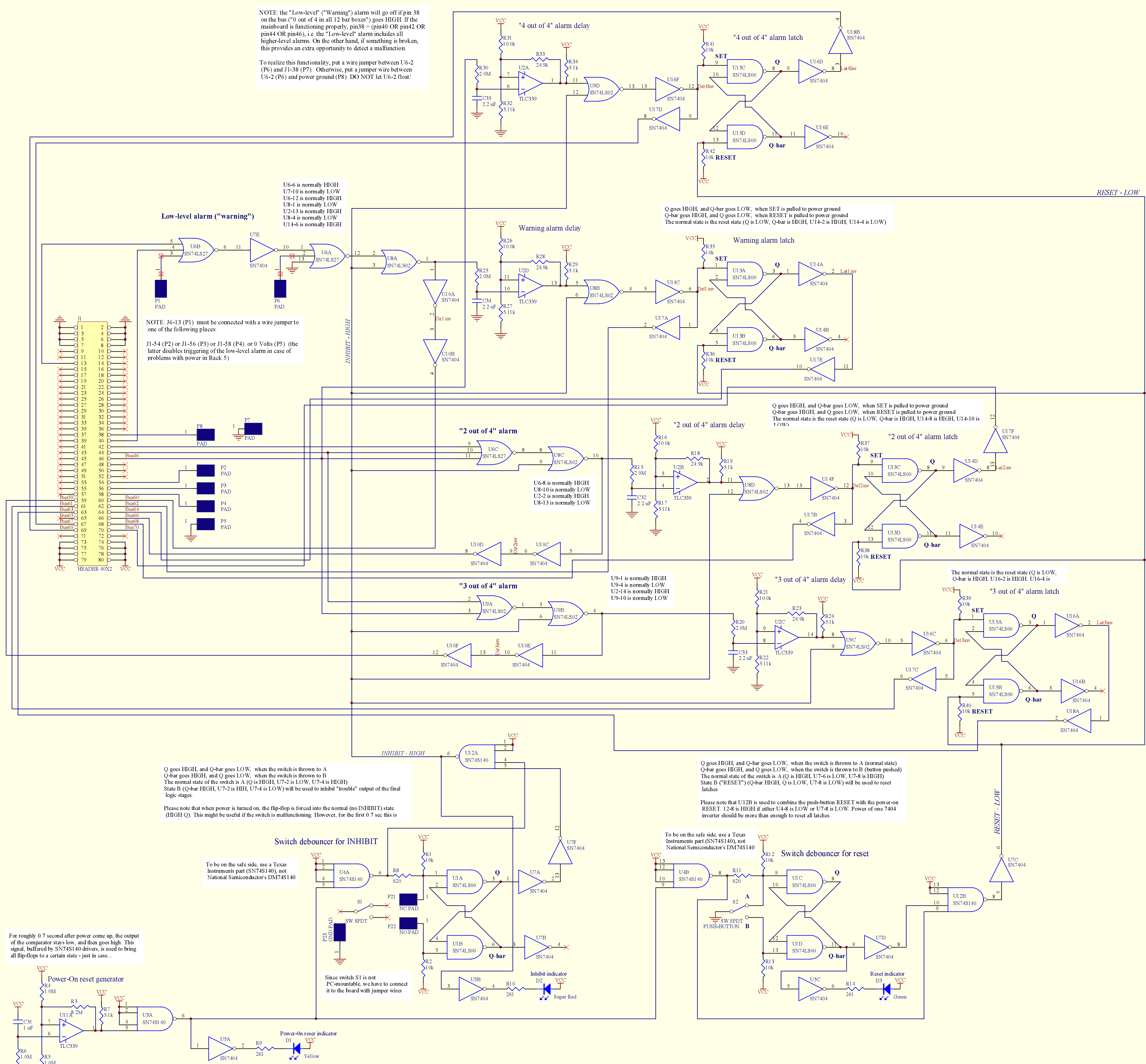
These timings can be scaled by changing RC (cap. 2.2 nF  $\rightarrow$  1.0 nF; 2.0M  $\rightarrow$  1.0M). Use mylar (polyester) capacitors, as they have lower leakage currents.  
 INHIBIT will immediately override delay's output, but will not immediately discharge capacitor C2. Please allow enough time (at least 5 sec) for C2 to discharge below 1.5V.  
 NOTE: If U8-10 randomly jumps between HIGH and LOW, U2-2 will go LOW if U8-10 spends at least 53% of all time in the HIGH state; U2-2 will then go back to normal (HIGH) if U8-10 spends not more than 36% of all time in the HIGH state. Time required for such a transition will grow EXPONENTIALLY, as time percentage approaches the threshold value. For example, if after sitting in normal state (LOW) for a long time U8-10 starts jumping around 70% of all time in the HIGH state, the time required for U2-2 to go LOW is approx. 6.3 sec; for 60%, it's approx. 9.3 sec. If this is unacceptable, decrease RC.

NOTE: Please do not worry about TLC339's input bias currents. They are typically in the picomper range. DO NOT substitute it with LM339.

- All of the following pins are normally LOW:  
 J1-13 Broken water sensor cable  
 J1-38 "0 out of 4" in all 12 bar boxes  
 J1-40 "1 out of 4" trouble  
 J1-42 "2 out of 4" trouble  
 J1-44 "3 out of 4" trouble  
 J1-46 "4 out of 4" trouble  
 J1-54 VCCs in rack 5 and rack 38 differ by more than 0.25V  
 J1-56 VCCs in rack 5 and rack 38 differ by more than 0.5V  
 J1-58 VCC in rack 5 is below 3.5V, i.e. effectively off
- Final logic card outputs (all of them are normally LOW):  
 J1-60 Low-level alarm, direct  
 J1-62 Low-level alarm, delayed  
 J1-64 Low-level alarm, latched delayed  
 J1-66 "2 out of 4" alarm, direct  
 J1-68 "2 out of 4" alarm, delayed  
 J1-70 "2 out of 4" alarm, latched delayed  
 J1-72 "3 out of 4" alarm, direct  
 J1-74 "3 out of 4" alarm, delayed  
 J1-76 "3 out of 4" alarm, latched delayed  
 J1-78 "4 out of 4" alarm, direct  
 J1-80 "4 out of 4" alarm, delayed  
 J1-82 "4 out of 4" alarm, latched delayed
- For the remaining part of bus pin-out, see the schematic diagram for DATMAN-2

Q goes HIGH, and Q-bar goes LOW, when SET is pulled to power ground  
 Q-bar goes HIGH, and Q goes LOW, when RESET is pulled to power ground  
 The normal state is the reset state (Q is LOW, Q-bar is HIGH, U14-2 is HIGH, U14-4 is LOW)

NOTE: the "Low-level" ("Warning") alarm will go off if pin 38 on the bus ("0 out of 4" in all 12 bar boxes) goes HIGH. If the mainboard is functioning properly, pins 38 (pin40 OR pin42 OR pin44 OR pin46), i.e. the "Low-level" alarm includes all higher-level alarms. On the other hand, if something is broken, this provides an extra opportunity to detect a malfunction.  
 To realize this functionality, put a wire jumper between U6-2 (P6) and J1-38 (P7). Otherwise, put a jumper wire between U6-2 (P6) and power ground (P8). DO NOT let U6-2 float!



Title: BATMAN-5: The final logic card for the DIRC safety system		
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